

# Introduction to Numpy





聚合操作:Min、Max及 其他



NumPy陣列基礎



在陣列上的計算:



Universal Functions

Broadcasting

# Numerical Python

Numpy的陣列就像是Python內建的list,但是當陣列很大時,Numpy提供更有效率的儲存和工作

```
In [1]: 1 import numpy as np
2 np.__version__

Out[1]: '1.15.4'

In [ ]: 1 np.

abs
absolute
absolute_import
add
add_docstring
add_newdoc
add_newdoc
```

```
/* C code */
int result = 0;
for(int i=0; i<100; i++){
   result += i;
}</pre>
```

While in Python the equivalent operation could be

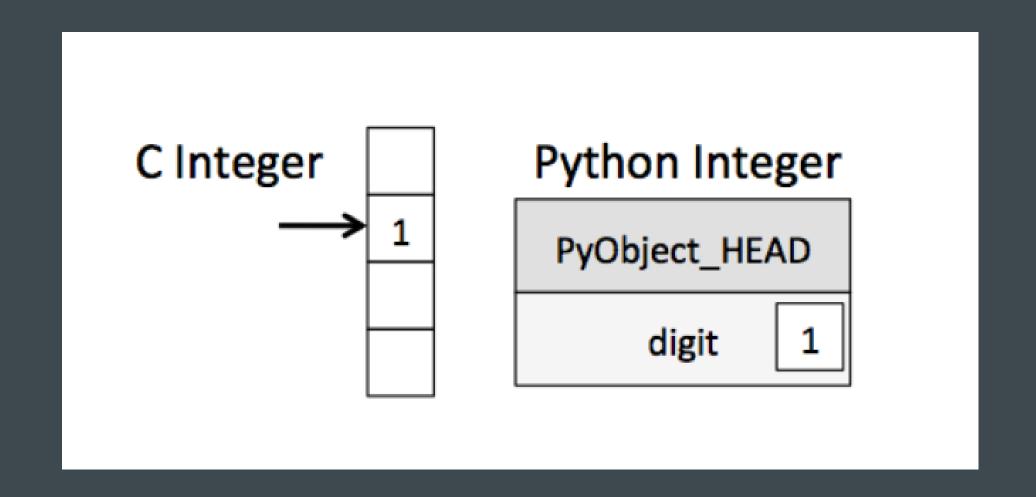
```
# Python code
result = 0
for i in range(100):
    result += i
```

```
# Python code
x = 4
x = "four"
```

Here we've switched the contents of x from an in thing in C would lead (depending on compiler sett other unintented consequences:

```
/* C code */
int x = 4;
x = "four"; // FAILS
```

Python的型態是動態推導的,也就是Python的變數不會只儲存值,必須包含關於型別的額外資訊



Python是以C語言寫成,表示每一個Python物件都是一個精巧設計的C結構,因此Python相對來說在儲存整數時多了一些額外的負擔。這些額外的資訊讓 Python可以自由及動態的編寫程式碼,然而也需要付出成本

```
In [5]: 1 L3 = [True, '2', 3.0, 4]
2 [type(item) for item in L3]
Out[5]: [bool, str, float, int]
```

Python的list中每個項目都必須包含它的型態資訊、參考計數和其他的資訊,即每個項目都是完整的Python物件,然而當大部分的資料型態相同時,大部分的資訊都是多餘的

```
In [8]: 

import array #python 3.3以後內建

A = array.array('i',L)

A #'i' means following content's type is interger

Out[8]: array('i', [0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
```

```
In [9]:
          1 | np.array([3.14,2,3])
          2 #統一被轉成float
Out[9]: array([3.14, 2. , 3. ])
In [10]:
          1 #numpy.ndarray
          2 np.array([1,2,3,4],dtype='float32')
Out[10]: array([1., 2., 3., 4.], dtype=float32)
          1 np.array([range(i,i+3) for i in [2,4,6]])
In [11]:
Out[11]: array([[2, 3, 4],
                [4, 5, 6],
                [6, 7, 8]])
```

```
1 | np.array([1,4,2])
In [3]:
Out[3]: array([1, 4, 2])
       1 | np.array([2,3,'hello'])
In [4]:
Out[4]: array(['2', '3', 'hello'], dtype='<U11')
        1 | a = np.array([2,3,'hello'])
In [7]:
         2 a[0]+a[1]
Out[7]: '23'
```

