# Estimation and inference for higher-order stochastic volatility models with leverage \*

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#### **ABSTRACT**

Statistical inference – estimation and testing – for stochastic volatility models is challenging and computationally expensive. This problem is compounded when leverage effects are allowed. We propose efficient simple estimators for higher-order stochastic volatility models with leverage [SVL(p)], based on a small number of moment equations derived from ARMA representations associated with SVL models, along with the possibility of using "winsorization" to improve stability and efficiency (W-ARMA estimators). The asymptotic distributional theory of the estimators is derived. The computationally simple estimators proposed allow one to easily perform simulation-based (possibly exact) tests, such as Monte Carlo tests (MCT) or bootstrap procedures. In simulation experiments, we show that: (1) the proposed W-ARMA estimators dominate alternative estimators (including Bayesian estimators) in terms of bias, root-mean-square error, and computation time; (2) local and maximized Monte Carlo tests based on W-ARMA estimators yield good control of the size and power of LR-type tests; (3) taking into account leverage improves volatility forecasting. The methods developed are applied to daily returns for three major stock indices (S&P 500, Dow Jones, Nasdaq), confirming the superiority of SVL(p) models over competing conditional volatility models in terms of forecast accuracy.

**Key words:** Stochastic volatility, financial leverage, asymptotic distribution, higher-order process. **JEL Classification:** C15, C22, C53, C58.

#### 1 Introduction

Stochastic volatility (SV) models, originally proposed by Taylor (1982, 1986), constitute a fundamental model of fluctuating volatility in financial and macroeconomic time series. In this paper, we consider higher-order stochastic volatility models with a leverage effect [SVL(p)], where the underlying volatility process follows an autoregressive process of order p. The leverage effect refers to the inverse relationship between asset returns and volatilities: when asset prices decrease, volatility tends to increase due to the rise in debt-equity ratio, making the asset riskier; see Black (1976) and Christie (1982) for initial discussions. SVL models are empirically significant, due to the ability of capturing asymmetric effects in financial markets; applications include modeling volatility clustering and persistence [Harvey and Shephard (1996)], improving option pricing [Hull and White (1987), Bates and Watts (1988)], implementing more effective risk mitigation strategies [Chen et al. (2019)], making better-informed asset allocation decisions [Andersen and Bollerslev (1998)], forecasting volatility during periods of market stress and uncertainty [Barndorff-Nielsen et al. (2002)], providing a better empirical understanding of market behavior [Andersen et al. (2003)], etc.

While the SVL model is conceptually simple and theoretically appealing, it poses difficulties for estimation due to the presence of latent variables. Inference on SVL models are thus challenging tasks. The existing methods are limited to the SVL(1) model, computationally expensive, difficult to implement, and typically inefficient. Notable work includes quasi-maximum likelihood (QML) [Harvey and Shephard (1996)] and Bayesian techniques based on Markov Chain Monte Carlo (MCMC) methods [Jacquier et al. (2004), Omori et al. (2007)]. The estimation of SVL(*p*) models is even more challenging and remains unexplored in the literature, primarily due to their intrinsic complexity.

In this paper, we extend the simple estimator of Ahsan and Dufour (2021) designed for SV(p) models, and we develop a closed-form estimator for SVL(p) models based on the moment structure of the logarithm of squared residual returns. The proposed moment-based closed-form estimator [which we call the CF-ARMA estimator] utilizes the ARMA representation associated with SVL models. It offers analytical tractability and computational efficiency. Specifically, it can be easily implemented without relying on numerical optimization, and eliminates the need for arbitrary initial parameters or auxiliary models. It is worth noting that existing methods, such as QML and Bayesian approaches, can be extended to incorporate higher lag orders. However, such extensions come with increased computational complexity and implementation challenges.

However, the CF-ARMA estimator may not satisfy stationarity conditions when the sample is not sufficiently large or in the presence of outliers. To overcome this issue, we consider two approaches.

- 1. A restricted estimation approach, which confines the estimates within an acceptable parameter solution space by adjusting the roots that lie on or outside the unit circle.
- 2. Winsorized versions of the ARMA-type estimator [which we call W-ARMA estimators]. These modifications significantly increase the likelihood of obtaining acceptable values and improve efficiency [see Hafner and Linton (2017), Ahsan and Dufour (2021)].

In winsorized estimators, the autoregressive parameters of the latent volatility process – which capture volatility clustering – are estimated using an OLS-based weighting. For details on other weighting schemes and simulation experiments regarding precision improvement, see Ahsan and Dufour (2019, 2021). This computationally simple adjustment enhances the stability and accuracy of the estimators. In particular, an OLS-based W-ARMA estimator consistently outperforms all other estimators in terms of bias and RMSE by a significant margin, including the Bayesian estimator proposed in this context. The W-ARMA-OLS estimator proposed in this paper can be interpreted as a *parsimonious moment-based* estimator, where only a few well-chosen moments are utilized. In moment-based (or GMM) inference, employing too many moments can prove to be very costly from the perspective of estimation efficiency and forecasting [see (Ahsan et al. 2023)]. To be more specific, the other contributions of the paper can be summarized as follows.

First, utilizing these simple estimators, we formulate recursive estimation methods for SVL(p) models by using a Durbin-Levinson-type (DL) algorithm. We discuss the algorithmic framework that extends the recursion outlined in Tsay and Tiao (1984), which is applicable to autoregressive-moving average models and facilitates the recursive computation of parameters for higher-order SV processes. In addition, the asymptotic properties of the proposed simple estimators are established under standard regularity assumptions, demonstrating consistency and asymptotic normality when the fourth moment of the latent volatility process exists.

Second, we emphasize that the proposed computationally inexpensive estimators can be useful in several ways.

- Since SVL models are parametric models involving only a finite number of unknown parameters (which can be easily estimated by our method), one can construct simulation-based tests, even exact tests based on the Monte Carlo test (MCT) technique [see Dufour (2006)], as opposed to procedures based on establishing asymptotic distributions. In particular, exact tests obtained in this way do not depend on stationarity assumptions, so that they can be useful when the latent volatility process has a unit root (or is close to this structure).
- The proposed estimators are helpful for procedures which require repeated estimation based on a rolling window method, *e.g.* backtesting of risk measures (such as Value-at-Risk or Expected Shortfall) in the context of risk management.
- Due to the  $\sqrt{T}$ -consistency, our simple estimators can be effortlessly applied to very large samples, which are not rare in empirical finance, *e.g.* high-frequency financial returns. In these situations, estimators based on simulation techniques and/or numerical optimization often require substantial computational effort to achieve convergence.

Third, we study by simulation the statistical properties of our estimators and compare them with QML and Bayesian methods. The simulation results confirm that W-ARMA estimators have excellent statistical properties in terms of bias and RMSE. In particular, it outperforms all other estimators studied, including the Bayesian estimator. Furthermore, the proposed ARMA estimators (CF-ARMA and W-ARMA) are extremely efficient in terms of computation time, especially when compared with Bayesian estimators.

Fourth, in a further simulation study, we compare the forecasting performance of SV(p) models with SVL(p) models in the presence of leverage in the true data. We consider different values of the leverage parameter for both p=1 and p=2 models. By employing the MSE loss function with the Diebold-Mariano (DM) test, we find that SVL(p) models consistently outperform SV(p) models in terms of forecast accuracy. We investigate two data-generating processes (DGPs) with p=1,2, as well as different forecasting horizons. Our findings reveal that, even though the difference in mean squared error (MSE) decreases with longer forecasting horizons, a statistically significant difference persists which favours SVL models.

Fifth, we study the performance of likelihood-ratio-type (LR-type) tests based on W-ARMA estimators for the noleverage hypothesis. Three approaches for controlling the level of the tests are considered: (1) standard chi-square asymptotic approximations, (2) local Monte Carlo (LMC) tests (parametric bootstrapping), and (3) maximized Monte Carlo (MMC) tests. Our results show that asymptotic tests are often unreliable, either under-rejecting and reducing power or severely over-rejecting. LMC tests improve performance in many cases but can still over-reject, especially when the volatility process is highly persistent. We propose a weighting matrix that mitigates this issue. In contrast, MMC tests consistently control size and remain robust even with high persistence. When considering level-corrected power, LMC tests perform comparably to infeasible asymptotic tests (infeasible because the true distribution of the test statistic is unknown), while MMC stands out for its effectiveness in power. Moreover, we observe a decline in power with increasing volatility persistence, although larger sample sizes substantially increase power.

