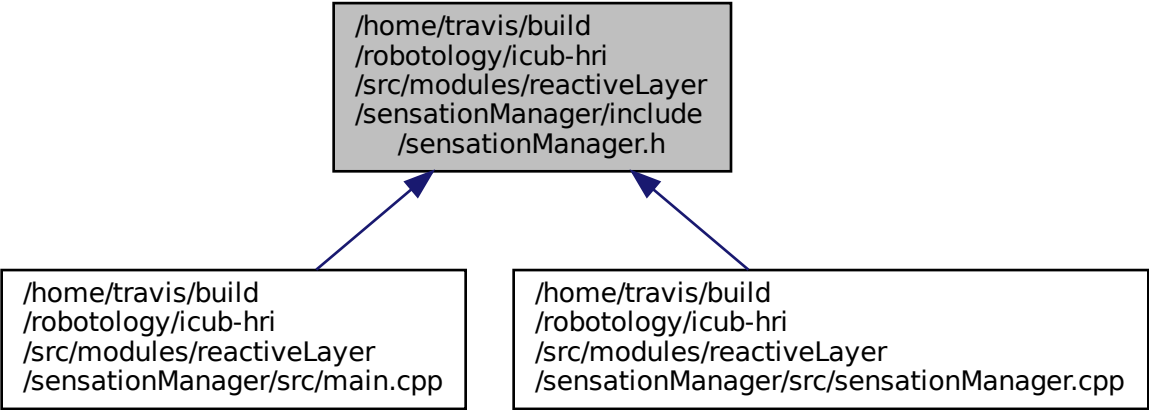


/home/travis/build
/robotology/icub-hri
/src/modules/reactiveLayer
/sensationManager/include
/sensationManager.h



```
graph BT; A["/home/travis/build<br/>/robotology/icub-hri<br/>/src/modules/reactiveLayer<br/>/sensationManager/src/main.cpp"] --> C["/home/travis/build<br/>/robotology/icub-hri<br/>/src/modules/reactiveLayer<br/>/sensationManager/include<br/>/sensationManager.h"]; B["/home/travis/build<br/>/robotology/icub-hri<br/>/src/modules/reactiveLayer<br/>/sensationManager/src/sensationManager.cpp"] --> C;
```

/home/travis/build
/robotology/icub-hri
/src/modules/reactiveLayer
/sensationManager/src/main.cpp

/home/travis/build
/robotology/icub-hri
/src/modules/reactiveLayer
/sensationManager/src/sensationManager.cpp