CS-E4820 Machine Learning: Advanced Probabilistic Methods (spring 2020)

Pekka Marttinen, Santosh Hiremath, Marko Järvenpää, Tianyu Cui, Yogesh Kumar, Diego Mesquita, Zheyang Shen, Alexander Aushev, Khaoula El Mekkaoui, Joakim Järvinen.

Assignment 9, due on Tuesday, 31st March at 23:55.

SVI for linear regression using PyTorch

In this exercise, we will see how to use stochastic variational inference (especially the pathwise estimator) to solve linear regression problem using autograd in PyTorch.

Bayesian Linear Regression

The model is defined as follows:

$$
\begin{aligned}
&y_i \sim \mathcal{N}(w_0 + w_1 x_i, \sigma_l^2), \quad x_i \in \mathbb{R}, \sigma_l = 5, i = 1, \ldots, N \\
&\mathbf{w} \sim \mathcal{N}(0, \alpha^2 I).
\end{aligned}
$$

Note: The data noise is large because the true model used to generate the data is more complex to which we are going to fit a linear model.

Given data $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^N$, we are interested in the posterior distribution $p(\mathbf{w}|\mathcal{D})$ which we approximate using mean-field approximation:

$$
p(\mathbf{w}|\mathcal{D}) \approx q(\mathbf{w}) = \prod_{d=0}^{1} q(w_d) = \prod_{d=0}^{1} \mathcal{N}(w_d|\mu_d, \sigma_d^2)
$$

That is, we model each w_d as an independent Gaussian with mean μ_d and σ_d^2 and use SVI to optimize them such that:

$$
\begin{aligned}
\hat{\lambda} &= \text{argmin}_\lambda \text{KL}[q(\mathbf{w})|p(\mathbf{w}|\mathcal{D})] &(1)\\
&= \text{argmin}_\lambda \underbrace{\mathbb{E}_{q_\lambda(\mathbf{w})}\left[-\log p(\mathcal{D}|\mathbf{w})\right] + \text{KL}\left[q(\mathbf{w})|p(\mathbf{w})\right]}_{Loss=-ELBO} + c. &(2)
\end{aligned}
$$

Here, the variational parameters are denotd by $\lambda = \{(\mu_d, \sigma_d), i = 0, 1\}$. The first term of the ELBO is the expected log likelihood, which will be estimated using pathwise estimator and the second term is the KL between the approximate posterior $q_\lambda(\mathbf{w})$ and the prior $p(\mathbf{w})$ that can be derived analytically in this case. We will solve this problem in three steps given as three problem below. In the first two problems we derive the two terms of the Loss which, in problem 3 are implemented using the pathwise estimator in PyTorch.

Problem 1: Negative log-likelihood

Write the negative log-likelihood (whose expectation is the first term in the Loss) as a scaled mean squared error.

Solution

$$-\log p(\mathcal{D}|\mathbf{w}) = -\sum_{i=1}^{N} \log \mathcal{N}(y_i|w_0 + w_1 x_i, \sigma_l^2) \tag{3}$$

$$\approx \frac{1}{2\sigma_l^2} \sum_{i=1}^{N} (y_i - w_0 - w_1 x_i)^2 \tag{4}$$

Problem 2: Derive KL Divergence

Derive the analytic solution of $\mathrm{KL}[q_\lambda(\mathbf{w})|p(\mathbf{w})]$. This will be required in Problem 3.

Hint: Given $\mathbf{w}$ is a MVN with diagonal covarience and the mean-field approximation of $q_\lambda(\mathbf{w})$, the KL divergence for both the components of $\mathbf{w} = (w_0, w_1)$ will have the same form. So this reduces to deriving the KL between two univariate Guassians.

Solution

Given that the prior $p(\mathbf{w})$ is an MVN with diagonal covariance and the mean-fild approximation of the posterior $q_\lambda(\mathbf{w})$, the KL simplifies as follows:

$$\mathrm{KL}[q_\lambda(\mathbf{w})|p(\mathbf{w})] = \mathrm{KL}_0\left[q(w_0)|p(w_0)\right] + \mathrm{KL}_1\left[q(w_1)|p(w_1)\right]$$

