

BACHELOR'S THESIS COMPUTING SCIENCE



RADBOUD UNIVERSITY NIJMEGEN

Thesis Title

Subtitle if you like

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Abstract

Brief outline of research questions, results. (The preferred size of an abstract is one paragraph or one page of text.)

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Chapter 1

Introduction

The introduction of your bachelor thesis introduces the research area, the research hypothesis, and the scientific contributions of your work. A good narrative structure is the one suggested by Simon Peyton Jones [1]:

- describe the problem / research question
- motivate why this problem must be solved
- demonstrate that a (new) solution is needed
- explain the intuition behind your solution
- motivate why / how your solution solves the problem (this is technical)
- explain how it compares with related work

Close the introduction with a paragraph in which the content of the next chapters is briefly mentioned (one sentence per chapter).

Starting a new paragraph is done by inserting an empty line like this.

Chapter 2

Rules

2.1 Rules Intuitionistic Logic

$$\begin{array}{c}
 \frac{}{A \vdash A} \text{Id} \qquad \frac{\Gamma, \Delta \vdash A}{\Delta, \Gamma \vdash A} \text{Exchange} \\
 \\
 \frac{\Gamma, A, A \vdash B}{\Gamma, A \vdash B} \text{Contraction} \qquad \frac{\Gamma \vdash B}{\Gamma, A \vdash B} \text{Weakening} \\
 \\
 \frac{\Gamma, A \vdash B}{\Gamma \vdash A \rightarrow B} \rightarrow\text{-I} \qquad \frac{\Gamma \vdash A \rightarrow B \quad \Delta \vdash A}{\Gamma, \Delta \vdash B} \rightarrow\text{-E} \\
 \\
 \frac{\Gamma \vdash A \quad \Delta \vdash B}{\Gamma, \Delta \vdash A \times B} \times\text{-I} \qquad \frac{\Gamma \vdash A \times B \quad \Delta, A, B \vdash C}{\Gamma, \Delta \vdash C} \times\text{-E} \\
 \\
 \frac{\Gamma \vdash A}{\Gamma \vdash A + B} +\text{-I}_1 \qquad \frac{\Gamma \vdash B}{\Gamma \vdash A + B} +\text{-I}_2 \\
 \\
 \frac{\Gamma, A \vdash C \quad \Delta, A \vdash C \quad \Delta, B \vdash C}{\Gamma, \Delta \vdash C} +\text{-E}
 \end{array}$$

Figure 2.1: Multiple Proof Rules in Columns

2.2 Rules Intuitionistic Logic with Types

$$\begin{array}{c}
\frac{}{x : A \vdash x : A} \text{Id} \qquad \frac{\Gamma, \Delta \vdash t : A}{\Delta, \Gamma \vdash t : A} \text{Exchange} \\
\\
\frac{\Gamma, y : A, z : A \vdash u : B}{\Gamma, x : A \vdash u[y \mapsto x][z \mapsto x] : B} \text{Contraction} \\
\\
\frac{\Gamma \vdash u : B}{\Gamma, x : A \vdash u : B} \text{Weakening} \\
\\
\frac{\Gamma, x : A \vdash t : B}{\Gamma \vdash \lambda x. t : A \rightarrow B} \rightarrow\text{-I} \\
\\
\frac{\Gamma \vdash s : A \rightarrow B \quad \Delta \vdash t : A}{\Gamma, \Delta \vdash s(t) : B} \rightarrow\text{-E} \\
\\
\frac{\Gamma \vdash t : A \quad \Delta \vdash u : B}{\Gamma, \Delta \vdash (t, u) : A \times B} \times\text{-I} \\
\\
\frac{\Gamma \vdash s : A \times B \quad \Delta, x : A, y : B \vdash v : C}{\Gamma, \Delta \vdash \text{case } s \text{ of } (x, y) \rightarrow v : C} \times\text{-E} \\
\\
\frac{\Gamma \vdash t : A}{\Gamma \vdash \text{inl}(t) : A + B} +\text{-I}_1 \qquad \frac{\Gamma \vdash u : B}{\Gamma \vdash \text{inr}(u) : A + B} +\text{-I}_2 \\
\\
\frac{\Gamma \vdash s : A + B \quad \Delta, x : A \vdash v : C \quad \Delta, y : B \vdash w : C}{\Gamma, \Delta \vdash \text{case } s \text{ of } \text{inl}(x) \rightarrow v; \text{inr}(y) \rightarrow w : C} +\text{-E}
\end{array}$$