NumPy限制所有陣列裡的內容需轉換成同樣的Type,如果不符合Numpy會自動將其轉換型態。也可以用dtype設定明確的資料型態

```
In [12]: # Create a length-10 integer array filled with zeros
          np.zeros(10, dtype=int)
Out[12]: array([0, 0, 0, 0, 0, 0, 0, 0, 0])
In [13]: # Create a 3x5 floating-point array filled with ones
          np.ones((3, 5), dtype=float)
Out[13]: array([[ 1., 1., 1., 1., 1.],
                [ 1., 1., 1., 1., 1.],
                [ 1., 1., 1., 1., 1.])
In [14]: # Create a 3x5 array filled with 3.14
          np.full((3, 5), 3.14)
Out[14]: array([[ 3.14, 3.14, 3.14, 3.14, 3.14],
                [ 3.14, 3.14, 3.14, 3.14, 3.14],
                [ 3.14, 3.14, 3.14, 3.14, 3.14]])
```

```
In [15]: # Create an array filled with a linear sequence
          # Starting at 0, ending at 20, stepping by 2
          # (this is similar to the built-in range() function)
          np.arange(0, 20, 2)
Out[15]: array([ 0, 2, 4, 6, 8, 10, 12, 14, 16, 18])
In [16]: # Create an array of five values evenly spaced between 0 and 1
          np.linspace(0, 1, 5)
Out[16]: array([ 0. , 0.25, 0.5 , 0.75, 1. ])
In [17]: # Create a 3x3 array of uniformly distributed
          # random values between 0 and 1
          np.random.random((3, 3))
Out[17]: array([[ 0.99844933, 0.52183819, 0.22421193],
                 [ 0.08007488, 0.45429293, 0.20941444],
                 [ 0.14360941, 0.96910973, 0.946117 ]])
```

```
In [17]: # Create a 3x3 array of uniformly distributed
          # random values between 0 and 1
          np.random.random((3, 3))
Out[17]: array([[ 0.99844933, 0.52183819, 0.22421193],
                 [ 0.08007488, 0.45429293, 0.20941444],
                 [ 0.14360941, 0.96910973, 0.946117 ]])
In [18]: # Create a 3x3 array of normally distributed random values
          # with mean 0 and standard deviation 1
          np.random.normal(0, 1, (3, 3))
Out[18]: array([[ 1.51772646, 0.39614948, -0.10634696],
                 [ 0.25671348, 0.00732722, 0.37783601],
                 [ 0.68446945, 0.15926039, -0.70744073]])
In [19]: # Create a 3x3 array of random integers in the interval [0, 10)
          np.random.randint(0, 10, (3, 3))
Out[19]: array([[2, 3, 4],
                 [5, 7, 8],
                 [0, 5, 0]])
```

```
In [20]:
          # Create a 3x3 identity matrix
          np.eye(3)
Out[20]: array([[ 1., 0., 0.],
                 [ 0., 1., 0.],
                 [0., 0., 1.]])
In [21]: # Create an uninitialized array of three
          # The values will be whatever happens to
          np.empty(3)
Out [21]: array([ 1., 1., 1.])
```

```
In [8]: 1 %memit np.ones(1000000)
    peak memory: 70.19 MiB, increment: 6.57 MiB
In [9]: 1 %memit np.empty(1000000)
    peak memory: 63.71 MiB, increment: 0.00 MiB
n [10]: 1 %memit np.zeros(1000000)
    peak memory: 63.72 MiB, increment: 0.00 MiB
```

bool\_ 布林值(True/False),以位元組來儲存

int16 整數 (-32768~32767)

int32 整數 (-2147483648 ~ 2147483647)

int32 整數 (-9223372036854775808 ~ 9223372036854775807)

