Tópicos Especiais em Matemática Aplicada - 2025-1 UERJ

10 - Caso 2D - Elementos Isoparamétricos

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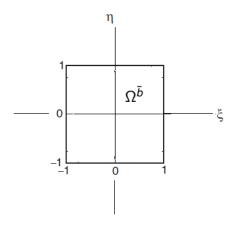
Github: https://github.com/rodrigolrmadureira/ElementosFinitos

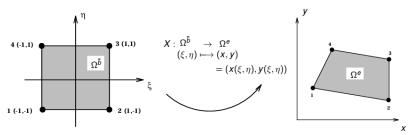
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- Elementos isoparamétricos
- Cálculo dos elementos da matriz local Ke
- Cálculo dos elementos do vetor local Fe
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Agora, vamos ver como são calculados K^e e F^e para cada elemento Ω^e .

Seja $\Omega^{\bar{b}}=[-1,1]\times[-1,1]$ o elemento finito biunitário como representado na figura abaixo.





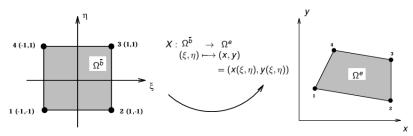
Seja

$$X: \Omega^{\bar{b}} \longrightarrow \Omega^{e}$$

$$(\xi, \eta) \longmapsto (x, y) = (x(\xi, \eta), y(\xi, \eta)),$$

onde

$$x(\xi,\eta) = \sum_{a=1}^{4} \varphi_a^{\bar{b}}(\xi,\eta) \cdot x_a^e; \qquad y(\xi,\eta) = \sum_{a=1}^{4} \varphi_a^{\bar{b}}(\xi,\eta) \cdot y_a^e;$$
$$\varphi_a^{\bar{b}}(\xi_c,\eta_c) = \begin{cases} 1, \text{ se } a = c, \\ 0, \text{ se } a \neq c. \end{cases}$$

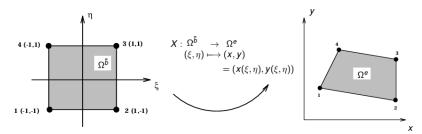


Por exemplo,

$$x(-1,-1) = x(\xi_{1},\eta_{1}) = \sum_{a=1}^{4} \varphi_{a}^{\bar{b}}(\xi_{1},\eta_{1}) \cdot x_{a}^{e}$$

$$= \underbrace{\varphi_{1}^{\bar{b}}(\xi_{1},\eta_{1})}_{1} \cdot x_{1}^{e} + \underbrace{\varphi_{2}^{\bar{b}}(\xi_{1},\eta_{1})}_{1} \cdot x_{2}^{e} + \underbrace{\varphi_{3}^{\bar{b}}(\xi_{1},\eta_{1})}_{1} \cdot x_{3}^{e} + \underbrace{\varphi_{4}^{\bar{b}}(\xi_{1},\eta_{1})}_{1} \cdot x_{4}^{e}$$

$$= x_{1}^{e}$$



Analogamente,

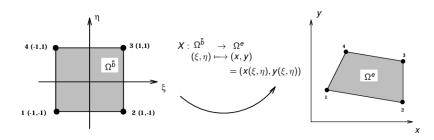
$$x(1,-1) = x(\xi_2, \eta_2) = x_2^e;$$

 $x(1,1) = x(\xi_3, \eta_3) = x_3^e;$
 $x(-1,1) = x(\xi_4, \eta_4) = x_4^e$

Ou seja, para todo a = 1, 2, 3, 4,

$$x(\xi_a, \eta_a) = x_a^e; \quad y(\xi_a, \eta_a) = y_a^e$$



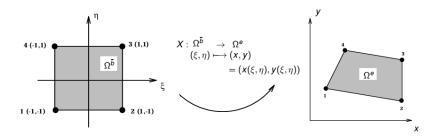


Vamos assumir que $x(\xi, \eta)$ e $y(\xi, \eta)$ são lineares em ξ e η , ou seja:

$$x(\xi, \eta) = a_1 + a_2 \xi + a_3 \eta + a_4 \xi \eta$$

 $y(\xi, \eta) = b_1 + b_2 \xi + b_3 \eta + b_4 \xi \eta$





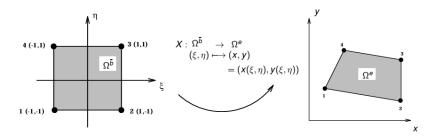
Então,

$$x(-1,-1) = x_1^e \Rightarrow a_1 - a_2 - a_3 + a_4 = x_1^e$$

$$x(1,-1) = x_2^e \Rightarrow a_1 + a_2 - a_3 - a_4 = x_2^e$$

$$x(1,1) = x_3^e \Rightarrow a_1 + a_2 + a_3 + a_4 = x_3^e$$

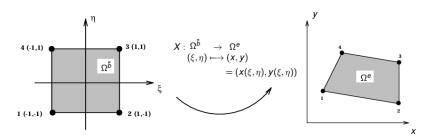
$$x(-1,1) = x_4^e \Rightarrow a_1 - a_2 + a_3 - a_4 = x_4^e$$



Resolvendo o sistema:

$$\begin{bmatrix} 1 & -1 & -1 & 1 \\ 1 & 1 & -1 & -1 \\ 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} x_1^e \\ x_2^e \\ x_3^e \\ x_4^e \end{bmatrix}$$





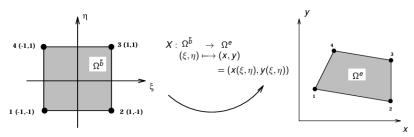
encontramos:

$$a_1 = (x_1^e + x_2^e + x_3^e + x_4^e)/4;$$

$$a_2 = (-x_1^e + x_2^e + x_3^e - x_4^e)/4;$$

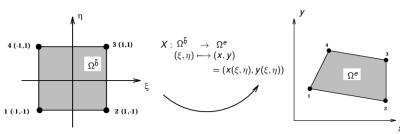
$$a_3 = (-x_1^e - x_2^e + x_3^e + x_4^e)/4;$$

$$a_4 = (x_1^e - x_2^e + x_3^e - x_4^e)/4$$



Substituindo a_1 , a_2 , a_3 , a_4 em $x(\xi, \eta)$ e arrumando os termos, obtemos:

$$x(\xi,\eta) = \underbrace{\frac{1}{4}(1-\xi)(1-\eta)}_{\varphi_{1}^{\bar{b}}(\xi,\eta)} x_{1}^{e} + \underbrace{\frac{1}{4}(1+\xi)(1-\eta)}_{\varphi_{2}^{\bar{b}}(\xi,\eta)} x_{2}^{e} + \underbrace{\frac{1}{4}(1+\xi)(1+\eta)}_{\varphi_{3}^{\bar{b}}(\xi,\eta)} x_{3}^{e} + \underbrace{\frac{1}{4}(1-\xi)(1+\eta)}_{\varphi_{4}^{\bar{b}}(\xi,\eta)} x_{4}^{e}$$



