

OpenCV (findContours) Detailed Guide



Raqueeb Shaikh

Follow

Jun 22, 2020 · 4 min read

OpenCV has many Image Processing features that are helpful in detecting edges, removing Noise, Threshold Image etc. One such feature that often confuses a lot of Beginners is (**findContours**). In this article I will try to go to all of the topics covered in the findContours and how it can be helpful to you.

To put in simple words findContours detects change in the image color and marks it as contour. As an example, the image of number written on paper the number would be detected as contour.



1.Original Image — 2.Gray Scale — 3. Binary Threshold Inverted — 4. findContours



1.Original Image — 2.Gray Scale — 3. Binary Threshold — 4. findContours

From the above two images we can see the findContours detects differently on the same image because of how we calculated the binary image. The above one is Binary Threshold Inverted (**cv2.THRESH_BINARY_INV**) which shows the numbers highlighted in White and the Below image is just Binary Threshold (**cv2.THRESH_BINARY**)

The part that you want to detect should be white like above numbers in 1st image.

```
import cv2

def show_image(image):
    cv2.imshow('image', image)
```

```

c = cv2.waitKey()
if c >= 0 : return -1
return 0

```

```

image = cv2.imread('./Photos/num.png')
img_gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
ret, im = cv2.threshold(img_gray, 100, 255, cv2.THRESH_BINARY_INV)
contours, hierarchy = cv2.findContours(im, cv2.RETR_EXTERNAL,
cv2.CHAIN_APPROX_SIMPLE)
img = cv2.drawContours(res_img, contours, -1, (0,255,75), 2)
show_image(res_img)

```

Parameters

image source, an 8-bit single-channel image. Non-zero pixels are treated as 1's. Zero pixels remain 0's, so the image is treated as binary.

contours detected contours.

hierarchy containing information about the image topology. It has as many elements as the number of contours.

mode contour retrieval mode(see [cv.RetrievalModes](#)).

method contour approximation method(see [cv.ContourApproximationModes](#)).

offset optional offset by which every contour point is shifted. This is useful if the contours are extracted from the image ROI and then they should be analyzed in the whole image context.

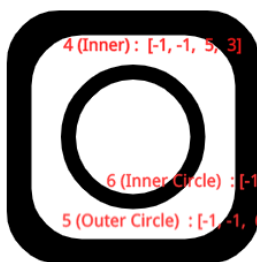
Parameter — Mode (RetrievalModes)

findContours function retrieve all the contours in the image that it can find . There can be various ways in which contours can be present in image. Some might me nested inother contours etc. To make it easy for to find the Contours which we are interested in and also to know the hierarchy in which the contours are nested **RetrievalModes** are very important . [source](#)

The output of RetrievalModes is array **Hierarchy** which shows how various contours are linked to each other, their relation with other contours, Parent Child relation

[Next, Previous, First_Child, Parent]

3 (Outer) : [-1, 1, 4, -1]



6 (Inner Circle) : [-1, -1, -1, 5]

5 (Outer Circle) : [-1, -1, 6, 4]

1 (Outer Square) : [3, 0, 2, -1]



2 (Inner Square) : [-1, -1, -1, 1]

0 (Outer Star) : [1, -1, -1, -1]



As you can see from the image OpenCV labels the hierarchy from bottom right.

0 : Star [1,-1,-1,-1]

... Next — Outer Square (1)

... Previous — No Contour(-1)

... Child — No Child (-1)

... Parent — No Parent (-1)

In the same manner all other contours are labeled. The above method is *RETR_TREE* where all contours as well as their occurrence Hierarchy is maintained. We will look about it in more details below

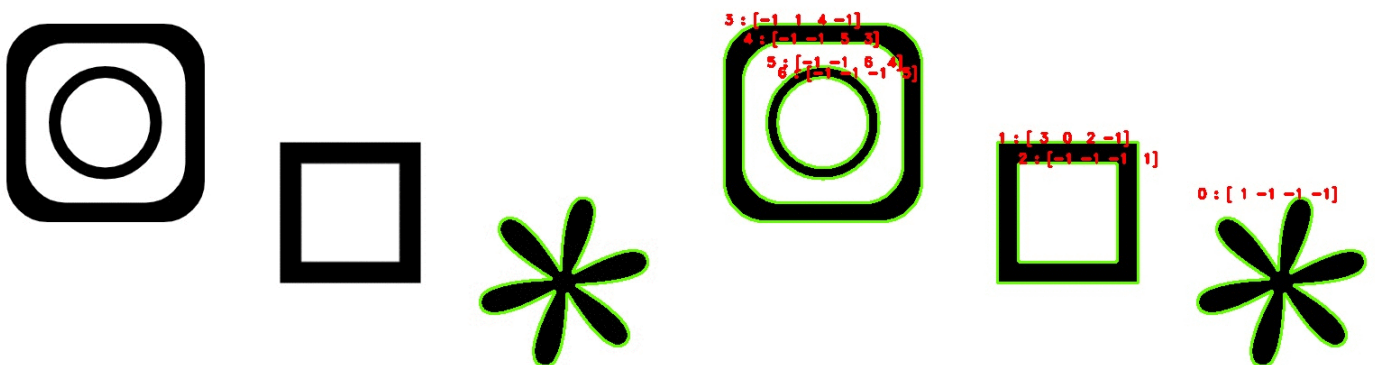
RETR_TREE — Python: cv.RETR_TREE

```
hierarchy
array([[ 1, -1, -1, -1],
       [ 3,  0,  2, -1],
       [-1, -1, -1,  1],
       [-1,  1,  4, -1],
       [-1, -1,  5,  3],
       [-1, -1,  6,  4],
       [-1, -1, -1,  5]])
```