float16 5位元指數,10位元尾數

float32 8位元指數,23位元尾數

float64 11位元指數,52位元尾數

```
In [1]:
         import numpy as np
         np.random.seed(0) # seed for reproducibility
         x1 = np.random.randint(10, size=6) # One-dimensional array
         x2 = np.random.randint(10, size=(3, 4)) # Two-dimensional array
         x3 = np.random.randint(10, size=(3, 4, 5)) # Three-dimensional array
         Each array has attributes ndim (the number of dimensions), shape (the size of
         each dimension), and size (the total size of the array):
In [2]:
         print("x3 ndim: ", x3.ndim)
         print("x3 shape:", x3.shape)
         print("x3 size: ", x3.size)
         x3 ndim: 3
         x3 shape: (3, 4, 5)
         x3 size: 60
```

```
In [5]: x1
Out[5]: array([5, 0, 3, 3, 7, 9])
In [6]: x1[0]
Out[6]: 5
```

```
In [9]: x1[-2]
Out[9]: 7
```

```
In [10]: x2
Out[10]: array([[3, 5, 2, 4],
                [7, 6, 8, 8],
                [1, 6, 7, 7]])
In [11]: x2[0, 0]
Out[11]: 3
In [12]: x2[2, 0]
Out[12]: 1
In [13]: x2[2, -1]
Out[13]: 7
```

```
In [15]: x1[0] = 3.14159 # this will be truncated!
x1
Out[15]: array([3, 0, 3, 3, 7, 9])
```

## A[a:b:c]

a:起始位置,默認0

b:結束位置,默認為size

c:每次步數,默認為1

```
In [16]: x = np.arange(10)
Out[16]: array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
In [17]: x[:5] # first five elements
Out[17]: array([0, 1, 2, 3, 4])
In [18]: x[5:] # elements after index 5
Out[18]: array([5, 6, 7, 8, 9])
In [19]: x[4:7] # middle sub-array
Out[19]: array([4, 5, 6])
In [20]: x[::2] # every other element
Out[20]: array([0, 2, 4, 6, 8])
In [21]: x[1::2] # every other element, starting at index 1
Out[21]: array([1, 3, 5, 7, 9])
```

## Question

```
input = 12345, type = int
output = 54321, type = int
```

```
In [16]:

1  print(x[::-1])
2  #當step是負值時start, step互換
3  print(x[5:2:-1])
4  print(x[2:5:-1])
5  print(x[5::-2])

[9 8 7 6 5 4 3 2 1 0]
[5 4 3]
[]
[5 3 1]
```

```
In [24]: x2
Out[24]: array([[12, 5, 2, 4],
               [7, 6, 8, 8],
               [1, 6, 7, 7]])
In [25]: x2[:2, :3] # two rows, three columns
Out[25]: array([[12, 5, 2],
               [7, 6, 8]])
In [26]: x2[:3, ::2] # all rows, every other column
Out[26]: array([[12, 2],
               [7, 8],
                [ 1, 7]])
         Finally, subarray dimensions can even be reversed together:
In [27]: x2[::-1, ::-1]
Out[27]: array([[ 7, 7, 6, 1],
               [8, 8, 6, 7],
                [ 4, 2, 5, 12]])
```

```
1 print(x2)
[24]:
       2 x2 sub = x2[:2,:2]
       3 print(x2 sub)
      [[3 5 2 4]
      [7 6 8 8]
      [1 6 7 7]]
     [[3 5]
      [7 6]]
       1 x2_{sub}[0,0] = 77
[27]:
       2 print(x2)
      [[77 5 2 4]
       [7 6 8 8]
       [1 6 7 7]]
       1 x2_sub_copy = x2[:2,:2].copy()
[28]:
       2 #With .copy(), the original value would not be changed
       3 print(x2_sub_copy)
       4 x2_sub_copy[0,0]=66
       5 print(x2_sub_copy)
       6 print(x2)
      [[77 5]
      [7 6]]
      [[66 5]
      [7 6]]
      [[77 5 2 4]
       [1 6 7 7]]
```

Numpy子陣列回傳的是視圖,不是複製一份出來, list則會直接複製子陣列的資料。

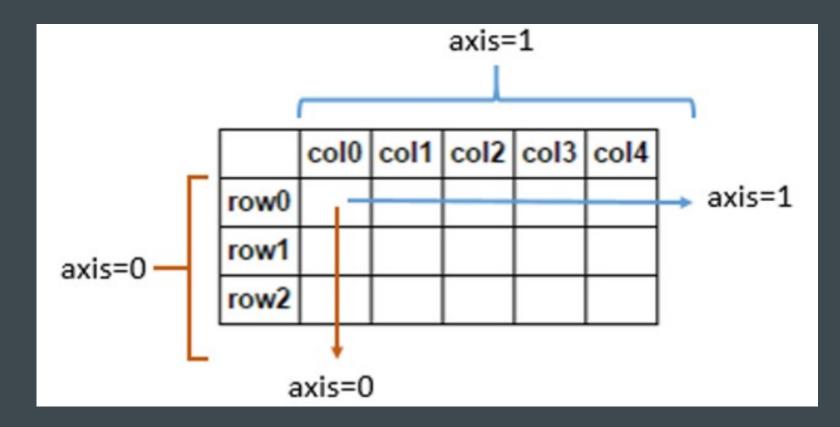
```
In [38]: grid = np.arange(1, 10).reshape((3, 3))
    print(grid)

[[1 2 3]
    [4 5 6]
    [7 8 9]]
```

```
In [53]: 1 x = np.array([1,2,3])
2 x.shape
Out[53]: (3,)
```

```
In [43]: x = np.array([1, 2, 3])
y = np.array([3, 2, 1])
np.concatenate([x, y])

Out[43]: array([1, 2, 3, 3, 2, 1])
```



