

Started on Thursday, 21 January 2021, 2:07 PM

State Finished

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Time taken 13 mins 28 secs

Grade 3.90 out of 10.00 (39%)

Question 1

Partially correct

Mark 0.90 out of 3.00

Consider two planes P1 and P2 that pass through the origin in 3D space (not homogeneous co-ordinates). They are represented by the corresponding normal vectors: $v_1: [1 \ 4 \ -3]$ and $v_2: [2 \ 1 \ 2]$. Which of the following are true regarding these planes? (NOTE: Select all correct answers)

- ☒ a. The two planes are perpendicular to each other ✓
- ☐ b. The planes P1 and P2 are neither perpendicular, nor parallel to each other
- ☐ c. The two planes are parallel to each other
- ☐ d. The point represented by v_1 lies on plane P2, and the point represented by v_2 lies on plane P1
- ☐ e. The intersection of the two planes is a line passing through origin

Your answer is partially correct.

You have correctly selected 1.

The correct answers are:

The two planes are perpendicular to each other,

The intersection of the two planes is a line passing through origin,

The point represented by v_1 lies on plane P2, and the point represented by v_2 lies on plane P1

Question 2

Incorrect

Mark 0.00 out of 3.00

The line joining the point at infinity: $[3 \ 4 \ 0]^T$ and the point: $[2 \ 3 \ 1]^T$ is given by the 3-vector: $[$ $]$ $1]^T$

NOTE: Give the answer as $[a/c \ b/c \ 1]^T$ if your answer is $[a \ b \ c]^T$.

Question **3**

Incorrect

Mark 0.00 out of 1.00

True or False: The only point in the projective space that does not have a corresponding image is the world origin.

Select one:

☒ True ✖

☐ False

It is the camera centre, not the world origin.

The correct answer is 'False'.

Question **4**

Correct

Mark 3.00 out of 3.00

You ran the camera calibration procedure with a set of known world points and ended up with the following P matrix.

Row1: $P1 = [0.1432 \ 0.0084 \ 0.0221 \ -0.0026]$

Row2: $P2 = [0.0088 \ 0.1071 \ -0.0976 \ 0.0534]$

Row3: $P3 = [0.0004 \ -0.0018 \ -0.0020 \ 0.9772]$

The image center, (u_0, v_0) is given by (✖ , ✖) $\times 10^{-6}$

Note: Answer should be given to two decimal places accuracy when multiplied by 10^6

[◀ Lecture 4 Quiz \(EVEN\) : Feature Detection](#)

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