

```
graph BT; A["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/touchDetector  
/src/main.cpp"] --> B["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/touchDetector  
/include/touchDetectorModule.h"]; C["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/touchDetector  
/src/touchDetectorModule.cpp"] --> B;
```

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/touchDetector  
/include/touchDetectorModule.h

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/touchDetector  
/src/main.cpp

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/touchDetector  
/src/touchDetectorModule.cpp