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Q.1 Among Eigen Value decomposition (EVD) & Singular Value decomposition (SVD), 'SVD' is more generalizable due to the following reasons:

- due to the following reasons:
- a) ~~It exists~~ Unlike EVD, SVD exist for all sorts of matrixes (Rectangular). Again EVD has some limitations i.e. though it's applicable to square matrices it doesn't guarantee the decomposition for some reasons:
    - i) Eigen-values computed may not exist in the underlying field.
    - ii) Non-equality of "Algebraic & Geometric" multiplicity.
  - b) Further with SVD eigenvectors obtained are "orthogonal" which <sup>in</sup> itself ~~gives~~ is a boon for subsequent operations, which may not be the case with EVD. Plus the eigen-values obtained are non-negative.

Now we'll discuss why SVD exists?

Now,  $X$  is an  $m \times n$  matrix (i.e.  $X: \mathbb{R}^n \rightarrow \mathbb{R}^m$ ) with rank  $r$  (where  $r \leq \min(m, n)$ ). Now, we claim that  $X^T X$  is symmetric & positive-semidefinite (which we'll show later why?).

show later why?)

★ Due to its symmetry (of  $X^T X$ ), it is diagonalizable with an orthonormal basis of eigen-vectors. And these eigenvalues (i.e., the square-root of them), the eigen-vectors of  $X^T X$  & the eigen-vectors of  $X X^T$ , all constitute to give the expression

$$X = \sum V^T \rightarrow \begin{matrix} \text{Eigen-vectors of } (X^T X) \\ \text{Eigen-vectors of } (X X^T) \end{matrix}$$

★ Now we'll show how we'd arrived to the above formula?

a) Symmetry:  $(X^T X)^T = X^T (X^T)^T = X^T X$

4) PSD: Claim: (Need to prove)  $X^T X$  is PSD  $\Leftrightarrow v^T (X^T X) v \geq 0$   
 $\forall v \neq 0$  ✓

$$u^T(X^T X)v = (Xv)^T Xv = (Xv)^2 \geq 0 \quad - \square$$

c) Why How eigen-values  $\geq 0$ ?

Now, since  $X^T X$  is diagonalizable, let it EVD form be  $V \Lambda V^T$  i.e.  $\boxed{X^T X = V \Lambda V^T} = \sum_{k=1}^n v_k \lambda_k v_k^T$

$$\begin{aligned} \Rightarrow u^T(X^T X)u &= u^T \left( \sum_{k=1}^n v_k \lambda_k v_k^T \right) u \\ &= \sum_{k=1}^n \lambda_k (u^T v_k v_k^T u) \\ &= \sum_{k=1}^n \lambda_k (v_k^T u)^2 \geq 0 \end{aligned}$$

Sufficient condition :

( $\because X^T X$  is PSD  $\Rightarrow$

$\rightarrow$  If All  $\lambda_k \geq 0$ , the above expression is true.

$$u^T(X^T X)u \geq 0)$$

But we want stricter conditions:

Consider  $v_i$  as eigen-value of  $X^T X$ , then

$$v_i^T (X^T X) v_i = v_i^T (\lambda_i v_i) = \lambda_i (v_i^T v_i) \geq 0$$

$$\Rightarrow \lambda_i \geq 0 \quad (\because v_i^T v_i = 1 \quad (\because X^T X \text{ is PSD}))$$



(since orthonormal))

d) let  $\lambda_1 = \sigma_1^2 \geq \lambda_2 = \sigma_2^2 \geq \dots \geq \lambda_r = \sigma_r^2 \geq 0$  (since  $\lambda_i$ 's are  $\geq 0$ )

$\rightarrow$  Now, why only  $r$  eigen-values, because

$\text{rank}(X) = \text{rank}(X^T X) = r \Rightarrow \exists$  only  $r$  non-zero eigen-values while others are 0.

$\rightarrow$  Since  $\dim(\text{Range-space}(X^T X)) = r$ , then  $\exists v_1, v_2, \dots, v_r$  orthonormal eigen-vectors corresponding to  $r$  non-zero eigen-values i.e.  $\lambda_1, \lambda_2, \dots, \lambda_r$  & construct  $v_{r+1}, \dots, v_n$  orthonormal basis for eigen-value = 0 (basically this spans the  $N(X^T X)$  & can be constructed using Gram-Schmidt orthogonalization process).

