

Goal: by the end of class students should understand how and be able to compute change of basis matrices using both the manual method and the Gauss-Jordan method.

Class Q: Is the notion of change of basis restricted to \mathbb{R}^n ? if so, why? if not, give an example.

last day: we covered what a change of basis matrix was and did some computations manually.

in particular we said a change of basis matrix $P_{\mathcal{D} \leftarrow \mathcal{B}}$ is the transformation matrix of the identity \mathbb{I} i.e.

$$P_{\mathcal{D} \leftarrow \mathcal{B}} = [Id]_{\mathcal{D} \leftarrow \mathcal{B}}$$

and why might we do this? different bases have their advantages, and sometimes we are given info in one basis and asked to ~~that~~ give an answer in another.

to do this manually we solved systems ~~systems~~ of the form

$$[\vec{v}_i]_{\mathcal{B}} = c_1 \vec{d}_1 + c_2 \vec{d}_2 + \dots + c_n \vec{d}_n \quad \text{for the } c_i\text{'s which involves}$$

an augmented matrix

$$\left[\begin{array}{ccc|c} c_{11}d_1 & \dots & c_{1n}d_n & v_{i1} \\ \vdots & & \vdots & \vdots \\ c_{n1}d_1 & \dots & c_{nn}d_n & v_{in} \end{array} \right]$$

and we would do this for each \vec{v}_i this is tedious but what do we notice? how can we do this a better way?

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a larger augmented matrix! (contractual obligation!)
we can solve them all at once!

↳ the Gauss-Jordan method. let $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_n\}$
& $\mathcal{D} = \{\vec{w}_1, \dots, \vec{w}_n\}$ be bases for V then we can
set up

$$[\mathcal{D} \mid \mathcal{B}] \xrightarrow[\text{reduce}]{\text{row}} [\text{Id} \mid P_{\mathcal{D} \leftarrow \mathcal{B}}]$$

and solve for the change of basis matrix. (note!
the order on \mathcal{B} & \mathcal{D} both for P and in the augmented
matrix)

Ex: let $V = \mathbb{R}^2$ $\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ $\mathcal{D} = \left\{ \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix} \right\}$

find $P_{\mathcal{D} \leftarrow \mathcal{B}}$

~~$$\begin{bmatrix} 0 & 2 & | & 1 & 1 \\ 1 & 3 & | & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 3 & | & 0 & 1 \\ 0 & 2 & | & 1 & 1 \end{bmatrix}$$~~

$$\xrightarrow{\frac{1}{2}R_2} \begin{bmatrix} 1 & 3 & | & 0 & 1 \\ 0 & 1 & | & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \xrightarrow{R_1 - 3R_2} \begin{bmatrix} 1 & 0 & | & -\frac{3}{2} & -\frac{1}{2} \\ 0 & 1 & | & \frac{1}{2} & \frac{1}{2} \end{bmatrix} = [\text{Id} \mid P_{\mathcal{D} \leftarrow \mathcal{B}}]$$

How can we check this? let $\vec{v} = \begin{bmatrix} 2 \\ 3 \end{bmatrix} \Rightarrow [\vec{v}]_{\mathcal{B}} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$

(this is done by inspection, it could be done systematically
or done by computing $P_{\mathcal{B} \leftarrow \mathcal{D}}$)

if we then compute $P_{\mathcal{D} \leftarrow \mathcal{B}} [\vec{v}]_{\mathcal{B}}$ we should get $[\vec{v}]_{\mathcal{D}}$

$$P_{\mathcal{D} \leftarrow \mathcal{B}} [\vec{v}]_{\mathcal{B}} = \begin{bmatrix} -\frac{3}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

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we can tell this is correct since

$$\begin{bmatrix} 2 \\ 3 \end{bmatrix} = 0 \underbrace{\begin{bmatrix} 0 \\ 1 \end{bmatrix}}_{\vec{w}_1} + 1 \underbrace{\begin{bmatrix} 2 \\ 3 \end{bmatrix}}_{\vec{w}_2}$$

it is important to remember that we can do this more generally in a vector space context i.e. $\mathcal{P}_n(\mathbb{R})$, $\text{Mat}_{n \times n}(\mathbb{R})$ and many others.

Ex: let $\mathcal{P}_2(\mathbb{R}) = V$ (~~the~~ polynomials of $\deg \leq 2$ with real coeffs)

$$\mathcal{B} = \{x, 1+x^2, x+x^2\} \quad \mathcal{D} = \{1, 1+x, x^2\}$$

(here $\mathcal{D} = \{1, x, x^2\}$) this looks different but is in fact the same process

$$[\mathcal{D} | \mathcal{B}] = \left[\begin{array}{ccc|ccc} 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{array} \right] \xrightarrow{R_1 - R_2} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & 1 & -1 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{array} \right]$$

Id $\mathcal{P}_{\mathcal{D} \leftarrow \mathcal{B}}$

lets test this on $4 - 2x - x^2$. to do this we need $[4 - 2x - x^2]_{\mathcal{B}}$ lets do this systematically, that is we need

$$c_1 x + c_2(1+x^2) + c_3(x+x^2) = 4 - 2x - x^2$$

or

$$c_2 + (c_1 + c_3)x + (c_2 + c_3)x^2 = 4 - 2x - x^2 \quad \text{which translates to the system}$$

$$c_2 = 4 \quad \text{which can be solved as}$$

$$c_1 + c_3 = -2$$

$$c_2 + c_3 = -1$$

$$c_1 = 3 \quad c_2 = 4 \quad c_3 = -5$$

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$$\therefore [4 - 2x - x^2]_B = \begin{bmatrix} 3 \\ 4 \\ -5 \end{bmatrix} \text{ making (hopefully) } [4 - 2x - x^2]_D =$$

$$\begin{bmatrix} -1 & 1 & -1 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \\ -5 \end{bmatrix} = \begin{bmatrix} 6 \\ -2 \\ -1 \end{bmatrix}$$

in other words we know how to write $4 - 2x - x^2$ in terms of \mathcal{D}
let's check

$$6(1) + (-2)(1+x) + (-1)(x^2) = 6 - 2 - 2x - x^2 = 4 - 2x - x^2 \text{ as desired.}$$

final notes

- when constructing $[D|B]$ it does not matter what basis you write the columns in as long as they are all the same basis
- all of the subscript notation is there for us not the math its to keep track of where things are and where they go to.

Exercise do the same as our previous 2 examples with

$$B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \right\}$$

test this on

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$D = \left\{ \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \right\}$$

you can use \mathcal{S} as the standard basis

$$\mathcal{S} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

Have a great
reading week 😊