Figure 2.2: Multiple Proof Rules in Columns

2.3 Rules Linear Logic

$$\begin{array}{c}
\frac{}{\langle A \rangle \vdash A} \langle \text{Id} \rangle \qquad \frac{}{[A] \vdash A} [\text{Id}] \qquad \frac{\Gamma, \Delta \vdash A}{\Delta, \Gamma \vdash A} \text{Exchange} \\
\\
\frac{\Gamma, [A], [A] \vdash B}{\Gamma, [A] \vdash B} \text{Contraction} \qquad \frac{\Gamma \vdash B}{\Gamma, [A] \vdash B} \text{Weakening} \\
\\
\frac{[\Gamma] \vdash A}{[\Gamma] \vdash !A} !\text{-I} \qquad \frac{\Gamma \vdash !A \quad \Delta, [A] \vdash B}{\Gamma, \Delta \vdash B} !\text{-E} \\
\\
\frac{\Gamma, \langle A \rangle \vdash B}{\Gamma \vdash A \multimap B} \multimap\text{-I} \qquad \frac{\Gamma \vdash A \multimap B \quad \Delta \vdash A}{\Gamma, \Delta \vdash B} \multimap\text{-E} \\
\\
\frac{\Gamma \vdash A \quad \Delta \vdash B}{\Gamma, \Delta \vdash A \otimes B} \otimes\text{-I} \\
\\
\frac{\Gamma \vdash A \otimes B \quad \Delta, \langle A \rangle, \langle B \rangle \vdash C}{\Gamma, \Delta \vdash C} \otimes\text{-E} \\
\\
\frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \& B} \&\text{-I} \\
\frac{\Gamma \vdash A \& B}{\Gamma \vdash A} \&\text{-E}_1 \qquad \frac{\Gamma \vdash A \& B}{\Gamma \vdash B} \&\text{-E}_2 \\
\\
\frac{\Gamma \vdash A}{\Gamma \vdash A \oplus B} \oplus\text{-I}_1 \qquad \frac{\Gamma \vdash B}{\Gamma \vdash A \oplus B} \oplus\text{-I}_2 \\
\\
\frac{\Gamma \vdash A \oplus B \quad \Delta, \langle A \rangle \vdash C \quad \Delta, \langle B \rangle \vdash C}{\Gamma, \Delta \vdash C} \oplus\text{-E}
\end{array}$$

