

Equation of motion for Coin (All symbols have same meaning as given in the question)

$$m \left(\frac{d^2}{dt^2} x(t) \right) = 0 \quad \dots \dots (eq 1)$$

$$m \left(\frac{d^2}{dt^2} y(t) \right) = 0 \quad \dots \dots (eq 2)$$

$$m \left(\frac{d^2}{dt^2} z(t) \right) = 0 \quad \dots \dots (eq 3)$$

$$\frac{m \left(r^2 \left(\frac{d}{dt} \theta_2(t) \right) \cos(\theta_2(t)) \sin(\theta_2(t)) \left(\frac{d}{dt} \theta_1(t) \right) - \frac{r^2 (\cos^2(\theta_2(t)) - 2) \left(\frac{d^2}{dt^2} \theta_1(t) \right)}{2} + r^2 \left(\frac{d}{dt} \theta_2(t) \right) \cos(\theta_2(t)) \left(\frac{d}{dt} \theta_3(t) \right) + r^2 \sin(\theta_2(t)) \left(\frac{d^2}{dt^2} \theta_3(t) \right) \right)}{2} = 0 \quad \dots (eq 4)$$

$$\frac{m r^2 \left(\frac{d^2}{dt^2} \theta_2(t) \right)}{4} - \frac{m \left(\frac{r^2 \cos(\theta_2(t)) \sin(\theta_2(t)) \left(\frac{d}{dt} \theta_1(t) \right)^2}{2} + r^2 \left(\frac{d}{dt} \theta_1(t) \right) \cos(\theta_2(t)) \left(\frac{d}{dt} \theta_3(t) \right) \right)}{2} - mgr \sin(\theta_2(t)) = 0 \quad \dots \dots (eq 5)$$

$$\frac{m \left(r^2 \left(\frac{d^2}{dt^2} \theta_1(t) \right) \sin(\theta_2(t)) + r^2 \left(\frac{d}{dt} \theta_1(t) \right) \left(\frac{d}{dt} \theta_2(t) \right) \cos(\theta_2(t)) + r^2 \left(\frac{d^2}{dt^2} \theta_3(t) \right) \right)}{2} = 0 \quad \dots \dots (eq 6)$$