

CPE301 – SPRING 2019
MIDTERM I

Student Name: Rocky Yasuaki Gonzalez

Student #: 5003229733

Student Email: gonzar14@unlv.nevada.edu

Primary Github address: <https://github.com/rockyg1995/ihswwpdar>

Directory: https://github.com/rockyg1995/ihswwpdar/tree/master/Midterms/Midterm_I

Submit the following for all Labs:

1. In the document, for each task submit the modified or included code (only) with highlights and justifications of the modifications. Also, include the comments.
2. Use the previously create a Github repository with a random name (no CPE/301, Lastname, Firstname). Place all labs under the root folder ESD301/Midterm, sub-folder named LABXX, with one document and one video link file for each lab, place modified asm/c files named as LabXX-TYY.asm/c.
3. If multiple asm/c files or other libraries are used, create a folder LabXX-TYY and place these files inside the folder.
4. The folder should have a) Word document (see template), b) source code file(s) and other include files, c) text file with youtube video links (see template).

1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

Atmega328PB Xplained Mini
Micro USB Cable (Power Supply)
Wire Connectors
LM35
ESP01

2. INITIAL/MODIFIED/DEVELOPED CODE

```
/*
 * MIDTERM_I.c
 *
 * Created: 4/7/2019 11:11:38 PM
 * Author: rocky
 */

#define F_CPU 16000000UL // Frequency of Xplained Mini (16MHz)
#include <avr/io.h> // Standard AVR Library
#include <stdio.h> // AVR library containing printf functions
#include <avr/interrupt.h> // AVR library containing interrupt functions
#include <util/delay.h> // AVR library containing _delay_ms() function

#define BAUDRATE 115200 // Baudrate in Bits per second (bps)
#define BAUD_PRESCALER ((F_CPU / (BAUDRATE * 16UL)) - 1) // Baudrate Prescaler
#define MAX_1s 15624 // 1s delay: OCR1A = (16MHz*1000ms/prescaler) -1

//Declaration of our functions
void Timer1_init(void); // Function to initialize Timer1
void USART_init(void); // Function to initialize USART
void adc_init(void); // Function to initialize Analog to Digital Converter

unsigned char USART_receive(void); // Function to receive Serial data from UDR0
void USART_send(unsigned char data); // Function to send char data into UDR0
void USART_putstring(char* StringPtr); // Function to break string into chars and send
void read_adc(void); // Function to read temp received from ADC

volatile float adc_temp; // Stores ADC Value representing Temperature
char outs[20]; // 'outs[]' to store values into array of chars

int main(void) {
    DDRD = 0b00000010; // Main Importance: PD0/RX Input, PD1/TX Output
    TIMSK1 |= (1 << OCIE1A); // Set Interrupt on Compare Match
    sei(); // Enable Global Interrupts
    Timer1_init(); // Call the Timer1 initialization code
    USART_init(); // Call the USART initialization code
    adc_init(); // Call the ADC initialization code
    USART_putstring("Connected!\r\n"); // Pass 'Connected!' to function to send chars
    _delay_ms(125); // Wait a bit
    float adc_tempf; // to store ADC Fahrenheit Temperature

    USART_putstring("AT+CWJAP=\"WIFI_NAME_HERE\", \"WIFI_PASSWORD_HERE\""); //Login WiFi
```

```

while (1) {
    if (TCNT1 == OCR1A) {
        read_adc();
        adc_tempf = (ADCH << 8) + ADCL;
        adc_tempf = (9/5)*adc_tempf + 32;
        snprintf(outs, sizeof(outs), "%3f\r\n", adc_tempf);
        USART_putstring("AT+CIPSTART=\\"TCP\\",\\"api.thingspeak.com\\",80");
        // Connect API Key
        USART_putstring("AT+CIPSEND=51");
        // Send Serial Data
        USART_putstring("GET /update?key=YR8DHQMB2YJS3AAX&field1=outs\r\n");
        // Send Value
        USART_putstring("AT+CIPCLOSE");
        // Close Data
    }
}
return 0;
}

//-----
void Timer1_init(void) {
    OCR1A = MAX_1s;
    TCCR1A = (0<<COM1A1)|(0<<COM1A0);
    TCCR1B = (0<<COM1B1)|(0<<COM1B0);
    TCCR1A = (0<<WGM11)|(0<<WGM10);
    TCCR1B = (0<<WGM13)|(1<<WGM12);
    TCCR1B = (1<<CS12)|(0<<CS11)|(1<<CS10);
}

ISR(TIMER1_COMPA_vect) {
    TCNT1 = 0;
    return;
}

//-----
void USART_init(void) {
    UBRR0H = (uint8_t)(BAUD_PRESCALLER >> 8);
    UBRR0L = (uint8_t)(BAUD_PRESCALLER);
    UCSR0B = (1 << RXEN0) | (1 << TXEN0);
    UCSR0C = (3 << UCSZ00);
}

unsigned char USART_receive(void) {
    while (!(UCSR0A & (1 << RXC0)));
    return UDR0;
}

void USART_send(unsigned char data) {
    while (!(UCSR0A & (1 << UDRE0)));
    UDR0 = data;
}

void USART_putstring(char* StringPtr) {
    while (*StringPtr != 0x00) {
        USART_send(*StringPtr);
        StringPtr++;
    }
}