from: Stack overflow debaonline4u

```
In [45]: grid = np.array([[1, 2, 3],
                           [4, 5, 6]])
In [46]: # concatenate along the first axis
          np.concatenate([grid, grid])
Out[46]: array([[1, 2, 3],
                 [4, 5, 6],
                 [1, 2, 3],
                 [4, 5, 6]])
In [47]: # concatenate along the second axis (zero
          np.concatenate([grid, grid], axis=1)
Out[47]: array([[1, 2, 3, 1, 2, 3],
                 [4, 5, 6, 4, 5, 6]])
```

```
In [48]: x = np.array([1, 2, 3])
          grid = np.array([[9, 8, 7],
                           [6, 5, 4]])
          # vertically stack the arrays
          np.vstack([x, grid])
Out[48]: array([[1, 2, 3],
                 [9, 8, 7],
                 [6, 5, 4]])
In [49]: # horizontally stack the arrays
          y = np.array([[99],
                        [99]])
          np.hstack([grid, y])
Out[49]: array([[ 9, 8, 7, 99],
                [ 6, 5, 4, 99]])
```

不同shape的話可以用vstack(vertical)或 hstack(horizontal)合併arrays

```
In [51]: grid = np.arange(16).reshape((4, 4))
          grid
Out[51]: array([[ 0, 1, 2, 3],
                [4, 5, 6, 7],
                [8, 9, 10, 11],
                [12, 13, 14, 15]])
In [52]: upper, lower = np.vsplit(grid, [2])
          print(upper)
          print(lower)
          [[0 1 2 3]
          [4 5 6 7]]
          [[ 8 9 10 11]
          [12 13 14 15]]
In [53]: left, right = np.hsplit(grid, [2])
          print(left)
          print(right)
          [[0 1]
          [45]
          [8 9]
          [12 13]]
          [[ 2 3]
          [67]
          [10 11]
          [14 15]]
```

NumPy在陣列中的計算可快可慢,要讓它的快速的關鍵在於使用向量化的操作, 通常都是透過NumPy的universal functions(ufuncs)

迴圈運算緩慢的原因不是來自於運算本身,而是每次迴圈都必須檢查該物件的 type,才會呼叫適合這個 type的函式

Note: (1)同一時間執行多次操作,通常是對不同的數據執行同樣的一個或一批指令 (2)記憶體儲存位置相近 (3)資料類型相同

```
In [7]: x = np.arange(4)
         print("x =", x)
         print("x + 5 = ", x + 5)
         print("x - 5 = ", x - 5)
         print("x * 2 =", x * 2)
         print("x / 2 = ", x / 2)
         print("x // 2 =", x // 2) # floor division
               = [0 1 2 3]
         x + 5 = [5 6 7 8]
         x - 5 = [-5 -4 -3 -2]
         x * 2 = [0 2 4 6]
         x / 2 = [0. 0.5 1. 1.5]
         \times // 2 = [0 \ 0 \ 1 \ 1]
         There is also a unary ufunc for negation, and a ** operator for
         and a % operator for modulus:
In [8]: print("-x = ", -x)
         print("x ** 2 = ", x ** 2)
         print("x % 2 = ", x % 2)
                = [ 0 -1 -2 -3]
         x ** 2 = [0 1 4 9]
         x \% 2 = [0 1 0 1]
```

```
np.add
        np.subtract
        np.negative
        np.multiply
        np.divide
        np.floor_divide
**
        np.power
        np.mod
```

```
In [11]: x = np.array([-2, -1, 0, 1, 2])
    abs(x)
Out[11]: array([2, 1, 0, 1, 2])
```

```
In [13]: np.abs(x)
Out[13]: array([2, 1, 0, 1, 2])
```

np.sin
np.cos
np.tan
np.arcsin
np.arccos
np.arctan

```
In [18]: x = [1, 2, 3]
print("x =", x)
print("e^x =", np.exp(x))
print("2^x =", np.exp2(x))
print("3^x =", np.power(3, x))
```

```
In [19]: x = [1, 2, 4, 10]
    print("x =", x)
    print("ln(x) =", np.log(x))
    print("log2(x) =", np.log2(x))
    print("log10(x) =", np.log10(x))
```

