

1M-BIT [128K x 8/64K x 16] CMOS EPROM

FEATURES

- 64K x 16 organization(MX27C1024, JEDEC pin out)
- 128K x 8 or 64K x 16 organization(MX27C1100, ROM pin out compatible)
- +12.5V programming voltage
- Fast access time: 55/70/85/100/120/150 ns
- Totally static operation
- Completely TTL compatible

- Operating current: 40mA
- Standby current: 100uA
- · Package type:
 - 40 pin plastic DIP
 - 40 pin plastic SOP
 - 44 pin PLCC

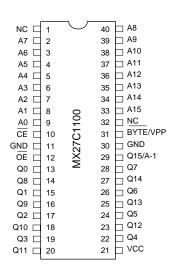
GENERAL DESCRIPTION

The MX27C1024 is a 5V only, 1M-bit, One Time Programmable Read Only Memory. It is organized as 64K words by 16 bits per word(MX27C1024), 128K x 8 or 64K x 16(MX27C1100), operates from a single + 5 volt supply, has a static standby mode, and features fast single address location programming. All programming signals are TTL levels, requiring a single pulse. For programming outside from the system, existing

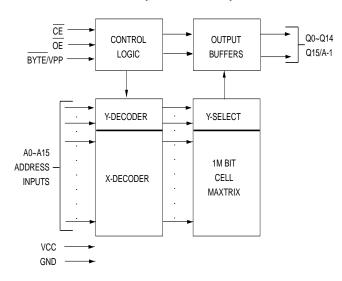
EPROM programmers may be used. The MX27C1100/1024 supports a intelligent fast programming algorithm which can result in programming time of less than thirty seconds.

This EPROM is packaged in industry standard 40 pin dual-in-line packages, 40 lead SOP and 44 lead PLCC packages.

PIN CONFIGURATIONS PDIP/SOP(MX27C1100)

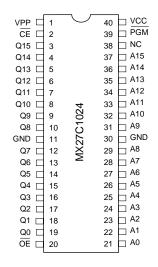


BLOCK DIAGRAM (MX27C1100)

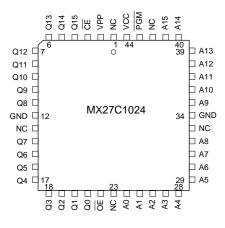




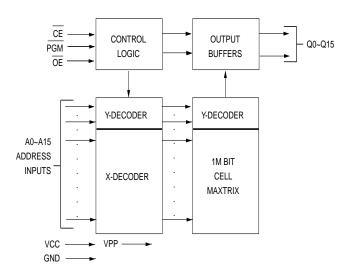
PIN CONFIGURATIONS PDIP/SOP(MX27C1024)



PLCC(MX27C1024)



BLOCK DIAGRAM (MX27C1024)





PIN DESCRIPTION(MX27C1100)

SYMBOL	PIN NAME
A0~A15	Address Input
Q0~Q14	Data Input/Output
CE	Chip Enable Input
ŌĒ	Output Enable Input
BYTE/VPP	Word/Byte Selection
	/Program Supply Voltage
Q15/A-1	Q15(Word mode)/LSB addr. (Byte mode)
VCC	Power Supply Pin (+5V)
GND	Ground Pin

PIN DESCRIPTION(MX27C1024)

SYMBOL	PIN NAME
A0~A15	Address Input
Q0~Q15	Data Input/Output
CE	Chip Enable Input
ŌĒ	Output Enable Input
PGM	Program Enable Input
VPP	Program Supply Voltage
VCC	Power Supply Pin (+5V)
GND	Ground Pin

TRUTH TABLE OF BYTE FUNCTION(MX27C1100)

BYTE $MODE(\overline{BYTE} = GND)$

CE	ŌĒ	Q15/A-1	MODE	Q0-Q7	SUPPLY CURRENT
Н	Χ	X	Non selected	High Z	Standby(ICC2)
L	Н	X	Non selected	High Z	Operating(ICC1)
L	L	A-1 input	Selected	DOUT	Operating(ICC1)

WORD MODE($\overline{\text{BYTE}} = \text{VCC}$)

CE	OE	Q15/A-1	MODE	Q0-Q14	SUPPLY CURRENT	
Н	Х	High Z	Non selected	High Z	Standby(ICC2)	
L	Н	High Z	Non selected	High Z	Operating(ICC1)	
L	L	DOUT	Selected	DOUT	Operating(ICC1)	

NOTE: X = H or L



FUNCTIONAL DESCRIPTION

THE PROGRAMMING OF THE MX27C1100/1024

When the MX27C1100/1024 is delivered, or it is erased, the chip has all 1M bits in the "ONE" or HIGH state. "ZEROs" are loaded into the MX27C1100/1024 through the procedure of programming.