Finally, we present applications to daily observations on the returns for three major stock indices – S&P 500, Dow Jones, and NASDAQ – over the period 2000-2023. Using W-ARMA estimation, we find that returns exhibit stochastic volatility with strong persistence. The leverage parameter is significantly high for all three indices under the SVL(1) model but much lower for the SVL(2) and SVL(3) models. Moreover, we implemented MCT techniques to construct more reliable finite-sample inference, particularly since the estimated volatility persistence parameter is close to the unit circle. Tests on leverage reject the null of no leverage for the SVL(1) model. However, for the SVL(2) and SVL(3) models, we find insufficient evidence to reject the null. Our forecasting experiment demonstrates that SVL(p) models outperform alternative conditional volatility models, including GARCH and SV(p), in out-of-sample forecasting performance.

This paper is organized as follows. Section 2 specifies the model, assumptions, and motivation. Section 3 describes the simple estimators for SVL(p) models. Section 4 develops the asymptotic distributional theory for these estimators, and Section 5 discusses volatility forecasting with SVL(p) models. Section 6 discusses how finite-sample Monte Carlo tests can be applied using the proposed simple estimator. Section 7 presents the simulation study related to estimation, testing and forecasting. The empirical application is presented in Section 8. We conclude in Section 9. The mathematical proofs, other discussions, and additional results are provided in the Appendix.

#### 2 Framework

We consider a discrete-time SVL process of order (p), which can be viewed as an extension of the models considered by Harvey and Shephard (1996) and Omori et al. (2007). Specifically, we say that a variable  $y_t$  follows a stationary

SVL(p) process if it satisfies the following assumptions, where  $t \in \mathbb{N}_0$ , and  $\mathbb{N}_0$  represents the non-negative integers.

**Assumption 2.1.** Stochastic volatility models of order p with leverage. The process  $\{y_t : t \in \mathbb{N}_0\}$  satisfies the equations:

$$y_t = \sigma_y \exp\left(\frac{w_t}{2}\right) z_t, \tag{2.1}$$

$$w_{t} = \sum_{j=1}^{p} \phi_{j} w_{t-j} + \sigma_{v} v_{t}, \qquad (2.2)$$

where  $(\phi_1, ..., \phi_p, \sigma_y, \sigma_v, \delta_p)'$  are fixed parameters, with  $\sigma_y > 0$  and  $\sigma_v > 0$  controlling the level and variance of the latent log volatility process. The two innovations  $(z_t, v_{t+1})$  are assumed to jointly follow an independently and identically distributed (i.i.d) bivariate standard normal distribution with a correlation coefficient  $\delta_p$ :

$$\begin{pmatrix} z_t \\ v_{t+1} \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \delta_p \\ \delta_p & 1 \end{pmatrix} \right).$$
 (2.3)

The parameter  $\delta_p \in (-1,1)$  is the leverage parameter, representing the lag correlation between returns and log volatility shocks. For any  $i \neq 1$  and any t, the innovations are uncorrelated, i.e.,  $\operatorname{corr}(z_{t-i}, v_t) = 0$ .

**Assumption 2.2.** Stationarity of the latent process. All the roots of the characteristic equation of the volatility process  $w_t$ ,

$$\phi(z) := 1 - \phi_1 z - \phi_2 z^2 - \dots - \phi_p z^p = 0,$$

*lie outside the unit circle* (|z| > 1); that is,  $\phi(z) \neq 0$  for all  $|z| \leq 1$ .

Under the latter assumption, the process  $y_t$  is strictly stationary since  $y_t$  depends on the strictly stationary process  $w_t$  and a stationary i.i.d. Gaussian innovation  $z_t$ . This model consists of two stochastic processes, where  $y_t$  describes the dynamics of asset returns, and  $w_t := \log(\sigma_t^2)$  captures the dynamics of latent log volatilities. The latent process  $w_t$  can be interpreted as a random flow of uncertainty shocks or new information in financial markets, the  $\phi_j$ 's capture volatility persistence, and  $\delta_p$  represents the leverage effect. If  $\delta_p < 0$ , given a negative shock to  $y_t$  at time t-1, the volatility at time t tends to be larger.

Compared with the SV(p) model in Ahsan and Dufour (2021), a dependence structure between  $z_{t-1}$  and  $v_t$  is allowed in this SVL(p) model. So the SVL(p) model, defined in Assumptions 2.1 - 2.2, has p+3 fixed parameters and has one additional leverage parameter compared to Ahsan and Dufour (2021). On setting p=1, we get the SVL(1) model, considered by Harvey and Shephard (1996), Omori et al. (2007) and Yu (2005). This model is the Euler approximation to the continuous time asymmetric SV model widely used in the option pricing literature; see for an example Hull and White (1987). As argued in Harvey and Shephard (1996), this model is a martingale difference sequence, consistent with the efficient market hypothesis. This is obvious because for SVL models, we have:

$$\mathbb{E}[y_{t+1}|y_t, w_t] = \sigma_V \exp(\phi w_t/2) \mathbb{E}[\exp(\sigma_V v_{t+1}/2)] \mathbb{E}[z_{t+1}|y_t, w_t] = 0. \tag{2.4}$$

<sup>&</sup>lt;sup>1</sup>Usually the  $y_t$ 's are residual returns, such that  $y_t := r_t - \mu_r$  and  $r_t := 100[\log(p_t) - \log(p_{t-1})]$ , where  $\mu_r$  is the mean of returns  $(r_t)$  and  $p_t$  is the raw prices of an asset. It is noteworthy to mention that  $y_t$  is ordinarily the error term of any time series regression model, see Jurado et al. (2015).

<sup>&</sup>lt;sup>2</sup>Instead of assuming corr $(z_{t-1}, v_t) = \delta_p$ , Jacquier et al. (2004) adopt the specification of corr $(z_t, v_t) = \delta_p$ .

Since the disturbances  $(z_t, v_{t+1})'$  are conditionally Gaussian, we can write  $v_t = \delta_p z_{t-1} + (1 - \delta_p^2)^{1/2} \bar{v}_t$ , where  $\bar{v}_t \sim \mathcal{N}(0,1)$ . The state equation (2.2) can then be reformulated as:

$$w_{t} = \sum_{i=1}^{p} \phi_{j} w_{t-j} + \delta_{p} \sigma_{v} z_{t-1} + (1 - \delta_{p}^{2})^{1/2} \sigma_{v} \bar{v}_{t}.$$
(2.5)

Let us now transform  $y_t$  by taking the logarithm of its squared value. We get in this way the following *measurement* equation:

$$\log(y_t^2) = \log(\sigma_y^2) + w_t + \log(z_t^2) = \mu + w_t + \epsilon_t$$
 (2.6)

where  $\mu := \mathbb{E}[\log(y_t^2)] = \log(\sigma_y^2) + \mathbb{E}[\log(z_t^2)]$  and  $\epsilon_t := \log(z_t^2) - \mathbb{E}[\log(z_t^2)]$ . Under the normality assumption on  $z_t$ , the errors  $\epsilon_t$  are i.i.d. according to the distribution of a centered  $\log(\chi_1^2)$  random variable [i.e.,  $\epsilon_t$  has mean zero and variance  $\mathbb{E}[\epsilon_t^2]$ ] and

$$\bar{\mu} := \mathbb{E}[\log(z_t^2)] = \psi(1/2) + \log(2) \simeq -1.2704, \quad \sigma_{\epsilon}^2 := \mathbb{E}(\epsilon_t^2) = \pi^2/2, \quad \mathbb{E}(\epsilon_t^3) = \psi^{(2)}(1/2), \quad \mathbb{E}(\epsilon_t^4) = \pi^4 + 3\sigma_{\epsilon}^2, \tag{2.7}$$

where  $\psi^{(2)}(z)$  is the *polygamma function* of order 2; see Abramowitz and Stegun (1970, Chapter 6).<sup>3</sup> On setting

$$y_t^* := \log(y_t^2) - \mu \tag{2.8}$$

and combining (2.5) and (2.6), the SVL(p) model can be written in state-space form:

State Transition Equation: 
$$w_t = \sum_{j=1}^{p} \phi_j w_{t-j} + \tilde{\delta}_p z_{t-1} + \tilde{\sigma}_v \bar{v}_t,$$
 (2.9)

Measurement Equation: 
$$y_t^* = w_t + \epsilon_t$$
, (2.10)

where  $\tilde{\delta}_p := \delta_p \sigma_v$ ,  $\tilde{\sigma}_v := \sqrt{\left(1 - \delta_p^2\right)} \sigma_v$ , and  $\bar{v}_t$ 's are i.i.d.  $\mathcal{N}(0,1)$  and  $\epsilon_t$ 's are i.i.d.  $\log(\chi_1^2)$ . Note that transformed structural error  $\bar{v}_t$  is uncorrelated with  $z_t$  and also its transformed error  $\epsilon_t$ .

