# 1. Description

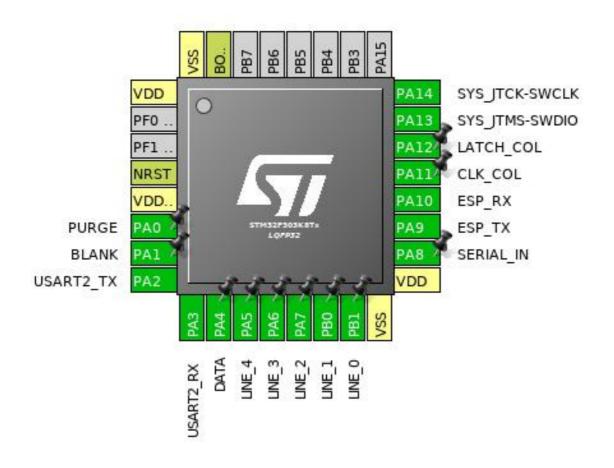
## 1.1. Project

Project Name	SCREEN
Board Name	SCREEN
Generated with:	STM32CubeMX 4.24.0
Date	03/13/2018

## 1.2. MCU

MCU Series	STM32F3
MCU Line	STM32F303
MCU name	STM32F303K8Tx
MCU Package	LQFP32
MCU Pin number	32

# 2. Pinout Configuration

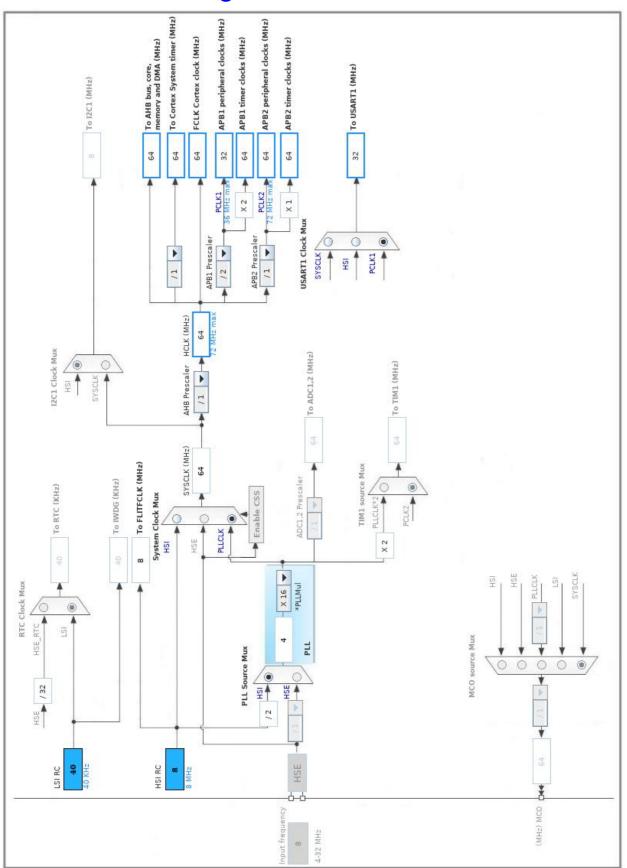


# 3. Pins Configuration

Pin Number LQFP32	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VDD	Power		
4	NRST	Reset		
5	VDDA/VREF+	Power		
6	PA0 *	I/O	GPIO_Output	PURGE
7	PA1 *	I/O	GPIO_Output	BLANK
8	PA2	I/O	USART2_TX	
9	PA3	I/O	USART2_RX	
10	PA4 *	I/O	GPIO_Output	DATA
11	PA5 *	I/O	GPIO_Output	LINE_4
12	PA6 *	I/O	GPIO_Output	LINE_3
13	PA7 *	I/O	GPIO_Output	LINE_2
14	PB0 *	I/O	GPIO_Output	LINE_1
15	PB1 *	I/O	GPIO_Output	LINE_0
16	VSS	Power		
17	VDD	Power		
18	PA8 *	I/O	GPIO_Output	SERIAL_IN
19	PA9	I/O	USART1_TX	ESP_TX
20	PA10	I/O	USART1_RX	ESP_RX
21	PA11 *	I/O	GPIO_Output	CLK_COL
22	PA12 *	I/O	GPIO_Output	LATCH_COL
23	PA13	I/O	SYS_JTMS-SWDIO	
24	PA14	I/O	SYS_JTCK-SWCLK	
31	воото	Boot		
32	VSS	Power		