Figure 2.3: Multiple Proof Rules in Columns

2.4 Rules Linear Logic with Types

$$\begin{array}{c}
\frac{}{\langle x : A \rangle \vdash x : A} \langle \text{Id} \rangle \qquad \frac{}{[x : A] \vdash x : A} [\text{Id}] \\[10pt]
\frac{\Gamma, \Delta \vdash t : A}{\Delta, \Gamma \vdash t : A} \text{Exchange} \qquad \frac{\Gamma \vdash u : B}{\Gamma, [x : A] \vdash u : B} \text{Weakening} \\[10pt]
\frac{\Gamma, [y : A], [z : A] \vdash u : B}{\Gamma, [x : A] \vdash u[y \mapsto x][z \mapsto x] : B} \text{Contraction} \\[10pt]
\frac{[\Gamma] \vdash t : A}{[\Gamma] \vdash !t : !A} !\text{-I} \\[10pt]
\frac{\Gamma \vdash s : !A \quad \Delta, [x : A] \vdash u : B}{\Gamma, \Delta \vdash \text{case } s \text{ of } !x \rightarrow u : B} !\text{-E} \\[10pt]
\frac{\Gamma, \langle x : A \rangle \vdash u : B}{\Gamma \vdash \lambda \langle x \rangle. u : A \multimap B} \multimap\text{-I} \\[10pt]
\frac{\Gamma \vdash s : A \multimap B \quad \Delta \vdash t : A}{\Gamma, \Delta \vdash s \langle t \rangle : B} \multimap\text{-E} \\[10pt]
\frac{\Gamma \vdash t : A \quad \Delta \vdash u : B}{\Gamma, \Delta \vdash \langle t, u \rangle : A \otimes B} \otimes\text{-I} \\[10pt]
\frac{\Gamma \vdash s : A \otimes B \quad \Delta, \langle x : A \rangle, \langle y : B \rangle \vdash v : C}{\Gamma, \Delta \vdash \text{case } s \text{ of } \langle x, y \rangle \rightarrow v : C} \otimes\text{-E} \\[10pt]
\frac{\Gamma \vdash t : A \quad \Gamma \vdash u : B}{\Gamma \vdash \langle \langle t, u \rangle \rangle : A \& B} \&\text{-I} \\[10pt]
\frac{\Gamma \vdash s : A \& B}{\Gamma \vdash \text{fst} \langle s \rangle : A} \&\text{-E}_1 \qquad \frac{\Gamma \vdash s : A \& B}{\Gamma \vdash \text{snd} \langle s \rangle : B} \&\text{-E}_2 \\[10pt]
\frac{\Gamma \vdash t : A}{\Gamma \vdash \text{inl} \langle t \rangle : A \oplus B} \oplus\text{-I}_1 \qquad \frac{\Gamma \vdash u : B}{\Gamma \vdash \text{inr} \langle u \rangle : A \oplus B} \oplus\text{-I}_2 \\[10pt]
\frac{\Gamma \vdash s : A \oplus B \quad \Delta, \langle x : A \rangle \vdash v : C \quad \Delta, \langle y : B \rangle \vdash w : C}{\Gamma, \Delta \vdash \text{case } s \text{ of } \text{inl} \langle x \rangle \xrightarrow{7} v; \text{inr} \langle y \rangle \rightarrow w : C} \oplus\text{-E}
\end{array}$$

Figure 2.4: Multiple Proof Rules in Columns

Chapter 3

Lambda Calculus

This section provides a detailed and formal description of the λ -calculus. We define a formal grammar of the λ -calculus and give examples of some terms in the λ -calculus. Then we explain β -reduction, after which we define call-by-name evaluation and call-by-value evaluation.

3.1 Introduction to the λ -calculus

The grammar of the lambda calculus is as follows:

$$M, N, P, Q ::= x \mid \lambda x.M \mid MN$$

Terms are denoted by M, N, P or Q and can either be of the form x , $\lambda x.M$ or MN :

- x is a variable, which is a symbol that represents an input or a value.
- $\lambda x.M$ is an abstraction. An abstraction is an anonymous function, where x is the parameter and M is the body of the function.
- MN is a function application, where M and N are terms.

The λ -term $\lambda x.x$ is an abstraction. This specific abstraction is called the identity function and has one input parameter, namely x , and returns the input x . The body of the function is also x in this case and the function is often abbreviated as **I**. The λ -term $(\lambda x.x)y$ is a function application. So the identity function is applied to the variable y and the λ -term reduces to the variable y .

3.2 β -Reduction

Before we discuss β -reduction, we first define bound and free variables and substitution.

3.2.1 Variables

Let us first define free variables. Let P be any term in the λ -calculus and $FV(P)$ be the set that contains all free variables in P . We define FV inductively on P . Since P can only be a variable, an abstraction or a function application, P can only be of the form x , $\lambda x.M$ and MN . Therefore, we define FV as follows:

$$\begin{aligned} FV(x) &= \{x\} \\ FV(\lambda x.M) &= FV(M) \setminus \{x\} \\ FV(MN) &= FV(M) \cup FV(N) \end{aligned}$$

We see that if a variable is free if it is by itself. All free variables in an abstraction are those that are not the parameter of the abstraction. For example, the λ -term $\lambda x.yx$ has one free variable, y . We can use the following reasoning:

$$\begin{aligned} FV(\lambda x.yx) &= FV(yx) \setminus \{x\} \\ &= (FV(x) \cup FV(y)) \setminus \{x\} \\ &= (\{x\} \cup \{y\}) \setminus \{x\} \\ &= \{x, y\} \setminus \{x\} \\ &= \{y\} \end{aligned}$$