## 3 Simple SV estimation with leverage

In this section, we propose simple estimators for SVL(p) models, including a corresponding recursive procedure. Besides, we suggest alternative methods to improve the performance of these simple estimators.

#### 3.1 ARMA-based estimation

In this subsection, we propose another simple estimator for SVL(p) models, which exploits the autocovariance structure of  $y_t^*$ . This estimator is based on considering a small set of moments associated with  $y_t^* = \log(y_t^2) - \mu$ , and the fact that this process has an ARMA representation.

**Proposition 3.1.** ARMA REPRESENTATION OF SVL(P) MODELS. Under the Assumptions 2.1 - 2.2, the process  $y_t^*$ 

<sup>&</sup>lt;sup>3</sup>The  $\log(\chi_1^2)$  distribution is often approximated by a normal distribution with mean of  $\bar{\mu}$  and variance of  $\pi^2/2$  [see Broto and Ruiz (2004)], or by a mixture distribution [Kim et al. (1998)].

defined in (2.8) has the following ARMA(p, p) representation:

$$y_t^* = \sum_{j=1}^p \phi_j y_{t-j}^* + \eta_t - \sum_{j=1}^p \theta_j \eta_{t-j},$$
(3.1)

where  $\eta_t - \sum_{j=1}^p \theta_j \eta_{t-j} = v_t + \epsilon_t - \sum_{j=1}^p \phi_j \epsilon_{t-j}$ ,  $\{v_t\}$  and  $\{\epsilon_t\}$  are mutually independent error processes, the errors  $v_t$  are i.i.d.  $\mathcal{N}(0, \sigma_v^2)$ , and the errors  $\epsilon_t$  are i.i.d. according to the distribution of a  $\log(\chi_1^2)$  random variable.

From the above proposition, we derive simple expressions for the autocovariances and parameters of the SVL(p) model.

**Corollary 3.2.** AUTOCOVARIANCES OF THE OBSERVED PROCESS. Under the Assumptions of Proposition 3.1, the autocovariances of the observed process  $y_t^*$  defined in (2.8) satisfy the following equations:

$$\operatorname{cov}(y_{t}^{*},y_{t-k}^{*}) := \gamma_{y^{*}}(k) = \begin{cases} \phi_{1}\gamma_{y^{*}}(k-1) + \dots + \phi_{p}\gamma_{y^{*}}(k-p) + \sigma_{v}^{2} + \sigma_{\varepsilon}^{2} & \text{if } k = 0 \\ \phi_{1}\gamma_{y^{*}}(k-1) + \dots + \phi_{p}\gamma_{y^{*}}(k-p) - \phi_{k}\sigma_{\varepsilon}^{2} & \text{if } 1 \leq k \leq p \\ \phi_{1}\gamma_{y^{*}}(k-1) + \dots + \phi_{p}\gamma_{y^{*}}(k-p) & \text{if } k > p. \end{cases}$$

$$(3.2)$$

In order to get the unsquared parameter solution for  $\delta_p$ , we will exploit the following lemma.

**Lemma 3.3.** Moment equation involving unsquared leverage parameter. *Under Assumptions* 2.1 - 2.2, *the following moment condition holds:* 

$$\mathbb{E}[|y_t|y_{t-1}] = \frac{\delta\sigma_v\sigma_y^2}{\sqrt{2\pi}}\exp(\tilde{\gamma}_p/4)$$
(3.3)

where  $\tilde{\gamma}_p := \operatorname{var}(w_t) + \operatorname{cov}(w_t, w_{t-1})$ .

**Corollary 3.4.** Closed-form expressions for SVL(p) parameters. Under the Assumptions of Proposition 3.1, we have:

$$\phi_p = \Gamma(p, j)^{-1} \gamma(p, j), \quad j \ge 1,$$
(3.4)

$$\sigma_{\gamma} = [\exp(\mu - \bar{\mu})]^{1/2}, \quad \sigma_{\nu} = [\gamma_{\nu^*}(0) - \phi_{n}'\gamma(1) - \pi^2/2]^{1/2},$$
(3.5)

$$\delta_p = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_y\sigma_y^2} \exp\left(-\frac{1}{4}\tilde{\gamma}_p\right),\tag{3.6}$$

where  $\bar{\mu} = \psi(1/2) + \log(2)$ ,  $\lambda_y(1) := \mathbb{E}[|y_t|y_{t-1}]$ ,  $\tilde{\gamma}_p := \text{var}(w_t) + \text{cov}(w_t, w_{t-1})$ ,  $\phi_p := (\phi_1, \dots, \phi_p)'$ ,

$$\gamma(p,j) := \left[\gamma_{v^*}(p+j), \dots, \gamma_{v^*}(2p+j-1)\right]', \quad \gamma(p) := \left[\gamma_{v^*}(1), \dots, \gamma_{v^*}(p)\right]'$$
(3.7)

are  $p \times 1$  vectors, and  $\Gamma(p, j)$  is the following  $p \times p$  matrix:

$$\Gamma(p,j) := \begin{bmatrix}
\gamma_{y^*}(j+p-1) & \gamma_{y^*}(j+p-2) & \cdots & \gamma_{y^*}(j) \\
\gamma_{y^*}(j+p) & \gamma_{y^*}(j+p-1) & \cdots & \gamma_{y^*}(j+1) \\
\vdots & \vdots & & \vdots \\
\gamma_{y^*}(j+2p-2) & \gamma_{y^*}(j+2p-3) & \cdots & \gamma_{y^*}(j+p-1)
\end{bmatrix}$$
(3.8)

where p is the SV order,  $\gamma_{y^*}(k) = \text{cov}(y_t^*, y_{t-k}^*)$ , with  $y_t^* = [\log(y_t^2) - \mu]$  and  $\mu := \mathbb{E}[\log(y_t^2)]$ . Expressions of  $\delta_p$  for the

lower order SVL(p) models are:

$$\delta_1 = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_v \sigma_y^2} \exp\left(-\frac{1}{4}\frac{\sigma_v^2}{1-\phi_1}\right),\tag{3.9}$$

$$\delta_2 = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_v \sigma_v^2} \exp\left(-\frac{1}{4} \frac{\sigma_v^2}{(1 - \phi_1 - \phi_2)(1 + \phi_2)}\right),\tag{3.10}$$

$$\delta_3 = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_v \sigma_y^2} \exp\left(-\frac{1}{4} \frac{(1-\phi_3)\sigma_v^2}{(1-\phi_1-\phi_2-\phi_3)(1+\phi_1\phi_3+\phi_2-\phi_3^2)}\right),\tag{3.11}$$

$$\delta_4 = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_v\sigma_y^2} \exp\left(-\frac{1}{4} \frac{(1-\phi_3-\phi_1\phi_4-\phi_4^2)(1-\phi_1-\phi_2-\phi_3-\phi_4)^{-1}\sigma_v^2}{(1+\phi_1\phi_3+\phi_2+\phi_4+2\phi_2\phi_4+\phi_1^2\phi_4+\phi_2\phi_4^2-\phi_3^2-\phi_4^2-\phi_4^3-\phi_1\phi_3\phi_4)}\right). \tag{3.12}$$