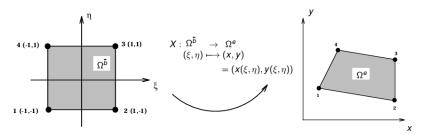
Assim, temos as quatro funções de base para Q_4 :

$$\varphi_{1}^{\bar{b}}(\xi,\eta) = \frac{1}{4}(1-\xi)(1-\eta);$$

$$\varphi_{2}^{\bar{b}}(\xi,\eta) = \frac{1}{4}(1+\xi)(1-\eta);$$

$$\varphi_{3}^{\bar{b}}(\xi,\eta) = \frac{1}{4}(1+\xi)(1+\eta);$$

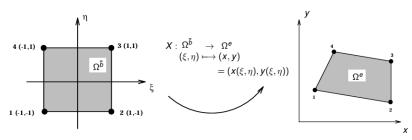
$$\varphi_{4}^{\bar{b}}(\xi,\eta) = \frac{1}{4}(1-\xi)(1+\eta)$$



Logo, podemos reescrever:

$$x(\xi,\eta) = \sum_{a=1}^{4} \varphi_{a}^{\bar{b}}(\xi,\eta) \cdot x_{a}^{e}$$
$$y(\xi,\eta) = \sum_{a=1}^{4} \varphi_{a}^{\bar{b}}(\xi,\eta) \cdot y_{a}^{e}$$





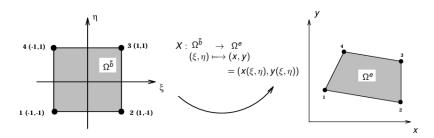
Assim, escrevemos a solução aproximada u_h^e em cada elemento Ω^e como:

$$u_h^e(x,y) = \sum_{a=1}^4 c_a^e \cdot \varphi_a^e(x,y)$$

Com a mudança de variáveis $(x, y) \longmapsto (\xi, \eta)$, obtemos:

$$u_h^e(x,y) = u_h^{\bar{b}}(\xi,\eta) = \sum_{a=1}^4 c_a^{\bar{b}} \cdot \varphi_a^{\bar{b}}(\xi,\eta)$$

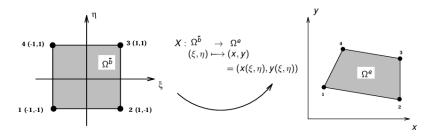
Elemento da matriz local Ke



Também temos para cada elemento Ω^e , ou seja, para todo a, b = 1, 2, 3, 4:

$$\mathcal{K}_{ab}^e = a(\varphi_a^e, \varphi_b^e) = (\nabla \varphi_a^e, \mathbf{k} \cdot \nabla \varphi_b^e) = \int_{\Omega^e} \nabla \varphi_a^e \cdot \mathbf{k} \cdot \nabla \varphi_b^e \, dxdy$$

Elemento do vetor local Fe



Também temos para cada elemento Ω^e , ou seja, para todo a = 1, 2, 3, 4:

$$\begin{split} F_a^e &= (f, \varphi_a^e) - (\bar{q}, \varphi_a^e)_{\Gamma_q} - \sum_{b=1}^4 a(\varphi_a^e, \varphi_b^e) p_b^e \\ &= \int_{\Omega^e} f \varphi_a^e \ dx dy - \int_{\Gamma_q} \bar{q} \varphi_a^e \ d\Gamma_q - \sum_{b=1}^4 a(\varphi_a^e, \varphi_b^e) p_b^e \end{split}$$

Pela definição do vetor gradiente no \mathbb{R}^2 , temos que:

$$\nabla \varphi_a^{\theta}(x, y) = \begin{bmatrix} \frac{\partial \varphi_a^{\theta}}{\partial x} \\ \frac{\partial \varphi_a^{\theta}}{\partial y} \end{bmatrix}$$

Usando notação matricial do produto interno (ou escalar) de dois vetores x, y no \mathbb{R}^2 , temos que:

$$x \cdot y = x^T y$$

Logo, podemos reescrever K_{ab}^e para todo a, b = 1, 2, 3, 4 como:

$$K_{ab}^{e} = a(\varphi_{a}^{e}, \varphi_{b}^{e}) = (\nabla \varphi_{a}^{e}, k \cdot \nabla \varphi_{b}^{e}) = \int_{\Omega^{e}} \nabla \varphi_{a}^{e} \cdot k \cdot \nabla \varphi_{b}^{e} \, dxdy$$

$$= \int_{\Omega^{e}} (\nabla \varphi_{a}^{e})^{\mathsf{T}} \, k \, \nabla \varphi_{b}^{e} \, dxdy = \int_{\Omega^{e}} \left[\frac{\partial \varphi_{a}^{e}}{\partial x} \quad \frac{\partial \varphi_{a}^{e}}{\partial y} \right] \, k \, \left[\frac{\partial \varphi_{a}^{e}}{\partial x} \quad \frac{\partial \varphi_{a}^{e}}{\partial y} \right] \, dxdy$$

$$(1)$$

De forma análoga ao que vimos no caso 1D, devemos usar mudança de variáveis através da transformação isoparamétrica

$$T_{\xi\eta} \colon \Omega^e \longrightarrow \Omega^{\bar{b}}$$

 $(x,y) \longmapsto (\xi,\eta) = (\xi(x,y),\eta(x,y)),$

para aproximar a integral dupla com quadratura de Gauss.

