

On my honor, I submit that I have neither given or received assistance on this exam or consulted any prohibited materials (beyond the one page crib sheet allowed for the exam).

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## MEGR 3122 Dynamics Systems II: Exam 1, Spring 2022

### Multiple Choice Problems (Total 20 Points)

Directions: Circle the best answer. Each question is worth 2 points.

1. In this course, system dynamics are modeled as:

A. partial differential equations  
☒ B. ordinary differential equations  
 C. hyperbolic equations  
 D. asymptotic equations

2. If  $x(t)$  is a function of time (the state of a mechanical system), and  $a$  and  $b$  are constants, then  $\ddot{x} + a\dot{x} + \sqrt{b}t = 1$  is which of the following?

A. linear, time-varying, second-order, homogeneous  
 B. linear, time-invariant, second-order, homogeneous  
☒ C. linear, time-invariant, second-order, inhomogeneous  
 D. nonlinear

$$\ddot{x} + a\dot{x} = g(t) \\ \text{time invariant} \quad = 1 - \sqrt{b}t \\ \neq 0 \text{ inhomog.}$$

3. Which case in Fig. 1 (below) could plausibly represent the response of a system  $\dot{x} - 2x = 0$ ? (Note: the initial condition is not necessary to answer this question.)

A. Case 1  
☒ B. Case 2  
 C. Case 3  
 D. Both Case 1 and Case 2

if  $a < 0$  then  $x(t)$  diverges to  $+\infty$  or  $-\infty$

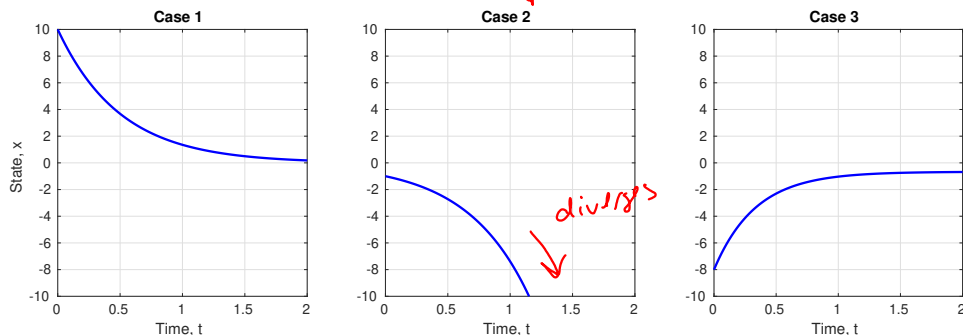


Figure 1: System response

4. Consider the following initial value problem:

$$\dot{x} + 4x = 0, \quad \underline{x(0) = 5}$$

The solution is:

☒ A.  $x(t) = 5e^{-4t}$       B.  $x(t) = 4e^{-5t}$       C.  $x(t) = e^{-4t} \cos 5t$       D.  $x(t) = e^{4t} \sin t$

5. If  $z_1 = -i$  and  $z_2 = e^{i\pi/2}$ , then what is the sum  $z_1 + z_2$ ?

A.  $i$   
 B. 1  
 C. -1  
☒ D. 0

$$\begin{aligned} z_2 &= i \\ z_1 &= -i \\ \Rightarrow z_1 + z_2 &= 0 \end{aligned}$$

6. Consider the following system

$$\dot{x} + ax = 0$$

with initial condition of  $x(0) = 100$ . The state  $x(t)$  decays to a value of 36.8 after 3 seconds. That is,  $x(3) = 36.8$ . What is the value of  $a$ ?

- A.  $a = 100/3$   
 B.  $a = 1/3$   
 C.  $a = 3$   
 D.  $a = (100 - 36.8)/3$

36.8% of 100 implies  
 1 time constant  
 $\tau = 3, \Rightarrow a = \frac{1}{\tau} = \frac{1}{3}$

7. What is the Laplace transform of the function  $x(t) = (t-2)H(t-2)$ , where  $H(\cdot)$  is the unit step or Heaviside function?