→ Define:  $u_i = \frac{1}{\sigma_i} X v_i$ , then ' $u_i$ ' is the unit eigenvector of  $XX^T$  with eigen-value  $\sigma_i^2$  (check).

[Now here an elementary form of SVD can be seen, i.e.]

$$X v_i = u_i \sigma_i$$

Construct  $V_{n \times r} = \begin{bmatrix} v_1 & v_2 & \dots & v_r \end{bmatrix}_{n \times r}$ ,  $\Sigma_r = \begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \sigma_r \end{bmatrix}_{r \times r}$

&  $U_r = m \times r$  matrix with  $u_i = \frac{1}{\sigma_i} X v_i$  (as  $i$ th column).

Then, we have  $U_r = \frac{1}{\sigma_i} X V_r \Sigma_r^{-1} \Rightarrow \boxed{U_r \Sigma_r = X V_r}$

$$\Rightarrow \boxed{U_r \Sigma_r V_r^T = X V_r V_r^T = X \underset{m \times n}{I_{n \times n}} = X_{m \times n}}$$

Again, we can invoke the <sup>orthonormal</sup> vectors from null space of  $X^T X$  & in  $V_r$  & of  $XX^T$  in  $U_r$  & pack the  $\Sigma_r$  with 0's to obtain

to obtain  $\boxed{X = U_{m \times m} \Sigma_{m \times n} V_{n \times n}^T}$  which is basically same as  $\hat{U}_{m \times n} \hat{\Sigma}_{n \times n} \hat{V}_{n \times n}^T$

Note:

→ Again SVD can be ~~decom~~ computed using QR decomposition method to make it fast.

→ for a symmetric matrix,  $SVD = EVD$ .

(Truncated SVD form)

B) The method for SVD is already shown above → now we'll use the motivation from above derivation to decompose the given matrix.

$$M = \begin{bmatrix} 4 & 8 \\ 11 & 7 \\ 14 & -2 \end{bmatrix}$$

a) let  $A := M^T M = \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix} \begin{bmatrix} 4 & 8 \\ 11 & 7 \\ 14 & -2 \end{bmatrix} = \begin{bmatrix} 333 & 81 \\ 81 & 17 \end{bmatrix}$

b) for a symmetric matrix  $EVD = SVD$ .

Let's compute the eigen-value of  $A$  using "characteristic" equation:

$$|A - \lambda I| = \left| \begin{pmatrix} \lambda - 333 & 81 \\ 0 & \lambda - 117 \end{pmatrix} \right| = 0$$

$$\Rightarrow \lambda = 360 \xrightarrow{\lambda_1} \quad 90 \xrightarrow{\lambda_2}$$

$$\Rightarrow Av_1 = \lambda_1 v_1 = \lambda_1 \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix}$$

$$\Rightarrow 9(37v_{11} + 9v_{12}) = 360v_{11} \quad \& \quad 9(9v_{11} + 13v_{12}) = 360v_{12}$$

$$\Rightarrow v_{11} = 3v_{12} \Rightarrow v_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \frac{1}{\sqrt{10}} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = v_1 \text{ (normalized)}$$

$$\Rightarrow Av_2 = \lambda_2 v_2 = \lambda_2 \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix}$$

$$\Rightarrow 9(37v_{21} + 9v_{22}) = 90v_{21} \quad \& \quad 9(9v_{21} + 13v_{22}) = 90v_{22}$$

$$\Rightarrow v_{21} = -\frac{1}{3}v_{22} \Rightarrow v_2 = \begin{bmatrix} 1 \\ -3 \end{bmatrix} = \frac{1}{\sqrt{10}} \begin{bmatrix} 1 \\ -3 \end{bmatrix} = v_2$$

$\Rightarrow$  Verify that  $v_1^T v_2 = 0$  (orthogonal) (normalized).