Let us now define bound variables. Again, let P be any term in the λ -calculus and $BV(P)$ be the set of all bound variables in P . We define BV inductively on P as follows:

$$\begin{aligned} BV(x) &= \emptyset \\ BV(\lambda x.M) &= BV(M) \cup \{x\} \\ BV(MN) &= BV(M) \cup BV(N) \end{aligned}$$

Using our previous example of the λ -term $\lambda x.yx$, we can now reason that $BV(\lambda x.xy) = \{x\}$.

$$\begin{aligned} BV(\lambda x.xy) &= BV(xy) \cup \{x\} \\ &= (BV(x) \cup BV(y)) \cup \{x\} \\ &= (\emptyset \cup \emptyset) \cup \{x\} \\ &= \{x\} \end{aligned}$$

3.2.2 Substitution

Keeping the definitions of free and bound variables in mind, we now define substitution. In this research, substitution is often denoted as $P[x \mapsto Q]$ and defined inductively on P by:

$$\begin{aligned}
x[x \mapsto Q] &= Q \\
y[x \mapsto Q] &= y \text{ if } (x \neq y) \\
(MN)[x \mapsto Q] &= M[x \mapsto Q]N[x \mapsto Q] \\
(\lambda x.M)[x \mapsto Q] &= \lambda x.M \\
(\lambda y.M)[x \mapsto Q] &= \lambda z.M[y \mapsto z][x \mapsto Q] \text{ if } (x \neq y)
\end{aligned}$$

with z a variable defined by:

1. If $x \notin FV(N)$ or $y \notin FV(M)$ then $z = y$
2. Otherwise, z can be any variable such that $z \notin FV(N)$ or $z \notin FV(M)$

It might not be clear why need to use the variable z and one can expect that the following rule is good enough:

$$(\lambda y.M)[x \mapsto Q] = \lambda z.M[x \mapsto Q] \text{ if } (x \neq y)$$

However, the following example will illustrate why the more complicated rule is necessary. Consider the substitution $(\lambda y.xy)[x \mapsto y]$. The free variable of λ -term $\lambda y.xy$ is x and the bound variable is y . If we use the simple rule above, we get that $(\lambda y.xy)[x \mapsto y] = \lambda y.yy$, the meaning of the λ -term changes. However, the free variable we substituted, is not free anymore. The variable y is not a free variable in the term that we substituted y in. Therefore, we change the bound variable y in $\lambda y.xy$ to a new variable z . We can pick z as z is not a free variable in xy . Following the more complex rule, we get:

$$\begin{aligned}
(\lambda y.xy)[x \mapsto y] &= \lambda z.(xy)[y \mapsto z][x \mapsto y] \\
&= \lambda z.yz
\end{aligned}$$

3.2.3 β -Reduction

Now, we are ready to discuss β -reduction. In the λ -calculus, there is one way to simplify terms, which is β -reduction. We can define:

$$(\lambda x.M)N \rightarrow M[x \mapsto N] \quad (\beta)$$

So a λ -term of the form $(\lambda x.M)N$ can be reduced by substituting x by N in M . However, without additional rules, we cannot apply β -reduction to subterms. For example, the following reduction would not be possible: $\lambda x.(\lambda y.y)x \rightarrow \lambda x.x$. Therefore, we can define the following rules:

$$\frac{MN \rightarrow M'N}{M \rightarrow M'} (\mu) \quad \frac{MN \rightarrow MN'}{N \rightarrow N'} (\nu) \quad \frac{\lambda x.M \rightarrow \lambda x.M'}{M \rightarrow M'} (\xi)$$

