

Accuracy of original MPM

Lisa Wobbes, Roel Tielen

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Outline

- “Original” MPM
- Numerical accuracy
- Benchmarks
 - Vibrating bar
 - Oedometer
- Sources of spatial errors
 - Analogy with FEM
 - Grid crossing
- Outlook

“Original” MPM

- Modified Lagrangian algorithm
- Euler-Cromer time integration
- Piecewise linear basis functions
- No additional interventions

“Original” MPM

- Modified Lagrangian algorithm
- Euler-Cromer time integration
- Piecewise linear basis functions
- No additional interventions
- Own MATLAB implementation
- 1D (UL)FEM/MPM
- Simplified version of Deltares' code

Numerical accuracy

Numerical Approximation

$$u_{ex} = u_{num} + O(\Delta x^n) + O(\Delta t^m)$$

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Example

n	Grid size	Error
	Δx	E
1	$\Delta x/2$	$E/2$

Numerical accuracy

Numerical Approximation

$$u_{ex} = u_{num} + O(\Delta x^n) + O(\Delta t^m)$$

Example

n	Grid size	Error
	Δx	E
2	$\Delta x/2$	$E/4$

Numerical accuracy

Numerical Approximation

$$u_{ex} = u_{num} + O(\Delta x^n) + O(\Delta t^m)$$

Example

n	Grid size Δx	Error E
2	$\Delta x/2$	$E/4$

RMS Error

$$Error_{RMS} = \sqrt{\frac{1}{n_p} \sum_{p=1}^{n_p} \left(u_{num}(x_p, t) - u_{ex}(x_p, t) \right)^2}$$

Numerical Accuracy

Temporal accuracy

MPM is first order accurate in time, i.e. $m = 1$.

Numerical Accuracy

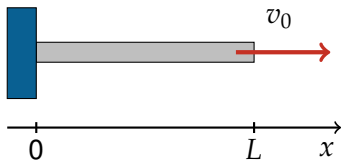
Temporal accuracy

MPM is first order accurate in time, i.e. $m = 1$.

Spatial accuracy

Order of spatial accuracy	Source
2	Gong (2015); Steffen (2008)
0.5 - 1	Tran (2010)
lack of spatial convergence	Gong (2015); Steffen (2008)

Vibrating bar



$$\frac{\partial^2 u}{\partial t^2} = \frac{E}{\rho} \frac{\partial^2 u}{\partial x^2}$$

Boundary conditions:

$$u(0, t) = 0$$

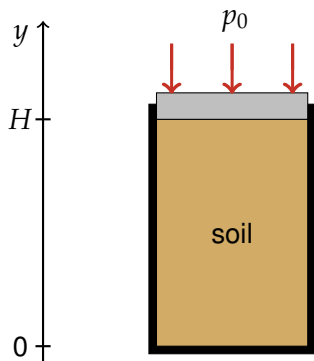
$$\frac{\partial u}{\partial x}(L, t) = 0$$

Initial conditions:

$$u(x, 0) = 0$$

$$\frac{\partial u}{\partial t}(x, 0) = v_0 \sin\left(\frac{\pi x}{2L}\right)$$

Oedometer



$$\frac{\partial^2 u}{\partial t^2} = \frac{E}{\rho} \frac{\partial^2 u}{\partial y^2} - g$$

Boundary conditions:

$$u(0, t) = 0$$

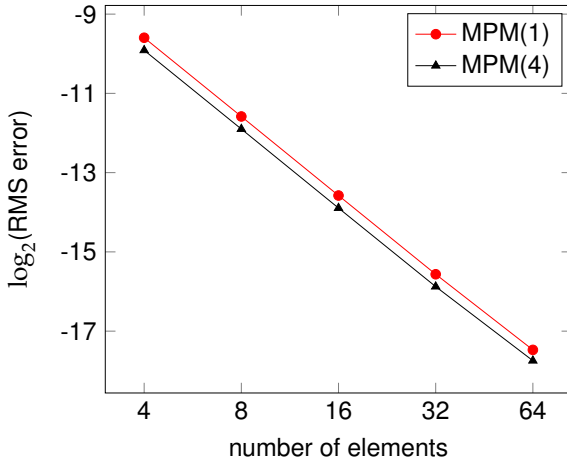
$$\frac{\partial u}{\partial y}(H, t) = \frac{p_0}{E}$$

Initial conditions:

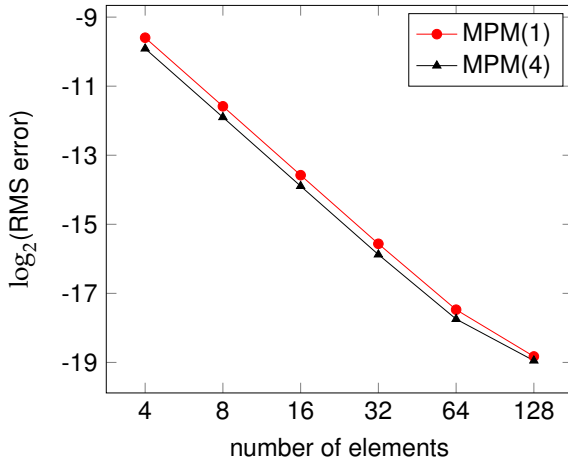
$$u(y, 0) = 0$$

$$\frac{\partial u}{\partial t}(y, 0) = 0$$

Accuracy: vibrating bar



Accuracy: vibrating bar

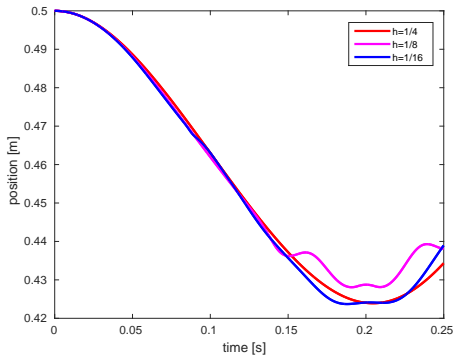


Accuracy: oedometer

Richardson's extrapolation

The order of accuracy n is obtained from

$$\frac{u_{num}(2h) - u_{num}(4h)}{u_{num}(h) - u_{num}(2h)} = 2^n.$$



Accuracy: oedometer

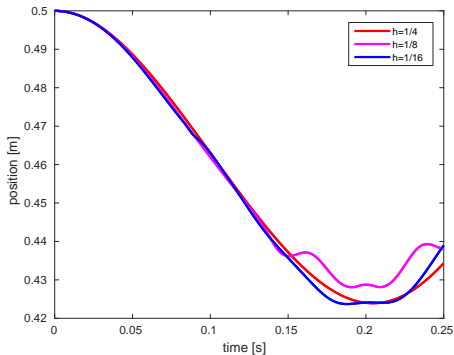
Richardson's extrapolation

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Conclusion

Lack of spatial convergence.



FEM: oedometer

Theoretical order of accuracy

$k + 1$, where k is the order of the interpolating polynomials¹.

¹Van Kan (2008)

FEM: oedometer

Theoretical order of accuracy

$k + 1$, where k is the order of the interpolating polynomials¹.

Observations

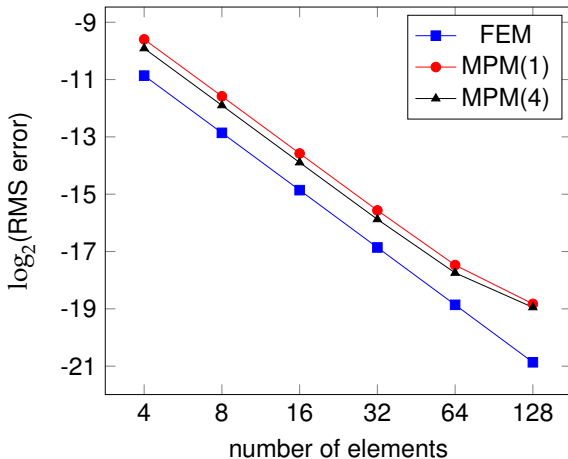
- Lack of spatial convergence
- Problems arise due to external forces

$$\mathbf{M} \frac{d\mathbf{v}}{dt} = \mathbf{F}_{ext} - \mathbf{F}_{int},$$

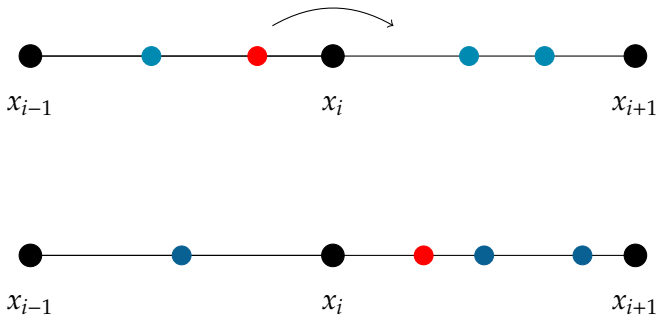
$$\text{where } \mathbf{F}_{ext} = \mathbf{N}(H)^T p_0 - \int_0^H \mathbf{N}^T \rho g dy$$

¹Van Kan (2008)

