CS 241 Honors Concurrent Data Structures

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What to go over

- Terminology
- What is lock free
- Example of Lock Free
- Transactions and Linearizability
- The ABA problem
- Drawbacks
- Use Cases

• Measure, Measure!

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- Then, you have to choose the right lock free data structure. Most of them work best under circumstances with high contention and where the structure is full of elements.
- Then, you have to measure. If you don't measure, then you don't know if you improved.

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- Atomic Compare and Swap

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```
int atomic_cas(int *addr, int *expected,
    int value){
        if(*addr == *expected){
            *addr = value;
                return 1; //swap success
        }else{
            *expected = *addr;
                 return 0; //swap failed
        }
}
```

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But this all happens atomically!

Types of Data Structures

- Blocking Data Structures
- Lock-Free Data Structures
- Bounded-Wait Data Structures
- Wait-Free Data Structures

Advantages:

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- Well defined critical sections
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Disadvantages

- Slower under high contention; Mutexes are not scalable across cores
- Lower priority processes often get locks
- Deadlock! Convoy Effect!
- Preemption/Signal Handler Safety





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Disadvantages

- Critical Section a little harder to define
- Harder to debug
- Can get really complicated

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Disadvantages

- Not always possible
- Hard to guarantee
- Can get *really* complicated.

Building a lock free Data Structure

Alright, let's make a queue. What do we have to think about? Well there are two types of threads. Those pushing things on to the queue, and those popping off the queue.

Starting out - No Code but Ownership

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Ownership?

- We want to introduce the idea that a thread owns a piece of memory. This is to avoid race conditions.
- There is going to be a shared part of memory and a part only visible to the thread. We are going to do all of our initialization in our memory part and then with one atomic instructions that are carefully placed
- After that the data structure will be initialized

Lock Free initialization

```
typedef struct node;
typedef struct queue;
new_queue()
destory_queue()
```

Lock Free Enqueue

```
void enqueue(queue *fifo, void *val){
    node *pkg = malloc(sizeof(*pkg)), *ptr;
    *pkg = {val, NULL};
    int succeeded = 0;
    while (!succeeded) {
        node *none = NULL:
        ptr = fifo->tail;
        succeeded = cas(&ptr->next, none, pkg)
    }
    // This is actually a critical section
    cas(&fifo->tail, &ptr, package);
```

Lock Free Dequeue

```
node* dequeue(queue *fifo){
    if (!fifo->head) { return NULL; }
    node *start = &fifo->head;
    while (!atomic_cas(&fifo->head, start,
             &fifo->head->next)){
        start = atomic_load(&fifo->head);
        if(start == NULL){
            return NULL;
        // May do sleeping here
    //You now have exclusive access
    return start;
}
```

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- You can see this in the previous example.

Lock Free Enqueue

```
node *package = malloc(sizeof(*package));
package->data = val;
package->next = NULL;
node *ptr;
...
```

Lock Free Enqueue

```
ctx *tex = begin_transaction(queue);
queue_pop(tex);
queue_push(tex, 1);
queue_push(tex, 2);
queue_push(tex, 3);
end_transaction(tex);
// Results pushed (only 2 atomics computed)
```

Alterations

```
pop (tex) {
    // Push the pop on the context
}
push (tex) {
    /* Allocate memory and push the
       value on the stack. if there
       is another pop instruction,
            squish the two nodes */
}
```

Alterations

```
end_transaction (tex) {
    void *none = NULL;
    cas(&tex->queue->head,
        &tex->queue->head, none);
    // My queue
    for (transaction in tex) {
        if (transaction->type == push)
            queue_push (tex->queue,
                 transaction -> data)
       //...
```

Transactions

Of course, you have to resolve the idea of what a pop means in an empty queue in a transaction. More often than not in high performance parallel programming we just throw away bad pops in the case of a queue.

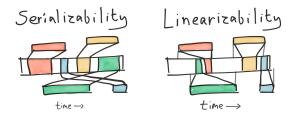
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- You also may have to deal with a transaction failing because the queue may have run out of space.
- This is mainly a tool for the people using the lock free data structures keep track of their operations.

Linearizability & Serializability



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- But sometimes we need stronger consistency models.

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- Think of a stock market application that needs to tell which monetary transaction happened first. We need the application to be fast but we need to know who bought and sold first

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- Hardest to obtain.

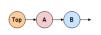
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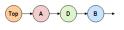
- The ABA problem, no it's not a problem about Dancing Queen.
- It is the idea that a thread A can do something half way, then thread B does a lot of things, and A tries to complete its transaction but incorrectly succeeds.
- This is a problem because over the long term the entire data structure could either break or leak memory.
- Some cases there are no ways of preventing this problem, especially in a language like C without automagic garbage collection.