It is natural to estimate  $\gamma_{v^*}(k)$  and  $\mu$  by the corresponding empirical moments:

$$\hat{\gamma}_{y^*}(k) = \frac{1}{T - k} \sum_{t=1}^{T - k} y_t^* y_{t+k}^*, \quad \hat{\mu} = \frac{1}{T} \sum_{t=1}^{T} \log(y_t^2), \quad \hat{\lambda}_y(1) := \frac{1}{T - 1} \sum_{t=1}^{T - 1} [|y_t| y_{t-1}], \quad (3.13)$$

where  $y_t^*$  is a mean corrected process (by construction). Setting j = 1 in (3.4) and replacing theoretical moments by their corresponding empirical moments in (3.4)-(3.6) yield the following *simple CF-ARMA* estimator of the SVL(p) coefficients:

$$\hat{\phi}_{p} = \hat{\boldsymbol{\Gamma}}(p, 1)^{-1} \hat{\gamma}(p, 1), \quad \hat{\sigma}_{y} = \left[\exp(\hat{\mu} - \bar{\mu})\right]^{1/2}, \quad \hat{\sigma}_{v} = \left[\hat{\gamma}_{v^{*}}(0) - \hat{\phi}_{p}'\hat{\gamma}(p) - \pi^{2}/2\right]^{1/2}, \tag{3.14}$$

$$\hat{\delta}_{p} = \frac{\sqrt{2\pi}\hat{\lambda}_{y}(1)}{\hat{\sigma}_{v}\hat{\sigma}_{v}^{2}} \exp\left(-\frac{1}{4}\hat{\hat{\gamma}}_{p}\right), \tag{3.15}$$

where expressions of  $\hat{\delta}_p$  for the lower order SVL(p) models are:

$$\hat{\delta}_1 = \frac{\sqrt{2\pi}\hat{\lambda}_y(1)}{\hat{\sigma}_y\hat{\sigma}_y^2} \exp\left(-\frac{1}{4}\frac{\hat{\sigma}_v^2}{1-\hat{\phi}_1}\right),\tag{3.16}$$

$$\hat{\delta}_{2} = \frac{\sqrt{2\pi}\hat{\lambda}_{y}(1)}{\hat{\sigma}_{v}\hat{\sigma}_{v}^{2}} \exp\left(-\frac{1}{4} \frac{\hat{\sigma}_{v}^{2}}{(1-\hat{\phi}_{1}-\hat{\phi}_{2})(1+\hat{\phi}_{2})}\right), \tag{3.17}$$

$$\hat{\delta}_{3} = \frac{\sqrt{2\pi}\hat{\lambda}_{y}(1)}{\hat{\sigma}_{v}\hat{\sigma}_{y}^{2}} \exp\left(-\frac{1}{4} \frac{(1-\hat{\phi}_{3})\hat{\sigma}_{v}^{2}}{(1-\hat{\phi}_{1}-\hat{\phi}_{2}-\hat{\phi}_{3})(1+\hat{\phi}_{1}\hat{\phi}_{3}+\hat{\phi}_{2}-\hat{\phi}_{3}^{2})}\right), \tag{3.18}$$

$$\hat{\delta}_{4} = \frac{\sqrt{2\pi}\hat{\lambda}_{y}(1)}{\hat{\sigma}_{v}\hat{\sigma}_{y}^{2}} \exp\left(-\frac{1}{4} \frac{(1-\hat{\phi}_{3}-\hat{\phi}_{1}\hat{\phi}_{4}-\hat{\phi}_{4}^{2})(1-\hat{\phi}_{1}-\hat{\phi}_{2}-\hat{\phi}_{3}-\hat{\phi}_{4})^{-1}\hat{\sigma}_{v}^{2}}{(1+\hat{\phi}_{1}\hat{\phi}_{3}+\hat{\phi}_{2}+\hat{\phi}_{4}+2\hat{\phi}_{2}\hat{\phi}_{4}+\hat{\phi}_{1}^{2}\hat{\phi}_{4}+\hat{\phi}_{2}\hat{\phi}_{4}^{2}-\hat{\phi}_{3}^{2}-\hat{\phi}_{4}^{2}-\hat{\phi}_{3}^{3}-\hat{\phi}_{1}\hat{\phi}_{3}\hat{\phi}_{4})}\right).$$
(3.19)

Note that our simple estimator is based on the log-squared transformation of the residual returns minus the mean (i.e.,  $\log(y_t^2) - \mu$ ). Therefore, we need to account for the inlier problem. When the residual returns  $y_t$  are very close to zero, the log-squared transformation yields large negative values, which is referred to as the inlier problem. In the extreme case, if the return is equal to zero, the log-squared transformation is undefined. In the simulation and empirical sections, we address this issue by adjusting the squared returns by adding a fixed constant of 1e - 10 for all time periods; for an alternative methodology, see Fuller (1996).

#### 3.2 Restricted estimation

These simple estimators yield values outside the admissible area, *i.e.*, some of the roots of the latent volatility AR(p) model may not correspond to a stationary process. This issue can arise especially in small samples or in the presence

of outliers. When this happens, a simple fix consists in altering the eigenvalues that lie on or outside the unit circle. The characteristic equation of the latent AR(p) process is given by  $C(\lambda) = \lambda^p - \phi_1 \lambda^{p-1} - \cdots - \phi_p = 0$ , and the stationary condition requires all roots lie inside the unit circle, *i.e.*,  $|\lambda_i| < 1$ , i = 1, ..., p. If the estimated parameters fail to satisfy this condition, then the restricted estimation can be done in the following two steps: (1) given the estimated unstable parameters, we calculate the roots of the characteristic equation and restrict their absolute values to less than unity; (2) given these restricted roots, we calculate constrained parameters ensuring stationarity.

For an SVL(2) model, the characteristic equation of the latent volatility process is  $C(\lambda) = \lambda^2 - \phi_1 \lambda - \phi_2 = 0$ . It may have two types of roots: (i) if  $\phi_1^2 + 4\phi_2 \ge 0$ , then  $C(\lambda)$  has two real roots given by  $\lambda_{1,2} = [\phi_1 \pm \sqrt{\phi_1^2 + 4\phi_2}]/2$ ; (ii) if  $\phi_1^2 + 4\phi_2 < 0$  then  $C(\lambda)$  has two complex roots given by  $\lambda_{1,2} = [\phi_1 \pm i\sqrt{-(\phi_1^2 + 4\phi_2)}]/2$ . When the estimated polynomial coefficients produce an unstable solution, then we restrict the absolute value of the roots less than unity, i.e.  $|\lambda_{1,2}| < 1$  or  $|\lambda_{1,2}| = 1 - \Delta$  where  $\Delta$  is a very small number. Given these restricted roots, we solve for restricted parameters which ensure stationarity. These steps can be done very easily in MATLAB. In MATLAB, the **roots** function calculates the roots given the parameters, and the **poly** function calculates the parameters given the roots. Further, the estimate  $\hat{\delta}_p$  may yield a value outside the acceptable region (-1, 1). In this case, we can restrict it within the admissible parameter space.

#### 3.3 ARMA-based winsorized estimation

We can achieve better stability and efficiency of the CF-ARMA estimator by using "winsorization". This procedure substantially increases the probability of getting admissible values. From (3.4), it is easy to see that

$$\phi_p = \sum_{j=1}^{\infty} \omega_j B(p, j) = \sum_{j=1}^{\infty} \omega_j \Gamma(p, j)^{-1} \gamma(p, j)$$
(3.20)

for any  $\omega_j$  sequence with  $\sum_{j=1}^{\infty} \omega_j = 1$ , where  $\boldsymbol{B}(p,j) := \boldsymbol{\Gamma}(p,j)^{-1} \gamma(p,j) = [\boldsymbol{B}(p,j)_1,\ldots,\boldsymbol{B}(p,j)_p]'$  is a  $p \times 1$  vector. Using (3.20), we can define a more general class of estimators for  $\phi_p$  by taking a weighted average of several sample analogs of the  $p \times 1$  vector:

$$\tilde{\phi}_p := \sum_{j=1}^J \omega_j \hat{B}(p,j), \quad \hat{B}(p,j) := \hat{\Gamma}(p,j)^{-1} \hat{\gamma}(p,j) = [\hat{B}(p,j)_1, \dots, \hat{B}(p,j)_p]', \tag{3.21}$$

where  $\sum_{j=1}^{J} \omega_j = 1$ ,  $1 \le J \le T - 2p$ , and T is the length of time series. We can expect that a sufficiently general class of weights will improve the efficiency of the CF-ARMA estimator.