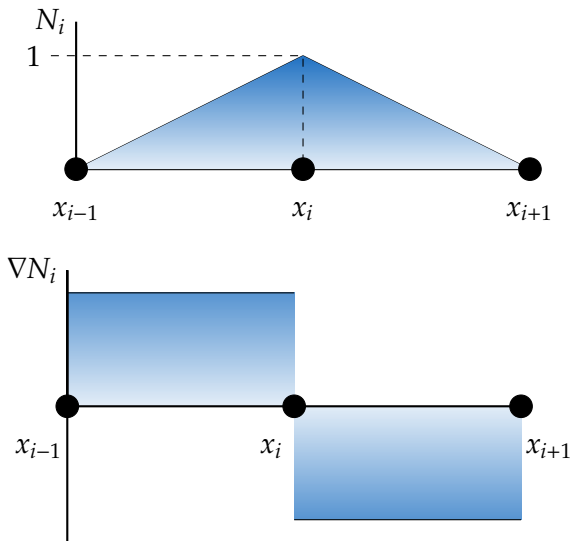
FEM: vibrating bar



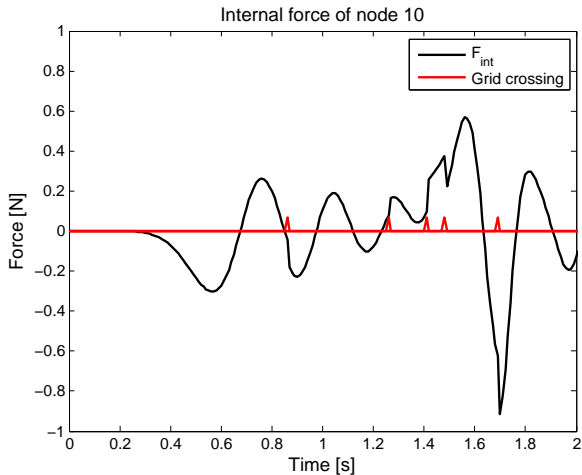
Grid-crossing



Grid-crossing: properties of shape functions



Grid crossing: internal force



Grid crossing: vibrating bar

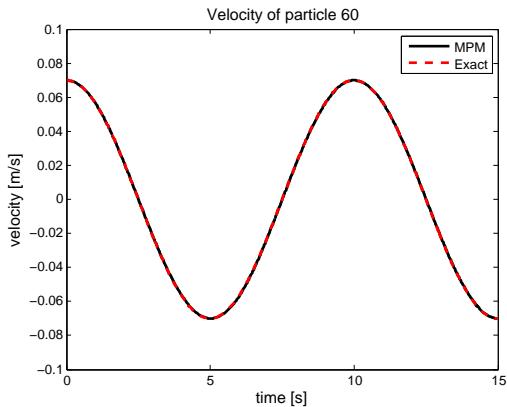


Figure: No grid crossing (30 elements).

Grid crossing: vibrating bar

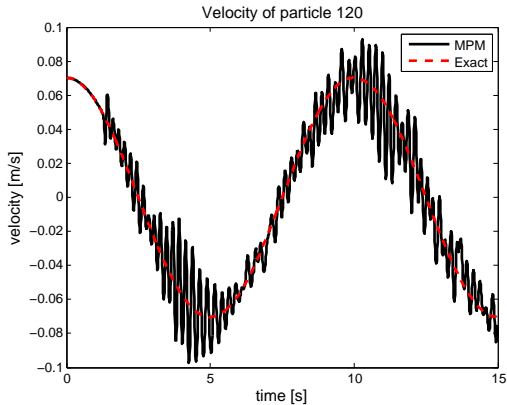
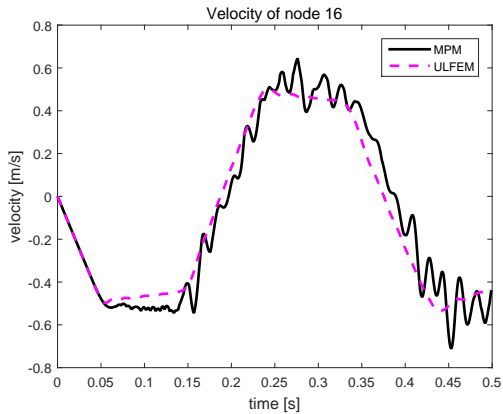


Figure: Grid crossing (60 elements).

Grid crossing: oedometer



Main sources of spatial errors

Presented today

- Errors arising due to external forces
- Grid crossing errors

Other sources²

- Mass mapping error
- Momentum mapping error
- Force mapping error

²Tran (2010)

Conclusions

Vibrating bar

Second order accuracy: unless particles cross element boundaries.

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Oedometer

Lack of convergence: due to external forces and grid crossing.

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Vibrating bar

Second order accuracy: unless particles cross element boundaries.

