

The L-Shaped Method

Operations Research

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- 1 The L-Shaped Method [§5.1 of BL]
- 2 Optimality Cuts [§5.1a of BL]
- 3 Feasibility Cuts [§5.1b of BL]
- 4 Proof of Convergence [§5.1c of BL]
- 5 Example: Capacity Expansion Planning

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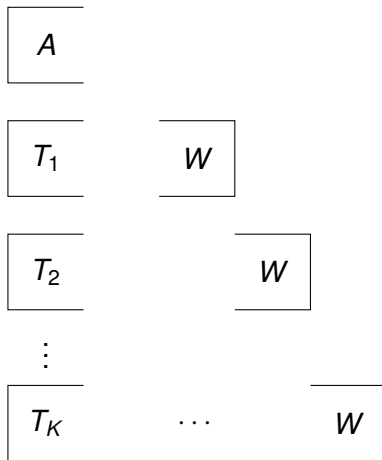
Extensive Form 2-Stage Stochastic Linear Program

$$\begin{aligned}(EF) : \min & c^T x + \sum_{k=1}^K p_k q_k^T y_k \\ \text{s.t. } & Ax = b \\ & T_k x + W y_k = h_k, k = 1, \dots, K \\ & x \geq 0, y_k \geq 0, k = 1, \dots, K\end{aligned}$$

- K realizations of random vector ξ , with probabilities $p_k, k = 1, \dots, K$
- Randomness: q_k, h_k, T_k
- y_k : second-stage decision given realization k

Block Structure

Multi-stage decision making process



Idea: ignore constraints of future stages

Master Problem

We know that

$$V(x) = \left\{ \min \sum_{k=1}^K p_k q_k^T y_k \mid W y_k = h_k - T_k x, y_k \geq 0 \right\}$$

is a *piecewise linear* function of x

Define **master problem** as

$$(M) : \min z = c^T x + \theta \tag{1}$$

$$\text{s.t. } Ax = b$$

$$D_l x \geq d_l, l = 1, \dots, r \tag{2}$$

$$E_l x + \theta \geq e_l, l = 1, \dots, s \tag{3}$$

$$x \geq 0, \theta \in \mathbb{R}$$

- Feasibility cuts: equation 2
- Optimality cuts: equation 3

Optimality Cuts

Consider a trial first-stage decision x^v

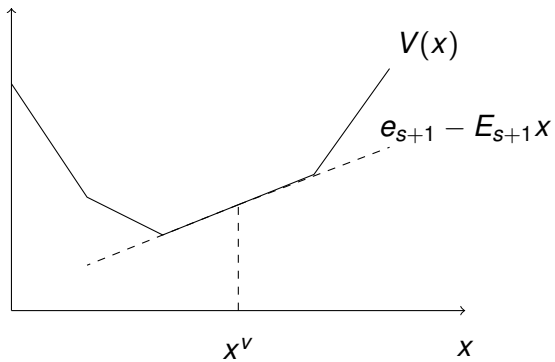
Let π_k^v be simplex multipliers of second-stage problem:

$$\begin{aligned} \min w &= q_k^T y \\ \text{s.t. } Wy &= h_k - T_k x^v \\ y &\geq 0 \end{aligned}$$

$e_{s+1} - E_{s+1}x$ supports $V(x)$ at x^v , where

$$E_{s+1} = \sum_{k=1}^K p_k \cdot (\pi_k^v)^T T_k \quad (4)$$

$$e_{s+1} = \sum_{k=1}^K p_k \cdot (\pi_k^v)^T h_k \quad (5)$$



The L-Shaped Algorithm

- Step 0. Set $r = s = v = 0$
- Step 1. Solve master problem (M). Let (x^v, θ^v) be an optimal solution.
If $s = 0$ (no optimality cuts), remove θ from (M) and set $\theta^0 = -\infty$
- Step 2. If $x \notin K_2$, add feasibility cut (equation 2) and return to Step 1. Otherwise, go to Step 3.
$$K_2 = \{x | \exists y : Wy = h_k - T_k x, y \geq 0, k = 1, \dots, K\}$$
- Step 3. Compute E_{s+1}, e_{s+1} . Let $w^v = e_{s+1} - E_{s+1}x^v$. If $\theta^v \geq w^v$, stop with x^v an optimal solution. Otherwise, set $s = s + 1$, add optimality cut to equation 3 and return to Step 1.