Então,

$$\varphi_{\mathsf{a}}^{\mathsf{e}}(\mathsf{x},\mathsf{y}) = \varphi_{\mathsf{a}}^{\bar{b}}(\xi,\eta) = \varphi_{\mathsf{a}}^{\bar{b}}(\xi(\mathsf{x},\mathsf{y}),\eta(\mathsf{x},\mathsf{y}))$$

e usando a Regra da Cadeia, obtemos as derivadas parciais:

$$\begin{split} \frac{\partial \varphi_a^e}{\partial x} &= \frac{\partial \varphi_a^{\bar{b}}}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial \varphi_a^{\bar{b}}}{\partial \eta} \frac{\partial \eta}{\partial x} \\ \frac{\partial \varphi_a^e}{\partial y} &= \frac{\partial \varphi_a^{\bar{b}}}{\partial \xi} \frac{\partial \xi}{\partial y} + \frac{\partial \varphi_a^{\bar{b}}}{\partial \eta} \frac{\partial \eta}{\partial y} \end{split}$$

Passando as duas equações para a forma matricial, obtemos:

$$\underbrace{\begin{bmatrix} \frac{\partial \varphi_a^e}{\partial \mathbf{x}} \\ \frac{\partial \varphi_a^e}{\partial \mathbf{y}} \end{bmatrix}}_{=\nabla \varphi_a^e(\mathbf{x}, \mathbf{y})} = \begin{bmatrix} \frac{\partial \xi}{\partial \mathbf{x}} & \frac{\partial \eta}{\partial \mathbf{x}} \\ \frac{\partial \xi}{\partial \mathbf{y}} & \frac{\partial \eta}{\partial \mathbf{y}} \end{bmatrix} \underbrace{\begin{bmatrix} \frac{\partial \varphi_a^{\bar{b}}}{\partial \xi} \\ \frac{\partial \xi}{\partial \eta} \end{bmatrix}}_{=\nabla \varphi_a^{\bar{b}}(\xi, \eta)}$$

Usando a notação $\xi_x = \frac{\partial \xi}{\partial x}$ para as derivadas parciais da matriz, temos:

$$\nabla \varphi_{a}^{e}(x,y) = \begin{vmatrix} \xi_{x} & \eta_{x} \\ \xi_{y} & \eta_{y} \end{vmatrix} \nabla \varphi_{a}^{\bar{b}}(\xi,\eta)$$
 (2)

Do estudo de mudança de variáveis em integrais duplas, sabemos que:

$$\int_{\Omega^e} g(x,y) \, dxdy = \int_{\Omega^{\bar{b}}} g(\xi,\eta) \, |J(\xi,\eta)| \, d\xi d\eta, \tag{3}$$

onde

$$J(\xi,\eta) = \left[\begin{array}{cc} x_{\xi} & x_{\eta} \\ y_{\xi} & y_{\eta} \end{array} \right]$$

é a matriz jacobiana da transformação isoparamétrica

$$T_{xy} \colon \Omega^{\bar{b}} \longrightarrow \Omega^{e}$$

 $(\xi, \eta) \longmapsto (x, y) = (x(\xi, \eta), y(\xi, \eta))$

е

$$|J(\xi,\eta)| = \mathsf{det}(J(\xi,\eta)) = \mathsf{x}_{\xi} \mathsf{y}_{\eta} - \mathsf{x}_{\eta} \mathsf{y}_{\xi}$$

é o jacobiano dessa transformação.



Usando os resultados de (2) e (3) na Eq. (1), obtemos:

$$\begin{split} \mathcal{K}_{ab}^{e} &= \int_{\Omega^{e}} (\nabla \varphi_{a}^{e})^{T} \ k \ \nabla \varphi_{b}^{e} \ dxdy \\ &= \int_{\Omega^{\bar{b}}} (\nabla \varphi_{a}^{\bar{b}}(\xi, \eta))^{T} \left[\begin{array}{cc} \xi_{x} & \xi_{y} \\ \eta_{x} & \eta_{y} \end{array} \right] \ k \ \left[\begin{array}{cc} \xi_{x} & \eta_{x} \\ \xi_{y} & \eta_{y} \end{array} \right] \nabla \varphi_{b}^{\bar{b}}(\xi, \eta) \ |J(\xi, \eta)| \ d\xi d\eta \end{split}$$

(4)

Note que se:

$$T_{xy} \colon \Omega^{\bar{b}} \longrightarrow \Omega^{e}$$

 $(\xi, \eta) \longmapsto (x, y) = (x(\xi, \eta), y(\xi, \eta))$

é a transformação onde a matriz jacobiana é

$$J(\xi,\eta) = \left[\begin{array}{cc} x_{\xi} & x_{\eta} \\ y_{\xi} & y_{\eta} \end{array} \right],$$

a transformação inversa é dada por

$$T_{xy}^{-1} = T_{\xi\eta} \colon \Omega^e \longrightarrow \Omega^{\bar{b}}$$

 $(x, y) \longmapsto (\xi, \eta) = (\xi(x, y), \eta(x, y)),$

onde a matriz jacobiana é

$$J(x,y) = \begin{vmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{vmatrix} = J^{-1}(\xi,\eta)$$
 (5)

Portanto, usando a definição de $J^{-1}(\xi,\eta)$ de (5) na Eq. (4), obtemos:

Elemento K_{ab}^e da matriz local K^e (Materiais isotrópicos: Q = kI)

$$\mathcal{K}_{ab}^{e} = \int_{\Omega^{e}} (\nabla \varphi_{a}^{e})^{T} k \nabla \varphi_{b}^{e} dxdy
= \int_{\Omega^{\bar{b}}} (\nabla \varphi_{a}^{\bar{b}}(\xi, \eta))^{T} \cdot J^{-1} \cdot k \cdot (J^{-1})^{T} \cdot \nabla \varphi_{b}^{\bar{b}}(\xi, \eta) \cdot |J| d\xi d\eta,$$
(6)

para a, b = 1, 2, 3, 4, onde

$$J=J(\xi,\eta)=\left[egin{array}{cc} x_{\xi} & x_{\eta} \ y_{\xi} & y_{\eta} \end{array}
ight].$$

Expandindo em colunas o vetor gradiente

$$abla arphi_{f a}^{ar b}(\xi,\eta) = egin{bmatrix} rac{\partial arphi_{f a}^{ar b}}{\partial \xi} \ rac{\partial arphi_{f a}^{ar b}}{\partial \eta} \end{bmatrix}$$

para todo a = 1, 2, 3, 4, obtemos a matriz

$$\begin{split} N &= \begin{bmatrix} \begin{vmatrix} & & & & \\ & & & \\ & \nabla \varphi_1^{\bar{b}}(\xi, \eta) & \nabla \varphi_2^{\bar{b}}(\xi, \eta) & \nabla \varphi_3^{\bar{b}}(\xi, \eta) & \nabla \varphi_4^{\bar{b}}(\xi, \eta) \\ & & & \\ & & & \\ \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial \varphi_1^{\bar{b}}}{\partial \xi} & \frac{\partial \varphi_2^{\bar{b}}}{\partial \xi} & \frac{\partial \varphi_3^{\bar{b}}}{\partial \xi} & \frac{\partial \varphi_4^{\bar{b}}}{\partial \xi} \\ \frac{\partial \varphi_1^{\bar{b}}}{\partial \eta} & \frac{\partial \varphi_2^{\bar{b}}}{\partial \eta} & \frac{\partial \varphi_3^{\bar{b}}}{\partial \eta} & \frac{\partial \varphi_4^{\bar{b}}}{\partial \eta} \end{bmatrix} \end{split}$$