For programming, the data to be programmed is applied with 16 bits in parallel to the data pins.

VCC must be applied simultaneously or before VPP, and removed simultaneously or after VPP. When programming an MXIC EPROM, a 0.1uF capacitor is required across VPP and ground to suppress spurious voltage transients which may damage the device.

FAST PROGRAMMING

The device is set up in the fast programming mode when the programming voltage VPP = 12.75V is applied, with VCC = 6.25 V and \overrightarrow{PGM} = VIL(or \overrightarrow{OE} = VIH) (Algorithm is shown in Figure 1). The programming is achieved by applying a single TTL low level 100us pulse to the \overrightarrow{PGM} input after addresses and data line are stable. If the data is not verified, an additional pulse is applied for a maximum of 25 pulses. This process is repeated while sequencing through each address of the device. When the programming mode is completed, the data in all address is verified at VCC = VPP = 5V \pm 10%.

PROGRAM INHIBIT MODE

Programming of multiple MX27C1100/1024's in parallel with different data is also easily accomplished by using the Program Inhibit Mode. Except for \overline{CE} and \overline{OE} , all like inputs of the parallel MX27C1100/1024 may be common. A TTL low-level program pulse applied to an MX27C1100/1024 \overline{CE} input with VPP = 12.5 ± $\overline{0.5}$ V will program the MX27C1100/1024. A high-level \overline{CE} input inhibits the other MX27C1100/1024s from being programmed.

PROGRAM VERIFY MODE

Verification should be performed on the programmed bits to determine that they were correctly programmed. The verification should be performed with \overline{OE} and \overline{CE} at

VIL(for MX27C1024), \overline{OE} at VIL, \overline{CE} at VIH(for MX27C1100)and VPP at its programming voltage.

AUTO IDENTIFY MODE

The auto identify mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and device type. This mode is intended for use by programming equipment for the purpose of automatically matching the device to be programmed with its corresponding programming algorithm. This mode is functional in the $25\,^{\circ}\text{C}$ \pm $5\,^{\circ}\text{C}$ ambient temperature range that is required when programming the MX27C1100/1024.

To activate this mode, the programming equipment must force $12.0\pm0.5\,\text{V}$ on address line A9 of the device. Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from VIL to VIH. All other address lines must be held at VIL during auto identify mode.

Byte 0 (A0 = VIL) represents the manufacturer code, and byte 1 (A0 = VIH), the device identifier code. For the MX27C1100/1024, these two identifier bytes are given in the Mode Select Table. All identifiers for manufacturer and device codes will possess odd parity, with the MSB (Q15) defined as the parity bit.

READ MODE

The MX27C1100/1024 has two control functions, both of which must be logically satisfied in order to obtain data at the outputs. Chip Enable (\overline{CE}) is the power control and should be used for device selection. Output Enable (\overline{OE}) is the output control and should be used to gate data to the output pins, independent of device selection. Assuming that addresses are stable, address access time (tACC) is equal to the delay from \overline{CE} to output (tCE). Data is available at the outputs tOE after the falling edge of \overline{OE} 's, assuming that \overline{CE} has been LOW and addresses have been stable for at least tACC - t OE.

WORD-WIDE MODE

With $\overline{\text{BYTE}}/\text{VPP}$ at VCC \pm 0.2V outputs Q0-7 present data Q0-7 and outputs Q8-15 present data Q8-15, after $\overline{\text{CE}}$ and $\overline{\text{OE}}$ are appropriately enabled.



BYTE-WIDE MODE

With $\overline{\text{BYTE}}/\text{VPP}$ at GND \pm 0.2V, outputs Q8-15 are tristated. If Q15/A-1 = VIH, outputs Q0-7 present data bits Q8-15. If Q15/A-1 = VIL, outputs Q0-7 present data bits Q0-7.

arrays, a 4.7 uF bulk electrolytic capacitor should be used between VCC and GND for each eight devices. The location of the capacitor should be close to where the power supply is connected to the array.

STANDBY MODE

The MX27C1100/1024 has a CMOS standby mode which reduces the maximum VCC current to 100 uA. It is placed in CMOS standby when $\overline{\text{CE}}$ is at VCC \pm 0.3 V. The MX27C1100/1024 also has a TTL-standby mode which reduces the maximum VCC current to 1.5 mA. It is placed in TTL-standby when $\overline{\text{CE}}$ is at VIH. When in standby mode, the outputs are in a high-impedance state, independent of the $\overline{\text{OE}}$ input.

