















CAN<sub>H</sub> CAN<sub>L</sub>

V<sub>OUT</sub> GND

C<sub>1</sub> C<sub>2</sub> —

R<sub>1</sub> C<sub>4</sub> R<sub>3</sub> C<sub>8</sub> C<sub>3</sub> R<sub>6</sub> C<sub>1</sub> —

C<sub>a</sub> — U<sub>1</sub>

U<sub>1</sub>

R<sub>2</sub> C<sub>6</sub> R<sub>5</sub> R<sub>4</sub> —

ROVU2  
Robotique Uqes  
5052-04-13



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