Using (3.21), we propose alternative estimators of  $\phi_p$  and we call these estimators *winsorized ARMA* estimators (or *W-ARMA* estimators). For a full list of W-ARMA methods, see Appendix B. These estimation techniques have been examined within the framework of SV(p) models by Ahsan and Dufour (2021) and have also been explored by Hafner and Linton (2017) in the context of closed-form estimation for the EGARCH(1,1) model.

In this paper, we use a W-ARMA estimator based on an OLS regression without intercept, since its performance stands out among the W-ARMA methods [see Section 6 of Ahsan and Dufour (2021)]:

$$\hat{\phi}_p^{\text{ols}} = [A(p, I)'A(p, I)]^{-1}A(p, I)'e(p, I)$$
(3.22)

where e(p, J) is a  $(pJ) \times 1$  vector and A(p, J) is a  $(pJ) \times p$  matrix defined by

$$e(p, J) = [\hat{\gamma}(p, 1)\omega_1^{1/2}, \dots, \hat{\gamma}(p, J)\omega_I^{1/2}]', \quad A(p, J) = [\hat{\Gamma}(p, 1)\omega_1^{1/2}, \dots, \hat{\Gamma}(p, J)\omega_I^{1/2}]'. \tag{3.23}$$

Different OLS-based W-ARMA can be generated by considering different weights  $\omega_1, \dots, \omega_J$ . In our simulations below as well as in empirical applications, we focus on the case where the weights are equal *i.e.*,  $\omega_j = 1/J$  where  $j = 1, \dots, J$ . For J = 1, this estimator is equivalent to the CF-ARMA estimator given in (3.14).

#### 3.4 Recursive estimation for SVL(p) models

In this section, we describe a recursive estimation algorithm tailored for SVL(p) models. For ease of notation, we adopt a different indexing scheme solely for the autoregressive parameters of the volatility process within this section. For instance, the SVL(p) parameters are now represented as  $\theta_p^{SVL} := \left( \left\{ \phi_{p,j} \right\}_{j=1,\dots,p}, \sigma_{pv}, \sigma_y, \delta_p \right)^T$ .

The recursive estimation of the CF-ARMA estimator capitalizes on the extended Yule-Walker (EYW) equations governing the observed process. When the MA order remains constant, the EYW equations form a nested Toeplitz system. Introducing a *Generalized Durbin-Levinson* algorithm for the CF-ARMA estimator in the SVL(p) model proves beneficial when neither the AR nor the MA order is predetermined. Here, we specifically examine the scenario where i = p, meaning the MA order equals p, implying an identical AR order of p.

For i=0, use the Durbin-Levinson algorithm to calculate  $\left\{\hat{\phi}_{p,j}^{(0)} \mid p \geq 1, j=1,\ldots,p\right\}$  and for  $i\geq 1$ , calculate

$$\hat{\phi}_{p,0}^{(i-1)} = -1, \quad \hat{\phi}_{p,j}^{(i)} = \hat{\phi}_{p+1,j}^{(i-1)} - \frac{\hat{\phi}_{p+1,p+1}^{(i-1)}}{\hat{\phi}_{p,p}^{(i-1)}} \hat{\phi}_{p,j-1}^{(i-1)}, \quad p \ge 1, \quad j = 1, \dots, p, \quad \hat{\sigma}_{y} = [\exp(\hat{\mu} - \bar{\mu})]^{1/2}, \tag{3.24}$$

$$\hat{\sigma}_{pv} = [\hat{\gamma}_{y^*}(0) - \sum_{j=1}^p \hat{\phi}_{p,j} \hat{\gamma}_{y^*}(j) - \pi^2/2]^{1/2}, \quad \hat{\delta}_p = \frac{\sqrt{2\pi}\hat{\lambda}_y(1)}{\hat{\sigma}_v \hat{\sigma}_v^2} \exp\left(-\frac{1}{4}\hat{\tilde{\gamma}}_p\right), \tag{3.25}$$

where full expressions of  $\hat{\delta}_p$  for the lower order SVL(p) models are given in (3.15). This algorithm is the same as the Tsay and Tiao (1984) algorithm [except for the equations involving  $\hat{\sigma}_y$  and  $\hat{\sigma}_{pv}$ ] for calculating the extended sample autocorrelation function under the stationarity assumption.

## 4 Asymptotic distributional theory

In this section, we derive the asymptotic properties of the CF-ARMA estimator  $\hat{\theta} := (\hat{\phi}_1, \dots, \hat{\phi}_p, \hat{\sigma}_y, \hat{\sigma}_v, \hat{\delta}_p)'$ . Under Assumptions 2.1 and 2.2, the latent log-volatility process  $\{w_t\}$  and the transformed squared innovations  $\{\log(z_t^2)\}$  are strictly stationary and possess finite moments of all orders.<sup>4</sup> Consequently, the process  $y_t^* := \log(y_t^2) - \mathbb{E}[\log(y_t^2)]$  is strictly stationary, ergodic, and  $\beta$ -mixing, with  $\mathbb{E}[(y_t^*)^s] < \infty$  for any integer  $s \ge 1$ .<sup>5</sup> This result follows because  $y_t^*$  is a measurable function of the strictly stationary processes  $w_t$  and  $z_t$ , and both  $w_t$  and  $\log(z_t^2)$  have finite moments of all orders. The strict stationarity of  $y_t^*$  arises from its dependence on  $w_t$  and  $z_t$ , while its ergodicity is established

<sup>&</sup>lt;sup>4</sup>Since  $z_t$  is a standard normal random variable,  $z_t^2$  follows a chi-squared distribution with one degree of freedom. The logarithm of a chi-squared distributed variable is well-defined and has finite moments of all orders due to the exponential decay of its tail probabilities, ensuring the convergence of the integrals defining the moments.

<sup>&</sup>lt;sup>5</sup>These properties also hold for any measurable function of  $y_t$ .

due to the exponential decay of dependencies in  $w_t$ ; combined with the properties of  $z_t$ , this ensures that time averages converge to their expected values. The  $\beta$ -mixing property (absolute regularity) follows from the decreasing dependence between observations over time, causing the mixing coefficients  $\beta(n)$  to approach zero as the lag n increases.

Thus under Assumptions 2.1 and 2.2, the SVL model admits a strictly stationary solution with a finite fourth moment of  $y_t^*$ ; that is,  $\mathbb{E}[(y_t^*)^4] < \infty$ . Notably, the finiteness of the fourth moment of  $y_t^*$  implies the existence of the eighth moment of  $y_t$ . In the subsequent lemmas, we utilize the Ergodic Theorem to establish the consistency of the empirical moments. Furthermore, by applying a Central Limit Theorem suitable for stationary and ergodic processes - specifically, the Lindeberg-Levy Theorem for dependent sequences - we derive the asymptotic distribution of the empirical moments in equation (3.13).