```

```

}
//-----
void adc_init(void) {
    ADMUX = (0<<REFS1)|(1<<REFS0)|    // Reference Selection Bits, AVcc Ext cap AREF
    (0<<ADLAR)|                        // ADC Left Adjust Result
    (0<<MUX3)|(1<<MUX2)|(0<<MUX1)|(1<<MUX0); // Analog Channel Select Bits 'ADC5'

    ADCSRA = (1<<ADEN)|                // ADC Enable
    (0<<ADSC)|                          // ADC Start Conversion
    (0<<ADATE)|                          // ADC Auto Trigger Enable
    (0<<ADIF)|                          // ADC Interrupt Flag
    (0<<ADIE)|                          // ADC Interrupt Enable
    (1<<ADPS2)|(0<<ADPS1)|(1<<ADPS0);    // ADC Prescaler Select Bits '32'
}

void read_adc(void) {
    unsigned char i = 4;                // Set 'i' for iterations
    adc_temp = 0;                       // set float 'adc_temp'
    while (i-->0) {                    // Decrement 'i' until 4 samples take
        ADCSRA |= (1<<ADSC);            // If ADSC is high (ADC Start Conversion)
        while (ADCSRA & (1<<ADSC));      // Start the ADC Conversion
        adc_temp += ADC;                 // Store analog value of current adc_temp
        _delay_ms(50);                  // delay 50ms for sampling
    }
    adc_temp = (adc_temp/4);             // Average 4 samples taken into adc_temp
}