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Example 1

$$z = \min 100x_1 + 150x_2 + \mathbb{E}_\xi(q_1y_1 + q_2y_2)$$

$$\text{s.t. } x_1 + x_2 \leq 120$$

$$6y_1 + 10y_2 \leq 60x_1$$

$$8y_1 + 5y_2 \leq 80x_2$$

$$y_1 \leq d_1, y_2 \leq d_2$$

$$x_1 \geq 40, x_2 \geq 20, y_1, y_2 \geq 0$$

$$\xi = (d_1, d_2, q_1, q_2) = \begin{cases} (500, 100, -24, -28), & p_1 = 0.4 \\ (300, 300, -28, -32), & p_2 = 0.6 \end{cases}$$

Iteration 1

- *Step 1.*

$$\min\{100x_1 + 150x_2 \mid x_1 + x_2 \leq 120, x_1 \geq 40, x_2 \geq 20\}$$

- $x^1 = (40, 20)^T, \theta^1 = -\infty$

- *Step 3.* For $\xi = \xi_1$ solve

$$\min\{-24y_1 - 28y_2 \mid 6y_1 + 10y_2 \leq 2400, 8y_1 + 5y_2 \leq 1600$$

$$0 \leq y_1 \leq 500, 0 \leq y_2 \leq 100\}$$

$$w_1 = -6100, y^T = (137.5, 100), \pi_1^T = (0, -3, 0, -13)$$

For $\xi = \xi_2$ solve

$$\min\{-28y_1 - 32y_2 \mid 6y_1 + 10y_2 \leq 2400, 8y_1 + 5y_2 \leq 1600$$

$$0 \leq y_1 \leq 300, 0 \leq y_2 \leq 300\}$$

$$w_2 = -8384, y^T = (80, 192), \pi_2^T = (-2.32, -1.76, 0, 0)$$

Iteration 1: Optimality Cut

$$h_1 = (0, 0, 500, 100)^T, h_2 = (0, 0, 300, 300)^T$$

$$T_{.,1} = (-60, 0, 0, 0)^T, T_{.,2} = (0, -80, 0, 0)^T$$

- $e_1 = 0.4 \cdot \pi_1^T \cdot h_1 + 0.6 \cdot \pi_2^T \cdot h_2 = 0.4 \cdot (-1300) + 0.6 \cdot (0) = -520$
- $E_1 = 0.4 \cdot \pi_1^T T + 0.6 \cdot \pi_2^T T =$
 $0.4(0, 240) + 0.6(139.2, 140.8) = (83.52, 180.48)$
- $w^1 = -520 - (83.52, 180.48) \cdot x^1 = -7470.4$
- $w^1 = -7470.4 > \theta^1 = -\infty$, therefore add the cut
 $83.52x_1 + 180.48x_2 + \theta \geq -520$

- *Step 1.* Solve master

$$\min\{100x_1 + 150x_2 + \theta \mid x_1 + x_2 \leq 120, x_1 \geq 40, x_2 \geq 20, \\ 83.52x_1 + 180.48x_2 + \theta \geq -520\}$$

$$z = -2299.2, x^2 = (40, 80)^T, \theta^2 = -18299.2$$

- *Step 3.* Add the cut $211.2x_1 + \theta \geq -1584$

- *Step 1.* Solve master.

$$z = -1039.375, x^3 = (66.828, 53.172)^T, \theta^3 = -15697.994$$

- *Step 3.* Add the cut $115.2x_1 + 96x_2 + \theta \geq -2104$

- *Step 1.* Solve master.

$$z = -889.5, x^4 = (40, 33.75)^T, \theta^4 = -9952$$

- *Step 3.* There are multiple solutions for $\xi = \xi_2$. Select one, add the cut $133.44x_1 + 130.56x_2 + \theta \geq 0$

- *Step 1.* Solve master

$$\begin{aligned} \min \{ & 100x_1 + 150x_2 + \theta \mid x_1 + x_2 \leq 120, x_1 \geq 40, x_2 \geq 20, \\ & 83.52x_1 + 180.48x_2 + \theta \geq -520, 211.2x_1 + \theta \geq -1584 \\ & 115.2x_1 + 96x_2 + \theta \geq -2104, 133.44x_1 + 130.56x_2 + \theta \geq 0 \} \\ z = & -855.833, x^5 = (46.667, 36.25)^T, \theta^5 = -10960 \end{aligned}$$

- *Step 3.* $w_5 = -520 - (83.52, 180.48) \cdot x^5 = -10960 = \theta^5$,
stop. $x = (46.667, 36.25)^T$ is the optimal solution.

