

/home/travis/build
/robotology/icub-hri
/src/libraries/icubclient
/include/icubclient/knowledge
/entity.h

```
graph TD; A["/home/travis/build<br/>/robotology/icub-hri<br/>/src/libraries/icubclient<br/>/include/icubclient/knowledge<br/>/entity.h"] --> B["yarp/os/all.h"]; A --> C["string"]; A --> D["map"]; A --> E["list"]; A --> F["iostream"]; A --> G["sstream"];
```

yarp/os/all.h

string

map

list

iostream

sstream