

Lab 6

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Nonlinear Dynamic Systems , Fall 2020

Experiment goals:

- Introduce dynamical systems and flows
- Model simple trajectory and observe initial condition changes

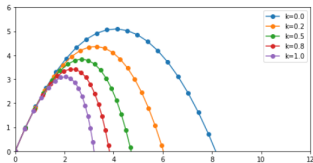
Why is this important?

- Many systems in the real world are continuous and multidimensional in nature

Trajectories

In the lab we simulated projectile motion through solving the differential equations that arise when applying newton's laws to this case.

```
fig, ax = plt.subplots(1, 1, figsize=(8, 4))
t = np.linspace(0., 3., 30)
for k in np.linspace(0., 1., 5):
    v = spi.odeint(f, v0, t, args=(k,)) #iteratively solves differential equation
    ax.plot(v[:, 0], v[:, 1], 'o-', label=f'k={k:.1f}') #plot each
ax.legend()
ax.set_xlim(0, 12)
ax.set_ylim(0, 6)
```



In conclusion, this system does not demonstrate chaotic behavior. This continuous model was solved by solving differential equations of the motion of the projectile.