Example 2

$$z = \min \mathbb{E}_{\xi}(y_1 + y_2)$$

$$\text{s.t. } 0 \leq x \leq 10$$

$$y_1 - y_2 = \xi - x$$

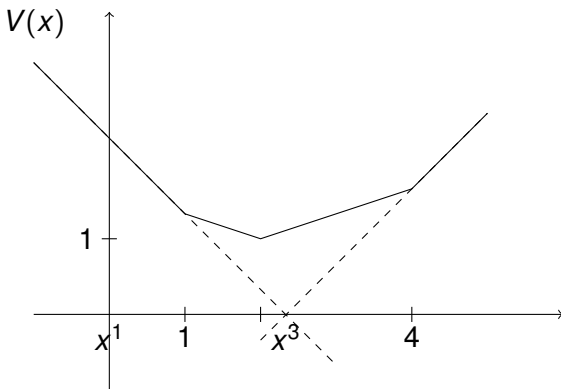
$$y_1, y_2 \geq 0$$

$$\xi = \begin{cases} 1 & p_1 = 1/3 \\ 2 & p_2 = 1/3 \\ 4 & p_3 = 1/3 \end{cases}$$

$$K_2 = \mathbb{R}$$

L-Shaped Method in Example 2

- Iteration 1, Step 1: $x^1 = 0$
- Iteration 1, Step 3: x^1 not optimal, add cut: $\theta \geq 7/3 - x$
- Iteration 2, Step 1: $x^2 = 10$
- Iteration 2, Step 3: x^2 not optimal, add cut: $\theta \geq x - 7/3$
- Iteration 3, Step 1: $x^3 = 7/3$
- Iteration 3, Step 3: x^3 not optimal, add cut: $\theta \geq (x + 1)/3$
- Iteration 4, Step 1: $x^4 = 1.5$
- Iteration 4, Step 3: x^4 not optimal, add cut: $\theta \geq (5 - x)/3$
- Iteration 5, Step 1: $x^5 = 2$
- Iteration 5, Step 3: x^5 is optimal



- $V(x^1) = 7/3$ and $V(x) = 7/3 - x$ 'around' x^1
- $(7 - x)/3$ is the optimality cut at x^1

Geometric Interpretation of Optimality Cuts

- $Q(x, \xi) = \min_y \{q(\omega)^T y \mid W(\omega)y = h(\omega) - T(\omega)x, y \geq 0\}$
yields dual optimal multipliers $\pi^T = q_B(\omega)^T \cdot B(\omega)^{-1}$
- From linear programming duality

$$Q(x, \xi) = q_B(\omega)^T \cdot B(\omega)^{-1} (h(\omega) - T(\omega)x)$$

- $B(\omega)$ is optimal basis as long as
 $y_B = B(\omega)^{-1} (h(\omega) - T(\omega)x) \geq 0$, $y_N = 0$ and
 $q_B(\omega)^T B(\omega)^{-1} \cdot W \leq q(\omega)^T$
- Taking expectation,

$$V(x) = \mathbb{E}_\xi \{q_B(\omega)^T \cdot B(\omega)^{-1} (h(\omega) - T(\omega)x)\}$$

in the set $\cap_{\xi \in \Xi} \{x \mid B(\omega)^{-1} (h(\omega) - T(\omega)x) \geq 0\}$

- This is exactly the expression for optimality cuts at x^v



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Feasibility Cuts

Consider the following problem:

$$\begin{aligned}(F) : \min w' &= e^T v^+ + e^T v^- \\ \text{s.t. } Wy + lv^+ - lv^- &= h_k - T_k x^v \\ y \geq 0, v^+ \geq 0, v^- &\geq 0\end{aligned}$$

with dual multipliers σ^v . Define

$$\begin{aligned}D_{r+1} &= (\sigma^v)^T T_k \\ d_{r+1} &= (\sigma^v)^T h_k\end{aligned}$$

Step 2 of L-shaped method: For $k = 1, \dots, K$ solve (F).