#### np.expm1 np.log1p

```
In [21]: from scipy import special
In [22]:
          # Gamma functions (generalized factorials) and
          x = [1, 5, 10]
          print("gamma(x) =", special.gamma(x))
          print("ln|gamma(x)| =", special.gammaln(x))
          print("beta(x, 2) =", special.beta(x, 2))
          gamma(x) = [1.000000000e+00 2.400000000e+0]
          \ln|\operatorname{gamma}(x)| = [0. 3.17805383 12.80]
          beta(x, 2) = [ 0.5 0.03333333 0.00909
```

```
In [24]: x = np.arange(5)
          y = np.empty(5)
          np.multiply(x, 10, out=y)
          print(y)
          [ 0. 10. 20. 30. 40.]
          This can even be used with array views. For example, we ca
          computation to every other element of a specified array:
In [25]: y = np.zeros(10)
          np.power(2, x, out=y[::2])
          print(y)
                           0. 4. 0. 8. 0. 16.
                                                         0.]
```

```
In [26]:
          x = np.arange(1, 6)
          np.add.reduce(x)
Out[26]: 15
          Similarly, calling reduce on the
          elements:
In [27]: np.multiply.reduce(x)
Out[27]: 120
```

```
In [28]: np.add.accumulate(x)
Out[28]: array([ 1,  3,  6, 10, 15])
In [29]: np.multiply.accumulate(x)
Out[29]: array([ 1,  2,  6, 24, 120])
```

```
In [4]: big_array = np.random.rand(1000000)
          %timeit sum(big_array)
          %timeit np.sum(big_array)
          10 loops, best of 3: 104 ms per loop
          1000 loops, best of 3: 442 μs per loop
          1 %timeit min(big array)
In [7]:
          2 %timeit np.min(big_array)
        6.91 ms ± 238 μs per loop (mean ± std. dev. of 7 runs, 100 loops each)
        29.7 μs ± 591 ns per loop (mean ± std. dev. of 7 runs, 10000 loops each)
In [6]:
          1 %timeit max(-big_array)
          2 %timeit np.max(-big_array)
            | #np.max(-A)跟np.min的速度選是會有點小差別
        7.07 ms ± 194 μs per loop (mean ± std. dev. of 7 runs, 100 loops each)
        84.8 \mus \pm 1.6 \mus per loop (mean \pm std. dev. of 7 runs, 10000 loops each)
```

```
1 M = np.random.random((3,4))
In [2]:
         2 print(M)
           print('min(M)=',M.min(axis=0))
           print('Max(M)=',M.max(axis=1))
           #Axis 0 will act on all the ROWS in each COLUMN, MO:每個columr
           #Axis 1 will act on all the COLUMNS in each ROW
            #Axis用來指定陣列中要被收合起來的維度,而不是要傳回來的那個
        [[0.55210724 0.80814256 0.43532497 0.7307955 ]
         [0.25110438 0.16880296 0.95427731 0.53061535]
         [0.79423024 0.01138292 0.08227069 0.20342719]]
        min(M)= [0.25110438 0.01138292 0.08227069 0.20342719]
        Max(M) = [0.80814256 \ 0.95427731 \ 0.79423024]
```

```
In [16]: print("25th percentile: ", np.percentile(heights, 25))
    print("Median: ", np.median(heights))
    print("75th percentile: ", np.percentile(heights, 75))

25th percentile: 174.25
    Median: 182.0
    75th percentile: 183.0
```