$\mathcal{L}[t] = 1/s^2$   
 using translated LT theorem  
 ramp shifted by  $\alpha = 2$

- A.  $\frac{1}{s^2}$   
 B.  $\frac{1}{(s+1)^2}$   
 C.  $\frac{e^{-2s}}{s^2}$   
 D.  $\frac{2!}{(s-2)^2}$

8. Consider the second order system  $6\ddot{x} + 3x = 0$  and define a new set of variables  $z_1 = x$  and  $z_2 = \dot{x}$ . Which of the following first-order systems of two equations (in  $z_1$  and  $z_2$ ) is equivalent to the second order system (in  $x$ )?

$\dot{z}_1 = \dot{x} = z_2$   
 $\dot{z}_2 = \ddot{x} = -\frac{3}{6}x = -\frac{1}{2}z_1$

- A.  $\begin{aligned} \dot{z}_1 &= z_2 \\ \dot{z}_2 &= 6z_1 + 3z_2 \end{aligned}$   
 B.  $\begin{aligned} \dot{z}_1 &= 3z_2 \\ \dot{z}_2 &= 6z_1 \end{aligned}$   
 C.  $\begin{aligned} \dot{z}_1 &= z_2 \\ \dot{z}_2 &= 6z_2 + 3z_1 \end{aligned}$   
 D.  $\begin{aligned} \dot{z}_1 &= z_2 \\ \dot{z}_2 &= -(1/2)z_1 \end{aligned}$

9. Which case in Fig. 2 (below) could plausibly represent the response of a system  $\ddot{x} + \dot{x} + x = 0$  with  $x(0) = 4$  and  $\dot{x}(0) = -10$ ?

- A. Case 1  
 B. Case 2  
 C. Case 3  
 D. None of the above

$\hookrightarrow$  slope should be downward

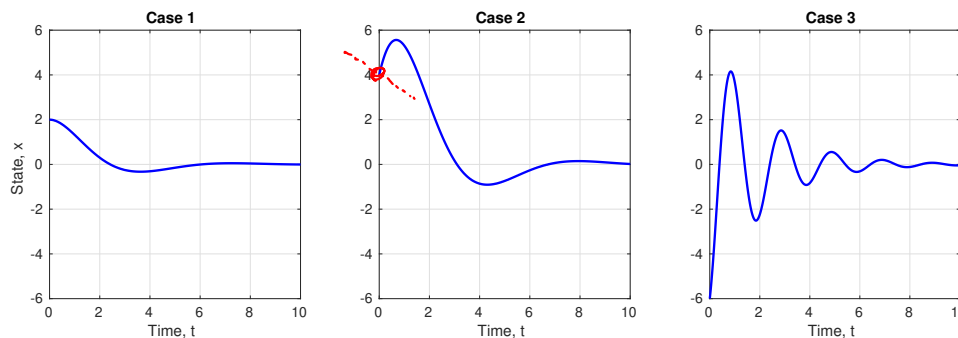


Figure 2: System response

10. What is the final value of  $x(t)$  as  $t \rightarrow \infty$  if the Laplace transform of  $x(t)$  is the following?

$$X(s) = \frac{s+10}{5s^2+2s+1}$$

- A.  $x(t) \rightarrow 10$   
 B.  $x(t) \rightarrow 5$   
 C.  $x(t) \rightarrow 2$   
 D.  $x(t) \rightarrow 1$

skipped

## Workout Problem Instructions

To receive full credit on the workout problems show all of your work.

### Workout Problem 1 (5 pts)

Consider the ODE

$$\ddot{x} + 4\dot{x} + 8x = 0$$

with initial conditions  $x(0) = 0$  and  $\dot{x}(0) = 10$ .

