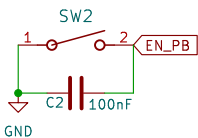
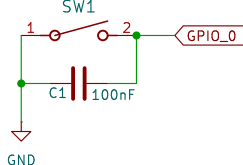


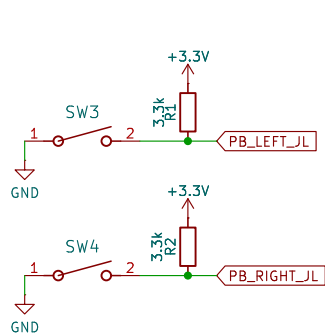
Enable ESP32 Button



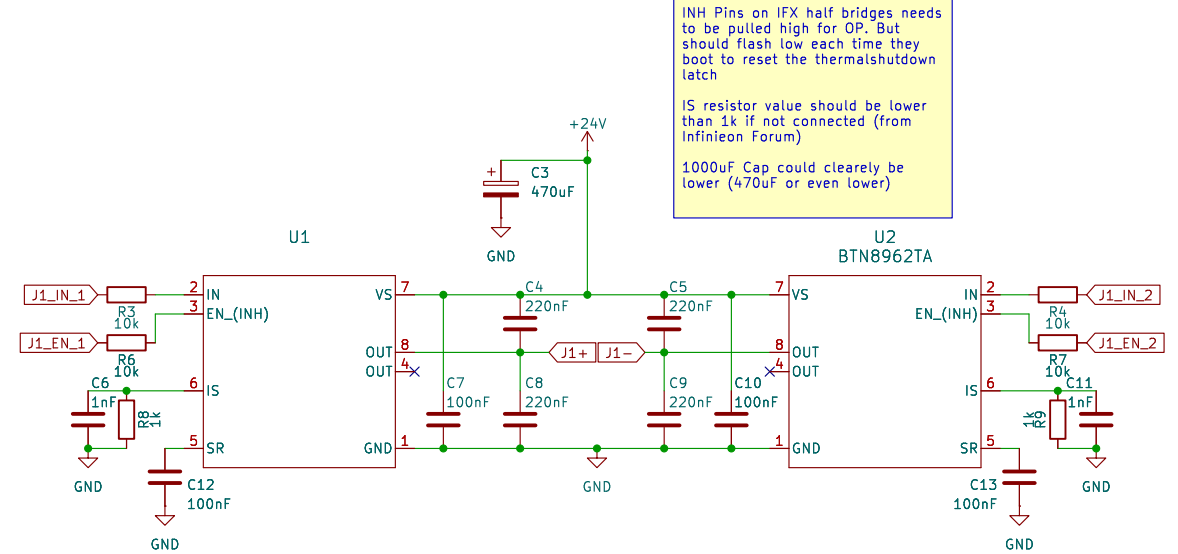
Boot ESP32 Button



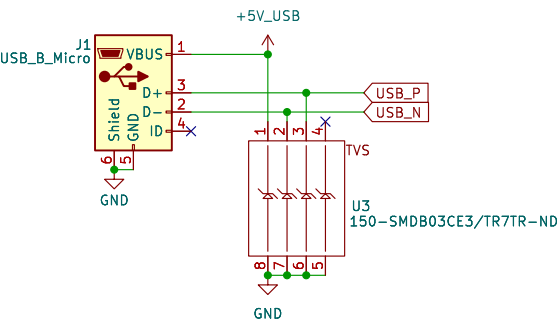
Manual Jog buttons



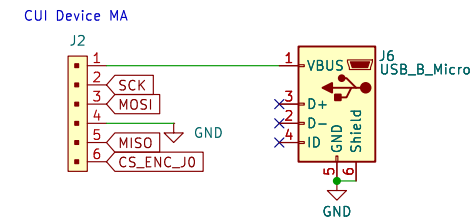
H-Bridge 20A motor



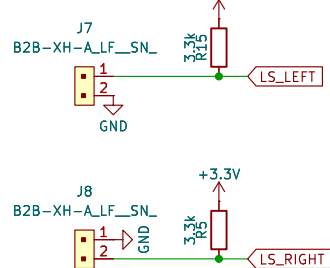
USB Port ESP32



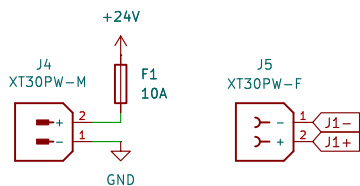
Encoder In



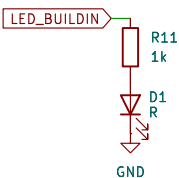
Limit switches



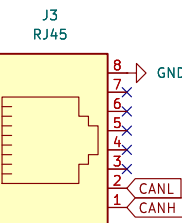
Power Connector (IN/OUT + J0 + J1)



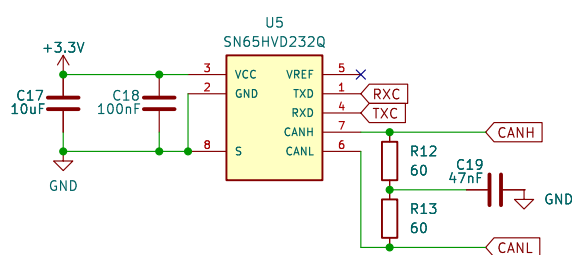
LED Build In



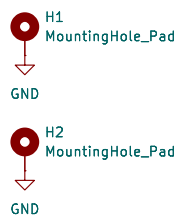
Data Connectors



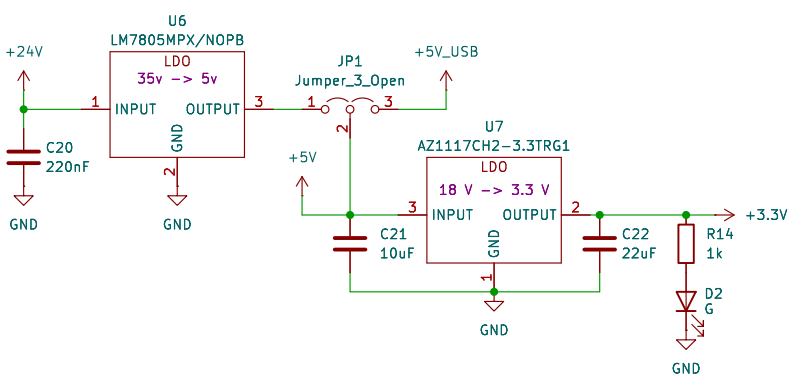
CAN Transceiver



Mounting Holes



ESP LDO



Rev1: Added fuse to 24V in and to both h-bridges

Philippe Michaud

Sheet: /

File: arm_drive_jl.kicad_sch

Title: Arm drive J0, j1

Size: A3

Date:

Rev: 1

KiCad E.D.A. 8.0.3

Id: 1/1