Function Name	NaN-safe Version	Description
np.sum	np.nansum	Compute sum of elements
np.prod	np.nanprod	Compute product of elements
np.mean	np.nanmean	Compute mean of elements
np.std	np.nanstd	Compute standard deviation
np.var	np.nanvar	Compute variance
np.min	np.nanmin	Find minimum value
np.max	np.nanmax	Find maximum value
np.argmin	np.nanargmin	Find index of minimum value
np.argmax	np.nanargmax	Find index of maximum value
np.median	np.nanmedian	Compute median of elements
np.percentile	np.nanpercentile	Compute rank-based statistics of elements
np.any	N/A	Evaluate whether any elements are true
np.all	N/A	Evaluate whether all elements are true

```
1 A = np.array([[[2,3,4],[4,5,6]],[[7,8,9],[10,11,12]]])
In [5]:
         1 | sum(A)
In [6]:
Out[6]: array([[ 9, 11, 13],
               [14, 16, 18]])
          1 np.sum(A, axis=0)
In [9]:
Out[9]: array([[ 9, 11, 13],
               [14, 16, 18]])
            np.sum(A)
In [8]:
Out[8]: 81
```

```
In [2]: 1 a = np.array([0, 1, 2])
2 b = np.array([5, 5, 5])
3 a + b

Out[2]: array([5, 6, 7])

In [3]: 1 a + 5

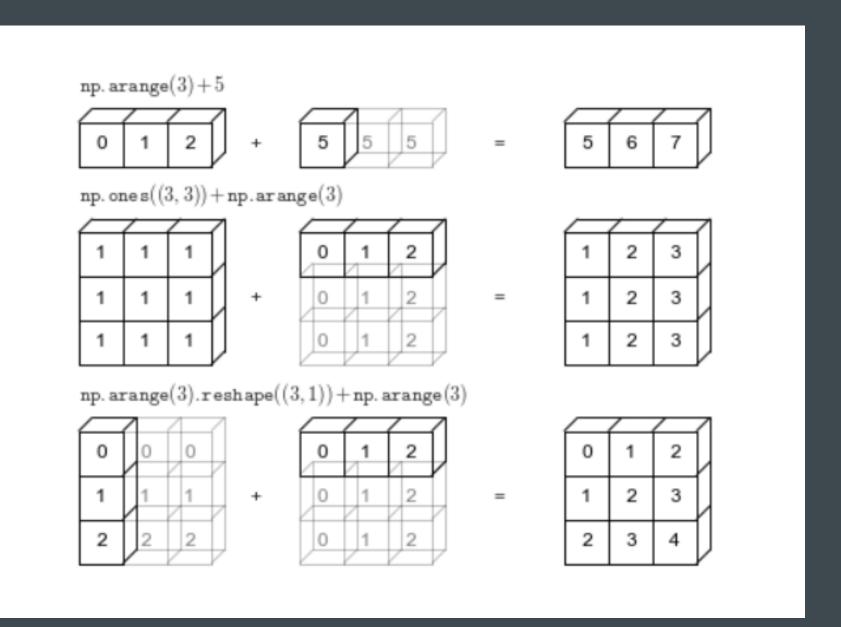
Out[3]: array([5, 6, 7])
```

```
1 M = np.ones((3, 3))
In [4]:
Out[4]: array([[1., 1., 1.],
               [1., 1., 1.],
               [1., 1., 1.]])
In [5]:
          1 M + a
Out[5]: array([[1., 2., 3.],
               [1., 2., 3.],
               [1., 2., 3.]]
```

把純量5拉伸成一維向量[5, 5, 5]

把一維陣列拉為二維

```
In [6]:
          1 | a = np.arange(3)
             b = np.arange(3)[:, np.newaxis]
             print(a)
            print(b)
        [0 1 2]
        [[0]]
          [1]
          [2]]
In [7]:
          1 a+b
Out[7]: array([[0, 1, 2],
                [1, 2, 3],
                [2, 3, 4]])
```



#### 規則一:

2陣列維度不同,低維度的陣列從最

左邊的元素墊充

#### 規則二:

如果兩個陣列有任一個維度不符合,

具有形狀是1的陣列該維度被拉長

#### 規則三:

如果有維度不相同,且該維度沒有兩 陣列值皆不等於1,則產生錯誤

```
• M.shape = (2, 3)
```

```
a.shape = (3, 1)
```

Rule 1 says we must pad the shape of

```
● a.shape -> (3, 1)
```

And rule 2 tells us that we upgrade e corresponding size of the other array

```
• a.shape -> (3, 3)
```

```
• M.shape = (3, 2)
```

Again, rule 1 tells us that we must pa

```
M.shape -> (3, 2)
```

By rule 2, the first dimension of a is

```
• M.shape -> (3, 2)
```

Broadcasting可以套用在任何Binary ufunc上