

```
graph BT; A["/home/travis/build  
/robotology/icub-hri  
/src/libraries/icubclient  
/include/icubclient/subsystems  
/subSystem_emotion.h"] <--> B["/home/travis/build  
/robotology/icub-hri  
/src/libraries/icubclient  
/src/clients/icubClient.cpp"]; A <--> C["/home/travis/build  
/robotology/icub-hri  
/src/libraries/icubclient  
/src/subsystems/subSystem  
_emotion.cpp"]
```

/home/travis/build
/robotology/icub-hri
/src/libraries/icubclient
/include/icubclient/subsystems
/subSystem_emotion.h

/home/travis/build
/robotology/icub-hri
/src/libraries/icubclient
/src/clients/icubClient.cpp

/home/travis/build
/robotology/icub-hri
/src/libraries/icubclient
/src/subsystems/subSystem
_emotion.cpp