- If $w' = 0$ for all k , go to Step 3.
- Else, add $D_{r+1}x \geq d_{r+1}$, set $r = r + 1$ and go to Step 1.

Example

$$\begin{aligned} \min & 3x_1 + 2x_2 - \mathbb{E}_\xi(15y_1 + 12y_2) \\ \text{s.t. } & 3y_1 + 2y_2 \leq x_1, 2y_1 + 5y_2 \leq x_2 \\ & 0.8\xi_1 \leq y_1 \leq \xi_1, 0.8\xi_2 \leq y_2 \leq \xi_2 \\ & x, y \geq 0 \end{aligned}$$

$$\xi = \begin{cases} (4, 4), p_1 = 0.25 \\ (4, 8), p_2 = 0.25 \\ (6, 4), p_3 = 0.25 \\ (6, 8), p_4 = 0.25 \end{cases}$$

Generating a Feasibility Cut

For $x^1 = (0, 0)^T$, $\xi = (6, 8)^T$, solve

$$\begin{aligned} \min_{v^+, v^-, y} \quad & v_1^+ + v_1^- + v_2^+ + v_2^- + v_3^+ + v_3^- + \\ & v_4^+ + v_4^- + v_5^+ + v_5^- + v_6^+ + v_6^- \\ \text{s.t.} \quad & v_1^+ - v_1^- + 3y_1 + 2y_2 \leq 0, v_2^+ - v_2^- + 2y_1 + 5y_2 \leq 0 \\ & v_3^+ - v_3^- + y_1 \geq 4.8, v_4^+ - v_4^- + y_2 \geq 6.4 \\ & v_5^+ - v_5^- + y_1 \leq 6, v_6^+ - v_6^- + y_2 \leq 8 \end{aligned}$$

We get $w' = 11.2$, $\sigma^1 = (-3/11, -1/11, 1, 1, 0, 0)$
 $h = (0, 0, 4.8, 6.4, 6, 8)^T$, $T_{\cdot,1} = (-1, 0, 0, 0, 0, 0)^T$,
 $T_{\cdot,2} = (0, -1, 0, 0, 0, 0)^T$
 $D_1 = (-3/11, -1/11, 1, 1, 0, 0) \cdot T = (3/11, 1/11)$,
 $d_1 = (-3/11, -1/11, 1, 1, 0, 0) \cdot h = 11.2$
 $3/11x_1 + 1/11x_2 \geq 11.2$

Going by the book:

- Iteration 2 master problem: $x^2 = (41.067, 0)^T$
- Iteration 2 feasibility cut: $x_2 \geq 22.4$
- Iteration 3 master problem: $x^3 = (33.6, 22.4)^T$
- Iteration 3 feasibility cut: $x_2 \geq 41.6$
- Iteration 4 master problem: $x^4 = (27.2, 41.6)^T$ is feasible

Induced Constraints:

- Observe that for $\xi = (6, 8)^T$, $y_1 \geq 4.8$, $y_2 \geq 6.4$
- This implies $x_1 \geq 27.2$, $x_2 \geq 41.6$, which should be added directly to the master

Personal experience: feasibility cuts are impractical

Complete Recourse and Relative Complete Recourse

$$\text{pos } W = \{z \mid z = Wy, y \geq 0\}$$

$$K_1 = \{x \mid Ax = b\}, K_2 = \{x \mid \exists y : Wy = h_k - T_k x, k = 1, \dots, K\}$$

Feasibility cuts are not necessary when we have:

- **Complete recourse:** $\text{pos } W = \mathbb{R}^{m_2}$
- **Relative complete recourse:** $K_2 \supseteq K_1$

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Proof of Convergence

Key observation: when we solve the master problem (M) subject to $x \in K_1 \cap K_2$ either

- $\theta^v \geq V(x^v)$ or
- $\theta^v < V(x^v)$

The first case is our termination criterion and implies optimality.

