

<b>Unit of Study</b>	COMP3888
<b>Team name</b>	COMP3888_T15A_Group1
<b>Project Name</b>	Optimal Path for Drone Delivery
<b>Project start date</b>	Monday, 14/09/2020
<b>Project end date</b>	Sunday, 29/11/2020
<b>Project point person</b>	Nicholas Hui
<b>Report Date</b>	9/11/2020

<b>Quick description</b>	Adding the weather factor into the algorithm, inserting multiple drones in the simulator, cleaning up the team's repository.
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Status item	Status up to last week	Planned for next week
<b>Scope</b>	Modification and improvement of the pathfinding algorithm.  Testing method for the algorithm.	Preparation for the group and individual reports and client demo and presentation.  Testing of the algorithm with weather factor included.
<b>Time</b>	Keeping on track with the project schedule, but a few problems arise after adding the weather factor.	
<b>Quality</b>	More testing of the algorithm will be needed for the weather-related factor.	
<b>Planned Activities</b>	Bitbucket repository clean up.  Generate more test cases for the pathfinding algorithm.  Obstacle avoidance feature working in the simulator but not able to implement in the project.  Implementation of multiple drone control in the simulator.  Started using ROS to launch the simulator environment, allowing for drone starting location to be specified.  World modelling for a demo of scenarios from the client's scope	Design more test cases related to different weather conditions.  Documentation of the obstacle avoidance features.  More testing of the MissionScript.  Setting up a new world environment for the client demo and presentation in the simulator.

<b>Achievements</b>	Weather conditions have been taken into considerations in the algorithm design.	
<b>Major deliverables</b>	Weather module added to the algorithm library to get an affected working route of the drone.	
<b>Major issues</b>	Part of the algorithm code needed to be rewritten due to the newly added weather module.	
<b>Major risks</b>	The weather module disturbs the result of the algorithm so that it didn't return our expected path.	
<b>External dependencies</b>	NIL	NIL
<b>Estimated effort (h)</b>	15hr/person	16hr/person
<b>Recorded effort (h)</b>	16hr/person (on average)	
<b>Overall Status (RYG)</b>	GREEN	