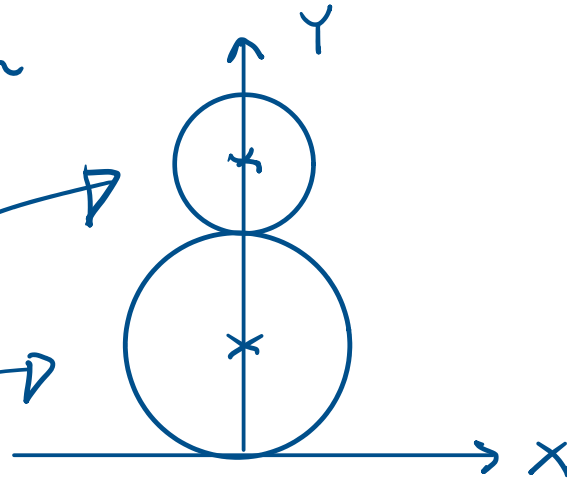


Desenhar um boneco de neve & Camera

6 de março de 2024

14:25

- Cone
- Esfera



{ translate 0, 0.75, 0
scale 0.75, 0.75, 0.75
esfera

~~x translate 0, 1, 0~~

~~x translate 0, 1.75, 0~~

{ scale $\frac{1}{0.75}$, $\frac{1}{0.75}$, $\frac{1}{0.75}$
translate 0.25, 0.25, 0.25
esfera

{ translate -0.05 0.1 0.2
scale 0.05 0.05 0.05
esfera
scale $\frac{1}{0.05}$ $\frac{1}{0.05}$ $\frac{1}{0.05}$

