Name: _____

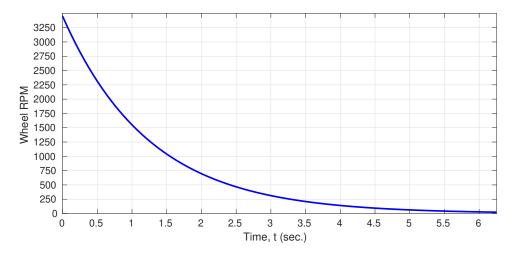
MEGR 3122 Dynamics Systems II: Exam 1, Spring 2023

Directions: Circle the best answer. Show your work to receive full credit.

1. (2 points) A bench grinder is spinning at a rate of $\omega_0 = 3{,}450$ RPM when it is turned off and the wheel coasts to a stop. The wheel velocity is modeled according to:

$$\dot{\omega} + b\omega = 0, \ \omega(t_0) = \omega_0, \ t_0 = 0$$

where b is a damping coefficient. A plot of the angular velocity measured with a tachometer is shown below. What is a reasonable estimate for the value of b?



- A. 1/3
- B. 0.8
- C. 1.4
- D. 3.1
- E. 6.3

Solution (B). Reading the plot we see that the RPM decays to $0.368\omega_0 \approx 1,269$ at around 1.2 seconds which implies that $\tau = 1.2$ and thus $a = 1/1.2 \approx 0.8$.

2. (4 points) What is the imaginary part of the quantity below?

$$z = \frac{i-4}{2i-3} \cdot e^{i\pi/2}$$

- A. 14/13
- B. 5/13
- C. 5/14
- D. $5/(2\pi)$
- E. -5/13

Solution (A). Note that $e^{i\pi/2} = i$

$$z = \frac{i-4}{2i-3} \frac{2i+3}{2i+3} \cdot i \tag{1}$$

$$= \frac{i(2i+3) - 4(2i+3)}{-4 - 9} \cdot i$$

$$= \frac{-2 + 3i - 8i - 12}{-13} \cdot i$$

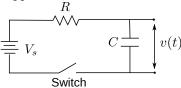
$$= \frac{-14i + 5}{-13}$$
(4)

$$= \frac{-2+3i-8i-12}{-13} \cdot i \tag{3}$$

$$=\frac{-14i+5}{-13}$$
 (4)

$$= -\frac{5}{13} + \frac{14}{13}i\tag{5}$$

3. (4 points) The RC circuit shown below has a resistor R = 0.5 and a capacitor C = 2 and voltage supplied $V_s = 5$.



The equation modeling the system is

$$RC\frac{dv(t)}{dt} + v(t) = V_s$$

where v(t) is the voltage measured at the output across the capacitor and V_s is a constant voltage supplied by a battery. What is the value of v(t) at one second after the switch is closed? Assume the initial output voltage is $v(t_0) = 0$. (Hint: re-write the above equation in more familiar notation.)

A. 0.47 V

B. 1.66 V

C. 2.30 V

D. 3.16 V

E. 5.00 V

Solution (D). First, we write this equation in more familiar notation. Divide through by RC and let a = 1/(RC) and $u = V_s/RC$:

$$\dot{v} + av = u$$

For a constant u the general solution is:

$$x(t) = ue^{-at} \int e^{at} dt + Ce^{-at}$$
(6)

$$= ue^{-at}[(1/a)e^{at}] + Ce^{-at}$$
 (7)

$$= (u/a) + Ce^{-at} \tag{8}$$

and with the initial condition

$$x(0) = 0 = (u/a) + C$$

implies that

$$x(t) = (u/a)(1 - e^{-at}) (9)$$

$$= ([V_s/RC]/[1/RC])(1 - e^{-at})$$
(10)

$$=V_s(1-e^{-(1/(RC))t}) (11)$$

Evaluating with the values provided gives v(t) = 3.16 V at t = 1.

- 4. (4 points) The general solution of a second order ODE with initial conditions x(0) = 1 and $\dot{x}(0) = 3$ is found to be $x(t) = e^{-t}(c_1 \cos 2t + c_2 \sin 2t)$. What is the particular solution?
 - A. $x(t) = e^{-t}(6\cos 2t + 4\sin 2t)$
 - B. $x(t) = e^{-t}(\cos 2t + 4\sin 2t)$
 - C. $x(t) = e^{-t}(\cos 2t + 2\sin 2t)$
 - D. $x(t) = 2e^{-t}(\cos 2t + \sin 2t)$
 - $E. \ x(t) = 6e^{-t} \sin 2t$

Solution (C). Using the first initial condition

$$x(0) = 1 = e^{0}(c_{1}\cos 0 + c_{2}\sin 0) \tag{12}$$

$$\implies c_1 = 1 \tag{13}$$

Differentiating the general solution,

$$\dot{x}(t) = -e^{-t}(c_1 \cos 2t + c_2 \sin 2t) + e^{-t}(c_1[-2\sin 2t] + c_2[2\cos 2t]) \tag{14}$$

and applying the second initial condition

$$\dot{x}(0) = 3 = -c_1 + 2c_2 \tag{15}$$

$$\implies c_2 = 2 \tag{16}$$

Thus,

$$x(t) = e^{-t}(\cos 2t + 2\sin 2t)$$

5. (4 points) What is the partial fraction expansion of the Laplace transform of $\ddot{x} + 4\dot{x} + 5x = 0$ with x(0) = 1 and $\dot{x}(0) = -1$?