Oedometer

Lack of convergence: due to external forces and grid crossing.

Both problems

Other error sources can be involved.

Outlook

- External forces: further analysis

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Outlook

- External forces: further analysis
- Other sources of spatial error
- Higher order interpolation functions
- 2D MPM code in MATLAB
- Deltares' implementation: analysis and recommendations

References

- Gong M. *Improving the Material Point Method*. The University of New Mexico, July, 2015.
- Van Kan J., Segal A., Vermolen F. *Numerical methods in scientific computing*. Delft University of Technology, 2008.
- Steffen M., Kirby R. M., Berzins M. *Analysis and reduction of quadrature errors in the material point method (MPM)*. International Journal for Numerical Methods in Engineering 76, pp. 922-946, 2008.
- Tran L.T., Kim J., Berzins M. *Solving time-dependent PDEs using the material point method, a case study from gas dynamics*. International Journal for Numerical Methods in Fluids 62, pp. 709-732, 2010.

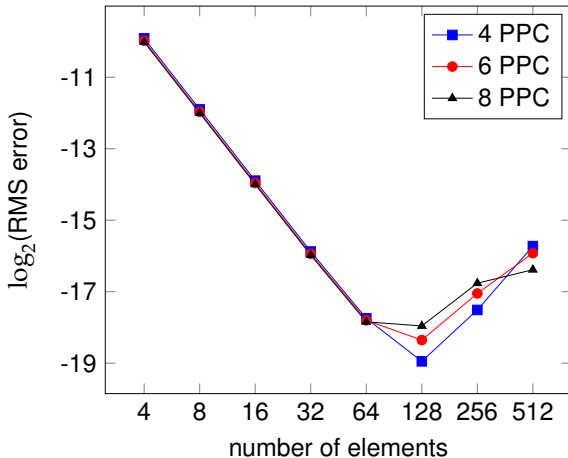
Grid crossing: internal force

$$F_{i+1}^{int} \approx \sum_{p=1}^{n_i} \nabla N_i(\xi_p) \sigma_p \Omega_p + \sum_{p=1}^{n_{i+1}} \nabla N_i(\xi_p) \sigma_p \Omega_p$$

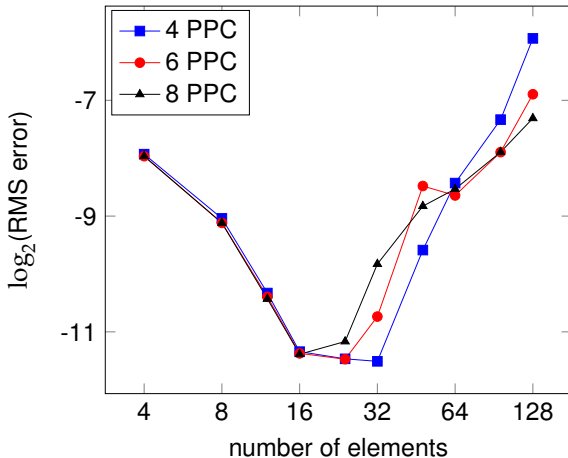
$$F_{i+1}^{int} \approx \sigma \Omega (n_i - n_{i+1})$$

$$\begin{cases} F_{i+1}^{int} = 0, & \text{if } n_i = n_{i+1} \\ F_{i+1}^{int} \neq 0, & \text{otherwise} \end{cases}$$

Depenence on PPC: vibrating string



Depenence on PPC: oedometer



Settings: vibrating bar

	Symbol	Value	Unit
Length	L	25	m
Tension	E	100	Pa
Density	ρ	1	kg/m ³
Maximum velocity	v_0	0.1	m/s
Time step	Δt	$1 \cdot 10^{-3}$	s
Measurement time ¹	t	0.5	s
PPC ²		4	

Settings: oedometer

	Symbol	Value	Unit
Height	L	1	m
Young's modulus	E	$1 \cdot 10^5$	Pa
Density	ρ	$1 \cdot 10^3$	kg/m ³
Load	p_0	0	Pa
Gravitational acceleration	g	9.81	m/s ²
Time step	Δt	$1 \cdot 10^{-3}$	s
Measurement time ¹	t	0.5	s
Position particle ¹	x_p	≈ 0.5	m
Number of elements ²		30	
PPC ²		10	

Settings: Steffen

	Symbol	Value	Unit
Length	L	1	m
Tension	E	100	Pa
Density	ρ	100	kg/m ³
Load	p_0	0.7	Pa
Gravitational acceleration	g	0	m/s ²
Time step	Δt	$1 \cdot 10^{-2}$	s
Domain		1.15	m
Number of elements		20	
PPC		10	