Now, we define \rightarrow_β as β closed under μ , ν and ξ . So with \rightarrow_β we can use β -reduction on all subterms if the subterm is of the form $(\lambda x.M)N$. A subterm of the form $(\lambda x.M)N$ is called a β -redex. In one reduction, we may need to use multiple rules. The β -redex that is reduced is underlined. For instance, we need to use the μ and ξ rule in the last example of the following reductions:

$$\begin{array}{ll}
(\underline{\mathbf{II}})(\mathbf{II}) \rightarrow_\beta \mathbf{I}(\mathbf{II}) & \beta \text{ with } \mu \text{ rule} \\
(\mathbf{II})(\underline{\mathbf{II}}) \rightarrow_\beta (\mathbf{II})\mathbf{I} & \beta \text{ with } \nu \text{ rule} \\
\lambda x.\underline{\mathbf{Ix}} \rightarrow_\beta \lambda x.x & \beta \text{ with } \xi \text{ rule} \\
(\mathbf{I}(\lambda x.\underline{\mathbf{Ix}}))(\mathbf{II}) \rightarrow_\beta (\mathbf{I}(\lambda x.x))(\mathbf{II}) & \beta \text{ with } \mu \text{ and } \xi \text{ rule}
\end{array}$$

3.3 Call-by-name calculus

In this section, we discuss the call-by-name λ -calculus. The reduction rule that is used in this calculus is the same as the β reduction rule. However, we name the rule β_n to make it clear that it is the reduction rule of the call-by-name λ -calculus.

$$(\lambda x.M)N \rightarrow M[x \mapsto N] \quad \beta_n$$

We can define weak reduction, \rightarrow_w , as β_n closed under μ and ν . So \rightarrow_w has the only restriction that it cannot reduce under λ 's. The relation \rightarrow_n is defined as β_n closed under μ . So using name evaluation, we can not evaluate the argument of a function. Call-by-name evaluation is defined as \rightarrow_n^* . In the following example, we give the call-by-name evaluation of the λ -term $(\mathbf{I}(\lambda x.\mathbf{Ix}))(\mathbf{II})$. The β -redex that is reduced is underlined. Note that \rightarrow_n is deterministic, so there is only one way to apply \rightarrow_n on a λ -term.

$$\begin{array}{l}
(\mathbf{I}(\underline{\lambda x.\mathbf{Ix}}))(\mathbf{II}) \rightarrow_n \underline{(\lambda x.\mathbf{Ix})(\mathbf{II})} \\
\rightarrow_n \underline{\mathbf{I}(\mathbf{II})} \\
\rightarrow_n \underline{\mathbf{II}} \\
\rightarrow_n \mathbf{I}
\end{array}$$

3.4 Call-by-value calculus

Before we can define the call-by-value λ -calculus (abbreviated as λ_v), we first define what we mean by values. Values are all λ -terms that are either a variable or an abstractions. Values are usually denoted by V or W .

$$V ::= x \mid \lambda x.M$$

In the λ_v , we can only reduce if the argument is a value. Therefore, the reduction rule is as follows:

$$(\lambda x.M)V \rightarrow M[x \mapsto V] \quad \beta_v$$

In order to define the \rightarrow_v relation, we first define the rule $\nu_{<}$.

$$\frac{N \rightarrow N'}{VN \rightarrow VN'} \nu_{<}$$

The relation \rightarrow_v can be defined as β_v , closed under μ and $\nu_{<}$. The $\nu_{<}$ forces evaluation from left to right and β_v makes sure that the argument needs to be a value. In the following example, we give the call-by-value evaluation of the λ -term $(\mathbf{I}(\lambda x.\mathbf{I}x))(\mathbf{II})$. The β -redex that is reduced is underlined. Note that \rightarrow_v is deterministic, so there is only one way to apply \rightarrow_v on a λ -term.

$$\begin{aligned} (\mathbf{I}(\lambda x.\mathbf{I}x))(\mathbf{II}) &\rightarrow_v (\lambda x.\mathbf{I}x)(\mathbf{II}) \\ &\rightarrow_v \underline{(\lambda x.\mathbf{I}x)\mathbf{I}} \\ &\rightarrow_v \underline{\mathbf{II}} \\ &\rightarrow_v \mathbf{I} \end{aligned}$$

