

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/opcPopulator  
/include/opcPopulator.h

```
graph BT; A["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/opcPopulator  
/src/main.cpp"] --> C["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/opcPopulator  
/include/opcPopulator.h"]; B["/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/opcPopulator  
/src/opcPopulator.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `main.cpp` and `opcPopulator.cpp`, both include the `opcPopulator.h` header file. The header file is located in the `/include` subdirectory, while the source files are in the `/src` subdirectory of the same directory tree.

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/opcPopulator  
/src/main.cpp

/home/travis/build  
/robotology/icub-hri  
/src/modules/tools/opcPopulator  
/src/opcPopulator.cpp