**Lemma 4.1.** Consistency of empirical moments. Under Assumptions 2.1 and 2.2, the estimators  $\hat{\mu}$ ,  $\hat{\lambda}_y(1)$  and  $\hat{\Gamma}(m) := [\hat{\gamma}_{y^*}(0), \hat{\gamma}_{y^*}(1), \dots, \hat{\gamma}_{y^*}(m)]'$  defined by (3.13) satisfy:

$$\hat{\mu} \xrightarrow{p} \mu$$
,  $\hat{\lambda}_{y}(1) \xrightarrow{p} \lambda_{y}(1)$  and  $\hat{\Gamma}(m) \xrightarrow{p} \Gamma(m) := [\gamma_{y^{*}}(0), \gamma_{y^{*}}(1), \dots, \gamma_{y^{*}}(m)]'$ . (4.1)

**Lemma 4.2.** Asymptotic distribution of empirical moments. *Under Assumptions 2.1 and 2.2, the estimators*  $\hat{\mu}$ ,  $\hat{\lambda}_{\gamma}(1)$  and  $\hat{\Gamma}(m) := [\hat{\gamma}_{\gamma^*}(0), \hat{\gamma}_{\gamma^*}(1), \dots, \hat{\gamma}_{\gamma^*}(m)]'$  defined by defined by (3.13) satisfy:

$$\sqrt{T} \begin{bmatrix} \hat{\mu} - \mu \\ \hat{\Gamma}(m) - \Gamma(m) \\ \hat{\lambda}_{y}(1) - \lambda_{y}(1) \end{bmatrix} \xrightarrow{d} \mathcal{N} \begin{bmatrix} V_{\mu} & C'_{\mu,\Gamma(m)} & C_{\mu,\lambda_{y}(1)} \\ C_{\mu,\Gamma(m)} & V_{\Gamma(m)} & C_{\Gamma(m),\lambda_{y}(1)} \\ C_{\mu,\lambda_{y}(1)} & C'_{\Gamma(m),\lambda_{y}(1)} & V_{\lambda_{y}(1)} \end{bmatrix} \right), \tag{4.2}$$

where

$$V_{\mu} = \gamma_{y^*}(0) + 2\sum_{\tau=1}^{\infty} \gamma_{y^*}(\tau), \quad V_{\Gamma(m)} = \text{Var}(\Lambda_t) + 2\sum_{\tau=1}^{\infty} \text{cov}(\Lambda_t, \Lambda_{t+\tau}), \quad V_{\lambda_y(1)} = \lambda_y^2(1),$$
(4.3)

$$C_{\mu,\Gamma(m)} = (\bar{c}, \ 0_{[1 \times m]})', \quad \bar{c} := C_{\mu,\Gamma(0)} = 2\sum_{t=1}^{\infty} \mathbb{E}[y_t^{*3}] = 2\sum_{t=1}^{\infty} \mathbb{E}[\epsilon_t^3], \quad \Lambda_t := [\Lambda_{t,0}, \Lambda_{t,1}, \dots, \Lambda_{t,m}]', \tag{4.4}$$

$$\Lambda_{t,k} := y_t^* y_{t+k}^* - \gamma_{y^*}(k) = [\log(y_t^2) - \mu] [\log(y_{t+k}^2) - \mu] - \gamma_{y^*}(k), \quad k = 0, ..., m,$$

$$(4.5)$$

$$C_{\mu,\lambda_{y}(1)} = 2\sum_{t=1}^{\infty} \frac{\delta_{p}\sigma_{v}\sigma_{y}^{2}}{\sqrt{2\pi}} \exp\left(\frac{\gamma_{w}(0)}{4}\right) \left[8 - \left(\gamma^{\epsilon} + \psi^{(0)}(0.5)\right) \exp\left(\frac{\gamma_{w}(1)}{4}\right)\right],\tag{4.6}$$

$$C_{\Gamma(m),\lambda_{\gamma}(1)} = [C_{\lambda 0}, C_{\lambda 1}, \dots, C_{\lambda m}]', \tag{4.7}$$

$$C_{\lambda k} = 2 \sum_{t=1}^{\infty} \left( \frac{\delta_p \sigma_v \sigma_y^2}{\sqrt{2\pi}} \exp\left(\frac{\gamma_w(0)}{4}\right) \left( \gamma_w(0) + \bar{\psi}_k \gamma_w(1) + 0.5 \bar{\psi}_k \gamma_w(k) + \gamma_w(k+1) - \frac{\gamma^{\epsilon} + \psi^{(0)}(0.5)}{2} \right) \right),$$

$$k = 0, 1, 2, ..., m. \tag{4.8}$$

where  $\bar{\psi}_k$  is k-th parameter of the MA( $\infty$ ) representation of the latent log volatility process,  $\gamma_w(k) = \text{cov}(w_t, w_{t+k})$ ,  $\psi^{(0)}(z)$  is the digamma function and  $\gamma^{\epsilon}$  is the Euler-Mascheroni constant.

This in turn yields the asymptotic distribution of the simple ARMA-type estimator  $(\hat{\phi}_1, \dots, \hat{\phi}_p, \hat{\sigma}_y, \hat{\sigma}_v, \delta_p)'$ .

**Theorem 4.3.** Asymptotic distribution of simple ARMA-SV estimator. Under Assumptions 2.1 and 2.2, the estimator  $\hat{\theta} := (\hat{\phi}_1, \dots, \hat{\phi}_p, \hat{\sigma}_y, \hat{\sigma}_v, \hat{\delta}_p)'$  given in (3.14) is consistent, i.e.,  $\hat{\theta} \xrightarrow{p} \theta$ , and

$$\sqrt{T}(\hat{\theta} - \theta) \xrightarrow{d} \mathcal{N}(0, V),$$
 (4.9)

where  $\theta := (\phi_1, \dots, \phi_p, \sigma_y, \sigma_v, \delta_p)'$  and

$$V = G(\beta) \begin{bmatrix} V_{\mu} & C'_{\mu,\Gamma(2p)} & C_{\mu,\lambda_{y}(1)} \\ C_{\mu,\Gamma(2p)} & V_{\Gamma(2p)} & C_{\Gamma(2p),\lambda_{y}(1)} \\ C_{\mu,\lambda_{y}(1)} & C'_{\Gamma(2p),\lambda_{y}(1)} & V_{\lambda_{y}(1)} \end{bmatrix} G(\beta)', \tag{4.10}$$

$$G(\beta) := \frac{\partial D_p}{\partial \beta'}, \quad D_p := D_p(\beta) = (D_{\phi_p}, D_{\sigma_y}, D_{\sigma_v}, D_{\delta_p})', \quad \beta := [\mu, \gamma_{y^*}(0), \gamma_{y^*}(1), \dots, \gamma_{y^*}(2p), \lambda_y(1)]', \tag{4.11}$$

$$D_{\phi_{p}} := \boldsymbol{\Gamma}(p, 1)^{-1} \gamma(p, 1), \quad D_{\sigma_{y}} := \exp(\mu - \bar{\mu})^{1/2}, \quad D_{\sigma_{v}} := [\gamma_{y^{*}}(0) - \phi_{p}^{'} \gamma(1) - \pi^{2}/2]^{1/2}, \quad (4.12)$$

$$D_{\delta_{p}} = \frac{\sqrt{2\pi}\lambda_{y}(1)}{\sigma_{v}\sigma_{v}^{2}} \exp\left(-\frac{1}{4}\tilde{\gamma}_{p}\right), \quad \lambda_{y}(1) := \mathbb{E}[|y_{t}|y_{t-1}], \tag{4.13}$$

$$\phi_{p} = (\phi_{1}, \dots, \phi_{p})', \quad \gamma(p, 1) = [\gamma_{y^{*}}(p+1), \dots, \gamma_{y^{*}}(2p)]', \\ \gamma(p) = [\gamma_{y^{*}}(1), \dots, \gamma_{y^{*}}(p)]',$$

$$(4.14)$$

$$\Gamma(p,1)_{[p\times p]} = \begin{bmatrix}
\gamma_{y^*}(p) & \gamma_{y^*}(p-1) & \cdots & \gamma_{y^*}(1) \\
\gamma_{y^*}(p+1) & \gamma_{y^*}(p) & \cdots & \gamma_{y^*}(2) \\
\vdots & \vdots & & \vdots \\
\gamma_{y^*}(2p-1) & \gamma_{y^*}(2p-2) & \cdots & \gamma_{y^*}(p)
\end{bmatrix},$$
(4.15)

$$\gamma_{y^*}(k) = \text{cov}(y_t^*, y_{t-k}^*) \,, \quad y_t^* = (\log y_t^2 - \mu) \,, \quad \mu := \mathbb{E}[\log(y_t^2)] \,, \quad \tilde{\gamma}_p := \text{var}(w_t) + \text{cov}(w_t, w_{t-1}). \tag{4.16}$$

The explicit form of the analytical moment derivative,  $G(\beta)$ , is given in the proof. An estimator of the covariance matrix V can be obtained by using heteroskedasticity and autocorrelation consistent (HAC) covariance estimators [see Den Haan and Levin (1997) and Robinson and Velasco (1997)] and then substituting  $\hat{\beta} = [\hat{\mu}, \ \hat{\gamma}_{y^*}(0), \ \hat{\gamma}_{y^*}(1), \ \hat{\gamma}_{y^*}(2), \dots, \ \hat{\gamma}_{y^*}(2p), \ \hat{\lambda}_y(1)]'$  into  $G(\beta)$ . In our empirical applications, we use a Bartlett kernel estimator with the bandwidth varying with the sample size; see Newey and West (1994). One can alternatively use the analytic expressions of  $\gamma_{y^*}(k)$  to obtain an estimator of  $V_{\mu}$ . The ARMA-type estimator can be viewed as a GMM-type estimator, so one can also use GMM standard errors.