Retrieves all of the contours and reconstructs a full hierarchy of nested contours. [source](#)

Below is have shown how contours are created and its Hierarchy

Parent and Child Relationship are created as well in TREE

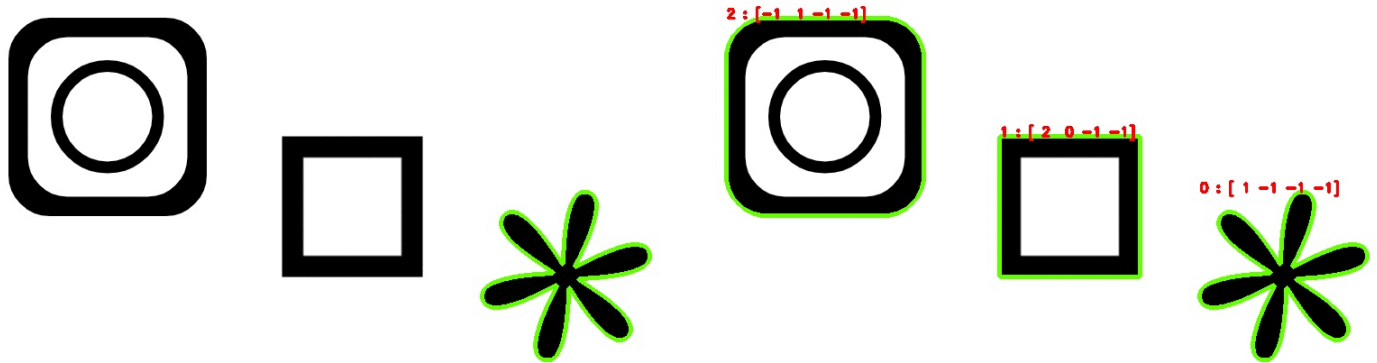


RETR_EXTERNAL — Python: cv.RETR_EXTERNAL

```
hierarchy
array([[ 1, -1, -1, -1],
       [ 2,  0, -1, -1],
       [-1,  1, -1, -1]])
```

Retrieves only the extreme outer contours. As you can see only three contours are created i.e the external one .

No Parent ,Child relation ship is given. All External contours are at same hierarchy (Level)



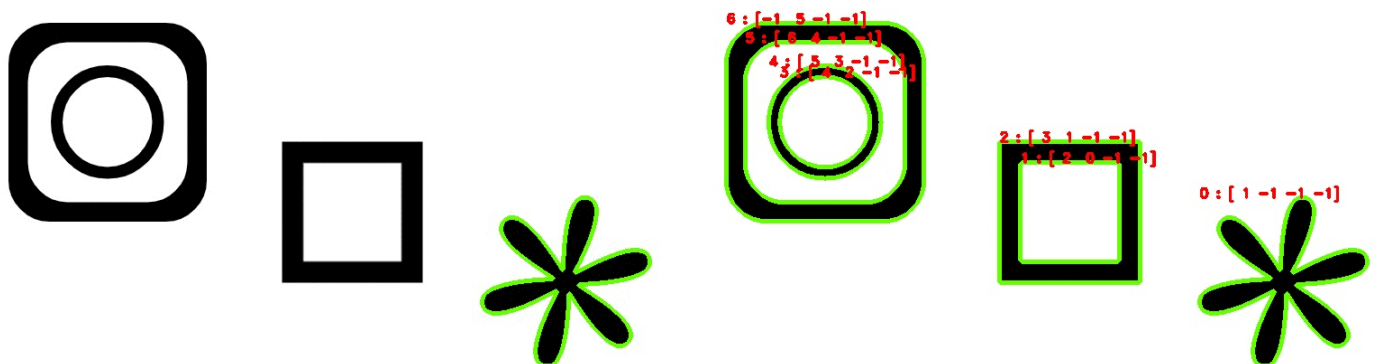
RETR_LIST — Python: cv.RETR_LIST

hierarchy

```
array([[ 1, -1, -1, -1],
       [ 2,  0, -1, -1],
       [ 3,  1, -1, -1],
       [ 4,  2, -1, -1],
       [ 5,  3, -1, -1],
       [ 6,  4, -1, -1],
       [-1,  5, -1, -1]], dtype=int32)
```

It is similar to Tree but it does not establish any parent child relationship .
Retrieves all of the contours without establishing any hierarchical relationships.