$$\Rightarrow \text{define: } u_1 = \frac{1}{\sigma_1} M v_1 = \frac{1}{6\sqrt{10}} \cdot \frac{1}{\sqrt{10}} \begin{bmatrix} 20 \\ 40 \\ 40 \end{bmatrix}$$

$$= \frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$$

$$u_2 = \frac{1}{\sigma_2} M v_2 = \frac{1}{3\sqrt{10}} \cdot \frac{1}{\sqrt{10}} \begin{bmatrix} 20 \\ 10 \\ -20 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$$

~~(check)~~ Again  $u_1^T u_2 = 0 \rightarrow$  orthogonal

$$\rightarrow \text{Now let's check: if } \underbrace{\begin{bmatrix} u_1 & u_2 \\ 1 & 1 \end{bmatrix}}_U \underbrace{\begin{bmatrix} \sqrt{360} & 0 \\ 0 & \sqrt{90} \end{bmatrix}}_\Sigma \underbrace{\begin{bmatrix} \frac{1}{\sqrt{10}} & \frac{1}{\sqrt{10}} \\ \frac{1}{\sqrt{10}} & \frac{1}{\sqrt{10}} \end{bmatrix}^T}_V = M$$

$\rightarrow$



$$\frac{\sqrt{90}}{3\sqrt{10}} \underbrace{\begin{bmatrix} 1 & 2 \\ 2 & 1 \\ 2 & -2 \end{bmatrix}}_U \underbrace{\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}}_\Sigma \underbrace{\begin{bmatrix} 3 & 1 \\ -1 & 3 \end{bmatrix}}_{V^T}$$

$$= \frac{1}{3} \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 6 & 2 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 8 \\ 11 & 7 \\ 14 & -2 \end{bmatrix} = M$$

Hence  $M = \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ -1 & 3 \end{bmatrix} = \text{Truncated SVD form} = \text{Same as full SVD.}$

Q2) A) Since  $X'$  is in 2D  $\Rightarrow X'$  data has 2 features.

$$\Delta [X^T X]_{2 \times 2} \quad \text{where } X \in \mathbb{R}^{m \times 2}$$

$$\dim(X) = m \times 2, \\ m = \text{no. of data points}$$

a) If all elements of  $D$  are equal can be interpreted in 2 ways:

$$\triangleright D = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \Rightarrow \text{Rank}(D) = 0 \Rightarrow \text{All vectors}$$

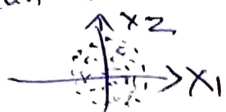
$$\text{in } \mathbb{R}^2 \text{ lies in Null-space of } X^T X \Rightarrow (X^T X)v = 0 \quad \forall v \in \mathbb{R}^2$$

$$\text{So } X^T X = \text{zero map} \quad \Delta \text{ as } R(X) = R(X^T X) = 0$$

$$\Rightarrow R(X) = 0 \Rightarrow 'X' \text{ consists of 'm' zero-vectors.}$$

$$2) D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_1 \end{bmatrix} \Rightarrow \text{Rank}(D) = 2 \Rightarrow \text{Both eigen-}$$

vectors (orthonormal of course) are important principal directions, so projecting onto one would result in huge loss of info. And here if we visualize the data, they can be seen to scattered in 'spherical' manner



So, no PCA can't be useful if all elements of  $D$  are equal.

b) True, if  $D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$ , with  $\lambda_1 > \lambda_2 \Rightarrow \lambda_1$  corresponding to  $\lambda_1$  (i.e.  $v_1$ ) is the direction along which maximum variance is captured. And hence the data point can be projected onto that line.

c) ~~False~~ True since all points in  $X$  are lying on a straight line  $\Rightarrow X = \begin{bmatrix} a & b \\ 2a & 2b \\ \vdots \\ na & nb \end{bmatrix} \Rightarrow \text{Rank}(\hat{X}) = 1 = \text{Rank}(\hat{X}^T \hat{X})$  (where  $\hat{X} = X - \bar{\mu} = \text{mean-shifted}$ )

$\Rightarrow$  since  $D^2 = \text{Eigen-value matrix of } X^T X$ , then

$$\Rightarrow \text{Nullity}(X^T X) = \dim(\text{Null-space}(X^T X)) = 2 - \text{Rank}(X^T X) \text{ (from rank nullity)}$$

$$\Rightarrow \exists \text{ only one (upto span)} \quad v (\neq 0) \in \mathbb{R}^2 \text{ s.t. } (X^T X)v = 0 \cdot v = 0$$

Hence  $0$  is an eigen-value

$$\Rightarrow D = \begin{bmatrix} \sqrt{\lambda} & 0 \\ 0 & 0 \end{bmatrix} \text{ where } \lambda \neq 0 \text{ (} \lambda > 0 \text{). (exists as Rank = 1)}$$

$\Rightarrow$  Hence  $D$  is not full rank

$\Rightarrow$  And  $v_1$  is the direction (or line) on which they  $X$  are lying while  $v_2$  is the  $\perp$  to  $v_1$ .