Portanto,

Matriz local K^e (Materiais isotrópicos: Q = kI)

$$K^{e} = \int_{\Omega^{\bar{b}}} N^{T} \cdot J^{-1} \cdot k \cdot (J^{-1})^{T} \cdot N \cdot |J| \ d\xi d\eta, \tag{7}$$

onde

$$J=J(\xi,\eta)=\left[egin{array}{cc} x_{\xi} & x_{\eta} \ y_{\xi} & y_{\eta} \end{array}
ight].$$

Sabendo que

$$\begin{aligned} x(\xi,\eta) &= \sum_{a=1}^{4} \varphi_a^{\bar{b}}(\xi,\eta) \cdot x_a^e = \begin{bmatrix} \varphi_1^{\bar{b}}(\xi,\eta) & \varphi_2^{\bar{b}}(\xi,\eta) & \varphi_3^{\bar{b}}(\xi,\eta) & \varphi_4^{\bar{b}}(\xi,\eta) \end{bmatrix} \cdot \begin{bmatrix} x_1^e \\ x_2^e \\ x_3^e \\ x_4^e \end{bmatrix} \\ y(\xi,\eta) &= \sum_{a=1}^{4} \varphi_a^{\bar{b}}(\xi,\eta) \cdot y_a^e = \begin{bmatrix} \varphi_1^{\bar{b}}(\xi,\eta) & \varphi_2^{\bar{b}}(\xi,\eta) & \varphi_3^{\bar{b}}(\xi,\eta) & \varphi_4^{\bar{b}}(\xi,\eta) \end{bmatrix} \cdot \begin{bmatrix} y_1^e \\ y_2^e \\ y_3^e \\ y_4^e \end{bmatrix} \end{aligned}$$

e usando as funções de base do Q₄,

$$\varphi_{1}^{\bar{b}}(\xi,\eta) = (1-\xi)(1-\eta)/4;$$

$$\varphi_{2}^{\bar{b}}(\xi,\eta) = (1+\xi)(1-\eta)/4;$$

$$\varphi_{3}^{\bar{b}}(\xi,\eta) = (1+\xi)(1+\eta)/4;$$

$$\varphi_{4}^{\bar{b}}(\xi,\eta) = (1-\xi)(1+\eta)/4,$$

obtemos

$$x(\xi,\eta) = \frac{1}{4} \begin{bmatrix} (1-\xi)(1-\eta) & (1+\xi)(1-\eta) & (1+\xi)(1+\eta) & (1-\xi)(1+\eta) \end{bmatrix} \begin{bmatrix} x_1^e \\ x_2^e \\ x_3^e \\ x_4^e \end{bmatrix}$$

$$y(\xi,\eta) = \frac{1}{4} \begin{bmatrix} (1-\xi)(1-\eta) & (1+\xi)(1-\eta) & (1+\xi)(1+\eta) & (1-\xi)(1+\eta) \end{bmatrix} \begin{bmatrix} y_1^e \\ y_2^e \\ y_3^e \\ y_4^e \end{bmatrix}$$

e os elementos da matriz jacobiana J são:

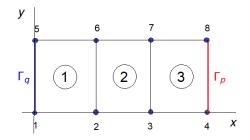
$$x_{\xi} = (1/4) \cdot \begin{bmatrix} -(1-\eta) & 1-\eta & 1+\eta & -(1+\eta) \end{bmatrix} \begin{bmatrix} x_{1}^{e} & x_{2}^{e} & x_{3}^{e} & x_{4}^{e} \end{bmatrix}^{T}$$

$$y_{\xi} = (1/4) \cdot \begin{bmatrix} -(1-\eta) & 1-\eta & 1+\eta & -(1+\eta) \end{bmatrix} \begin{bmatrix} y_{1}^{e} & y_{2}^{e} & y_{3}^{e} & y_{4}^{e} \end{bmatrix}^{T}$$

$$x_{\eta} = (1/4) \cdot \begin{bmatrix} -(1-\xi) & -(1+\xi) & 1+\xi & 1-\xi \end{bmatrix} \begin{bmatrix} x_{1}^{e} & x_{2}^{e} & x_{3}^{e} & x_{4}^{e} \end{bmatrix}^{T}$$

$$y_{\eta} = (1/4) \cdot \begin{bmatrix} -(1-\xi) & -(1+\xi) & 1+\xi & 1-\xi \end{bmatrix} \begin{bmatrix} y_{1}^{e} & y_{2}^{e} & y_{3}^{e} & y_{4}^{e} \end{bmatrix}^{T}$$

Exemplo: Considere o domínio Ω

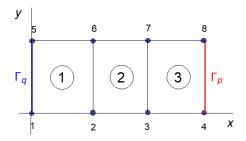


onde $0 \le x \le 1$, $0 \le y \le 1/3$.

Note que:

Número de subintervalos de x: nelx = 3Número de subintervalos de y: nely = 1

Total de elementos: $nelx \cdot nely = 3$.

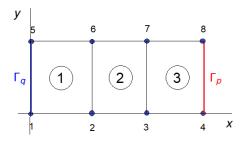


Número de nós de x: Nnosx = nelx + 1 = 4.

Tamanho dos subintervalos de x: $h_x = (x_f - x_1)/nelx$, onde x_f é o nó final e x_1 é o nó inicial em x. Neste exemplo, $h_x = (1-0)/3 = 1/3$.

Número de nós de y: Nnosy = nely + 1 = 2.

Tamanho dos subintervalos de y: $h_y = (y_f - y_1)/nelx$, onde y_f é o nó final e y_1 é o nó inicial em y. Neste exemplo, $h_y = (y_f - x_0)/nely = ((1/3) - 0)/1 = 1/3$.

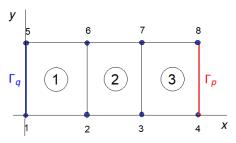


Cada nó de x é dado por: $x_j = x_1 + (j-1) \cdot h_x$, para todo j = 1, 2, ..., Nnosx.

Neste exemplo, os nós de x são: $x_1 = 0$, $x_2 = 1/3$, $x_3 = 2/3$, $x_4 = 1$.

