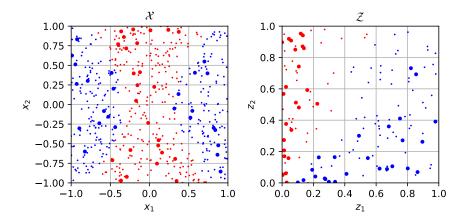
### QUESTION 1

Since all necessary values seem to be given, we simply calculate the expected in-sample error using the formula given.

The smallest N that has an in-sample error of  $E_{in} > 0.008$  is N = 100. The answer is c.

## QUESTION 2

First, generate some points that fit the classification boundaries given in the figure. Create some random points with  $-1 \le x_1, x_2 \le 1$ . Then, classify them using the following conditions: +1 for  $(\|\mathbf{x}-(1,0)\| > 0.7 \land |x_1| < 0.8)$ . Apply the nonlinear transform to the points and use the perceptron algorithm to learn the weight vector  $\tilde{\mathbf{w}}$  for classifying them in  $\mathbb{Z}$ -space. Here,  $\tilde{w_1}$  is negative while  $\tilde{w_2}$  is positive, therefore answer d applies. The classified points in  $\mathbb{X}$  and  $\mathbb{Z}$  space are shown in figure 1.



**Fig. 1:** Classified points in  $\mathcal X$  and  $\mathcal Z$  space. Large points are training points, small ones belong to the test data set.

Find the VC dimension for a 4<sup>th</sup> order nonlinear transform function. The VC-dimension  $d_{VC}$  for a nonlinear feature transform  $\Phi_Q$  of order Q can be

$$d_{VC} \le \frac{Q(Q+3)}{2} + 1.$$
 (1)

See the book page 105 for more. For Q = 4 we get  $d_{VC} \le 15$ . Thus, the smallest choice that is not smaller than 15 is c: 15.

#### QUESTION 4

Find  $\frac{\partial E}{\partial u}$  where  $E(u, v) = (ue^{v} - 2ve^{-u})^{2}$ .

First, we apply the chain rule to get rid of the square brackets. Substitute the inner term by w so that

$$w = (ue^{v} - 2ve^{-u}). (2)$$

We can now calculate the derivative of the outer term  $w^2$  and the inner term separately and combine them to

$$\frac{\partial E}{\partial u} = \frac{\partial}{\partial w} w^2 \cdot \frac{\partial}{\partial u} (u e^v - 2v e^{-u}). \tag{3}$$

The outer derivative is given by

$$\frac{\partial}{\partial w}w^2 = 2w \tag{4}$$

$$= 2(ue^{\nu} - 2\nu e^{-u}) \tag{5}$$

The inner derivative is given by

$$\frac{\partial}{\partial u}(ue^{\nu} - 2\nu e^{-u}) = \frac{\partial}{\partial u}ue^{\nu} - \frac{\partial}{\partial u}2\nu e^{-u}) \tag{6}$$

$$= 1 \cdot e^{\nu} - 2\nu(-e^{-u}) \tag{7}$$

$$= e^{\nu} + 2\nu e^{-u} \tag{8}$$

We can now combine the inner and outer parts to get

$$\frac{\partial E}{\partial u} = 2(ue^{\nu} - 2\nu e^{-u})(e^{\nu} + 2\nu e^{-u}). \tag{9}$$

This corresponds to answer *e*.

Compute the minimum number of generations to optimize the vector  $w = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  that lives in the (u, v) space until  $E(w) < 10^{-14}$ .

First, we need the partial derivative in  $\nu$ -direction as well. Using the process outlined in question 5 above, we get

$$\frac{\partial E}{\partial v} = 2(ue^{v} - 2ve^{-u})(ue^{v} - 2e^{-u}). \tag{10}$$

With both partial derivatives we can construct the gradient vector

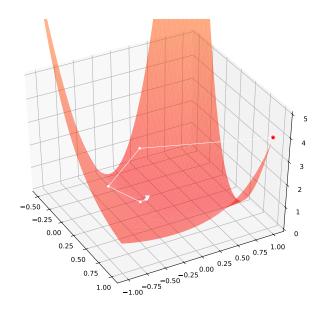
$$\nabla E = \begin{pmatrix} \frac{\partial E}{\partial u} \\ \frac{\partial E}{\partial v} \end{pmatrix} \tag{11}$$

This vector lives in the (u, v) space and points into the direction of the largest change of E. To improve the weight vector at the current iteration  $\binom{u}{v}^{(i)}$  we need to move the previous iterations weight vector  $\binom{u}{v}^{(i-1)}$  into the gradient's negative direction with the distance  $\eta$ . The new position of the weights  $\binom{u}{v}^{(i)}$  is therefore given by

$$\begin{pmatrix} u \\ v \end{pmatrix}^{(i)} = \begin{pmatrix} u \\ v \end{pmatrix}^{(i-1)} - \nabla E \cdot \eta \tag{12}$$

See hw5-question5-7.py for the code.

