

## Ray tracer designed (continued)

Now we are finally ready to build an image. This will be a very crude image because it will support ambient lighting only. Nevertheless this is a significant milestone because the 3-D geometry problem must be addressed.

### Overview of the *make\_image()* function

The *make\_image()* function should live in a separate module named *image.c*

```
void make_image(  
FILE *outFP,  
model_t *model)  
{  
    unsigned char *pixmap;  
  
    compute size of output image and malloc() pixmap.  
  
    for y = 0 to window size in pixels  
    {  
        for x = 0 to window size in pixels  
        {  
            make_pixel(model, x, y, pixmap_location);  
        }  
    }  
    write .ppm P6 header to outFP  
    write pixmap to outFP  
}
```

## The *make\_pixel* function

This function is responsible for driving the construction of the  $(r, g, b)$  components of a single pixel. Within the ray tracing process pixel colors are represented as

- 1.double precision values in the range  $[0.0, 1.0]$  where
- 2.0.0 represents black and 1.0 the brightest level of the corresponding color.

However, depending upon input values its possible for the raytracing algorithm *to compute intensities that exceed 1.0*. When this happens this module must *clamp* them back to the allowable range  $[0.0, 1.0]$ .

```
void make_pixel(  
model_t *model,  
int      x,          /* Pixel x coord          */  
int      y,          /* Pixel y coord          */  
unsigned char *pixval) /* -> to (r, g, b) in pixmap */  
{  
    double *world = malloc(3 * sizeof(double));  
    double *intensity = malloc(3 * sizeof(double));  
  
    map_pix_to_world(x, y, world);  
  
    initilize intensity to (0.0, 0.0, 0.0)  
  
    compute unit vector dir in the direction from the view_point to world;  
  
    ray_trace(model, model->proj->view_point, dir, intensity,  
              0.0, NULL);  
  
    clamp each element of intensity to the range [0.0, 1.0]  
  
    set (r, g, b) components of vector pointed to by pixval to 255 * corresponding intensity  
}
```

## The *ray\_trace* function

The *ray\_trace* function is responsible for tracing a single ray. It should reside in *ray.c*

```
/**/
/* This function traces a single ray and returns the composite
*/
/* intensity of the light it encounters It is recursive and */
/* so the start of the ray cannot be assumed to be the viewpt
*/
/* Recursion won't be involved until we take on specular light
*/

void ray_trace(
model_t *model,          /* pointer to model container */
double base[3],          /* location of viewer or previous hit */
double dir[3],           /* unit vector in direction of object */
double intensity[3],     /* intensity return location */
double total_dist,       /* distance ray has traveled so far */
obj_t *last_hit)        /* obj that reflected this ray or NULL*/
{
```

The ray trace function should rely upon *find\_closest\_object* to identify the nearest object that is hit by the ray. If none of the objects in the scene is hit, NULL is returned.

```
    closest = find_closest_obj(model->scene,
                               base, dir, NULL);

    if (closest == NULL)
        return;

    add distance from base to closest object to total_dist
    set intensity to the ambient reflectivity of closest
    divide intensity by total_dist

}
```

Note: the “distance” to the closest object can be found in the “distance” field of the *sceneobj\_t* structure associated with the closest object. The functions *sphere\_hits()* and *plane\_hits()* will set this field.

### The *find\_closest\_obj* function

The prototype for the `find_closest_obj()` function is:

```
obj_t *find_closest_obj(  
    list_t *scene,      /* head-pointer of scene objects list */  
    double base[],      /* starting coordinates of ray      */  
    double unitDir[],    /* Direction of ray                  */  
    void *lasthit,      /* Object last hit by ray, or NULL   */  
);
```

The `find_closest_obj()` function processes each object in the scene list and uses the “hits” functions described in the following sections to determine if a ray that starts at `base` and goes in the direction `unitDir` hits the object. If one or more objects is hit by the ray the function determines which object is the closest to the base and returns a pointer to that object. If no object is hit, the function returns NULL.

For the initial version of the raytracer the `lasthit` parameter will always be NULL. We will use this parameter in later versions of the raytracer when a ray bounces from one object to another.