The second case can occur finitely many times.

$$K_1 = \{x | Ax = b, x \geq 0\},$$

$$K_2 = \{x | \exists y : Wy = h_k - T_k x, y \geq 0, k = 1, \dots, K\}$$

$\theta^v \geq V(x^v)$ Is Equivalent to the Termination Criterion

$$Q(x, \xi(\omega)) = \min_y \{q(\omega)^T y \mid Wy = h(\omega) - T(\omega)x, y \geq 0\}$$

- From linear programming duality,

$$Q(x^v, \xi_k) = (\pi_k^v)^T (h_k - T_k x^v)$$

- Taking expectation,

$$V(x) = \mathbb{E}_\xi Q(x^v, \xi) = \sum_{k=1}^K p_k \cdot (\pi_k^v)^T (h_k - T_k x^v)$$

- Our termination criterion is $\theta^v \geq w^v$, where

$$w^v = e_{s+1} - E_{s+1} x^v = \left(\sum_{k=1}^K p_k \cdot (\pi_k^v)^T h_k \right) - \left(\sum_{k=1}^K p_k \cdot (\pi_k^v)^T T_k \right) x^v$$

$\theta^v \geq V(x^v)$ Implies Optimality

- Fact: $Q(x, \xi)$ is convex in x , and π_k^v is a subgradient at x^v :

$$Q(x, \xi_k) \geq (\pi_k^v)^T h_k - (\pi_k^v)^T T_k x$$

- Taking expectation: $V(x) \geq \sum_{k=1}^K p_k \cdot (\pi_k^v)^T (h_k - T_k x)$
- Full problem can be written as

$$\min c^T x + \theta$$

$$\text{s.t. } V(x) \leq \theta$$

$$x \in K_1 \cap K_2$$

Therefore master (M) is a relaxation and gives lower bound

- If there were $\bar{x} \in K_1 \cap K_2$ with $c^T \bar{x} + V(\bar{x}) < c^T x^v + V(x^v)$ then x^v would not be optimal for (M) since (M) would be at most $c^T \bar{x} + V(\bar{x})$

$\theta^v < V(x^v)$ Occurs Finitely Many Times

- We have seen that each optimality cut is equivalent to $\theta \geq V(x^l) + \partial V(x^l)(x - x^l), l = 1, \dots, s$
- Every time $\theta^v < V(x^v)$ occurs, the set of new multipliers $(\pi_k^v), k = 1, \dots, K$ must be different from those generated previously
- Optimal multipliers π_k^v correspond to optimal bases of $\min_y \{q_k^T y \mid Wy = h_k - T_k x, y \geq 0\}$
- There are finitely many bases, therefore finitely many combinations of optimal multipliers $(\pi_k^v), k = 1, \dots, K$

Finite Termination of Feasibility Cuts

Key observations:

- 1 Only a finite number of feasibility cuts can be generated
- 2 The feasibility cuts of equation 2 are **valid**

Valid feasibility cuts:

- remove current candidate x^v from consideration
- do not remove any other candidates $x \in K_2$ from consideration

Finite Number of Possible Cuts

Recall feasibility cuts: $D_l x \geq d_l, l = 1, \dots, r + 1$, where

$$D_{r+1} = (\sigma^v)^T T_k$$

$$d_{r+1} = (\sigma^v)^T h_k$$

and σ^v the dual multipliers of

$$(F) : \min w' = e^T v^+ + e^T v^-$$

$$\text{s.t. } Wy + lv^+ - lv^- = h_k - T_k x^v$$

$$y \geq 0, v^+ \geq 0, v^- \geq 0$$

- σ^v corresponds to a basis B of W : $\sigma^v = c_B^T B^{-1}$
- W has a finite number of bases

Valid Feasibility Cuts: x^v Is Cut Off

If $w' > 0$ then by linear programming duality

$(\sigma^v)^T(h_k - T_k x^v) > 0$, therefore $D_{r+1}x \geq d_{r+1}$ removes x^v from consideration