Theorem 4.3 covers the simplest CF-ARMA estimator. It is easy to see that the asymptotic distribution of more general winsorized estimators can be derived in the same way upon using Lemmas 4.1 - 4.2.

## 5 Forecasting with SVL(p) models

As discussed earlier, SVL(p) models can be written as a linear state-space model without losing any information. The state-space representation of SVL(p) models is given by

$$y_t^* = w_t + \epsilon_t, \qquad w_{t+1} = \sum_{j=1}^p \phi_j w_{t-j+1} + \tilde{\delta}_p z_t + \tilde{\sigma}_v \bar{v}_{t+1},$$
 (5.1)

where  $\tilde{\delta} = \delta \sigma_v$ ,  $\tilde{\sigma}_v = \sqrt{\left(1 - \delta^2\right)} \sigma_v$ ,  $\bar{\nu}_t$ 's are i.i.d.  $\mathcal{N}(0,1)$ , and  $\epsilon_t$ 's are approximated by a normal distribution with mean 0 and variance  $\pi^2/2$ . Using similar notation as that found in Hamilton (1994), this model can also be rewritten as follows:

$$y_{t}^{*} = H'\xi_{t} + \epsilon_{t}, \quad \xi_{t+1} = F\xi_{t} + \sigma_{v}u_{t+1}, \quad u_{t+1} = \delta\eta_{t} + (1 - \delta^{2})^{1/2}\zeta_{t+1}, \quad \mathbb{E}[u_{t}u'_{t}] = \mathbb{E}[z_{t}z'_{t}] = \mathbb{E}[\tilde{v}_{t}\tilde{v}'_{t}] = \Omega_{1}, \quad (5.2)$$

where H' = [1, 0, ..., 0] is a  $1 \times p$  vector, u and

$$\xi_{t} = \begin{bmatrix} w_{t} \\ w_{t-1} \\ w_{t-2} \\ \vdots \\ w_{t-p+1} \end{bmatrix}, F = \begin{bmatrix} \phi_{1} & \phi_{2} & \cdots & \phi_{p-1} & \phi_{p} \\ 1 & 0 & \cdots & 0 & 0 \\ 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \end{bmatrix}, \eta_{t} = \begin{bmatrix} z_{t} \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \zeta_{t} = \begin{bmatrix} \tilde{v}_{t} \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, u_{t+1} = \begin{bmatrix} v_{t+1} \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \Omega_{1} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \dots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix},$$

where F and  $\Omega_1$  are  $p \times p$  matrices, and  $\xi_t$ ,  $u_t$ ,  $\eta_t$ ,  $\zeta_t$  are  $p \times 1$  vectors. Using (5.2), the Kalman filter can be applied as follows.

- Initialization:  $\hat{\boldsymbol{\xi}}_{1|0} = \mathbb{E}[\boldsymbol{\xi}_1] = \mathbf{0}_{(p \times 1)}$ ,  $\boldsymbol{P}_{1|0} = \mathbb{E}[(\boldsymbol{\xi}_1 \mathbb{E}[\boldsymbol{\xi}_1])(\boldsymbol{\xi}_1 \mathbb{E}[\boldsymbol{\xi}_1])'] = \operatorname{diag}[\sigma_v^2, \dots, \sigma_v^2]_{(p \times p)}$ , where  $\boldsymbol{P}_{1|0}$  is the MSE associated with  $\hat{\boldsymbol{\xi}}_{1|0}$ .
- Sequential updating:  $K_t = \mathbf{P}_{t|t-1}H\left(H'\mathbf{P}_{t|t-1}H + \frac{\pi^2}{2}\right)^{-1}$ ,  $\hat{\boldsymbol{\xi}}_{t|t} = \hat{\boldsymbol{\xi}}_{t|t-1} + K_t\left(y_t^* H'\hat{\boldsymbol{\xi}}_{t|t-1}\right)$ ,  $\mathbf{P}_{t|t} = \mathbf{P}_{t|t-1} K_tH'P_{t|t-1}$ .
- In-sample prediction:  $\hat{\xi}_{t+1|t} = F\hat{\xi}_{t|t} + \tilde{\delta}\eta_{t|t}$ ,  $P_{t+1|t} = FP_{t|t}F_v'^2\Omega_1$ ,  $\hat{y}_{t+1|t} = H'\hat{\xi}_{t+1|t}$ ,  $\mathbb{E}[(y_{t+1} \hat{y}_{t+1|t})(y_{t+1} \hat{y}_{t+1|t})'] = H'\mathbf{P}_{t+1|t}H + \frac{\pi^2}{2}, \tag{5.3}$

where the last two lines follow from (5.2).

• Out-of-sample *h* step-ahead forecasting:

$$\hat{\xi}_{T+h|T} = F^h \hat{\xi}_{T|T} + F^{(h-1)} \tilde{\delta} \eta_{T|T}, \quad \hat{y}_{T+h|T}^* = H' \hat{\xi}_{T+h|T}.$$
 (5.4)

Hence, the h-step ahead forecast is computed using (5.4) and the simple estimates. Note that here, the leverage parameter  $\delta$  appears in prediction equation given in the first line of (5.3) and (5.4). When there is no leverage, this value will simply be zero and as a result, in sample predictions will also differ. It can also be seen from the first line in (5.4) that as h becomes larger, the effect from leverage will decay. Hence, we may expect that forecasts from a model with leverage and that from a model without leverage may not differ too much when forecasting very far out of sample.

## 6 Hypothesis testing

In this section, we discuss how to test a hypothesis on an SVL(p) model. First, we discuss asymptotic tests based on LR-type test statistics. Second, we show how to construct finite-sample tests using the Monte Carlo test technique.

Finally, we show how we can derive implicit standard errors (ISE) for the parameters of our model from simulationbased confidence intervals.

#### 6.1 Asymptotic tests

The SVL(p) model has three parameters in addition to the p autoregressive parameters (*i.e.*, a total of p+3 parameters). These are given by  $\theta = (\phi_1, \ldots, \phi_p, \sigma_y, \sigma_v, \delta_p)'$ . To test the values of individual parameters, we can consider t-type statistics of the form:

$$T(\theta_i) = (\hat{\theta}_i - \theta_1) / SE(\hat{\theta}_i) \tag{6.1}$$

where the standard error  $SE(\hat{\theta}_i)$  is calculated from the asymptotic covariance matrix given in (4.9). Alternatively, we can also consider GMM-based LR-type statistics, based on the following moment-based objective function:

$$M_T(\theta) := g_T(\theta)' A_T g_T(\theta) \tag{6.2}$$

where  $g_T(\theta)$  is  $(p+3) \times 1$  vector of moment functions, defined as

$$g_{T}(\theta) = \begin{bmatrix} \hat{\mu} + 1.2704 - \log(\sigma_{y}^{2}) \\ \hat{\gamma}_{y^{*}}(0) + \hat{\gamma}_{y^{*}}(1) - (\pi^{2}/2) - (1 - \phi_{1})^{-1} \left( \sum_{j=2}^{p} \left[ \phi_{j}(\hat{\gamma}_{y^{*}}(j-1) + \hat{\gamma}_{y^{*}}(j) \right] - \sigma_{v}^{2} \right) \\ \hat{\gamma}_{y^{*}}(p+1) - \left[ \phi_{1}\hat{\gamma}_{y^{*}}(p) + \dots + \phi_{p}\hat{\gamma}_{y^{*}}(1) \right] \\ \vdots \\ \hat{\gamma}_{y^{*}}(2p) - \left[ \phi_{1}\hat{\gamma}_{y^{*}}(2p-1) + \dots + \phi_{p}\hat{\gamma}_{y^{*}}(p) \right] \\ \delta - \frac{\sqrt{2\pi}\hat{\lambda}_{y}(1)}{\sigma_{v}\sigma_{y}^{2}} \exp\left( -\frac{1}{4}\tilde{\gamma}_{p} \right) \end{bmatrix}$$

$$(6.3)$$

and  $A_T$  is an appropriate weighting matrix.  $M_T(\theta)$  is (up to an asymptotically negligible term) a GMM objective function.