Cada nó de y é dado por: $y_k = y_1 + (k-1) \cdot h_y$, para todo $k = 1, 2, \dots, Nnosy$.

Neste exemplo, os nós de y são: $y_1 = 0$, $y_2 = 1/3$.



Neste exemplo, o número de nós total da malha é:

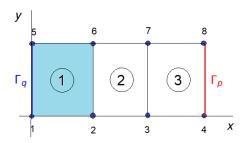
$$\textit{Nnos} = \textit{Nosx} \cdot \textit{Nnosy} = (\textit{nelx} + 1) \cdot (\textit{nely} + 1) = 4 \cdot 2 = 8.$$

Logo, cada ponto do domínio Ω é (x_j, y_k) , para j = 1, 2, ..., Nnosx, k = 1, 2, ..., Nnosy. Neste exemplo, temos os seguintes pontos:

• 1 :
$$(x_1, y_1) = (0, 0)$$
; • 2 : $(x_2, y_1) = (1/3, 0)$; • 3 : $(x_3, y_1) = (2/3, 0)$;

• 4:
$$(x_4, y_1) = (1, 0)$$
; • 5: $(x_1, y_2) = (0, 1/3)$; • 6: $(x_2, y_2) = (1/3, 1/3)$;

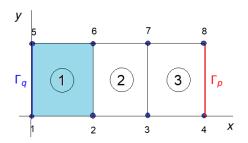
• 7:
$$(x_3, y_2) = (2/3, 1/3)$$
; • 8: $(x_4, y_2) = (1, 1/3)$.



• Exemplo: Cálculo dos elementos da matriz local

$$K^{1} = \begin{bmatrix} K_{11}^{1} & K_{12}^{1} & K_{13}^{1} & K_{14}^{1} \\ K_{21}^{1} & K_{22}^{1} & K_{23}^{1} & K_{24}^{1} \\ K_{31}^{1} & K_{32}^{1} & K_{33}^{1} & K_{34}^{1} \\ K_{41}^{1} & K_{42}^{1} & K_{43}^{1} & K_{43}^{1} \end{bmatrix}$$

para o elemento e = 1 do domínio Ω .

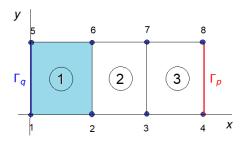


Para e = 1, temos:

$$K_{ab}^{1} = \int_{\Omega^{1}} (\nabla \varphi_{a}^{1}(x, y))^{T} k \nabla \varphi_{b}^{1}(x, y) dxdy$$
$$= \int_{0}^{1/3} \int_{0}^{1/3} (\nabla \varphi_{a}^{1}(x, y))^{T} k \nabla \varphi_{b}^{1}(x, y) dxdy,$$

para a, b = 1, 2, 3, 4.

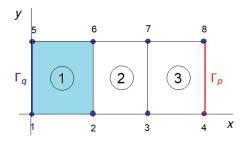




Com a mudança de variáveis na transformação isoparamétrica, temos:

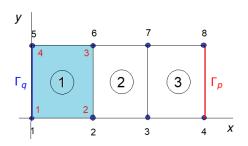
$$\begin{split} \mathcal{K}_{ab}^{1} &= \int_{\Omega^{\bar{1}}} (\nabla \varphi_{a}^{\bar{1}}(\xi, \eta))^{T} \cdot J^{-1} \cdot k \cdot (J^{-1})^{T} \cdot \nabla \varphi_{b}^{\bar{1}}(\xi, \eta) \cdot |J| \ d\xi d\eta \\ &= \int_{-1}^{1} \int_{-1}^{1} (\nabla \varphi_{a}^{\bar{1}}(\xi, \eta))^{T} \cdot J^{-1} \cdot k \cdot (J^{-1})^{T} \cdot \nabla \varphi_{b}^{\bar{1}}(\xi, \eta) \cdot |J| \ d\xi d\eta, \end{split}$$

para a, b = 1, 2, 3, 4.



Para o elemento K_{11}^1 da matriz local K^1 , fazemos a=b=1 na integral. Assim, obtemos:

$$\begin{split} K_{11}^{1} &= \int_{\Omega^{\bar{1}}} (\nabla \varphi_{1}^{\bar{1}}(\xi, \eta))^{T} \cdot J^{-1} \cdot k \cdot (J^{-1})^{T} \cdot \nabla \varphi_{1}^{\bar{1}}(\xi, \eta) \cdot |J| \ d\xi d\eta \\ &= \int_{-1}^{1} \int_{-1}^{1} (\nabla \varphi_{1}^{\bar{1}}(\xi, \eta))^{T} \cdot J^{-1} \cdot k \cdot (J^{-1})^{T} \cdot \nabla \varphi_{1}^{\bar{1}}(\xi, \eta) \cdot |J| \ d\xi d\eta \end{split}$$



Cálculo da matriz jacobiana J:

Neste exemplo, no elemento Ω^1 , temos:

$$(x^1)^T = \begin{bmatrix} x_1^1 & x_2^1 & x_3^1 & x_4^1 \end{bmatrix} = \begin{bmatrix} 0 & 1/3 & 1/3 & 0 \end{bmatrix};$$

 $(y^1)^T = \begin{bmatrix} y_1^1 & y_2^1 & y_3^1 & y_4^1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1/3 & 1/3 \end{bmatrix}.$

Logo, os elementos da matriz jacobiana *J* são:

$$x_{\xi} = (1/4) \cdot \begin{bmatrix} -(1-\eta) & 1-\eta & 1+\eta & -(1+\eta) \end{bmatrix} \begin{bmatrix} 0 \\ 1/3 \\ 1/3 \\ 0 \end{bmatrix}$$

$$= \frac{1}{4} \begin{bmatrix} \frac{1-\eta}{3} + \frac{1+\eta}{3} \end{bmatrix} = \frac{1}{6},$$

e verifique que:

$$y_{\xi} = 0; \quad x_{\eta} = 0; \quad y_{\eta} = \frac{1}{6}.$$

Portanto, a matriz jacobiana J e seu jacobiano (|J| = det(J)) são dados por:

$$J = J(\xi, \eta) = \begin{bmatrix} x_{\xi} & x_{\eta} \\ y_{\xi} & y_{\eta} \end{bmatrix} = \begin{bmatrix} 1/6 & 0 \\ 0 & 1/6 \end{bmatrix};$$
$$|J| = 1/36.$$

A inversa da matriz J é dada por:

$$J^{-1} = \frac{1}{|J|} \begin{bmatrix} 1/6 & 0 \\ 0 & 1/6 \end{bmatrix} = \frac{1}{1/36} \begin{bmatrix} 1/6 & 0 \\ 0 & 1/6 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix}$$