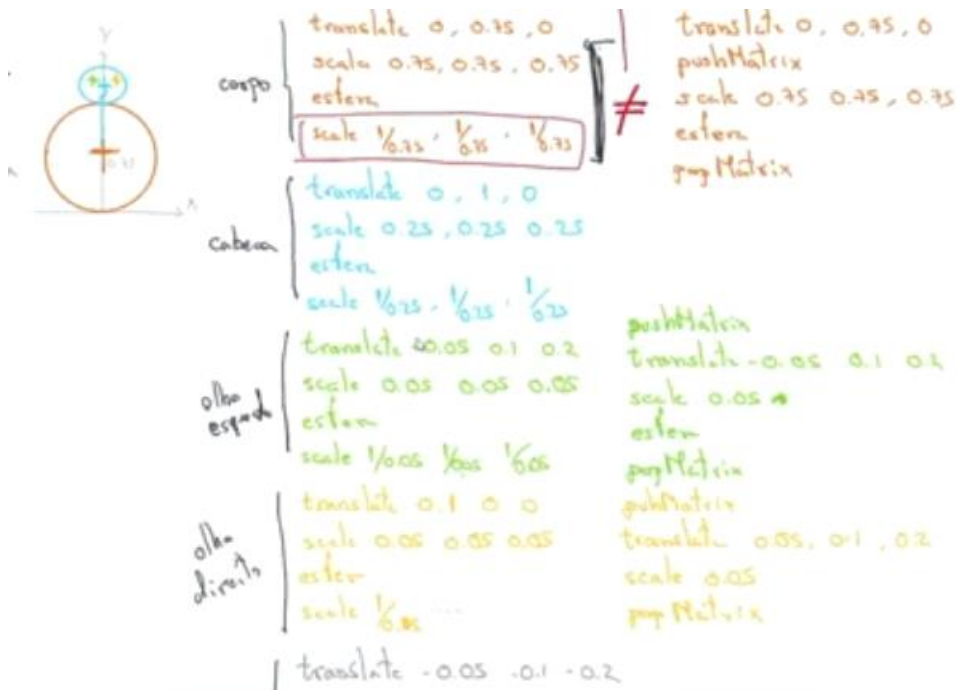
Informática

↳ Usar uma
stack de matrizes
→ Fazer push e pop

translate 0, 0.75, 0
push Matrix
scale 0.75, 0.75, 0.75
esfera
pop Matrix

OPERATIONS with
Floating point numbers
⇒ Small ERRORS

↓
"erros de vírgula
flutuante"



```
void drawSnowMan() {
    glColor3f(1.0f, 1.0f, 1.0f);

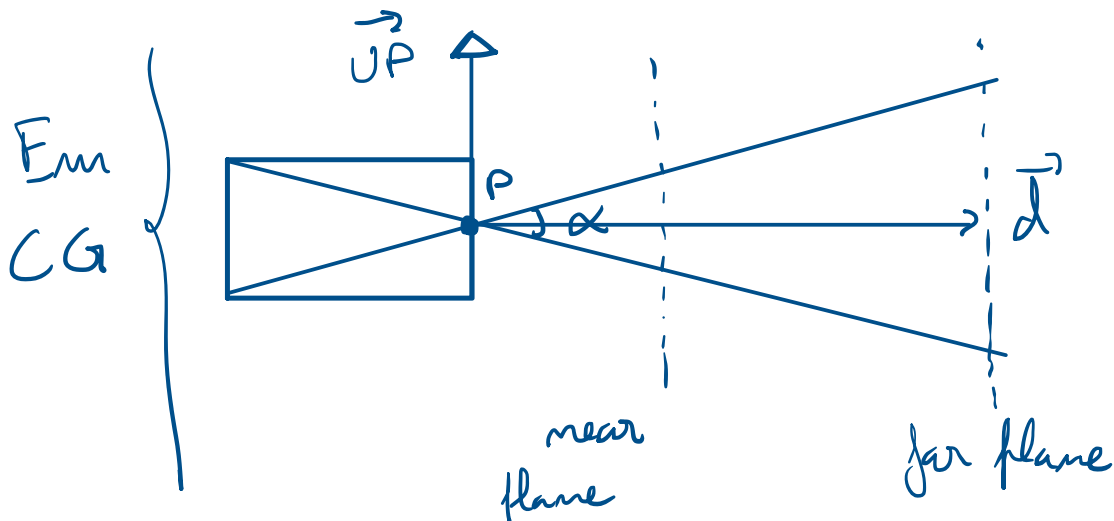
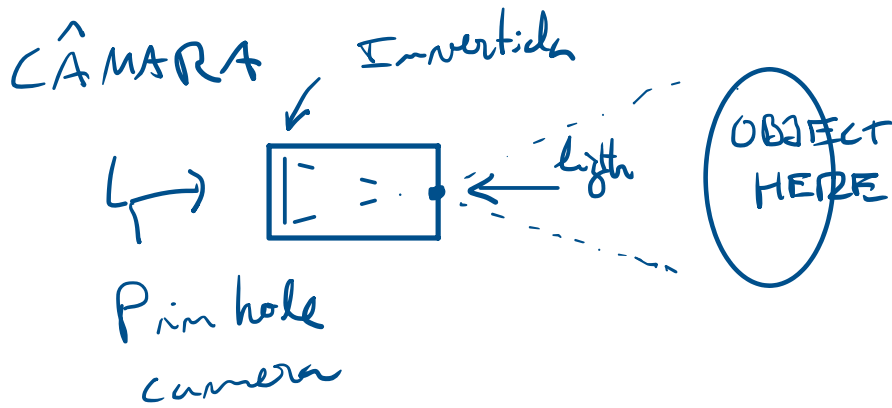
    // Draw Body
    glTranslatef(0.0f, 0.75f, 0.0f);
    glutSolidSphere(0.75f, 20, 20);

    // Draw Head
    glTranslatef(0.0f, 1.0f, 0.0f);
    glutSolidSphere(0.25f, 20, 20);

    // Draw Eyes
    glPushMatrix();
    glColor3f(0.0f, 0.0f, 0.0f);
    glTranslatef(0.05f, 1.05f, 0.18f);
    glutSolidSphere(0.05f, 10, 10);
    glTranslatef(-0.1f, 0.0f, 0.0f);
    glutSolidSphere(0.05f, 10, 10);
    glPopMatrix();

    // Draw Nose
    glColor3f(1.0, 0.5, 0.0);
    glRotatef(0.0f, 1.0f, 0.0f, 0.0f);
    glutSolidCone(0.05f, 0.5f, 10, 2);
}
```

