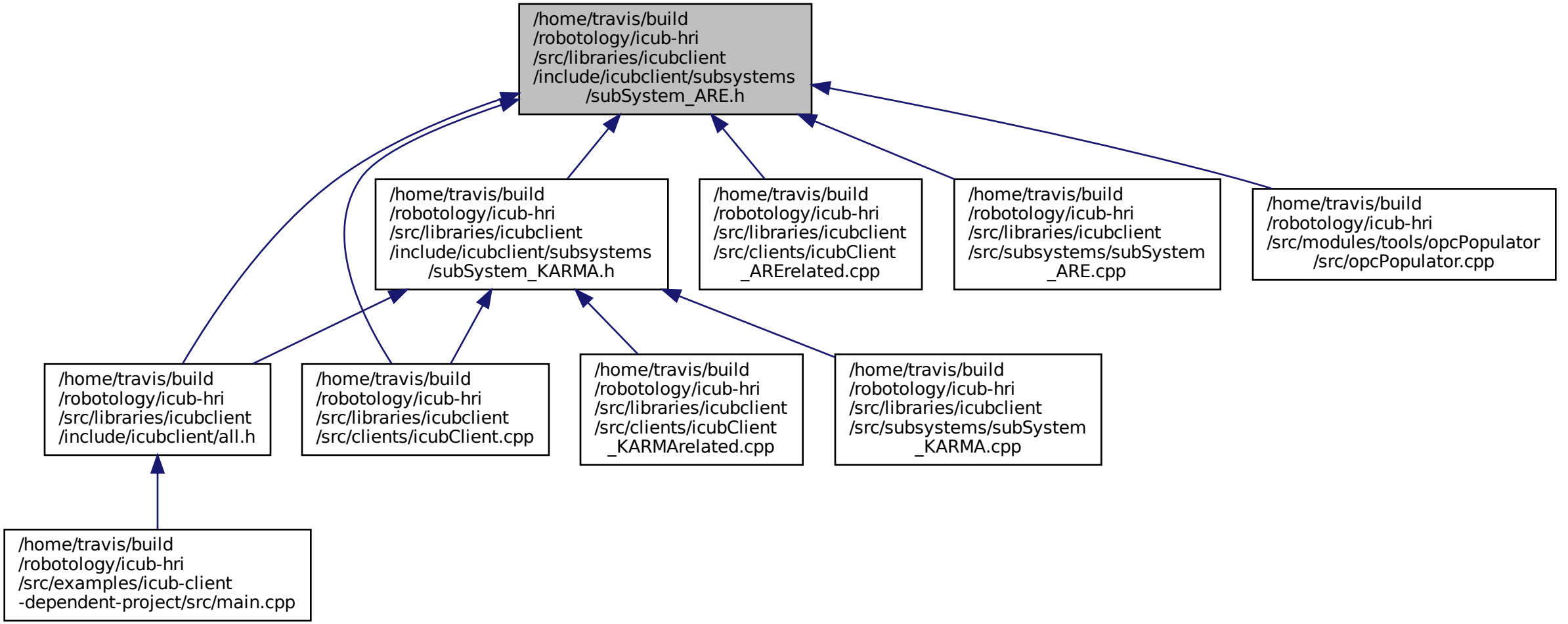
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /include/icubclient/subsystems /subSystem_ARE.h
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /include/icubclient/subsystems /subSystem_KARMA.h
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /src/clients/icubClient _AREelated.cpp
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /src/subsystems/subSystem _ARE.cpp
/home/travis/build /robotology/icub-hri /src/modules/tools/opcPopulator /src/opcPopulator.cpp
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /include/icubclient/all.h
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /src/clients/icubClient.cpp
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /src/clients/icubClient _KARMArelated.cpp
/home/travis/build /robotology/icub-hri /src/libraries/icubclient /src/subsystems/subSystem _KARMA.cpp
/home/travis/build /robotology/icub-hri /src/examples/icub-client -dependent-project/src/main.cpp