Portanto, no integrando de K_{11}^1 , já temos que:

$$J^{-1} \cdot k \cdot (J^{-1})^{T} = \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix} \cdot k \cdot \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix}$$
$$= 6 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot k \cdot 6 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
$$= 36 \cdot k \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

Substituindo em K_{11}^1 , obtemos:

$$K_{11}^{1} = \int_{-1}^{1} \int_{-1}^{1} (\nabla \varphi_{1}^{\overline{1}}(\xi, \eta))^{T} \cdot 36 \cdot k \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot \nabla \varphi_{1}^{\overline{1}}(\xi, \eta) \cdot \frac{1}{36} d\xi d\eta$$

$$= \int_{-1}^{1} \int_{-1}^{1} (\nabla \varphi_{1}^{\overline{1}}(\xi, \eta))^{T} \cdot k \cdot \nabla \varphi_{1}^{\overline{1}}(\xi, \eta) d\xi d\eta$$

$$= k \int_{-1}^{1} \int_{-1}^{1} (\nabla \varphi_{1}^{\overline{1}}(\xi, \eta))^{T} \cdot \nabla \varphi_{1}^{\overline{1}}(\xi, \eta) d\xi d\eta$$

• Cálculo do gradiente: No integrando, sabendo que

$$\varphi_1^{\bar{1}}(\xi,\eta) = (1/4) \cdot (1-\xi)(1-\eta)$$
, temos:

$$\nabla \varphi_{1}^{\overline{1}}(\xi,\eta)) = \begin{bmatrix} \frac{\partial \varphi_{1}^{\overline{1}}}{\partial \xi} \\ \frac{\partial \varphi_{1}^{\overline{1}}}{\partial \eta} \end{bmatrix} = \frac{1}{4} \begin{bmatrix} -(1-\eta) \\ -(1-\xi) \end{bmatrix} = \frac{1}{4} \begin{bmatrix} \eta-1 \\ \xi-1 \end{bmatrix}$$

Portanto,

$$K_{11}^{1} = k \int_{-1}^{1} \int_{-1}^{1} \frac{1}{4} \left[\eta - 1 \quad \xi - 1 \right] \cdot \frac{1}{4} \begin{bmatrix} \eta - 1 \\ \xi - 1 \end{bmatrix} d\xi d\eta$$
$$= k \int_{-1}^{1} \int_{-1}^{1} \frac{1}{16} \left[(\eta - 1)^{2} + (\xi - 1)^{2} \right] d\xi d\eta$$
$$= \frac{k}{16} \int_{-1}^{1} \int_{-1}^{1} \left[(\eta - 1)^{2} + (\xi - 1)^{2} \right] d\xi d\eta$$

Devemos aproximar esta integral dupla usando quadratura gaussiana. Aqui, vamos usar apenas npg=2.

Neste caso, os pontos de Gauss serão: $-\frac{\sqrt{3}}{3}$, $\frac{\sqrt{3}}{3}$, enquanto os pesos de Gauss serão iguais a 1.

Na integral dupla, denotamos a função que está no integrando por:

$$g(\xi,\eta) = (\eta-1)^2 + (\xi-1)^2.$$

Assim, calculamos em

$$\int_{-1}^{1} \int_{-1}^{1} g(\xi, \eta) \ d\xi d\eta = \int_{-1}^{1} \left[\int_{-1}^{1} g(\xi, \eta) \ d\xi \right] d\eta$$

a integral que está entre colchetes primeiro. Note que nesta integral, somente ξ está variando no intervalo [-1,1].

Outra alternativa é calcular em

$$\int_{-1}^{1} \int_{-1}^{1} g(\xi, \eta) \ d\xi d\eta = \int_{-1}^{1} \left[\int_{-1}^{1} g(\xi, \eta) \ d\eta \right] d\xi$$

, onde a integral que está entre colchetes possui somente η variando em [-1,1].

Calculando a integral entre colchetes pela primeira alternativa usando quadratura gaussiana, obtemos:

$$\int_{-1}^{1} g(\xi, \eta) d\xi = \sum_{j=1}^{npg} g(\xi_{j}, \eta) \cdot w_{j} = \sum_{j=1}^{2} g(\xi_{j}, \eta) \cdot w_{j}$$
$$= g(\xi_{1}, \eta) \cdot w_{1} + g(\xi_{2}, \eta) \cdot w_{2}$$

Como
$$\xi_1 = -\frac{\sqrt{3}}{3}$$
, $\xi_2 = \frac{\sqrt{3}}{3}$, $w_1 = w_2 = 1$, obtemos:

$$\int_{-1}^{1} g(\xi, \eta) \ d\xi = g\left(-\frac{\sqrt{3}}{3}, \eta\right) \cdot 1 + g\left(\frac{\sqrt{3}}{3}, \eta\right) \cdot 1$$

$$= \left[(\eta - 1)^{2} + \left(-\frac{\sqrt{3}}{3} - 1\right)^{2}\right] \cdot 1 + \left[(\eta - 1)^{2} + \left(\frac{\sqrt{3}}{3} - 1\right)^{2}\right] \cdot 1$$

$$= \frac{8}{3} + 2(\eta - 1)^{2}$$

Agora, calculamos por quadratura gaussiana

$$\int_{-1}^{1} \left[\frac{8}{3} + 2(\eta - 1)^{2} \right] d\eta,$$

onde denotamos $\bar{g}(\eta) = \frac{8}{3} + 2(\eta - 1)^2$. Assim, obtemos:

$$\int_{-1}^{1} \bar{g}(\eta) \ d\eta = \sum_{k=1}^{npg} \bar{g}(\eta_{k}) \cdot w_{k} = \sum_{k=1}^{2} \bar{g}(\eta_{k}) \cdot w_{k} = \bar{g}(\eta_{1}) \cdot w_{1} + \bar{g}(\eta_{2}) \cdot w_{2}$$

Como
$$\eta_1 = -\frac{\sqrt{3}}{3}$$
, $\eta_2 = \frac{\sqrt{3}}{3}$, $w_1 = w_2 = 1$, obtemos:

$$\int_{-1}^{1} \bar{g}(\eta) d\eta = \bar{g}\left(-\frac{\sqrt{3}}{3}\right) \cdot 1 + \bar{g}\left(\frac{\sqrt{3}}{3}\right) \cdot 1$$
$$= \left[\frac{8}{3} + 2\left(-\frac{\sqrt{3}}{3} - 1\right)^{2}\right] + \left[\frac{8}{3} + 2\left(\frac{\sqrt{3}}{3} - 1\right)^{2}\right] = \frac{32}{3}$$