- Find the eigenvalues of the system
- State the general solution of the ODE
- Determine the particular solution  $x(t)$  that satisfies the initial conditions

Eigenvalues

$$\lambda^2 + 4\lambda + 8 = 0$$

$$(\lambda + 2)^2 = \lambda^2 + 4\lambda + 4 = -4$$

$$\lambda_{1,2} = -2 \pm 2i$$

General soln:  $x(t) = e^{-2t} (A \cos(2t) + B \sin(2t))$

I.C.s

$$x(0) = 0 = A \cdot \underbrace{\cos(0)}_{=1} \Rightarrow A = 0$$

$\Rightarrow$

$$\dot{x}(0) = 10 = -2e^{-2t} B \sin(2t) \big|_{t=0} + e^{-2t} (B \cdot 2 \cdot \cos(2t)) \big|_{t=0}$$

$$10 = 2B \Rightarrow B = 5$$

$x(t) = 5e^{-2t} \sin(2t)$

### Workout Problem 2 (5 pts)

Compute the Laplace transform  $F(s) = \mathcal{L}[f(t)]$  of the following function:

$$f(t) = \frac{e^{-t}}{4} [2 + t^2 + \cos(3t)]$$

$$f(t) = \frac{e^{-t}}{4} (2 + t^2 + \cos(3t))$$

$$= \frac{2}{4} e^{-t} + \frac{1}{2} \left( \frac{t^2}{2} e^{-t} \right) + \frac{1}{4} e^{-t} \cos 3t$$

$$\begin{aligned} F(s) &= \frac{1}{2} \mathcal{L}[e^{-t}] + \frac{1}{2} \mathcal{L}\left[\frac{t^2 e^{-t}}{2}\right] + \frac{1}{4} \mathcal{L}[e^{-t} \cos(3t)] \\ &\quad \left\{ \begin{array}{l} \text{row 6} \\ \text{row 8} \\ \text{row 21} \end{array} \right. \quad \begin{array}{l} a=1 \\ \omega=3 \end{array} \\ &= \frac{1}{2} \left[ \frac{1}{s+1} \right] + \frac{1}{2} \left[ \frac{1}{(s+1)^3} \right] + \frac{1}{4} \left[ \frac{s+1}{(s+1)^2 + 9} \right] \end{aligned}$$

### Workout Problem 3 (5 pts)

Compute the inverse Laplace transform  $f(t) = \mathcal{L}^{-1}[F(s)]$  of the following function:

$$F(s) = \frac{s+1}{s^2+6s+9}$$

$$F(s) = \frac{(s+1)}{(s^2+6s+9)} = \frac{(s+1)}{(s+3)^2} = \frac{C_1}{(s+3)} + \frac{C_2}{(s+3)^2}$$

$\nwarrow$   
repeated roots

$$\begin{aligned} (s+1) &= C_1(s+3) + C_2 \\ s+1 &= C_1 s + (3C_1 + C_2) \end{aligned}$$

$$\Rightarrow \boxed{C_1 = 1}$$

$$1 = 3 + C_2 \Rightarrow \boxed{C_2 = -2}$$

$$F(s) = \frac{1}{(s+3)} - \frac{2}{(s+3)^2}$$

$$\begin{aligned} f(t) &= \mathcal{L}^{-1}\left[\frac{1}{s+3}\right] - 2 \mathcal{L}^{-1}\left[\frac{1}{(s+3)^2}\right] \\ &= e^{-3t} - 2te^{-3t} \end{aligned}$$