Because no relationship is established all Child,Parent are (-1)



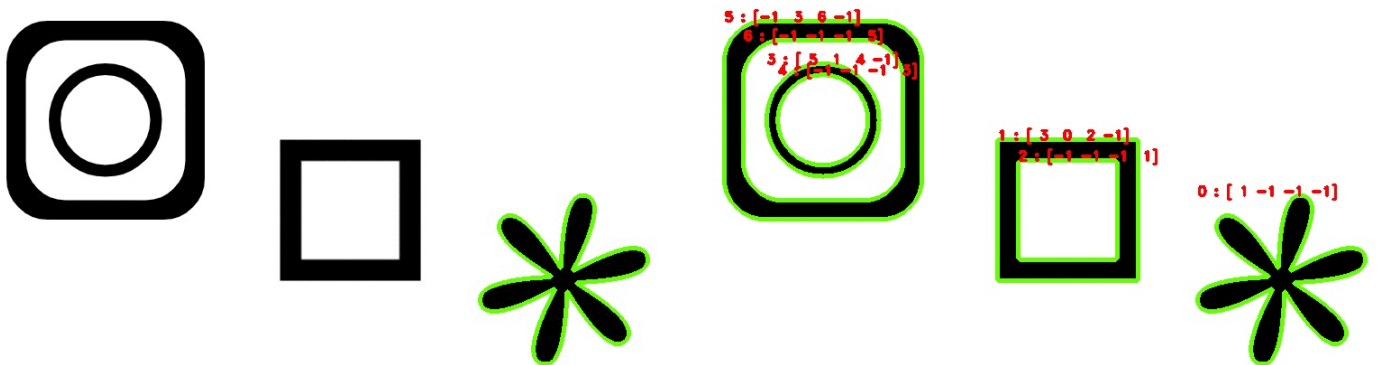
RETR_CCOMP — Python: cv.RETR_CCOMP

```

: hierarchy
: array([[ 1, -1, -1, -1],
        [ 3,  0,  2, -1],
        [-1, -1, -1,  1],
        [ 5,  1,  4, -1],
        [-1, -1, -1,  3],
        [-1,  3,  6, -1],
        [-1, -1, -1,  5]]], dtype=int32)

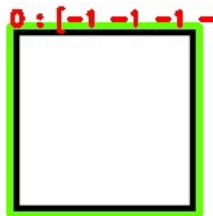
```

Retrieves all of the contours and organizes them into a two-level hierarchy. At the top level, there are external boundaries of the components. At the second level, there are boundaries of the holes. If there is another contour inside a hole of a connected component, it is still put at the top level.



Parameter — Method (Contour approximation method)

It is the method in which you want to store the Contours. If set to **CHAIN_APPROX_NONE** stores absolutely all the contour points. If set to **CHAIN_APPROX_SIMPLE** compresses horizontal, vertical, and diagonal segments and leaves only their end points. [source](#)



with **CHAIN_APPROX_NONE** length of contours stored is 524 i.e all points are stored in array

```

[82]: contours, hierarchy = cv2.findContours(im, cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_NONE)
[83]: len(contours[0])
[83]: 524
[84]: contours

```

```
[84]: [array([[16, 16],
           [[16, 17]],
           [[16, 18]],
           ...,
           [[19, 16]],
           [[18, 16]],
           [[17, 16]]], dtype=int32)]
```

With CHAIN_APPROX_SIMPLE length of contours stored is 4 i.e only corner four points are stored in array

```
[85]: contours, hierarchy = cv2.findContours(im, cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)
[86]: len(contours[0])
[86]: 4
[87]: contours
[87]: [array([[ 16,  16]],
           [[ 16, 147]],
           [[147, 147]],
           [[147,  16]]], dtype=int32)]
```

Reference:

https://docs.opencv.org/master/d9/d8b/tutorial_py_contours_hierarchy.html

Learn more.

Medium is an open platform where 170 million readers come to find insightful and dynamic thinking. Here, expert and undiscovered voices alike dive into the heart of any topic and bring new ideas to the surface. Learn more

Make Medium yours.

Follow the writers, publications, and topics that matter to you, and you'll see them on your homepage and in your inbox. Explore

Write a story on Medium.

If you have a story to tell, knowledge to share, or a perspective to offer — welcome home. It's easy and free to post your thinking on any topic. Start a blog