where each term has the following form

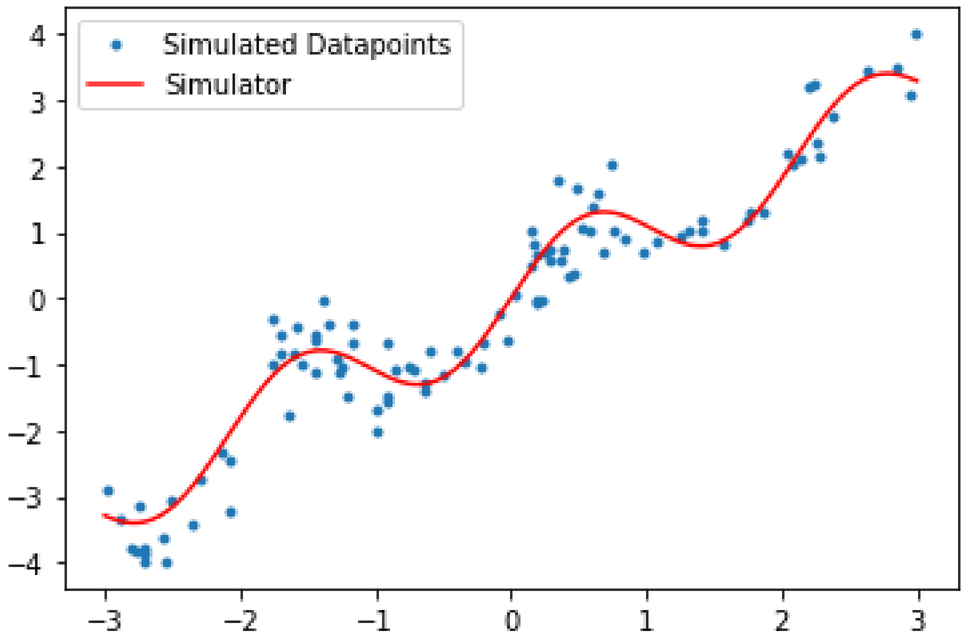
$$\begin{aligned}
\mathrm{KL}[q(w;\mu,\sigma)|p(w)] &= \int q(w;\mu,\sigma)\log q(w;\mu,\sigma)dw - \int q(w;\mu,\sigma)\log p(w)dw \\
&= -\frac{1}{2}(1+\log 2\pi\sigma^2) - \int q(w;\mu,\sigma)\log \frac{1}{\sqrt{2\pi\sigma_w^2}} e^{-\frac{w^2}{2\alpha^2}} dw \\
&= -\frac{1}{2}(1+\log 2\pi\sigma^2) + \frac{1}{2}\log 2\pi\alpha^2 + \frac{1}{2\alpha^2}\int q(w;\mu,\sigma)w^2 dw \\
&= -\frac{1}{2} + \log\frac{\alpha}{\sigma} + \frac{\mu^2+\sigma^2}{2\alpha^2}
\end{aligned}$$

Problem 3: Pathwise Estimator in PyTorch

Complete the code template below that implements the pathwise estimator.

[1]:
```
# Starter code for problem 3
# We first simulate the data using following simulator to generate our training␣
↪and test data:
# $y_i=x_i+0.7\sin(3x_i)+\epsilon,$ where $\epsilon\sim\mathcal{N}(0,0.16)$
import numpy as np
import torch
import torch.nn as nn
import torch.optim as optim
import matplotlib.pyplot as plt
# We define a function to generate the data according to the simulator
def data_generation(num_data, interval):
    x = np.random.rand(num_data,1) * (interval[1] - interval[0]) + interval[0]
    e = np.random.randn(num_data,1) * 0.4
    y =  x + 0.7 * np.sin(3 * x) + e
    return torch.tensor(x, dtype=torch.float), torch.tensor(y, dtype=torch.float)
# Generate the 100 data points with x in [-3, 3] for training, validation, and␣
↪test dataset.
interval = [-3,3]
num_data = 100
x_train, y_train = data_generation(num_data, interval)
x_val, y_val = data_generation(num_data, interval)
x_test, y_test = data_generation(num_data, interval)
# Visulize the data
fig, ax = plt.subplots()
x_plot = torch.linspace(-3., 3., 1000)
y_plot = x_plot + 0.7 * torch.sin(3 * x_plot)
ax.plot(x_train, y_train, '.')
ax.plot(x_plot, y_plot, '-', color='red')
ax.legend(('Simulated Datapoints','Simulator'))
```