TWO-LINE OUTPUT CONTROL FUNCTION

To accommodate multiple memory connections, a twoline control function is provided to allow for:

- 1. Low memory power dissipation,
- 2. Assurance that output bus contention will not occur.

It is recommended that \overline{CE} be decoded and used as the primary device-selecting function, while \overline{OE} be made a common connection to all devices in the array and connected to the READ line from the system control bus. This assures that all deselected memory devices are in their low-power standby mode and that the output pins are only active when data is desired from a particular memory device.

SYSTEM CONSIDERATIONS

During the switch between active and standby conditions, transient current peaks are produced on the rising and falling edges of Chip Enable. The magnitude of these transient current peaks is dependent on the output capacitance loading of the device. At a minimum, a 0.1 uF ceramic capacitor (high frequency, low inherent inductance) should be used on each device between Vcc and GND to minimize transient effects. In addition, to overcome the voltage drop caused by the inductive effects of the printed circuit board traces on EPROM



MODE SELECT TABLE (MX27C1024)

				PINS			
MODE	CE	OE	PGM	Α0	Α9	VPP	OUTPUTS
Read	VIL	VIL	Х	Х	Х	VCC	DOUT
Output Disable	VIL	VIH	Х	Х	Х	VCC	High Z
Standby (TTL)	VIH	Х	Х	Х	Х	VCC	High Z
Standby (CMOS)	VCC±0.3V	Х	Х	Х	Х	VCC	High Z
Program	VIL	VIH	VIL	Х	Х	VPP	DIN
Program Verify	VIL	VIL	VIH	Х	Х	VPP	DOUT
Program Inhibit	VIH	Х	Х	Х	Х	VPP	High Z
Manufacturer Code(3)	VIL	VIL	Х	VIL	VH	VCC	00C2H
Device Code(3)	VIL	VIL	Х	VIH	VH	VCC	0115H

NOTES:1. VH = $12.0 \text{ V} \pm 0.5 \text{ V}$ 2. X = Either VIH or VIL

- 3. A1 A8 = A10 A15 = VIL(For auto select)
- 4. See DC Programming Characteristics for VPP voltage during programming.

MODE SELECT TABLE (MX27C1100)

					BYTE/		
CE	OE	Α9	A0	Q15/A-1	VPP(5)	Q8-14	Q0-7
VIL	VIL	Х	Х	Q15 Out	VCC	Q8-14 Out	Q0-7 Out
VIL	VIL	Х	Х	VIH	GND	High Z	Q8-15 Out
VIL	VIL	Х	Х	VIL	GND	High Z	Q0-7 Out
VIL	VIH	Х	Х	High Z	Х	High Z	High Z
VIH	Х	Х	Х	High Z	Х	High Z	High Z
VIL	VIH	Х	Х	Q15 In	VPP	Q8-14 In	Q0-7 In
VIH	VIL	Х	Х	Q15 Out	VPP	Q8-14 Out	Q0-7 Out
VIH	VIH	Х	Х	High Z	VPP	High Z	High Z
VIL	VIL	VH	VIL	0B	VCC	00H	C2H
VIL	VIL	VH	VIH	0B	VCC	01H	12H
	VIL VIL VIL VIH VIL VIH VIH VIH VIH VIH	VIL VIL VIL VIL VIL VIL VIL VIH VIH X VIL VIH VIH VIH VIH VIL VIH VIH VIH VIH VIL VIL	VIL VIL X VIH X VIH X VIH X VIH X VIH X VIH VIH X VIH VIH X VIH VIH X VIH VIH X	VIL VIL X X VIL VIL X X VIL VIL X X VIL VIH X X VIH X X X VIH VIL X X VIH VIH X X VIH VIH X X VIL VIL VH VIL	VIL VIL X X Q15 Out VIL VIL X X VIH VIL VIL X X VIL VIL VIH X X High Z VIH X X X Q15 In VIH VIL X X Q15 Out VIH VIH X X High Z VIL VIL VIL VIL OB	CE OE A9 A0 Q15/A-1 VPP(5) VIL VIL X X Q15 Out VCC VIL VIL X X VIH GND VIL VIL X X VIL GND VIL VIH X X High Z X VIH X X X High Z X VIH VIH X X Q15 Out VPP VIH VIH X X High Z VPP VIL VIL VH VIL OB VCC	CE OE A9 A0 Q15/A-1 VPP(5) Q8-14 VIL VIL X X Q15 Out VCC Q8-14 Out VIL VIL X X VIH GND High Z VIL VIL X X VIL GND High Z VIL VIH X X High Z X High Z VIH X X X Q15 In VPP Q8-14 In VIH VIH X X Q15 Out VPP Q8-14 Out VIH VIH X X High Z VPP High Z VIL VIL VIL VIL OB VCC 00H