A.
$$X(s) = \frac{(s+2)}{(s+2)^2+1}$$

B.
$$X(s) = \frac{s+3}{s^2+4s+6}$$

C.
$$X(s) = \frac{1}{(s+2)^2+1} - \frac{2(s+1)}{(s+1)^2+2}$$

D.
$$X(s) = \frac{1}{(s+2)^2+1} - \frac{(s+2)}{(s+2)^2+1}$$

E.
$$X(s) = \frac{1}{(s+2)^2+1} + \frac{(s+2)}{(s+2)^2+1}$$

Solution (E). Taking the Laplace transform

$$\mathcal{L}[\ddot{x}] + 4\mathcal{L}[\dot{x}] + 5\mathcal{L}[x] = 0 \tag{17}$$

$$[s^{2}X(s) - sx(0) - \dot{x}(0)] + 4[sX(s) - x(0)] + 5X(s) = 0$$
(18)

$$[s^{2}X(s) - s + 1] + 4[sX(s) - 1] + 5X(s) = 0$$
(19)

$$s^{2}X(s) - s + 1 + 4sX(s) - 4 + 5X(s) = 0$$
(20)

$$s^{2}X(s) + 4sX(s) + 5X(s) = s + 3$$
(21)

$$X(s) = \frac{s+3}{s^2+4s+5} \tag{22}$$

The poles are $p_{1,2} = (-4 \pm \sqrt{16 - 20}/2 = -2 \pm i)$ and therefore the PFE is of the form

$$X(s) = c_1 \frac{1}{(s+2)^2 + 1} + c_2 \frac{(s+2)}{(s+2)^2 + 1}$$
(23)

Equating numerators,

$$s+3 = c_1 + c_2(s+2) \tag{24}$$

$$= c_2 s + (c_1 + 2c_2) (25)$$

which implies that $c_1 = 1$ and $c_2 = 1$ so

$$X(s) = \frac{1}{(s+2)^2 + 1} + \frac{(s+2)}{(s+2)^2 + 1}$$
 (26)

6. (4 points) What is the initial value of x(t) if the Laplace transform of x(t) is the following?

$$X(s) = \frac{5s^2 + 2s + 7}{4s^3 + 3s^2 + 2s}$$

A.
$$x(0) = 7/3$$

B.
$$x(0) = 5/4$$

C.
$$x(0) = 2/3$$

D.
$$x(0) = 7/9$$

E.
$$x(0) = 4/5$$

Solution (B). Using the initial value theorem

$$\lim_{t \to 0} x(t) = \lim_{s \to \infty} s \left(\frac{5s^2 + 2s + 7}{4s^3 + 3s^2 + 2s} \right)$$

$$= \lim_{s \to \infty} s \left(\frac{5s^2 + 2s + 7}{4s^2 + 3s + 2} \right)$$

$$= \lim_{s \to \infty} s \left(\frac{5 + 2/s + 7/s^2}{4 + 3/s + 2/s^2} \right)$$

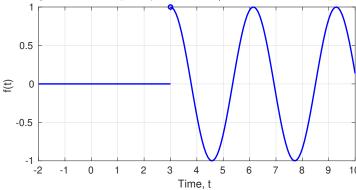
$$= 5/4 = 1.25$$
(27)
(28)

$$= \lim_{s \to \infty} s \left(\frac{5s^2 + 2s + 7}{4s^2 + 3s + 2} \right) \tag{28}$$

$$= \lim_{s \to \infty} s \left(\frac{5 + 2/s + 7/s^2}{4 + 3/s + 2/s^2} \right) \tag{29}$$

$$= 5/4 = 1.25 \tag{30}$$

7. (4 points) The input signal f(t) below is applied to a dynamic system starting at t=3 seconds. The signal has a frequency $\omega=2$ rad/s. What is the Laplace transform F(s)?



A.
$$e^{-s} \frac{(s+3)}{(s+3)^2+4}$$

B.
$$e^{-(s-3)} \frac{(s-3)}{(s-3)^2+4}$$

C.
$$e^{-3s} \frac{s}{s^2+4}$$

D.
$$\frac{1}{s^2+4}$$

E.
$$\frac{s}{s^2+4}$$

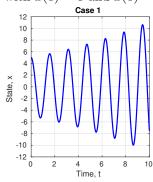
Solution (C). The unshifted/nominal signal is $f(t) = \cos \omega t$ whereas the shifted signal is f(t-3)H(t-3). Applying the Laplace transform for shifted signals:

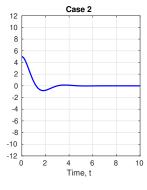
$$\mathcal{L}[f(t-3)H(t-3)] = e^{-3s}F(s)$$

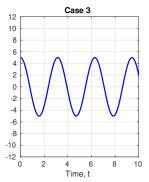
$$= e^{-3s}\frac{s}{s^2+4}$$

where we've used the LT table entry for $\cos(\omega t)$ with $\omega = 2$.