<sup>\*</sup> The pin is affected with an I/O function

# 4. Clock Tree Configuration



# 5. IPs and Middleware Configuration

### 5.1. SYS

**Debug: Serial Wire** 

Timebase Source: SysTick

### 5.2. TIM2

**Clock Source : Internal Clock** 

## 5.2.1. Parameter Settings:

### **Counter Settings:**

Prescaler (PSC - 16 bits value) 0
Counter Mode Up

Counter Period (AutoReload Register - 32 bits value ) 57143-1 \*
Internal Clock Division (CKD) No Division
auto-reload preload Disable

#### **Trigger Output (TRGO) Parameters:**

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection TRGO Reset (UG bit from TIMx\_EGR)

### 5.3. USART1

**Mode: Asynchronous** 

## 5.3.1. Parameter Settings:

#### **Basic Parameters:**

Baud Rate 115200 \*

Word Length 8 Bits (including Parity) \*

Parity None Stop Bits 1

**Advanced Parameters:** 

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

#### **Advanced Features:**

Auto Baudrate Disable TX Pin Active Level Inversion Disable **RX Pin Active Level Inversion** Disable Disable Data Inversion TX and RX Pins Swapping Disable Enable Overrun DMA on RX Error Enable MSB First Disable

### **5.4. USART2**

**Mode: Asynchronous** 

## 5.4.1. Parameter Settings:

#### **Basic Parameters:**

Baud Rate 38400

Word Length 7 Bits (including Parity)

Parity None Stop Bits 1

#### **Advanced Parameters:**

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

#### **Advanced Features:**

TX Pin Active Level Inversion Disable
RX Pin Active Level Inversion Disable
Data Inversion Disable
TX and RX Pins Swapping Disable
Overrun Enable
DMA on RX Error Enable
MSB First Disable

#### \* User modified value

# 6. System Configuration

# 6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
SYS	PA13	SYS_JTMS- SWDIO	n/a	n/a	n/a	
	PA14	SYS_JTCK- SWCLK	n/a	n/a	n/a	
USART1	PA9	USART1_TX	Alternate Function Push Pull	No pull up pull down	High *	ESP_TX
	PA10	USART1_RX	Alternate Function Push Pull	No pull up pull down	High *	ESP_RX
USART2	PA2	USART2_TX	Alternate Function Push Pull	No pull up pull down	High *	
	PA3	USART2_RX	Alternate Function Push Pull	No pull up pull down	High *	
GPIO	PA0	GPIO_Output	Output Push Pull	No pull up pull down	High *	PURGE
	PA1	GPIO_Output	Output Push Pull	No pull up pull down	High *	BLANK
	PA4	GPIO_Output	Output Push Pull	No pull up pull down	High *	DATA
	PA5	GPIO_Output	Output Push Pull	No pull up pull down	High *	LINE_4
	PA6	GPIO_Output	Output Push Pull	No pull up pull down	High *	LINE_3
	PA7	GPIO_Output	Output Push Pull	No pull up pull down	High *	LINE_2
	PB0	GPIO_Output	Output Push Pull	No pull up pull down	High *	LINE_1
	PB1	GPIO_Output	Output Push Pull	No pull up pull down	High *	LINE_0
	PA8	GPIO_Output	Output Push Pull	No pull up pull down	High *	SERIAL_IN
	PA11	GPIO_Output	Output Push Pull	No pull up pull down	High *	CLK_COL
	PA12	GPIO_Output	Output Push Pull	No pull up pull down	High *	LATCH_COL

# 6.2. DMA configuration

DMA request	Stream	Direction	Priority
USART1_RX	DMA1_Channel5	Peripheral To Memory	High *

## USART1\_RX: DMA1\_Channel5 DMA request Settings:

Mode: Circular \*

Peripheral Increment: Disable

Memory Increment: Enable \*

Peripheral Data Width: Byte
Memory Data Width: Byte

# 6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
DMA1 channel5 global interrupt	true	0	0
TIM2 global interrupt	true	0	0
USART1 global interrupt / USART1 wake-up interrupt through EXT line 25	true	0	0
PVD interrupt through EXTI line 16		unused	
Flash global interrupt	unused		
RCC global interrupt	unused		
USART2 global interrupt / USART2 wake-up interrupt through EXT line 26	unused		
Floating point unit interrupt		unused	

<sup>\*</sup> User modified value

# 7. Power Consumption Calculator report

### 7.1. Microcontroller Selection

Series	STM32F3
Line	STM32F303
мси	STM32F303K8Tx
Datasheet	025083_Rev5

#### 7.2. Parameter Selection

Temperature	25
Vdd	3.6



# 9. Software Project

## 9.1. Project Settings

Name	Value
Project Name	SCREEN
Project Folder	/home/antonin/Documents/Robotronik/git/cdfr2018/Programmation/Panneau_do
Toolchain / IDE	Makefile
Firmware Package Name and Version	STM32Cube FW_F3 V1.9.0

## 9.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	Yes
consumption)	