Logo, obtemos:

$$\int_{-1}^{1} \int_{-1}^{1} \left[(\eta - 1)^2 + (\xi - 1)^2 \right] \ d\xi d\eta = \frac{32}{3},$$

e portanto,

$$K_{11}^{1} = \frac{k}{16} \int_{-1}^{1} \int_{-1}^{1} \left[(\eta - 1)^{2} + (\xi - 1)^{2} \right] d\xi d\eta = \frac{k}{16} \cdot \frac{32}{3} = \frac{2}{3}k$$

Usando k = 1, obtemos:

$$K_{11}^1=\frac{2}{3}.$$

Exercício: verifique para os demais elementos de K^1 com k = 1 que:

$$\begin{split} & \mathcal{K}_{12}^1 = \mathcal{K}_{14}^1 = \mathcal{K}_{21}^1 = \mathcal{K}_{23}^1 = \mathcal{K}_{32}^1 = \mathcal{K}_{34}^1 = -\frac{1}{6}; \quad \mathcal{K}_{13}^1 = \mathcal{K}_{24}^1 = \mathcal{K}_{31}^1 = \mathcal{K}_{42}^1 = -\frac{1}{3}; \\ & \mathcal{K}_{22}^1 = \mathcal{K}_{33}^1 = \mathcal{K}_{44}^1 = \frac{2}{3}. \end{split}$$

Também temos para cada elemento Ω^e , ou seja, para todo a = 1, 2, 3, 4:

$$F_a^e = (f, \varphi_a^e) - (\bar{q}, \varphi_a^e)_{\Gamma_q} - \sum_{b=1}^4 a(\varphi_a^e, \varphi_b^e) \ p_b^e = \underbrace{(f, \varphi_a^e)}_{f_a^e} - \underbrace{(\bar{q}, \varphi_a^e)_{\Gamma_q}}_{q_a^e} - \underbrace{\sum_{b=1}^4 K_{ab}^e \ p_b^e}_{\bar{p}_a^e}$$

Cálculo de f_a^e:

$$f_a^e = (f, \varphi_a^e) = \int_{\Omega^e} f(x, y) \cdot \varphi_a^e(x, y) \, dxdy$$

Usando mudança de variáveis $(x, y) \longmapsto (\xi, \eta)$, obtemos:

$$f_a^e = (f, \varphi_a^e) = \int_{\Omega^{\bar{b}}} f(\xi, \eta) \cdot \varphi_a^{\bar{b}}(\xi, \eta) |J| d\xi d\eta$$

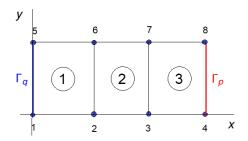
Logo,

$$f^e = egin{bmatrix} f_1^e \\ f_2^e \\ f_3^e \\ f_4^e \end{bmatrix}, ext{ para } e = 1, 2, 3.$$

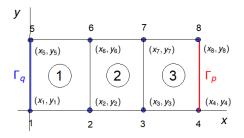
• Cálculo de q_a^e :

$$q_a^e = (\bar{q}, \varphi_a^e)_{\Gamma_q} = \int_{\Gamma_q} \bar{q}(s) \cdot \varphi_a^e(s) \; ds, \; ext{onde } s \in \Gamma_q$$

• Exemplo de cálculo de q_a^e :

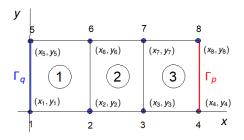


Note que: $\Gamma_q \in \Omega^1$



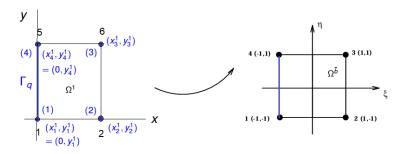
Aqui, os nós 1 e 5 da malha pertencem a $\Gamma_q = \{(0, y); y_1 \le y \le y_5\}$. Logo,

$$q_a^e = (\bar{q}, \varphi_a^e)_{\Gamma_q} = \int_{\Gamma_q} \bar{q}(0, y) \cdot \varphi_a^e(0, y) \ dy = \int_{y_1}^{y_5} \bar{q}(0, y) \cdot \varphi_a^e(0, y) \ dy$$



Aqui, os nós 1 e 5 da malha pertencem a $\Gamma_q = \{(0,y); y_1 \leq y \leq y_5\}$. Logo,

$$q_a^e = (\bar{q}, \varphi_a^e)_{\Gamma_q} = \int_{\Gamma_q} \bar{q}(0, y) \cdot \varphi_a^e(0, y) \ dy = \int_{y_1}^{y_5} \bar{q}(0, y) \cdot \varphi_a^e(0, y) \ dy$$



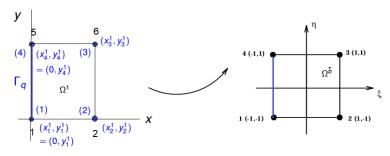
Na mudança de variáveis, $(0, y) \longmapsto (-1, \eta)$.

Logo, para a = 1, 4:

$$q_a^e = (\bar{q}, \varphi_a^e)_{\Gamma_q} = \int_{y_1^1 = y_1}^{y_4^1 = y_5} \bar{q}(0, y) \cdot \varphi_a^e(0, y) \ dy = \int_{-1}^1 \bar{q}(-1, \eta) \cdot \varphi_a^{\bar{b}}(-1, \eta) \cdot y_\eta \ d\eta$$

Para $a = 2, 3, q_a^e = 0.$

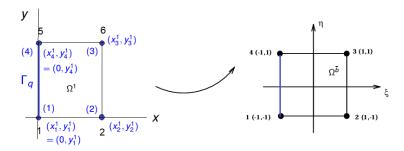




Lembre-se de que:

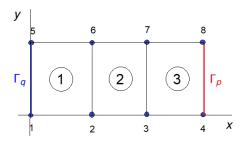
$$\begin{split} &\varphi_1^{\bar{b}}(-1,\eta) = (1/4)(1-(-1))(1-\eta) = (1-\eta)/2; \\ &\varphi_2^{\bar{b}}(-1,\eta) = (1/4)(1+(-1))(1-\eta) = 0; \\ &\varphi_3^{\bar{b}}(-1,\eta) = (1/4)(1+(-1))(1+\eta) = 0; \\ &\varphi_4^{\bar{b}}(-1,\eta) = (1/4)(1-(-1))(1+\eta) = (1+\eta)/2 \end{split}$$

