FBM 1: Object Perception

Team name: _____

Referee I: _____, **Referee II:** _____

Date and time: _____

Notes:

- Start and end time are based on the referee stop watch.
- Timeout is checked when the robot cannot detect the object within the specified test duration.
- GT is the ground truth which is the information provided by the referee box.
- Object identifier:
  - EM-01(1)=aid tray, EM-02(2)=cover plate box
  - AX-01(4)=bearing box type A, AX-16(3)=bearing box type B
  - AX-02(6)=bearing, AX-09(7)=motor, AX-03(5)=axis

Run 1 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

	Container		Bearing Box		Transmission		
GT	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

	x	y	θ		x	y	θ
GT				Robot			

Comments: _____

_____

Run 2 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

	Container		Bearing Box		Transmission		
GT	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

	x	y	θ		x	y	θ
GT				Robot			

Comments: _____

_____

Run 3 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Run 4 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Run 5 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Run 6 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Run 7 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Run 8 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Run 9 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Run 10 Start Time: _____, End Time: _____, ☐ Timeout

Object Detection

GT	Container		Bearing Box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)
Robot	Container		Bearing box		Transmission		
	EM-01(1)	EM-02(2)	AX-01(4)	AX-16(3)	AX-02(6)	AX-09(7)	AX-03(5)

Pose

GT	x	y	θ	Robot	x	y	θ

Comments: _____

_____

Benchmarking data delivered appropriately: ☐ yes / ☐ no

Team leader signature: _____

Referee signature: _____

FBM 2: Visual Servoing

Team name: _____

Referee I: _____, **Referee II:** _____

Date and time: _____

Notes:

- The start and the end time for each run are based on the referee stop watch.
- Timeout is checked when the robot cannot grasp the object within the specified test duration.
- The sequence of objects which are used in each run is defined by the team.
- Objects: EM-01=aid tray orange, EM-02=cardbox black, AX-01=bearing box type A, AX-16=Bearing box type B, AX-02=bearing, AX-03=axis, AX-09=motor

Run 1 Start time: _____, End time: _____, ☐ Timeout

Object id: _____, Orientation: _____, ☐ Success, ☐ Dropped

Comments: _____

_____

Run 2 Start time: _____, End time: _____, ☐ Timeout

Object id: _____, Orientation: _____, ☐ Success, ☐ Dropped

Comments: _____

_____

Run 3 Start time: _____, End time: _____, ☐ Timeout

Object id: _____, Orientation: _____, ☐ Success, ☐ Dropped

Comments: _____

_____

Run 4 Start time: _____, End time: _____, ☐ Timeout

Object id: _____, Orientation: _____, ☐ Success, ☐ Dropped

Comments: _____

_____

Run 5 Start time: _____, End time: _____, ☐ Timeout

Object id: _____, Orientation: _____, ☐ Success, ☐ Dropped

Comments: _____

_____

Run 6 Start time: _____, End time: _____, ☐ Timeout

Object id: _____, Orientation: _____, ☐ Success, ☐ Dropped

Comments: _____

Run 7 Start time: _____, End time: _____, ☐ Timeout

Object id: _____, Orientation: _____, ☐ Success, ☐ Dropped

Comments: _____

Benchmarking data delivered appropriately: ☐ yes / ☐ no

Team leader signature: _____

Referee signature: _____