```

3. SCHEMATICS

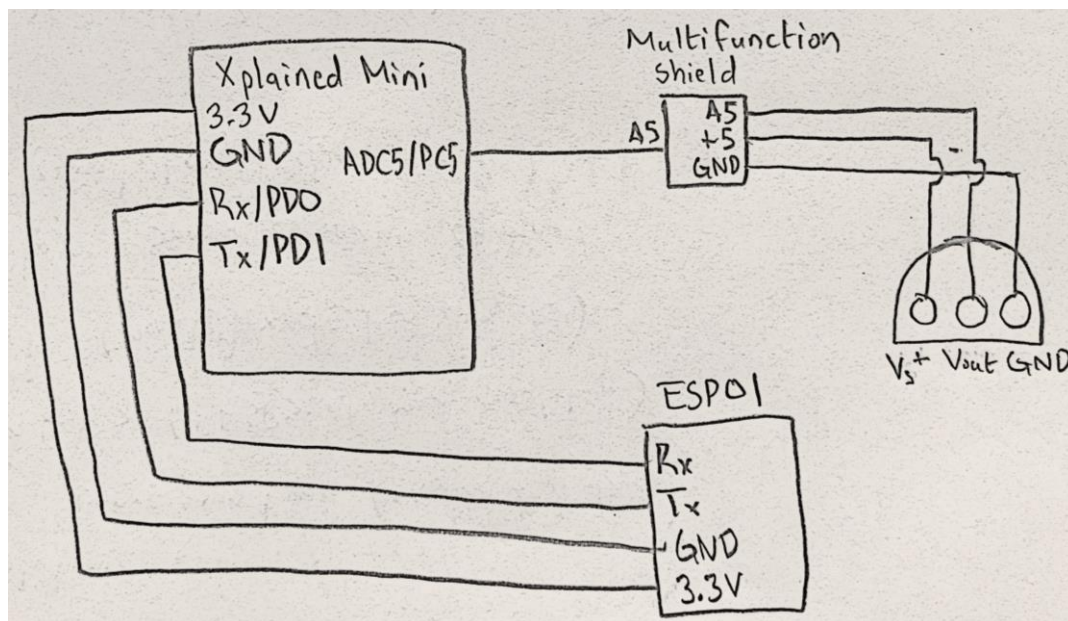


Figure 1 – Schematic Setup of ESP01 Module

4. SCREENSHOTS OF EACH TASK OUTPUT (ATMEL STUDIO OUTPUT)

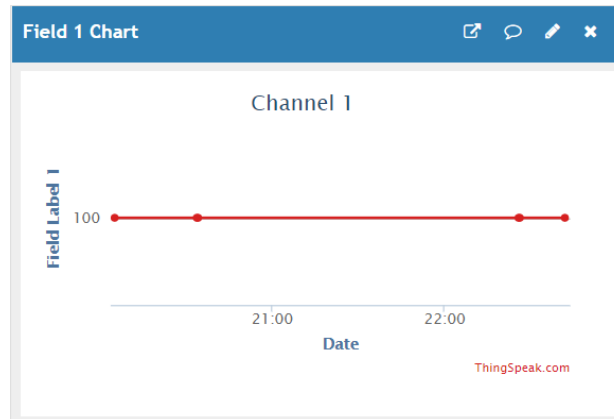


Figure 2 – Output through ThingSpeak Temperature Reading

5. SCREENSHOT OF EACH DEMO (BOARD SETUP)

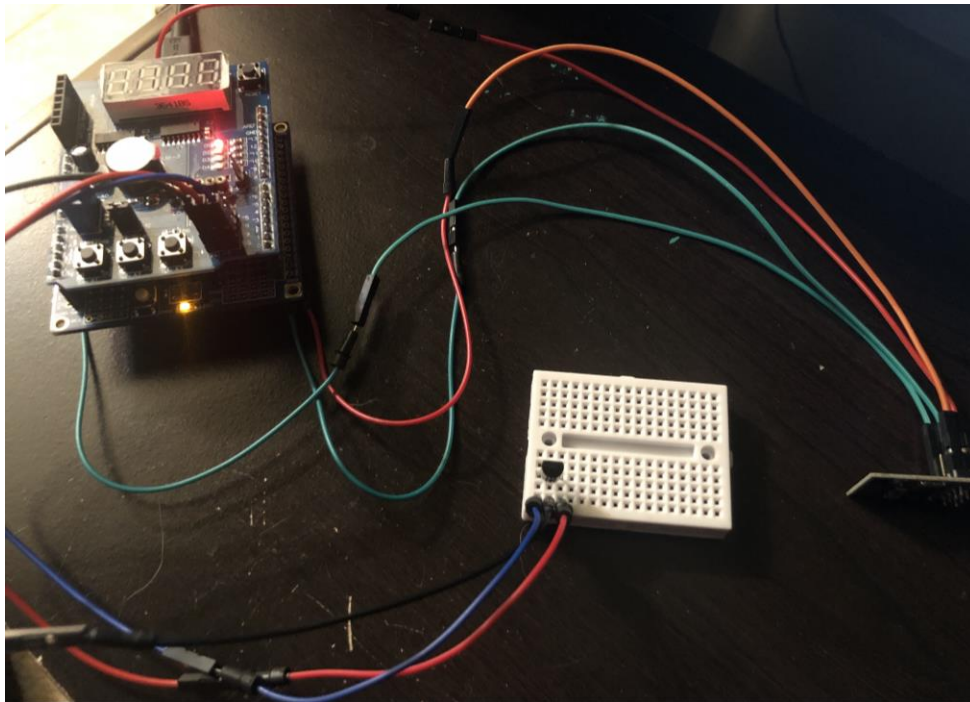


Figure 3 – Board Setup for ESP01 Modul and Atmega328PB w/ Temperature Sensor

6. VIDEO LINKS OF EACH DEMO

N/A

7. GITHUB LINK OF THIS DA

https://github.com/rockyg1995/ihswwpdar/tree/master/Midterms/Midterm_I

Student Academic Misconduct Policy

<http://studentconduct.unlv.edu/misconduct/policy.html>

"This assignment submission is my own, original work".

Rocky Yasuaki Gonzalez