⇒ Deixa o sistema de eixos como o encontraramos



- Parâmetros extrínsecos
 - P posição
 - \vec{UP} orientação vertical
 - \vec{d} direção do olhar
- Parâmetros intrínsecos
 - α : fov - field of view
 - near & far plane

↳ Definir um
"Volume de visualização"



"Colocar a câmara no espaço global"

$$M = TR$$

deslocar a câmara orientar a câmara

$$T = \begin{bmatrix} 1 & 0 & 0 & P_x \\ 0 & 1 & 0 & P_y \\ 0 & 0 & 1 & P_z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R = \begin{bmatrix} x & y & z & 0 \\ \boxed{} & \boxed{} & \boxed{} & 0 \\ \boxed{} & \boxed{} & \boxed{} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

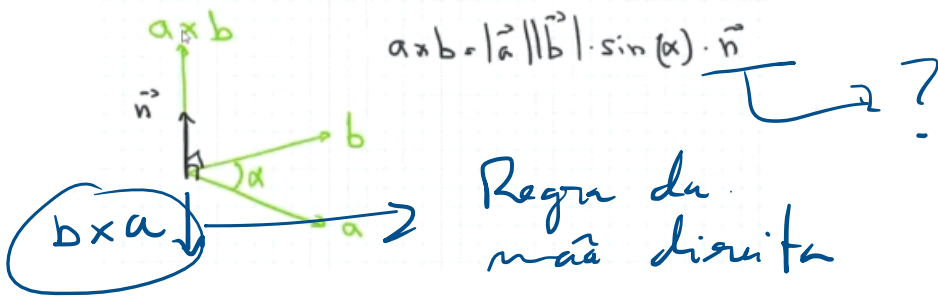
`gluLookAt (Px, Py, Pz, lx, ly, lz, ux, uy, uz)`

CROSS PRODUCT

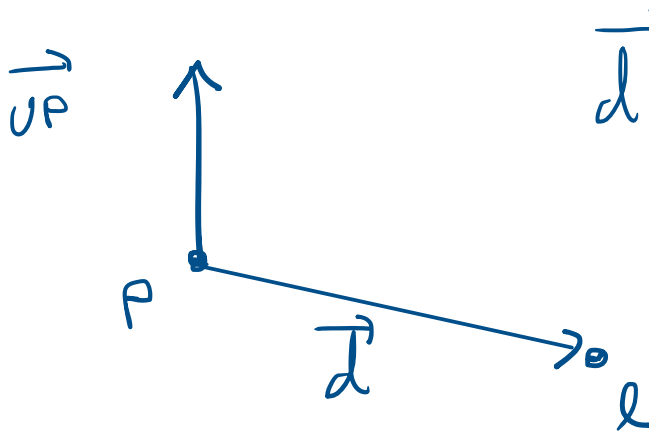
1. ... + ...

CRUZADO

→ produto externo
ou vetorial



$$\begin{aligned} \vec{v} &= \vec{a} \times \vec{b} \\ v_x &= a_y b_z - a_z b_y \\ v_y &= a_z b_x - a_x b_z \\ v_z &= a_x b_y - a_y b_x \end{aligned}$$



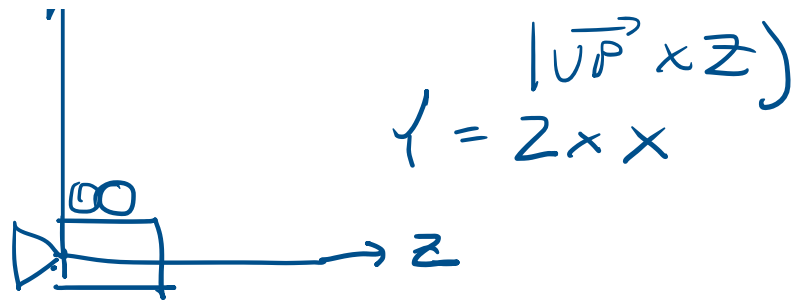
$$\vec{d} = l - p$$

$$\vec{z} = \frac{-\vec{d}}{|\vec{d}|}$$

→ normalizar
(evitar escalas)