NOTES: 1. VH = $12.0V \pm 0.5V$

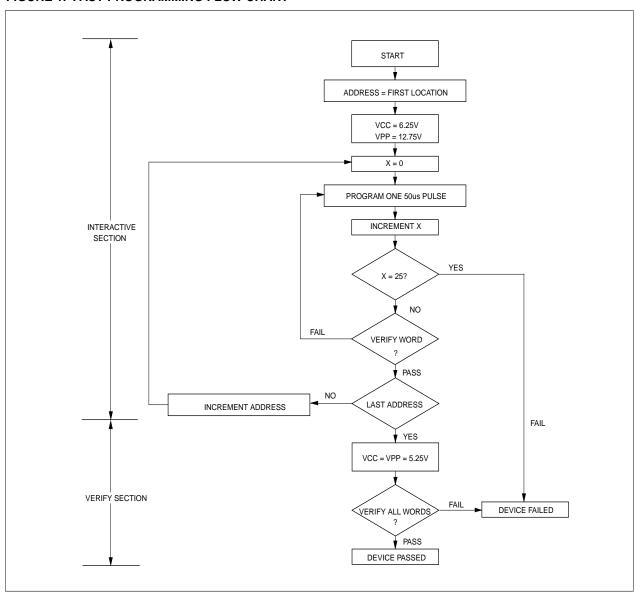
2. X = Either VIH or VIL

3. A1 - A8, A10 - A15 = VIL(For auto select)

4. See DC Programming Characteristics for VPP voltages.5. BYTE/VPP is intended for operation under DC Voltage conditions only.

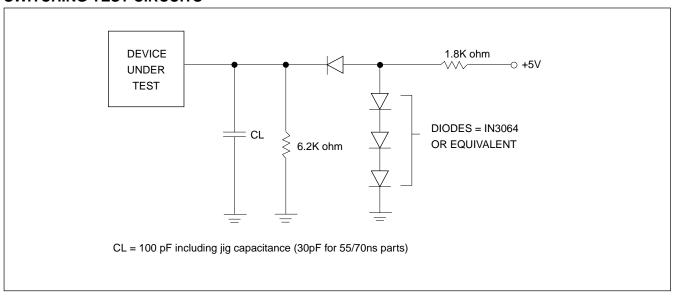
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FIGURE 1. FAST PROGRAMMING FLOW CHART

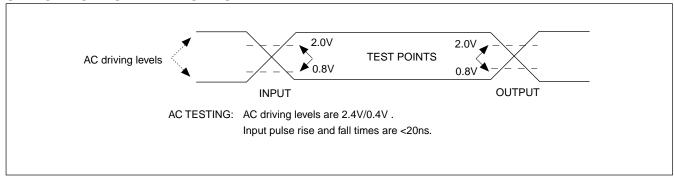


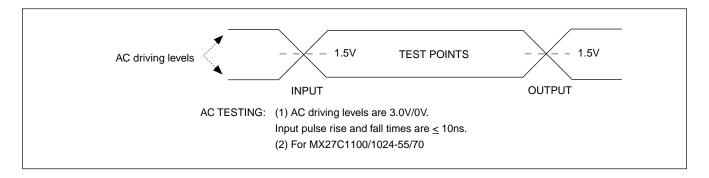


SWITCHING TEST CIRCUITS



SWITCHING TEST WAVEFORMS







ABSOLUTE MAXIMUM RATINGS

RATING	VALUE
Ambient Operating Temperature	-40°C to 85°C
Storage Temperature	-65°C to 125°C
Applied Input Voltage	-0.5V to 7.0V
Applied Output Voltage	-0.5V to VCC + 0.5V
VCC to Ground Potential	-0.5V to 7.0V
A9 & Vpp	-0.5V to 13.5V

NOTICE:

Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended period may affect reliability.

NOTICE:

Specifications contained within the following tables are subject to change.

