

COMP 5 – 3 (RC)

T.E. (Comp) Semester – V Examination, May 2010
(Revised Course)

MICROPROCESSORS AND MICROCONTROLLERS

Duration : 3 Hours

Total Marks : 100

Instructions: 1) Answer any five full questions with atleast one question from each Module.

2) Assume suitable data, if necessary.

3) Draw figure whenever required.

MODULE – I

1. a) With a neat diagram, explain the organization of the 8086 microprocessor. 8
- b) What are instruction prefixes in the instruction set of the 8086 ? Explain their usage with appropriate examples. 6
- c) Explain the advantages and disadvantages of a segmented memory model like that of 8086 microprocessors. 4
- d) Write the differences between the following instructions : 2
 - i) MOV CX, 437 AH and MOV CX, [437 AH]
 - ii) MOV BL, 437 AH and MOV BL, DS : BYTE PTR [437 AH].
- II. a) With the help of an example, describe the action performed by microprocessor 8086 for each of the following instructions : 6

AAM

CMPSB

IMUL

ROL

P.T.O.

- b) Explain what operation is performed by the following instructions :

SHL BYTE PTR [0400H], CL

MOV [BX] [DI] + 4, AX

XLAT

XTHL

PCHL

- c) Write an 8086 ALP program to sort set of N unsigned 8 bit numbers in descending order using selection sort. Add proper comments in the program.

MODULE - 2

- III. a) While considering the reset condition as a reference show how will the stack condition of 8087 co-processor change after three push operations with appropriate diagram.

- b) Convert the decimal number 2345.5625 to binary, normalized binary, long-real, and temporary real format and explain why are most floating point numbers are approximations.

- c) Write a program to compute the roots of the quadratic equation $ax^2 + bx + c = 0$. Using 8087 co-processor instructions, use comments to explain the logic and assumptions.

- IV. a) Explain the architecture of the 8087 floating math co-processor with a neat diagram. Highlight the host processor-coprocessor interface.

- b) Briefly describe the conditions cause the 8086 to perform each of the following types of interrupts. Type 0, Type 1, Type 2, Type 3 and Type 4.

- c) Implement the external procedures for inputting and outputting strings through the keyboard. (Use interrupt services and appropriate comments).

MODULE - 3

- V. a) Interface a 4x4 hex keyboard to 8255. Write a program which will detect key closure and store key in register AL.

- b) Draw the interfacing diagram between 8086 CPU and 8255 with 8 LEDs and 8 SPDT switches. Also write a program in 8086 assembly language to read the switch status and display it on the LEDs. Add proper comments in the program.



- c) Two 8255 PPI devices interfaced to 8086 microprocessor to read. 16 bit data, show interface and write assembly language program. 6
- VI. a) Interface an ADC to 8086 and demonstrate the BSR mode of 8255 operation. Write 8086 ALP to acquire 100 data by polling. 10
- b) Explain a method of measuring the period between two events (events generates pulses) using 8254. 6
- c) Describe different modes of communication supported by 8251. 4

MODULE – 4

- VII. a) Design an interface between 8086 and two chips of $16K \times 8$ EPROM and two chips of $32K \times 8$ RAM. Select the starting of EPROM suitably, the RAM address must start at 00000H. 10
- b) Describe the improvement of 80486 over 80386. 6
- c) List the features of protected mode operation. 4
- VIII. a) Describe the internal architecture of 8051 with neat block diagram. 10
- b) Explain the timer registers 8051. 4
- c) Describe TCON and TMOD function registers. 6