Valid Feasibility Cuts: No Other $x \in K_2$ Is Cut Off

- Consider the following subset of \mathbb{R}^{m_2} :
 $\{z | z = h_k - T_k x, x \in K_2\}$
- This set is contained in $\text{pos } W = \{z | z = Wy, y \geq 0\}$ by definition of K_2
- The half-space defined by $(\sigma^v)^T z \leq 0$ contains $\text{pos } W$
 - To see this, note that the reduced cost of y must be ≥ 0 :

$$c_N^T - c_B^T B^{-1} N = -(\sigma^v)^T W \geq 0$$

where $c_N^T = 0$, $(\sigma^v)^T = c_B^T B^{-1}$, $N = W$

- Any element of $\text{pos } W$ can be expressed as $z = Wy$, $y \geq 0$, hence from the previous inequality $(\sigma^v)^T z \leq 0$
- Therefore, $(\sigma^v)^T (h - Tx) \leq 0$ will be a valid feasibility cut

Feasibility Cuts

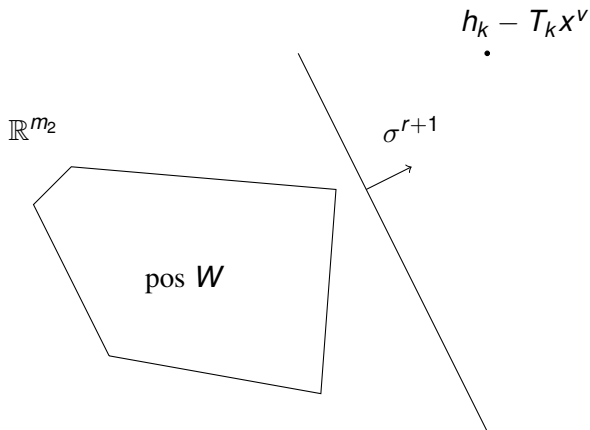


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Example: Capacity Expansion Planning

$$\begin{aligned} \min_{x, y \geq 0} \quad & \sum_{i=1}^n (l_i \cdot x_i + \mathbb{E}_{\xi} \sum_{j=1}^m C_i \cdot T_j \cdot y_{ij}(\omega)) \\ \text{s.t.} \quad & \sum_{i=1}^n y_{ij}(\omega) = D_j(\omega), j = 1, \dots, m \\ & \sum_{j=1}^m y_{ij}(\omega) \leq x_i, i = 1, \dots, n \end{aligned}$$

- l_i, C_i : fixed/variable cost of technology i
- $D_j(\omega), T_j$: height/width of load block j
- $y_{ij}(\omega)$: capacity of i allocated to j
- x_i : capacity of i

Note: D_j is not dependent on ω

Two possible realizations of load duration curve:

- Reference scenario: 10%
- 10x wind scenario: 90%

	Duration (hours)	Level (MW)	Level (MW)
		Reference scenario	10x wind scenario
Base load	8760	0-7086	0-3919
Medium load	7000	7086-9004	3919-7329
Peak load	1500	9004-11169	7329-10315

Slave Problem

$$(S_{\omega}) : \min_{y \geq 0} \sum_{i=1}^n \sum_{j=1}^m C_i \cdot T_j \cdot y_{ij}$$

$$(\lambda_j(\omega)) : \sum_{i=1}^n y_{ij} = D_j(\omega), j = 1, \dots, m$$

$$(\rho_i(\omega)) : \sum_{j=1}^m y_{ij} \leq \bar{x}_i, i = 1, \dots, n$$

where \bar{x} has been fixed from the master problem

Sequence of Investment Decisions

Iteration	Coal (MW)	Gas (MW)	Nuclear (MW)	Oil (MW)
1	0	0	0	0
2	0	0	0	8736
3	0	0	0	15999.6
4	0	14675.5	0	0
5	10673.8	0	0	0
6	10673.8	0	0	13331.8
7	0	163.8	7174.5	3830.8
8	0	3300.6	7868.4	0
9	0	5143.4	7303.9	1679.4
10	3123.9	1948.1	4953.7	1143.3
11	1680	4322.4	6625	0
12	8747.6	1652.8	0	768.6
13	5701.9	464.9	4233.6	768.6
14	4935.9	1405	3994.7	0
15	6552.6	386.3	3173.7	882.9
16	5085	1311	3919	854

- Investment candidate in each iteration necessarily different from *all* past iterations
- 'Greedy' behavior: low capital cost in early iterations