DC/AC Operating Conditions for Read Operation

		MX27C1100/1024								
		-55*	-70	-85	-10	-12	-15			
Operating Temperature	Commercial	0℃ to 55℃	0℃ to 70℃							
	Industrial **		-40℃ to 85℃							
Vcc Power Supply		Vcc ± 5%	Vcc ± 10%							

^{*: 55}ns for MX27C1024 only

DC CHARACTERISTICS

SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
VOH	Output High Voltage	2.4		V	IOH = -0.4mA
VOL	Output Low Voltage		0.4	V	IOL = 2.1mA
VIH	Input High Voltage	2.0	VCC + 0.5	V	
VIL	Input Low Voltage	-0.3	0.8	V	
ILI	Input Leakage Current	-10	10	uA	VIN = 0 to 5.5V
ILO	Output Leakage Current	-10	10	uA	VOUT = 0 to 5.5V
ICC3	VCC Power-Down Current		100	uA	CE = VCC ± 0.3V
ICC2	VCC Standby Current		1.5	mA	CE = VIH
ICC1	VCC Active Current		40	mA	CE = VIL, f=5MHz, lout = 0mA
IPP	VPP Supply Current Read		10	uA	CE = OE = VIL, VPP = 5.5V

CAPACITANCE TA = 25°C, f = 1.0 MHz (Sampled only)

SYMBOL	PARAMETER	TYP.	MAX.	UNIT	CONDITIONS	
CIN	Input Capacitance	8	12	pF	VIN = 0V	
COUT	Output Capacitance	8	12	pF	VOUT = 0V	
CVPP	VPP Capacitance	18	25	pF	VPP = 0V	

^{**:}Industrial grade for MX27C1024 only



AC CHARACTERISTICS

		27C1	024-55	27C1100	0/1024-70	27C110	0/1024-85	5	
SYMBOL	PARAMETER	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	UNIT	CONDITIONS
tACC	Address to Output Delay		55		70		85	ns	$\overline{CE} = \overline{OE} = VIL$
tCE	Chip Enable to Output Delay		55		70		85	ns	OE = VIL
tOE	Output Enable to Output Delay		30		35		40	ns	CE = VIL
tDF	OE High to Output Float,	0	20	0	20	0	25	ns	
	or CE High to Output Float								
tOH	Output Hold from Address,	0		0		0		ns	
	$\overline{\text{CE}}$ or $\overline{\text{OE}}$ which ever occurred first								
*tBHA	BYTE Access Time				70		85	ns	
*tOHB	BYTE Output Hold Time			0		0		ns	
*tBHZ	BYTE Output Delay Time				70		70	ns	
*tBLZ	BYTE Output Set Time			10		10		ns	

^{*:} for MX27C1100 only

AC CHARACTERISTICS

		27C1100	0/1024-10	27C1100	0/1024-12	27C110	0/1024-1	5	
SYMBOL	PARAMETER	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	UNIT	CONDITIONS
tACC	Address to Output Delay		100		120		150	ns	CE = OE = VIL
tCE	Chip Enable to Output Delay		100		120		150	ns	OE = VIL
tOE	Output Enable to Output Delay		45		50		65	ns	CE = VIL
tDF	OE High to Output Float,	0	30	0	35	0	50	ns	
	or CE High to Output Float								
tOH	Output Hold from Address,	0		0		0		ns	
	$\overline{\text{CE}}$ or $\overline{\text{OE}}$ which ever occurred first								
*tBHA	BYTE Access Time		100		120		150	ns	
*tOHB	BYTE Output Hold Time	0		0		0		ns	
*tBHZ	BYTE Output Delay Time		70		70		70	ns	
*tBLZ	BYTE Output Set Time	10		10		10		ns	

^{*:} for MX27C1100 only



DC PROGRAMMING CHARACTERISTICS $TA = 25^{\circ}C \pm 5^{\circ}C$

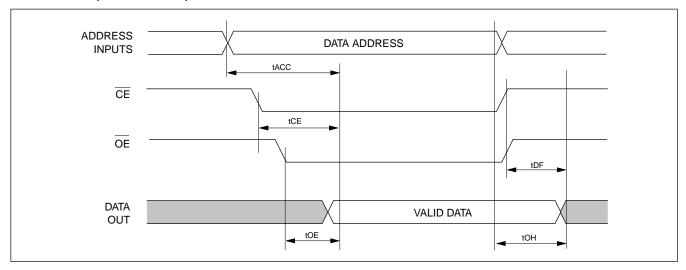
SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
VOH	Output High Voltage	2.4		V	IOH = -0.40mA
VOL	Output Low Voltage		0.4	V	IOL = 2.1mA
VIH	Input High Voltage	2.0	VCC + 0.5	V	
VIL	Input Low Voltage	-0.3	0.8	V	
ILI	Input Leakage Current	-10	10	uA	VIN = 0 to 5.5V
VH	A9 Auto Select Voltage	11.5	12.5	V	
ICC3	VCC Supply Current (Program & Verify)		50	mA	
IPP2	VPP Supply Current(Program)		30	mA	$\overline{CE} = VIL, \ \overline{OE} = VIH$
VCC1	Fast Programming Supply Voltage	6.00	6.50	V	
VPP1	Fast Programming Voltage	12.5	13.0	V	