[1]:
```
<matplotlib.legend.Legend at 0x7fd4c26480b8>
```



[5]:
```
# template for problem 3
# We define a multivariate Bayesian linear regression model, which has input_dim␣
↪features and output_dim outputs
class linear_regression(nn.Module):
    def __init__(self, input_dim, output_dim, sigma = 1.):
        super(linear_regression, self).__init__()
        # Define the input and output dimension of the LR model
        # In this example, input_dim and output_dim are both 1;
        # They can be other integers when this class is used as the Bayesian␣
↪neural network layers
        self.input_dim = input_dim
        self.output_dim = output_dim
        # set standard deviation of the prior (the $\sigma_w$)
        self.sigma = sigma
        scale = 1. * np.sqrt(6. / (input_dim + output_dim))
        # EXERCISE: Initialize the approximated posterior distribution over the␣
↪weight and bias terms
        # (i.e. specify values for the corresponding variational parameters).
        # All the weights are assumed independent from each other.
        # Initialize the mean parameters from a uniform distribution over␣
↪(-scale, scale) to improve stability.
        # Instead of parametrizing the standard deviation sigma directly, we␣
↪parametrize it using rho:
        # sigma = log(1 + exp(rho)) to keep it positive during training.
```

```
        # This way we don't need to use a positivity constraint during␣
↪optimization.
        self.mu_bias = nn.Parameter(torch.Tensor(self.output_dim).
↪uniform_(-scale, scale)) # given as example
        # self.rho_bias = ?
        # self.mu_weights = ?
        # self.rho_weights = ?
        ### BEGIN SOLUTION
        self.rho_bias = nn.Parameter(torch.Tensor(self.output_dim).uniform_(-4,␣
↪-2))
        self.mu_weights = nn.Parameter(torch.Tensor(self.input_dim, output_dim).
↪uniform_(-scale, scale))
        self.rho_weights= nn.Parameter(torch.Tensor(self.input_dim, self.
↪output_dim).uniform_(-4, -2))
        ### END SOLUTION
    def forward(self, x, stochastic_flag):
        eps = 1e-7
        # Compute the standard deviation according to previous parametrization.
        sigma_weights= torch.log(1 + torch.exp(self.rho_weights))
        sigma_bias = torch.log(1 + torch.exp(self.rho_bias))
        if stochastic_flag:
            # stochastic forward pass during training
            # EXERCISE: Sample one set of weights from the current posterior␣
↪approximation.
            # These sampled weights will then be used to complete a forward pass␣
↪for a mini-batch of data.
            # Hints: you should first generate a sample from a standard normal
            # distribution (epsilon-weights, epsilon-bias) and transform it to␣
↪the
            # posterior distribution (weights, bias) according to the posterior␣
↪mean
            # and variance (this is the 'reparametrization trick')
            epsilon_bias = torch.randn(self.output_dim) # shown as an example
            # epsilon_weights = ?
            # bias = ?
            # weights = ?
            ### BEGIN SOLUTION
            epsilon_weights = torch.randn(self.input_dim, self.output_dim)
            bias = self.mu_bias +  sigma_bias * epsilon_bias
            weights = self.mu_weights +  sigma_weights * epsilon_weights
            ### END SOLUTION
            # forward pass for a mini-batch
            output = torch.mm(x, weights) + bias
        else:
            # forward pass with the mean of posterior distribution during testing
            output = torch.mm(x, self.mu_weights) + self.mu_bias
```

```
        # calculate KL
        # EXERCISE: calculate the KL divergence between the prior and the␣
 ↪posterior
        # Hint: It is the solution you have computed in problem 1; the summation
        # of the KL between two one dimensional Gaussian distributions
        # KL_weights = ?
        # KL_bias = ?
        ### BEGIN SOLUTION
        KL_weights = torch.sum((sigma_weights ** 2 + self.mu_weights ** 2) / (2␣
 ↪* self.sigma ** 2)
                               - torch.log(sigma_weights + eps) + np.log(self.
 ↪sigma) - 0.5)
        KL_bias = torch.sum((sigma_bias ** 2 + self.mu_bias ** 2) / (2 * self.
 ↪sigma ** 2)
                            - torch.log(sigma_bias + eps) + np.log(self.sigma) -␣
 ↪0.5)
        ### END SOLUTION
        KL = KL_weights + KL_bias
        return output, KL
def training(blr, x, y, x_test, y_test, sigma_l, learning_rate = 0.001,␣
 ↪batch_size = 10, num_epoch=100):
    # Set the parameters that you want to optimize during training
    parameters = set(blr.parameters())
    # We use Adam to do optimization, with learning rate equals to␣
 ↪learning_rate, eps is used to stablize the training
    optimizer = optim.Adam(parameters, lr = learning_rate, eps=1e-3)
    # We use MSE loss since it's a regression problem
    criterion = nn.MSELoss()
    train_errors = []
    val_errors = []
    num_data, num_dim = x.shape
    y = y.view(-1, 1)
    data = torch.cat((x, y), 1)
    for epoch in range(num_epoch):
        # We permute the data for each epoch to decorrelate the training process
        data_perm = data[torch.randperm(len(data))]
        x = data_perm[:, 0:-1]
        y = data_perm[:, -1]
        for index in range(int(num_data/batch_size)):
            inputs = x[index*batch_size : (index+1)*batch_size]
            labels = y[index*batch_size : (index+1)*batch_size].view(-1,1)
            optimizer.zero_grad()
            # Forward passing for one mini-batch of data, and calculate the KL
            output, kl = blr(inputs, stochastic_flag=True)
            # Exercise: Calculate the value of the loss, the negative
            # ELBO, from the outputs of the linear regression model (output, kl)
```

```
            # Hint: the expected negative log-likelihood can be estimated by the␣
↪MSE
            # divided by (2*variance) for Gaussian likelihood functions␣
↪(allowing
            # you to use the 'criterion' defined above).
            # loss = ?
            ### BEGIN SOLUTION
            loss =  criterion(labels, output) * num_data / (2. * sigma_l ** 2) +␣
↪ kl
            ### END SOLUTION
            # backpropogate the gradient
            loss.backward()
            # optimize with SGD
            optimizer.step()
        # calculate the training loss after one epoach
        output_x, _= blr(x, stochastic_flag = False)
        train_errors.append(criterion(output_x, y.view(-1,1)))
        # calculate the validation loss after one epoach
        output_x_test, _ = blr(x_test, stochastic_flag = False)
        val_errors.append(criterion(output_x_test, y_test.view(-1,1)))
        if (epoch % 100) == 0:
            print('EPOACH %d: TRAIN LOSS: %.4f; VAL LOSS IS: %.5f.'% (epoch+1,␣
↪train_errors[epoch], val_errors[epoch]))
# train the model
num_input = 1; num_output = 1
BLR = linear_regression(num_input, num_output)
# Setting all the hyper-parameters
learning_rate = 1e-2
batch_size = 50; num_epoch = 500; sigma_l = 5
training(BLR, x_train, y_train, x_val, y_val, sigma_l, learning_rate,␣
↪batch_size, num_epoch)
```

