

```
graph BT; A["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/guiUpdater  
/include/guiUpdater.h"]; B["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/guiUpdater  
/src/guiUpdater.cpp"]; C["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/guiUpdater  
/src/main.cpp"]; B --> A; C --> A;
```

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/guiUpdater  
/include/guiUpdater.h

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/guiUpdater  
/src/guiUpdater.cpp

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/guiUpdater  
/src/main.cpp