AC PROGRAMMING CHARACTERISTICS TA = 25°C ± 5°C

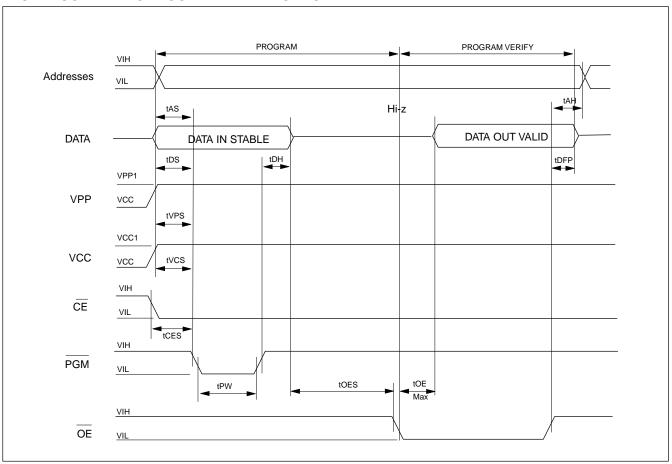
SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
tAS	Address Setup Time	2.0		us	
tOES	OE Setup Time	2.0		us	
tDS	Data Setup Time	2.0		us	
tAH	Address Hold Time	0		us	
tDH	Data Hold Time	2.0		us	
tDFP	Output Enable to Output Float Delay	0	130	ns	
tVPS	VPP Setup Time	2.0		us	
tPW	PGM Program Pulse Width	95	105	us	
tVCS	VCC Setup Time	2.0		us	
tCES	CE Setup Time	2.0		us	
tOE	Data valid from OE		150	ns	



WAVEFORMS(MX27C1024) READ CYCLE(WORD MODE)

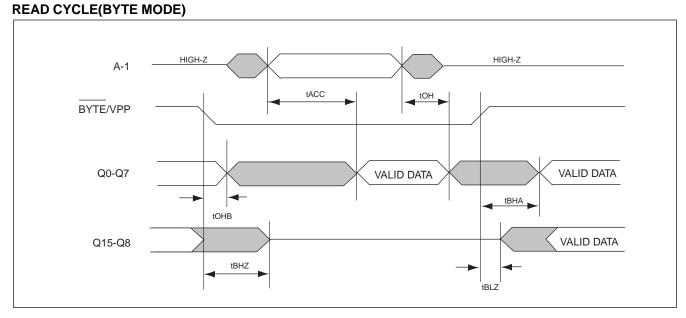


FAST PROGRAMMING ALGORITHM WAVEFORMS

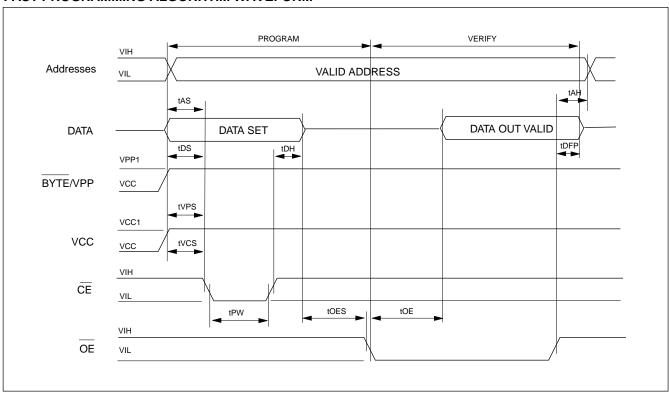




WAVEFORMS(MX27C1100)



