Accuracy of original MPM

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  - Vibrating bar
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Numerical accuracy

Numerical Approximation

$$u_{ex} = u_{num} + \mathcal{O}(\Delta x^n) + \mathcal{O}(\Delta t)$$

RMS Error

$$Error_{RMS} = \sqrt{\frac{1}{n_p}\left(\sum_{p=1}^{n_p} u_{num}(x_p, t) - u_{ex}(x_p, t)\right)^2}$$

Accuracy in displacement

For $\Delta t \rightarrow 0$, the order of accuracy is equal to n, i.e. the reduction of Δx by a factor of 2 decreases the RMS error by 2^n.

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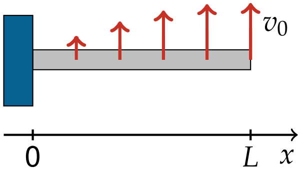
Vibrating bar



$$\frac{\partial^2 u}{\partial t^2} = \frac{E}{\rho}\frac{\partial^2 u}{\partial x^2}$$

Boundary conditions:

$$u(0,t) = 0$$

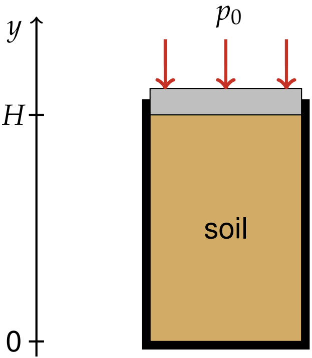
$$\frac{\partial u}{\partial x}(L,t) = 0$$

Initial conditions:

$$u(x,0) = 0$$

$$\frac{\partial u}{\partial t}(x,0) = v_0 \sin\left(\frac{\pi x}{2L}\right)$$

Oedometer



$$\frac{\partial^2 u}{\partial t^2} = \frac{E}{\rho}\frac{\partial^2 u}{\partial^2 x} - g$$

Boundary conditions:

$$u(0,t) = 0,$$

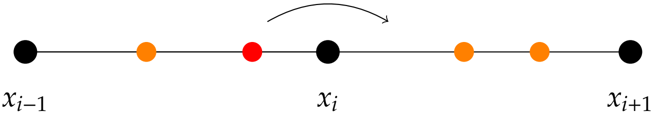
$$\frac{\partial u}{\partial x}(L,t) = \frac{p_0}{E}$$

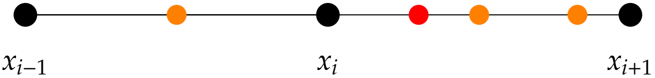
Initial conditions:

$$u(x,0) = 0$$

$$\frac{\partial u}{\partial t}(x,0) = v_0 \sin\left(\frac{\pi x}{2L}\right)$$

Grid-crossing





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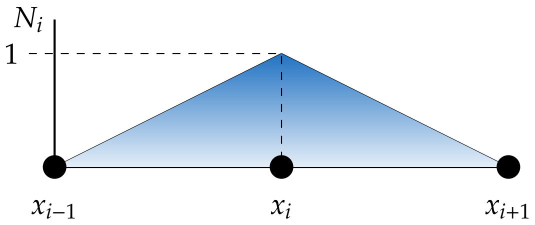
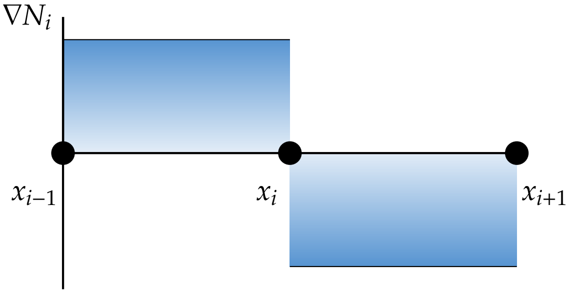
Grid-crossing: properties of shape functions





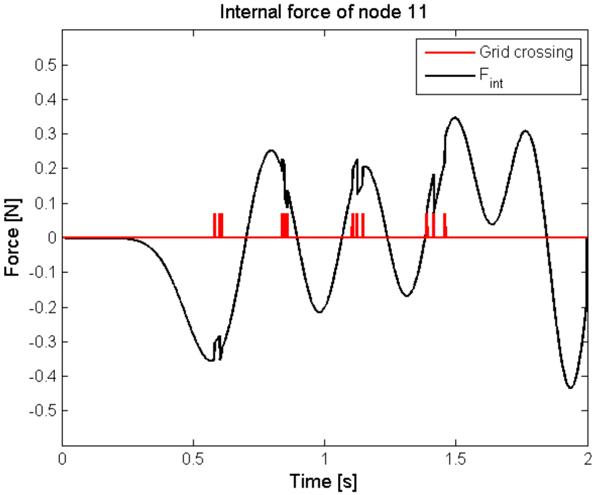
Grid crossing: internal force

$$F_{i+1}^{int} \approx \sum_{p=1}^{n_i} \nabla N_i(\xi_p)\sigma_p\Omega_p + \sum_{p=1}^{n_{i+1}} \nabla N_i(\xi_p)\sigma_p\Omega_p$$

$$F_{i+1}^{int} \approx \sigma\Omega(n_i - n_{i+1})$$

$$\begin{cases} F_{i+1}^{int} = 0, & \text{if } n_i = n_{i+1} \\ F_{i+1}^{int} \neq 0, & \text{otherwise} \end{cases}$$

Grid crossing: internal force



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Grid crossing: vibrating bar

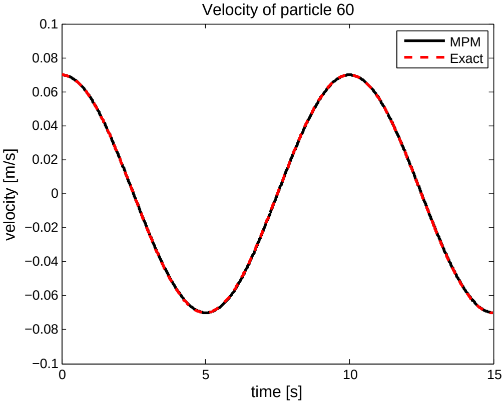

Figure: No grid crossing (30 elements).

Grid crossing: vibrating bar

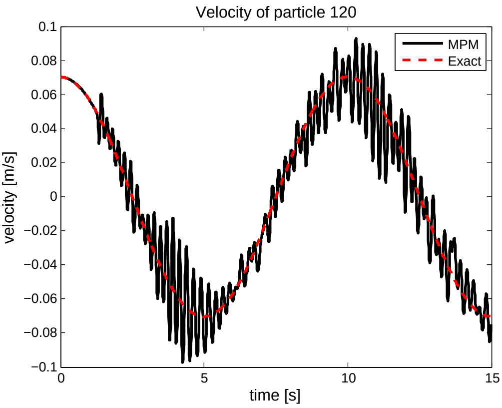

Figure: Grid crossing (60 elements).

Grid crossing: oedometer