$\Rightarrow$  But if  $X = \begin{bmatrix} 1 & 2 \\ 2 & 2 \\ 3 & 2 \end{bmatrix}$  i.e.  $4 = 2$  line, then  $\text{Rank}(\hat{X}) = \text{Rank}(\hat{X}^T \hat{X}) = \text{Rank}(D) = 2$

d) False, Since Nullity = 1 & Rank = 1, one eigen-vector would be from Range-space of  $X^T X$  & another one from Null-space (since  $0$  is an eigen-value). And in this case  $\text{Range-space}(X^T X) = [\text{Null-space}(X^T X)]^\perp$

$$\hat{X} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 1 & 0 \end{bmatrix}$$

where  $\hat{X} = X - \bar{\mu}$  (mean shifted)

as due to spectral theorem, symmetry of  $X^T X$  would yield orthogonal eigen-vectors. (4)

Now  $V = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$ , where both are independent  $\Rightarrow V$  is full rank.

e) False,

Since it is being said they are lying on a circle (presumably ~~there~~ <sup>only</sup> two points in  $X$  which are collinear & supposedly lying on circle) then  $\exists$  two such vectors which are independent  $\Rightarrow \text{Rank}(X) = 2 \Rightarrow \text{Rank}(X^T X) = \text{Rank}(X) = 2 \Rightarrow \text{Null-space}(X^T X) = \{0\} = \text{zero vector}$   
 $\Rightarrow \nexists$  any zero-eigen value  $\Rightarrow D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$   
 where  $\lambda_1, \lambda_2 \neq 0$ .

$\Rightarrow D$  is full-rank.

B) False. Since PCA relies on SVD & SVD doesn't involve any class labels, rather we use only the data-information to find suitable max-varying direction to preserve information, ~~the we want~~ it won't be useful for data classification. Again, it may so happen that the direction of max-variability is the direction of max-separation bet<sup>n</sup> classes which is just a mere co-incidence.

3) A) ~~Prior~~ According to Bayes formula:  
 if  $H$  = Hypothesis &  $E$  = Evidence

$$P(H|E) = \frac{P(E|H) P(H)}{P(E)}$$

$\Rightarrow$  Here,  $P(H)$  = prior (mathematically) &  $P(H|E)$  = posterior (mathematically)

Now, intuitively what it means is that: (of the statement we're proposing)

★  $P(H)$  = probability that hypothesis<sub>1</sub> hold (e.g. in our case, according to the question, the hypothesis is made about happening of flu to a given person in a given year) without considering any evidence

★  $P(H|E)$  = "posterior"

= It's the Belief about the hypothesis we proposed after seeing the evidence. In our case it would be framed as follows:

"If we have 'evidence' that person is having 'headache & sore throat', then what should be the likelihood of ~~catching flu~~ that that person has flu, or in other words, what is the probability that our hypothesis is true or what is the confidence on our hypothesis."

B) Ans Given:  $P(ST \& H | Flu) = \frac{90}{100}$  (ST & H = sore throat & headache)

$$2) P(Flu) = \frac{5}{100}$$

$$3) P(ST \& H) = \frac{20}{100}$$

To be found:  $P(Flu | ST \& H)$

Using Bayes Rule:

$$P(Flu | ST \& H) = \frac{P(ST \& H | Flu) \cdot P(Flu)}{P(ST \& H)}$$

$$= \frac{\frac{90}{100} \cdot \frac{5}{100}}{\frac{20}{100}} = \frac{90 \cdot 5}{20 \cdot 100}$$

$$= \frac{45}{200} = \boxed{22.5\%} \text{ or } \boxed{0.225}$$