Portanto, no elemento Ω^1 , só serão usadas as funções de base locais $\varphi_1^{ar b},\, \varphi_{4,\, \circ}^{ar b}$



Logo,

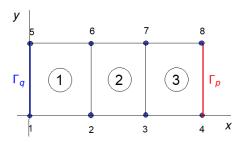
$$q^1 = egin{bmatrix} q_1^1 \ q_2^1 \ q_3^1 \ q_4^1 \end{bmatrix} = egin{bmatrix} (ar{q}, arphi_1^1)_{\Gamma_q} \ 0 \ 0 \ (ar{q}, arphi_4^1)_{\Gamma_q} \end{bmatrix}; \quad q^e = egin{bmatrix} 0 \ 0 \ 0 \ 0 \end{bmatrix}, ext{ para } e = 2, 3.$$



$$ar{p}_a^e = \sum_{b=1}^4 K_{ab}^e \ p_b^e$$

Neste exemplo, os nós prescritos 4 e 8 estão em $\Gamma_p = \{(x_4, y); y_4 \le y \le y_8\}$. Logo, os nós prescritos estão no elemento Ω^3 .

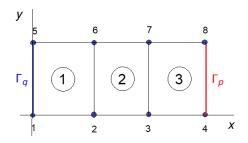
Neste caso, só vamos calcular \bar{p}^3 , enquanto $\bar{p}^e = 0$ para e = 1, 2.



Logo,

$$\bar{p}_{a}^{3} = \sum_{b=1}^{4} K_{ab}^{3} p_{b}^{3}$$

$$\bar{p}_{a}^{3} = \begin{bmatrix} \bar{p}_{1}^{3} \\ \bar{p}_{2}^{3} \\ \bar{p}_{3}^{3} \\ \bar{p}_{4}^{3} \end{bmatrix} = \begin{bmatrix} K_{11}^{3} & K_{12}^{3} & K_{13}^{3} & K_{14}^{3} \\ K_{21}^{3} & K_{22}^{3} & K_{23}^{3} & K_{24}^{3} \\ K_{31}^{3} & K_{32}^{3} & K_{33}^{3} & K_{34}^{3} \\ K_{41}^{3} & K_{42}^{3} & K_{43}^{3} & K_{44}^{3} \end{bmatrix} \begin{bmatrix} p_{1}^{3} \\ p_{2}^{3} \\ p_{3}^{3} \\ p_{4}^{3} \end{bmatrix}$$



Como $p_1^3 = p_4^3 = 0$, obtemos:

$$\bar{p}^3 = \begin{bmatrix} \bar{p}_1^3 \\ \bar{p}_2^3 \\ \bar{p}_3^3 \\ \bar{p}_4^3 \end{bmatrix} = \begin{bmatrix} K_{11}^3 & K_{12}^3 & K_{13}^3 & K_{14}^3 \\ K_{21}^3 & K_{22}^3 & K_{23}^3 & K_{24}^3 \\ K_{31}^3 & K_{32}^3 & K_{33}^3 & K_{34}^3 \\ K_{41}^3 & K_{42}^3 & K_{43}^3 & K_{44}^3 \end{bmatrix} \begin{bmatrix} 0 \\ p_2^3 \\ p_3^3 \\ 0 \end{bmatrix}; \ \bar{p}^e = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \ \text{para } e = 1, 2.$$

Portanto, neste exemplo, para os elementos e = 1, 2, 3:

$$F^e = f^e - q^e - \bar{p}^e,$$

onde

$$f^e = \begin{bmatrix} f_1^e \\ f_2^e \\ f_3^e \\ f_4^e \end{bmatrix}$$
, para $e = 1, 2, 3$; $q^1 = \begin{bmatrix} q_1^1 \\ 0 \\ 0 \\ q_4^1 \end{bmatrix}$; $q^e = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$, para $e = 2, 3$;

$$\bar{p}^{3} = \begin{bmatrix} \bar{p}_{1}^{3} \\ \bar{p}_{2}^{3} \\ \bar{p}_{3}^{3} \\ \bar{p}_{4}^{3} \end{bmatrix} = \begin{bmatrix} K_{11}^{3} & K_{12}^{3} & K_{13}^{3} & K_{14}^{3} \\ K_{21}^{3} & K_{22}^{3} & K_{23}^{3} & K_{24}^{3} \\ K_{31}^{3} & K_{32}^{3} & K_{33}^{3} & K_{34}^{3} \\ K_{41}^{3} & K_{42}^{3} & K_{43}^{3} & K_{44}^{3} \end{bmatrix} \begin{bmatrix} 0 \\ p_{2}^{3} \\ p_{3}^{3} \\ 0 \end{bmatrix}; \ \bar{p}^{e} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \ \text{para } e = 1, 2.$$

• Para *e* = 1:

$$F^{1} = f^{1} - q^{1} - \bar{p}^{1} = \begin{bmatrix} f_{1}^{1} \\ f_{2}^{1} \\ f_{3}^{1} \\ f_{4}^{1} \end{bmatrix} - \begin{bmatrix} q_{1}^{1} \\ 0 \\ 0 \\ q_{4}^{1} \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} f_{1}^{1} - q_{1}^{1} \\ f_{2}^{1} \\ f_{3}^{1} \\ f_{4}^{1} - q_{4}^{1} \end{bmatrix}$$

• Para *e* = 2:

$$F^{2} = f^{2} - q^{2} - \bar{p}^{2} = \begin{bmatrix} f_{1}^{2} \\ f_{2}^{2} \\ f_{3}^{2} \\ f_{4}^{2} \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} f_{1}^{2} \\ f_{2}^{2} \\ f_{3}^{2} \\ f_{4}^{2} \end{bmatrix}$$

Para *e* = 3:

$$F^{3} = f^{3} - q^{3} - \bar{p}^{3} = \begin{bmatrix} f_{1}^{3} \\ f_{2}^{3} \\ f_{3}^{3} \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} \bar{p}_{1}^{3} \\ \bar{p}_{2}^{3} \\ \bar{p}_{3}^{3} \end{bmatrix} = \begin{bmatrix} f_{1}^{3} - \bar{p}_{1}^{3} \\ f_{2}^{3} - \bar{p}_{2}^{3} \\ f_{3}^{3} - \bar{p}_{3}^{3} \end{bmatrix}$$

Referências I





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- Liu, I.S.; Rincon, M.A.. Introdução ao Método de Elementos Finitos, Análise e Aplicação. IM/UFRJ, 2003.