FAST PROGRAMMING ALGORITHM WAVEFORM





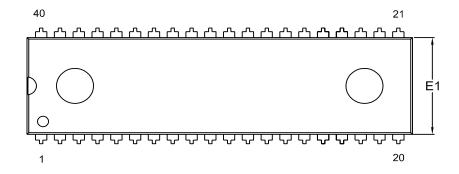
ORDER INFORMATION

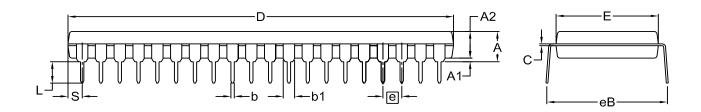
PLASTIC PACKAGE

PART NO.	ACCESS TIME	OPERATING CURRENT	STANDBY CURRENT	PACKAGE
	(ns)	MAX.(mA)	MAX.(uA)	
MX27C1100PC-70	70	40	100	40 Pin DIP(ROM pin out)
MX27C1100PC-85	85	40	100	40 Pin DIP(ROM pin out)
MX27C1100PC-10	100	40	100	40 Pin DIP(ROM pin out)
MX27C1100PC-12	120	40	100	40 Pin DIP(ROM pin out)
MX27C1100PC-15	150	40	100	40 Pin DIP(ROM pin out)
MX27C1100MC-70	70	40	100	40 Pin SOP
MX27C1100MC-85	85	40	100	40 Pin SOP
MX27C1100MC-10	100	40	100	40 Pin SOP
MX27C1100MC-12	120	40	100	40 Pin SOP
MX27C1100MC-15	150	40	100	40 Pin SOP
MX27C1024PC-55	55	40	100	40 Pin DIP(JEDEC pin out)
MX27C1024PC-70	70	40	100	40 Pin DIP(JEDEC pin out)
MX27C1024PC-85	85	40	100	40 Pin DIP(JEDEC pin out)
MX27C1024PC-10	100	40	100	40 Pin DIP(JEDEC pin out)
MX27C1024PC-12	120	40	100	40 Pin DIP(JEDEC pin out)
MX27C1024PC-15	150	40	100	40 Pin DIP(JEDEC pin out)
MX27C1024QC-55	55	40	100	44 Pin PLCC
MX27C1024QC-70	70	40	100	44 Pin PLCC
MX27C1024QC-85	85	40	100	44 Pin PLCC
MX27C1024QC-10	100	40	100	44 Pin PLCC
MX27C1024QC-12	120	40	100	44 Pin PLCC
MX27C1024QC-15	150	40	100	44 Pin PLCC
MX27C1024MC-55	55	40	100	40 Pin SOP
MX27C1024MC-70	70	40	100	40 Pin SOP
MX27C1024MC-85	85	40	100	40 Pin SOP
MX27C1024MC-10	100	40	100	40 Pin SOP
MX27C1024MC-12	120	40	100	40 Pin SOP
MX27C1024MC-15	150	40	100	40 Pin SOP

PACKAGE INFORMATION

Title: Package Outline for PDIP 40L(600MIL)





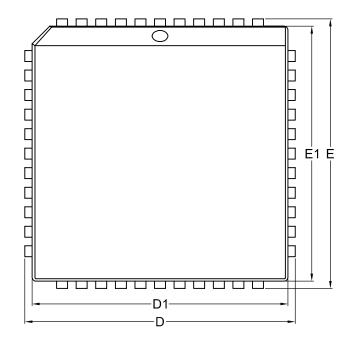
Dimensions (inch dimensions are derived from the original mm dimensions)

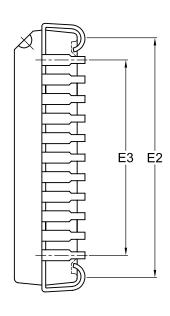
SY	MBOL	Α	A1	A2	b	b1	С	D	Е	E1	е	eВ		s
UNIT		(Λ'	AZ	ь	Di	<u> </u>		_		b	CD	_	
	MIn.	-	0.25	3.73	0.38	1.14	0.20	51.31	15.11	13.84		15.75	2.92	1.65
mm	Nom.	1	-	3.94	0.46	1.27	0.25	51.94	15.24	13.97	2.54	16.51	3.30	1.90
	Max.	4.90	0.76	4.14	0.53	1.40	0.30	52.57	15.37	14.10		17.27	3.68	2.16
	Min.		0.010	0.147	0.015	0.045	0.008	2.020	0.595	0.545		0.620	0.115	0.065
Inch	Nom.	-	-	0.155	0.018	0.050	0.010	2.045	0.600	0.550	0.100	0.650	0.130	0.075
	Max.	0.193	0.030	0.163	0.021	0.055	0.012	2.070	0.605	0.555		0.680	0.145	0.085

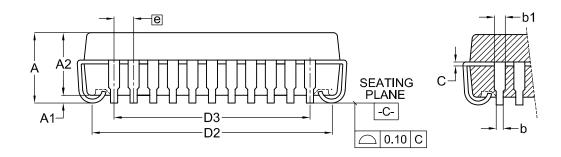
DWC NO	REVISION		ISSUE DATE		
DWG.NO.	REVISION	JEDEC	EIAJ		1330E DATE
6110-0202.4	6				11-19-'02