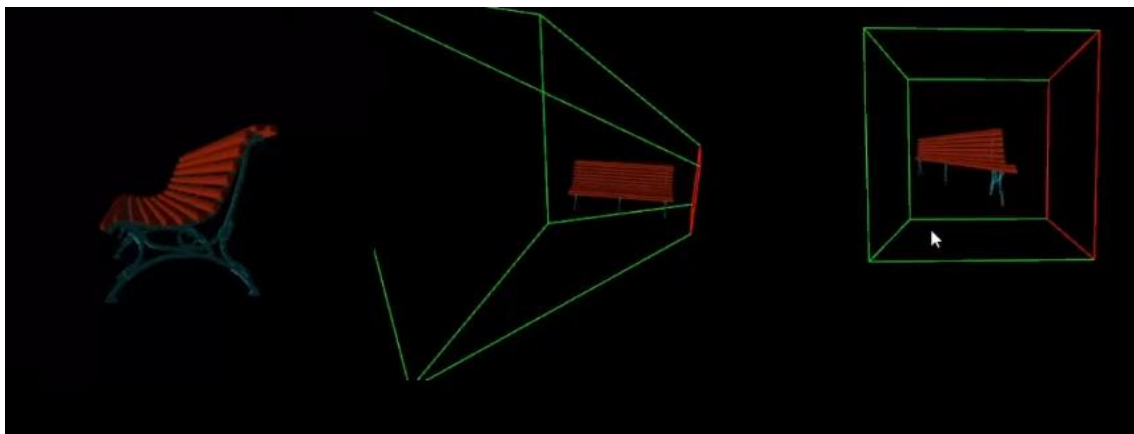
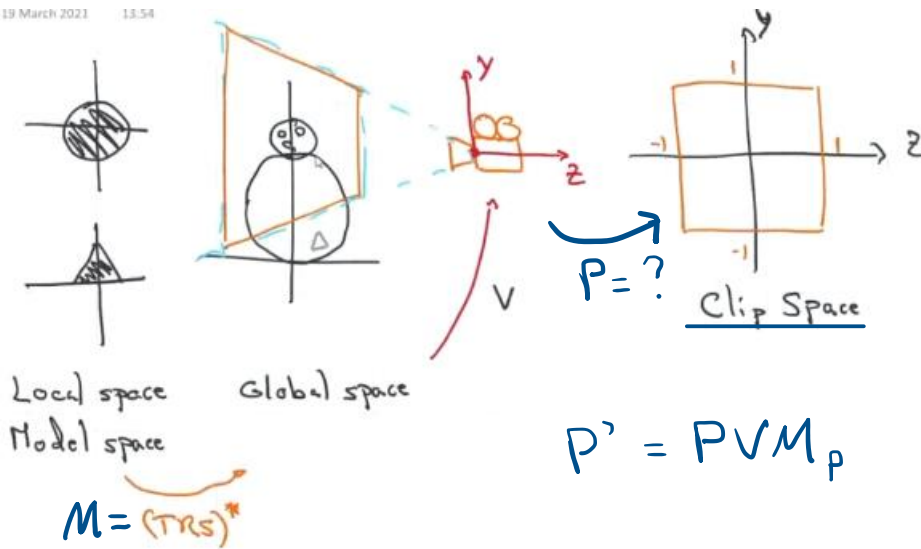
$$\vec{x} = \vec{y} \times \vec{z}$$

$$\vec{x} = \frac{\vec{uP} \times \vec{z}}{|\vec{uP} \times \vec{z}|}$$



$$V = M^{-1} = (TR^{-1}) = R^{-1}T^{-1}$$

v. 19 March 2021 13:54



Video: Projeção
min 13