**Table 2.1** Laplace transforms [2]

	$f(t)$	$F(s)$
1	Unit impulse $\delta(t)$	1
2	Unit step $u(t)$	$\frac{1}{s}$
3	$t$	$\frac{1}{s^2}$
4	$\frac{t^{n-1}}{(n-1)!}, \quad n = 1, 2, 3, \dots$	$\frac{1}{s^n}$
5	$t^n, \quad n = 1, 2, 3, \dots$	$\frac{n!}{s^{n+1}}$
6	$e^{-at}$	$\frac{1}{s+a}$
7	$te^{-at}$	$\frac{1}{(s+a)^2}$
8	$\frac{t^{n-1}}{(n-1)!}e^{-at}, \quad n = 1, 2, 3, \dots$	$\frac{1}{(s+a)^n}$
9	$t^n e^{-at}, \quad n = 1, 2, 3, \dots$	$\frac{n!}{(s+a)^{n+1}}$
10	$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$
11	$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$
12	$\sinh(\omega t)$	$\frac{\omega}{s^2 - \omega^2}$
13	$\cosh(\omega t)$	$\frac{s}{s^2 - \omega^2}$
14	$\frac{1}{a}(1 - e^{-at})$	$\frac{1}{s(s+a)}$
15	$\frac{1}{b-a}(e^{-at} - e^{-bt})$	$\frac{1}{(s+a)(s+b)}$
16	$\frac{1}{b-a}(be^{-bt} - ae^{-at})$	$\frac{s}{(s+a)(s+b)}$
17	$\frac{1}{ab}\left(1 + \frac{1}{a-b}(be^{-at} - ae^{-bt})\right)$	$\frac{1}{s(s+a)(s+b)}$
18	$\frac{1}{a^2}(1 - e^{-at} - ate^{-at})$	$\frac{1}{s(s+a)^2}$
19	$\frac{1}{a^2}(at - 1 + e^{-at})$	$\frac{1}{s^2(s+a)}$
20	$e^{-at} \sin(\omega t)$	$\frac{\omega}{(s+a)^2 + \omega^2}$
21	$e^{-at} \cos(\omega t)$	$\frac{s+a}{(s+a)^2 + \omega^2}$
22	$\frac{\omega_n}{\sqrt{1-\zeta^2}}e^{-\zeta\omega_n t} \sin\left(\omega_n \sqrt{1-\zeta^2} t\right)$	$\frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$

(continued)

**Table 2.1** (continued)

	$f(t)$	$F(s)$
23	$-\frac{1}{\sqrt{1-\zeta^2}}e^{-\zeta\omega_n t} \sin\left(\omega_n \sqrt{1-\zeta^2}t - \phi\right)$ $\phi = \tan^{-1}\left(\frac{\sqrt{1-\zeta^2}}{\zeta}\right)$	$\frac{s}{s^2 + 2\zeta\omega_n s + \omega_n^2}$
24	$1 - \frac{1}{\sqrt{1-\zeta^2}}e^{-\zeta\omega_n t} \sin\left(\omega_n \sqrt{1-\zeta^2}t + \phi\right)$ $\phi = \tan^{-1}\left(\frac{\sqrt{1-\zeta^2}}{\zeta}\right)$	$\frac{\omega_n^2}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)}$
25	$1 - \cos(\omega t)$	$\frac{\omega^2}{s(s^2 + \omega^2)}$
26	$\omega t - \sin(\omega t)$	$\frac{\omega^3}{s^2(s^2 + \omega^2)}$
27	$\sin(\omega t) - \omega t \cos(\omega t)$	$\frac{2\omega^3}{(s^2 + \omega^2)^2}$
28	$\frac{1}{2\omega}t \sin(\omega t)$	$\frac{s}{(s^2 + \omega^2)^2}$
29	$t \cos(\omega t)$	$\frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}$
30	$\frac{1}{\omega_2^2 - \omega_1^2}(\cos(\omega_1 t) - \cos(\omega_2 t)), \omega_1^2 \neq \omega_2^2$	$\frac{s}{(s^2 + \omega_1^2)(s^2 + \omega_2^2)}$
31	$\frac{1}{2\omega}(\sin(\omega t) + \omega t \cos(\omega t))$	$\frac{s^2}{(s^2 + \omega^2)^2}$