Title: Package Outline for 44L PLCC







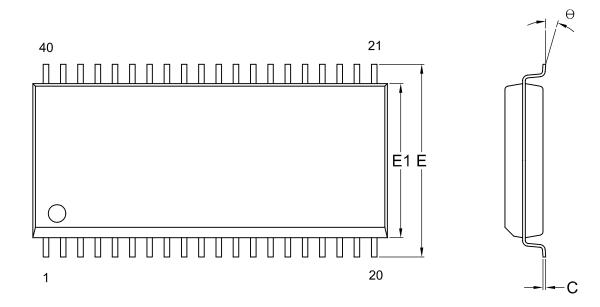
Dimensions (inch dimensions are derived from the original mm dimensions)

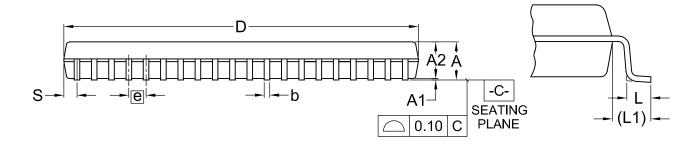
SY	MBOL	Α	A1	A2	b	b1	С	D	D1	D2	D3	E	E1	E2	E3	е
	Min.		0.38	3.71	0.38	0.61	0.20	17.40	16.52	15.19		17.40	16.52	15.19		
mm	Nom.		0.50	3,81	0.46	0.71	0.25	17.53	16,59	15.49	12.70	17.53	16.59	15.49	12.70	1.27
	Max.	4.57	0.66	3.91	0.54	0.81	0.30	17.66	16.66	15.79		17.66	16.66	15.79		
	Min.	_	0.015	0.146	0.015	0.024	0.008	0.685	0.650	0.598		0.685	0.650	0.598		
Inch	Nom.	_	0.020	0.150	0.018	0.028	0.010	0.690	0.653	0.610	0.500	0.690	0.653	0.610	0.500	0.050
	Max.	0.180	0.026	0.154	0.021	0.032	0.012	0.695	0.656	0.622		0.695	0.656	0.622		

DWG.NO.	REVISION		ICCUE DATE		
		JEDEC	EIAJ		ISSUE DATE
6110-2003	4	MS-016			09-24-'02



Title: Package Outline for SOP 40L (450MIL)





Dimensions (inch dimensions are derived from the original mm dimensions)

SY UNIT	MBOL	A	A 1	A2	b	С	D	E	E1	е	L	L1	s	θ
	Min.	-	0.10	2.59	0.36	0.15	25.93	13.92	11.17		0.56	1.20	0.84	0
mm	Nom.		0.15	2.69	0.41	0.20	26.06	14.12	11.30	1.27	0.76	1.40	0.97	5
	Max.	3.00	0.20	2.80	0.51	0.25	26.19	14.32	11.43		0.96	1.60	1.10	8
	Min.		0.004	0.102	0.014	0.006	1.021	0.548	0.440		0.022	0.047	0.033	0
Inch	Nom.	_	0.006	0.106	0.016	0.008	1.026	0.556	0.445	0.050	0.030	0.055	0.038	5
	Max.	0.118	0.008	0.110	0.020	0.010	1.031	0.564	0.450		0.038	0.063	0.043	8

DWC NO	DEVISION		ICCUE DATE			
DWG.NO.	REVISION	JEDEC	EIAJ		ISSUE DATE	
6110-1404.1	3	MO-099			09-24-'02	



REVISION HISTORY

Revision No.	Description	Page	Date
3.0	Revise speed grade from 70/90/120/150ns to 55/70/85/100/		10/15/1996
	120/150ns.		
	Add 40 pin SOP package type.		
4.0	Eliminate Interactive Programming Mode.		06/14/1997
	2) 40-CDIP package quartz lens, change to square shape.		
4.1	IPP: 100uA> 10uA		08/08/1997
4.2	Add industrial grade 70/85/100/120/150ns 40-TSOP(I)	P15	11/19/1998
4.3	Cancel ceramic DIP package type	P1,2,4,15,16	FEB/25/2000
4.4	Cancel "Ultraviolet Erasable" wording in General Description	P1	AUG/20/2001
	To modify Package Information	P15~18	
4.5	To modify Package Information	P15~18	NOV/19/2002
4.6	1. To remove 10 x 14mm 40-TSOP package type.	P1,2,14,18	JAN/14/2003
	2. To modify 40-PDIP package information	P15	



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