```
void enqueue(queue *fifo, void *val) {
    node *pkg = malloc(sizeof(*pkg)), *ptr;
    *pkg = {val, NULL};
    int succeeded = 0;
    while(!succeeded) {
        node *none = NULL;
        ptr = fifo->tail;
        succeeded = cas(&ptr->next, none, pkg)
        if(!succeeded){
            cas(&fifo->next, &ptr, ptr->next);
    cas(&fifo->tail, &ptr, package);
    void *data = pkg->val;
    free (pkg);
}
```



Thread A calls method POP that reads Top (pointer to A) and *Top (pointer to B). Thread A gets preemted before doing CAS(Top,*Top).

The ABA problem



Thread B also does POP by doing CAS(Top, "Top), then deletes returned pointer to A. After that Thread B calls PUSH with D by doing CAS(Top, D) and PUSH with new A by doing CAS(Top,A).



Thread A resumes and completes it's CAS(Top,B) leaving D hanging.

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- Our data structure does not need to worry about that!
- Our dequeue instead of returning the item returns the entire node.
- That means the ABA problem has a near zero chance of actually occurring if the user doesn't free the node until after they are done using it.

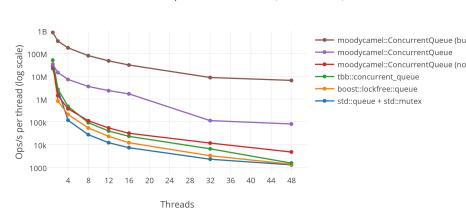
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- These data structures can get complicated fast
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- Sometimes they can't always work
- Sometimes they are slower

Dequeue Performance (AWS 32-core)



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- Memory orders or barriers are a way for you to tell the compiler not to out of order execute your instructions.
- There are different levels of orders most of the time you want the most restrictive in order to ensure your behavior works.
- Only then move down to other orders

Sequential Consistency

```
-Thread 1- -Thread 2-
y = 1 if (x.load() == 2)
store(x, 2); y != 1 && *NULL = 1;
```

Will never segfault

Relaxed Consistency

```
-Thread 1- -Thread 2-

store(x, 1) first = load(x)

store(x, 2); second = load(x)

first <= second
```

A new value will never become old

Use Cases

- RabbitMQ/Apache Kafka is a distributed message queue that uses a queue similar to the one we described to distribute messages to a group of nodes.
- Apache Spark and Hadoop use this for consensus, finger tables, and communicating and joining results together.
- Every distributed (and a lot of non-distributed) databases use lock-free data structures to service SQL queries or read/write form disks
- 4 HPC uses them to manage concurrency (Possible MPI)

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- Ever wonder why spurious wakeups happen?
- Well y'all are masters at lock free data structures now so you can guess.
- Let's take the Windows NT way of implementing a condition variable.
- The real problem with CVs are broadcast.

Windows NT

```
struct CV {
    linked_list waiters;
}

void wait(cv, mtx) { // mtx must be locked
    enqueue(cv.waiters, self());
    m.Release();
    self().sema.wait();
    m.Acquire();
}
```

Not Interesting

```
void signal(cv) {
    if (waiters != null) {
        waiters.sema.post();
        cas(waiters, waiters, waiters.next);
    }
}
```

Interesting

```
void broadcast(cv) {
    while (waiters != null) {
        waiters.sema.post();
        cas(waiters, waiters, waiters.next);
    }
}
```

Interesting



Questions?

Thanks for sticking along!