Basic Navigation Test

Team name:									
Referee:									
Date and time:		Task instance:							
Duration:	$oxed{\Box}$ Timeout								
Results									
	reached	reached							
Location 1:	yes no								
Location 2:		Location 7: □ □							
Location 3:		Location 8: □ □							
Location 4:		Location 9: □ □							
Location 5:									
Comments:									
Penalties									
Robot caused a collisi Restart used (-200):	on with the	e environment (-50): \square \square \square \square							
Score									
Maximum final score (excluding t	ime bonus): 500							
Reached position : Completed Task (Time Bonus =	50 points)	_x 50 = = onds x 0.75 =							
Final Score:									
Referee signature: _									
Team leader signatu	ıre:								

Basic Manipulation Test

Team name:							
Referee:							
Date and time:	Task instance:						
Duration:	\Box Tim	neout					
Results							
	-	ping		_			
Object 1:	Success	Failed	Success	Failed \Box			
Object 2:							
Object 3:							
Object 4:							
Object 5:							
Comments:							
Penalties A manipulation object	,	,					
Robot caused a collist Restart used (-200):	ion with t	the envir	ronment (-	50): \square \square			
Score							
Maximum final score (excluding	time bo	onus) : 110	00			
Grasped objects = Placed objects = Completed Task (Time Bonus =	100 point	x 100 s)	= = = 0.75 =				
Final Score:							
Referee signature:					_		
Team leader signate	ure:						

Basic Transportation Test

Team name:									
Referee:									
Date and time:		Task instance:							
Duration:	\square Tim	neout							
Results									
	_	ping		_					
Object 1:	Success	Failed	Success	Failed \Box					
Object 2:									
Object 3:									
Object 4:									
Object 5:									
Comments:									
Penalties									
A manipulation obje Robot caused a collis Restart used (-200):	`		onment (-	50): □ □]				
Score									
Maximum final score	(excluding	time bo	onus) : 110	00					
Grasped objects = Placed objects = Completed Task Time Bonus =	(100 point	x 100 s)	= = = 0.75 =						
Final Score:									
Referee signature:					-				
Team leader signat	ure:								

Precise Placement Test

Team name:		
Referee:		
Date and time:		Task instance:
Duration:	\square Timeout	
Results		
Object 1:	Placing Success Failed □ □	
Object 2:		
Object 3:		
Comments:		
Penalties A manipulation object Robot caused a collision Restart used (-200):	'	onment (-50):
Score		
Maximum final score (ex	cluding time bor	nus): 1000
Precisely placed obj Completed Task (10 Time Bonus =	00 points)	=
Final Score:		
Referee signature:		
Team leader signature	e:	

Conveyor Belt Test

Team name:		
Referee:		
Date and time:		Task instance:
Duration:	\Box Timeout	
Results		
Object 1:	Grasping Success Failed	d
Object 2:		
Object 3:		
Comments:		
Penalties		
A manipulation object Robot caused a collist Restart used (-200):	,	
Score		
Maximum final score (excluding time l	bonus): 1000
Precisely grasped Completed Task (Time Bonus =	(100 points)	=
Final Score:		
Referee signature: _		
Team leader signati	ure:	

Final Test

Team name:									
Referee:									
Date and time:					Task instance:				
Duration:	\Box Timeout								
Results									
		sping No	Plac Yes	_		Gras Yes	sping No	Plac Yes	_
Object 1:					Object 6:				
Object 2:					Object 7:				
Object 3:					Object 8:				
Object 4:					Object 9:				
Object 5:					Object 10:				
Comments:									
Penalties A manipulation object is lost (-100): Robot caused a collision with the environment (-50): Restart used (-200):									
Score									
Maximum final score (excluding time bonus) : 2100 Grasped objects =									
Final Score:									
Referee signature:									
Team leader signatu	ıre: _								