[6]:
```
## test the trained BLR
# We calculate the true values of x_plot
x_plot = torch.linspace(-3., 3., 1000)
y_plot = x_plot + 0.7 * torch.sin(3 * x_plot)

# One benefit of being a Bayesian is that you can capture the predictive␣
↪uncertainty:
# Use the stochastic forward passing during prediction, and calculate the sample␣
↪mean and
# sample standard deviation of predictions for different sets of weights.
iteration = 100;
x_pred = []
for i in range(iteration):
    stochastic_flag = True
```

```
    x_pred.append(BLR(x_plot.view(-1,1), stochastic_flag)[0].view(-1).tolist())
x_pred = np.array(x_pred)
# Calculate the mean and standard deviation of prediction according to the␣
 ↪samples
x_pred_mean = np.mean(x_pred, axis = 0)
x_pred_std = np.std(x_pred, axis = 0)
fig, ax = plt.subplots()
ax.plot(x_train, y_train, '.')
ax.plot(x_plot, y_plot, '-', color='red')
# Draw the mean of the prediction and also corresponding 95% crediable intervals.
ax.plot(x_plot, x_pred_mean, '-', color = 'deepskyblue')
ax.plot(x_plot, x_pred_mean - 2 * x_pred_std, '-', color = 'skyblue')
ax.plot(x_plot, x_pred_mean + 2 * x_pred_std, '-', color = 'skyblue')
ax.legend(('Simulated Datapoints','Simulator', 'Prediction Mean', '95%␣
 ↪Prediction CI'))
# We can see that Bayesian linear regression cannot fit the data perfectly,␣
 ↪because the simulator
# that generates the data is nonlinear. However, the 95% crediable interval␣
 ↪covers the true target
# nearly all the time (95%), which means we can still know the possible interval␣
 ↪of the target
# even the model is misspecified.
```

[6]: <matplotlib.legend.Legend at 0x7fd4bd3e0ba8>