8. (2 points) Which case below could plausibly represent the response of a system $\ddot{x} - 0.16\dot{x} + 16x = 0$ with x(0) = 5 and $\dot{x}(0) = 0$?







- A. Case 1
- B. Case 2
- C. Case 3
- D. None of the above
- E. All of the above
- **Solution (A).** All of the cases satisfy the initial condition. The ODE is second order with a < 0, hence the response should be unstable as shown in Case 1.

9. (4 points) The inverse Laplace transform of

$$X(s) = \frac{7}{(s+3)(s+5)}$$

is which of the following?

A.
$$x(t) = \frac{5}{2}e^{3t} - \frac{5}{2}e^{5t}$$

B.
$$x(t) = \frac{7}{2}e^{5t} - \frac{5}{2}e^{3t}$$

C.
$$x(t) = \frac{7}{2}e^{-3t} - \frac{7}{2}te^{-5t}$$

D.
$$x(t) = \frac{7}{2}e^{-3t} - \frac{7}{2}e^{-5t}$$

E.
$$x(t) = \frac{5}{3}\cos 3t - \frac{5}{3}\sin 5t$$

Solution(D). There are two real-distinct pole $p_1 = -3$ and $p_2 = -5$. Thus, the PFE has the form

$$X(s) = \frac{a_1}{(s+3)} + \frac{a_2}{(s+5)}$$

We can solve for a_1 as

$$a_1 = \frac{7}{(s+5)} \bigg|_{s=-3} = 7/2$$

We can solve for a_2 as

$$a_2 = \frac{7}{(s+3)} \Big|_{s=-5} = -7/2$$

Then the solution is:

$$x(t) = \frac{7}{2}e^{-3t} - \frac{7}{2}e^{-5t} \tag{31}$$

10. (6 points) What is the solution to the dynamic system below?

$$\ddot{x} + 16x = \cos 3t$$
, $x(0) = 0$, $\dot{x}(0) = 0$

- A. $x(t) = \sin 4t + \sin 3t$
- B. $x(t) = \frac{1}{7}\cos 3t \frac{1}{7}\cos 4t$
- C. $x(t) = 4\cos 3t \cos 4t$
- D. $x(t) = \frac{9}{16}\cos 3t \frac{9}{16}\cos 4t$
- E. $x(t) = \frac{9}{16}\sin 3t + \frac{1}{7}\cos 4t$

Solution (B). Take the Laplace transform

$$X(s)(s^{2}+16) = \frac{s}{s^{2}+9}$$

$$X(s) = \frac{s}{(s^{2}+16)(s^{2}+9)}$$
(32)

$$X(s) = \frac{s}{(s^2 + 16)(s^2 + 9)} \tag{33}$$

The poles are $p_{1,2}=\pm 3i$ and $p_{3,4}=\pm 4i$ so the partial fraction expansion is

$$X(s) = \frac{s}{(s^2 + 16)(s^2 + 9)} = \frac{a_1}{s^2 + 9} + \frac{a_2s}{s^2 + 9} + \frac{a_3}{s^2 + 16} + \frac{a_4s}{s^2 + 16}$$
(34)

Multiplying to eliminate the denominators

$$s = a_1(s^2 + 16) + a_2s(s^2 + 16) + a_3(s^2 + 9) + a_4s(s^2 + 9)$$
(35)

$$= a_1 s^2 + 16a_1 + c_2 s^3 + 16c_2 s + c_3 s^2 + 9c_3 + c_4 s^3 + 9c_4 s$$
(36)

$$= (c_2 + c_4)s^3 + (c_1 + c_3)s^2 + (16c_2 + 9c_4)s + 16c_1 + 9c_3$$
(37)

Equating coefficients:

$$s^3: c_2 + c_4 = 0 \implies c_2 = -c_4$$
 (38)

$$s^2: c_1 + c_3 = 0 \implies c_1 = -c_3$$
 (39)

$$s^1: 16c_2 + 9c_4 = 1 \implies -7c_4 + 9c_4 = 1$$
 (40)

$$s^0: 16c_1 + 9c_3 = 0 \implies -16c_2 + 9c_3 = 0$$
 (41)

(42)

so that $c_3 = c_1 = 0$, $c_2 = 1/7$ and $c_4 = -1/7$. The solution is then

$$x(t) = \frac{1}{7}\mathcal{L}^{-1} \left[\frac{s}{s^2 + 9} \right] - \frac{1}{7}\mathcal{L}^{-1} \left[\frac{s}{s^2 + 16} \right]$$
 (43)

$$= \frac{1}{7}\cos 3t - \frac{1}{7}\cos 4t \tag{44}$$