Chapter 4

Call-by-box Lambda Calculus

4.1 Specification of λ_b

The terms of λ_b are given by:

$$M, N, P, Q ::= \varepsilon(x) \mid \lambda x.M \mid MN \mid \text{box}(N)$$

Types are given by:

$$A, B ::= X \mid A \rightarrow B \mid \Box A$$

The typing rules of λ_b are give by:

$$\begin{array}{c} \frac{}{\Gamma, x : \Box A \vdash \varepsilon(x) : A} \text{Id}_{\Box} \\[10pt] \frac{\Gamma, x : A \vdash M : B}{\Gamma \vdash \lambda x.M : A \rightarrow B} \rightarrow\text{-I} \\[10pt] \frac{\Gamma \vdash M : A \rightarrow B \quad \Delta \vdash N : A}{\Gamma, \Delta \vdash MN : B} \rightarrow\text{-E} \\[10pt] \frac{\Gamma \vdash M : A}{\Gamma \vdash \text{box}(M) : \Box A} \Box\text{-I} \end{array}$$

Since variables always occur inside ε , we need to redefine free and bound variables and substitution. For λ_b , we have:

$$\begin{array}{llll} FV_b(\varepsilon(x)) & = \{\varepsilon(x)\} & BV(\varepsilon(x)) & = \emptyset \\ FV_b(\lambda x.M) & = FV(M) \setminus \{\varepsilon(x)\} & BV(\lambda x.M) & = BV(M) \cup \{\varepsilon(x)\} \\ FV_b(MN) & = FV(M) \cup FV(N) & BV(MN) & = BV(M) \cup BV(N) \end{array}$$

Thus, for substitution, we get:

$$\begin{aligned}
\varepsilon(x)[\varepsilon(x) \mapsto Q] &= Q \\
\varepsilon(y)[\varepsilon(x) \mapsto Q] &= \varepsilon(y) \text{ if } (x \neq y) \\
(MN)[\varepsilon(x) \mapsto Q] &= M[x \mapsto Q]N[x \mapsto Q] \\
(\lambda x.M)[\varepsilon(x) \mapsto Q] &= \lambda x.M \\
(\lambda y.M)[\varepsilon(x) \mapsto Q] &= \lambda z.M[\varepsilon(y) \mapsto \varepsilon(z)][\varepsilon(x) \mapsto Q] \text{ if } (x \neq y)
\end{aligned}$$

with z a variable defined by:

1. If $\varepsilon(x) \notin FV_b(N)$ or $\varepsilon(y) \notin FV_b(M)$ then $z = y$
2. Otherwise, z can be any variable such that $\varepsilon(z) \notin FV(N)$ or $\varepsilon(z) \notin FV(M)$

The reduction rule we can use for this λ -calculus is:

$$(\lambda x.M)\text{box}(N) \rightarrow M[\varepsilon(x) \mapsto N] \quad (\beta_b)$$

We define two relations: \rightarrow_{b_n} and \rightarrow_{b_v} . The relation \rightarrow_{b_n} will be used for cbn evaluation for embeddings of λ_n in λ_b . The relation \rightarrow_{b_v} will be used for cbn evaluation for embeddings of λ_v in λ_b .

4.2 Embedding of λ_n into λ_b

Let Λ_{CBN} be the set containing all λ -terms in the λ_n and let Λ_{CBB} be the set containing all λ -terms in the λ_b . The set \mathcal{T}_{CBN} contains all types of the λ_n and \mathcal{T}_{CBB} contains all types of the λ_b . Now we define functions from Λ_{CBN} to Λ_{CBB} for term translation and from \mathcal{T}_{CBN} to \mathcal{T}_{CBB} for type translation. These functions represent an embedding of the λ_n into the λ_b .

$$\begin{array}{ll}
T_t & : \mathcal{T}_{CBN} \rightarrow \mathcal{T}_{CBB} \\
T_t(X) & = X \\
T_t(A \rightarrow B) & = \Box T_t(A) \rightarrow T_t(B) \\
T & : \Lambda_{CBN} \rightarrow \Lambda_{CBB} \\
T(x) & = \varepsilon(x) \\
T(\lambda x.M) & = \lambda x.T(M) \\
T(MN) & = T(M)\text{box}(T(N))
\end{array}$$