The number of iterations needed is 10, therefore the answer is d. See figure 2 for the progression of the gradient descent.



**Fig. 2:** Progression of the gradient descent, starting at ★ and ending after 10 iterations.

What is the final value of w after reaching  $E(w) < 10^{-14}$ ? See hw5-question5-7.py for the code.

The final weight vector is  $w = \begin{pmatrix} 0.045 \\ 0.024 \end{pmatrix}$ . This corresponds to answer e.

# QUESTION 7

What is the final value of E(w) after 15 iterations with moving in u and v direction separately within each iteration?

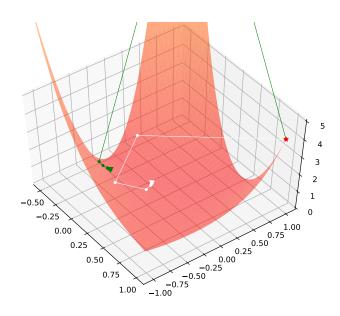
Within each iteration, we do

$$\begin{pmatrix} u \\ v \end{pmatrix}^{(i)} = \begin{pmatrix} u \\ v \end{pmatrix}^{(i-1)} - \begin{pmatrix} \frac{\partial E}{\partial u} \\ 0 \end{pmatrix} \cdot \eta \tag{13}$$

followed by

$$\begin{pmatrix} u \\ v \end{pmatrix}^{(i)} = \begin{pmatrix} u \\ v \end{pmatrix}^{(i-1)} - \begin{pmatrix} 0 \\ \frac{\partial E}{\partial v} \end{pmatrix} \cdot \eta. \tag{14}$$

This is like walking around Manhattan, making only 90° turns. After 15 iterations, we have arrived at  $E(w) = 2.91 \cdot 10^{-1}$ . This corresponds to answer a. See figure 3 for the progression of the gradient descent. The final result is notably degraded in comparison to the original gradient descent from Question 5.



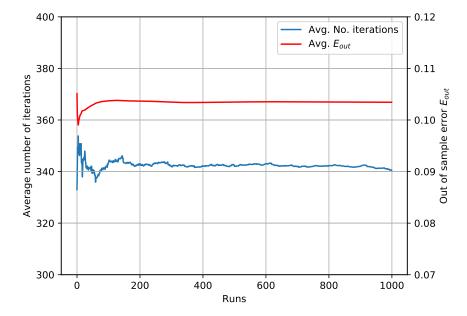
**Fig. 3:** Progression of the original (white line) and modified gradient descent (-), starting at  $\star$  and ending after 15 iterations.

## QUESTION 8

The solution is to code the logarithmic regression with stochastic gradient descent in Python and run it for 100 runs with one training (N=100) and testing (N=1000) data set each. See hw5-question8-9.py and learningModels.py for the code. To answer the question, the cross entropy error of the testing sets is averaged over all data sets. The result is  $E_{out}\approx 0.103$ , which is closest to answer d.

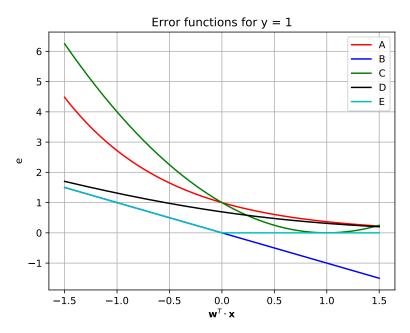
## QUESTION 9

With the same code as in Question 8, we simply average the number of iterations it takes the stochastic gradient descent to converge until  $\mathbf{k}\mathbf{w}^t - \mathbf{w}^{t-1}\mathbf{k} < 0.01$  over all runs. The average number iterations was 340.52, which corresponds to answer a.



**Fig. 4:** Convergence of the average number of iterations that the learning algorithm took to complete the stochastic gradient descent (SGD). Left: using the same permutation of input points for each epoch of the SGD. Right: using a different permutation of input points in each epoch.

As the classifier for the perceptron is  $sign(\mathbf{w}^T \cdot \mathbf{x})$ , we are interested in an error function that has a zero gradient as soon as the sign of  $\mathbf{w}^T \cdot \mathbf{x}$  matches that of y = 1 for a given data point. To see the different error measures for the case y = 1 in action, see figure 5. The error function of solution e features a derivative of 0 for all positive  $\mathbf{w}^T \cdot \mathbf{x}$  and would therefore stop the algorithm immediately if a match between  $\mathbf{w}^T \cdot \mathbf{x}$  and y = 1 is achieved. All other functions would not lead to immediate termination of the algorithm once the signs of  $sign(\mathbf{w}^T \cdot \mathbf{x})$  and y = 1 are equal. The error function of choice is therefore e.



**Fig. 5:** Plot of the error functions for different outputs of  $\mathbf{w}^T \cdot \mathbf{x}$  for y = 1. Error function E is the only one that would terminate the gradient descent algorithm immediately for matching signs of  $\mathbf{w}^T \cdot \mathbf{x}$  and y = 1