To clarify, we give the embedding of $\mathbf{I}x$ into λ_b after which we apply \rightarrow_{b_n} . It is clear that the result obtained after \rightarrow_{b_n} is equal to the embedding of the result of applying \rightarrow_{b_n} on $\mathbf{I}x$ in the λ_n , which is $T(x) = \varepsilon(x)$.

$$\begin{aligned}
T(\mathbf{I}x) &= (T(\lambda x.x))\text{box}(T(x)) \\
&= (\lambda x.T(x))\text{box}(T(x)) \\
&= (\lambda x.\varepsilon(x))\text{box}(\varepsilon(x)) \\
&\rightarrow_{b_n} (\lambda x.\varepsilon(x))[\varepsilon(x) \mapsto \varepsilon(x)] \\
&= \varepsilon(x)
\end{aligned}$$

4.3 Embedding of λ_v into λ_b

For the embedding of the λ_v into the λ_b , we make use of the abbreviation "raise" defined by:

$$\text{raise}(M) := \lambda z.\varepsilon(z)M$$

Let Λ_{CBV} be the set containing all λ -terms in the λ_v and let Λ_{CBB} be the set containing all λ -terms in the λ_b . The set \mathcal{T}_{CBV} contains all types of the λ_v and \mathcal{T}_{CBB} contains all types of the λ_b . Now we define functions from Λ_{CBV} to Λ_{CBB} for term translation and from \mathcal{T}_{CBV} to \mathcal{T}_{CBB} for type translation.

$$\begin{array}{ll}
T_t & : \mathcal{T}_{CBV} \rightarrow \mathcal{T}_{CBB} \\
T_t(X) & = \Box X \\
T_t(A \rightarrow B) & = \Box(\Box T_t(A) \rightarrow \Box T_t(B)) \\
T & : \Lambda_{CBN} \rightarrow \Lambda_{CBB} \\
T(x) & = \text{box}(\varepsilon(x)) \\
T(\lambda x.M) & = \text{box}(\lambda x.T(M)) \\
T(MN) & = \text{raise}(T(N))T(M)
\end{array}$$

To clarify, we give the embedding of $\mathbf{I}x$ into λ_b after which we apply \rightarrow_{b_v} twice. It is clear that the result obtained after \rightarrow_{b_v} is equal to the embedding of the result of applying \rightarrow_v on $\mathbf{I}x$ in the λ_v , which is $T(x) = \text{box}(\varepsilon(x))$.

$$\begin{aligned}
T(\mathbf{I}x) &= \text{raise}(T(x))T(\mathbf{I}) \\
&= \text{raise}(T(x))T(\lambda x.x) \\
&= \text{raise}(\text{box}(\varepsilon(x)))\text{box}(\lambda x.T(x)) \\
&= \text{raise}(\text{box}(\varepsilon(x)))\text{box}(\lambda x.\text{box}(\varepsilon(x))) \\
&= (\lambda z.\varepsilon(z)\text{box}(\varepsilon(x)))\text{box}(\lambda x.\text{box}(\varepsilon(x))) \\
&\rightarrow_{b_v} (\lambda x.\text{box}(\varepsilon(x)))\text{box}(\varepsilon(x)) \\
&\rightarrow_{b_v} \text{box}(\varepsilon(x))
\end{aligned}$$

Chapter 5

Related Work

In this chapter you demonstrate that you are sufficiently aware of the state-of-art knowledge of the problem domain that you have investigated as well as demonstrating that you have found a *new* solution / approach / method.

Chapter 6

Conclusions

In this chapter you present all conclusions that can be drawn from the preceding chapters. It should not introduce new experiments, theories, investigations, etc.: these should have been written down earlier in the thesis. Therefore, conclusions can be brief and to the point.

Bibliography

- [1] Simon Peyton Jones. How to write a good research paper, 2004. Presentation at Technical University of Vienna, <http://research.microsoft.com/en-us/um/people/simonpj/papers/giving-a-talk/writing-a-paper-slides.pdf>.

Appendix A

Appendix

Appendices are *optional* chapters in which you cover additional material that is required to support your hypothesis, experiments, measurements, conclusions, etc. that would otherwise clutter the presentation of your research.