The first moment function follows from first part of (3.5) after taking logarithm and the second moment condition follows from the Corollary of Autocovariances of SV Process on adding the equations for k = 0 and k = 1 [in (3.2)], which yields

$$\hat{\gamma}_{y^*}(0) + \hat{\gamma}_{y^*}(1) - (\pi^2/2) - (1 - \phi_1)^{-1} \left( \sum_{j=2}^p \left[ \phi_j(\hat{\gamma}_{y^*}(j-1) + \hat{\gamma}_{y^*}(j) \right] - \sigma_v^2 \right) = 0.$$
 (6.4)

The preceding p moment conditions prior to the final one are corresponds to (3.2) with k=p+1,...,2p and the last equation comes from (3.6) where  $\tilde{\gamma}_p$  is a function of  $(\phi_1,...,\phi_p,\sigma_v)$ .

Since the number of moment functions in (6.3) is equal to the number of parameters, we have a just identified case and could set  $A_T = I_{(p+3)}$  and consider the GMM-type objective function

$$M_T^I(\theta) = g_T(\theta)'g_T(\theta). \tag{6.5}$$

where the superscript I denotes the use of the identity matrix. However, in order to ensure that the LR-type test statistic in (6.10) has a  $\chi^2$  distribution asymptotically, we should set  $A_T = \hat{\Omega}_*^{-1}$  where  $\hat{\Omega}_*$  is a consistent estimator of

 $\Omega_*$ . Here, we propose the following estimator for  $\Omega_*$ :

$$\hat{\Omega}_* = \hat{\Gamma}_0 + \sum_{k=1}^{K(T)} \left( 1 - \frac{k}{K(T) + 1} \right) (\hat{\Gamma}_k + \hat{\Gamma}'_k) \tag{6.6}$$

where

$$\hat{\Gamma}_k = \frac{1}{T} \sum_{t=k+1}^{T} [g_t(\theta)g_t(\theta)']$$
 (6.7)

and where we use

$$g_{t}(\theta) = \begin{bmatrix} \log(y_{t}^{2}) + 1.2704 - \log(\sigma_{y}^{2}) \\ y_{t}^{*} y_{t}^{*} + y_{t}^{*} y_{t+1}^{*} - (\pi^{2}/2) - (1 - \phi_{1})^{-1} \left( \sum_{j=2}^{p} \left[ \phi_{j} (y_{t}^{*} y_{t+j-1}^{*} + y_{t}^{*} y_{t+j}^{*} \right] - \sigma_{v}^{2} \right) \\ y_{t}^{*} y_{p+1}^{*} - \left[ \phi_{1} y_{t}^{*} y_{t+p}^{*} + \dots + \phi_{p} y_{t}^{*} y_{t+1}^{*} \right] \\ \vdots \\ y_{t}^{*} y_{t+2p}^{*} - \left[ \phi_{1} y_{t}^{*} y_{t+2p-1}^{*} + \dots + \phi_{p} y_{t}^{*} y_{t+p}^{*} \right] \\ \delta - \frac{\sqrt{2\pi}(|y_{t+1}|y_{t})}{\sigma_{v} \sigma_{y}^{2}} \exp\left( -\frac{1}{4} \tilde{\gamma}_{p} \right) \end{bmatrix}$$

$$(6.8)$$

giving the GMM-type objective function

$$M_T^*(\theta) = g_T(\theta)' \hat{\Omega}_*^{-1} g_T(\theta).$$
 (6.9)

To test hypotheses on  $\theta$ , the LR-type statistic is the difference between the restricted and unrestricted optimal values of the objective function:

$$LR_T = T[M_T^*(\hat{\theta}_0) - M_T^*(\hat{\theta})]$$
(6.10)

where  $\hat{\theta}$  is the unrestricted estimator and  $\hat{\theta}_0$  is the constrained estimator under the null hypothesis. Under standard regularity conditions, the asymptotic distribution of  $LR_T$  is  $\chi^2_r$  where r is the number of constraints; see Newey and West (1987), Newey and McFadden (1994), Dufour et al. (2017). Note however that usual regularity conditions may not be satisfied when some parameters are not identified or the null hypothesis involves the frontier of the parameter space. Such cases may lead to the estimate  $\hat{\Omega}_*$  being infeasible, ill-defined, or near-singular. In the following subsection, we propose a simulation-based test that does not rely on  $\hat{\Omega}_*$ , nor the asymptotic distribution of the LR-type test statistic, making  $M_T^I(\theta)$ , more practical.

#### 6.2 Simulation-based finite-sample tests

In this section, we discuss simulation-based inference procedures for SVL(p) models with leverage. The simulation-based methods are more attainable in the context of this study for two reasons. First, the SVL(p) model is a parametric model with a finite number of parameters, and we can effortlessly simulate this model. Second, we can simulate the test statistic of SVL(p) parameters, which is based on a computationally inexpensive estimator. So, using our proposed computationally simple estimators, one can easily construct more reliable finite-sample inference. It should be noted that, in other cases, the simulation-based procedure may not be attainable when the estimator is computationally expensive, so that we cannot simulate the test statistic easily. However here, using our proposed computationally simple estimators, one can easily construct more reliable finite-sample inference.

We now examine the usefulness of our simple estimators in the context of simulation-based inference, *i.e.*, Monte Carlo test technique. The MCT technique was originally proposed by Dwass (1957) for implementing permutation tests and did not involve nuisance parameters. This technique was also independently proposed by Barnard (1963); for a review, see Dufour and Khalaf (2001) and for a general discussion and proofs, see Dufour (2006). It has the great attraction of providing exact (randomized) tests based on any statistic whose finite-sample distribution may be intractable but can be simulated. One can replace the unknown or intractable theoretical distribution  $F(S|\theta)$ , where  $\theta := (\phi_1, ..., \phi_p, \sigma_y, \sigma_v, \delta_p)'$ , by its sample analog based on the statistics  $S_1(\theta), ..., S_N(\theta)$  simulated under the null hypothesis.

Let us first consider the case of pivotal statistics, *i.e.* the case where the distribution of the test statistic under the null hypothesis does not depend on nuisance parameters. We can then proceed as follows to obtain an exact critical region for testing a null hypothesis  $H_0$ .

- 1. Compute the observed test statistic  $S_0$  from the available data.
- 2. By Monte Carlo methods, draw N i.i.d. replications of S, denoted by  $S(N) = (S_1, ..., S_N)$  under  $H_0$ .
- 3. From the simulated samples, compute the MC *p*-value  $\hat{p}_N[S] := p_N[S_0; S(N)]$ , where

$$p_N[x, S(N)] := \frac{NG_N[x; S(N)] + 1}{N+1},$$
(6.11)

$$G_N[x;S(N)] := \frac{1}{N} \sum_{i=1}^N \mathbb{1}_{[0,\infty)}(S_i - x), \quad \mathbb{1}_{[0,\infty)}(x) = \begin{cases} 1 & \text{if } x \in [0,\infty), \\ 0 & \text{if } x \notin [0,\infty). \end{cases}$$
(6.12)

In other words,  $p_N[S_0; S(N)] = (NG_N[S_0; S(N)] + 1)/(N+1)$  where  $NG_N[S_0; S(N)]$  is the number of simulated values which are greater than or equal to  $S_0$ . When  $S_0, S_1, ..., S_N$  are all distinct [an event with probability one when the vector  $(S_0, S_1, ..., S_N)'$  has an absolutely continuous distribution],  $\hat{R}_N(S_0) = N + 1 - NG_N[S_0; S(N)]$  is the rank of  $S_0$  in the series  $S_0, S_1, ..., S_N$ .

4. The MC critical region is:  $\hat{p}_N[S] \le \alpha$ ,  $0 < \alpha < 1$ . If  $\alpha(N+1)$  is an integer and the distribution of S is continuous under the null hypothesis, then under null,  $P[\hat{p}_N[S] \le \alpha] = \alpha$ ; see Dufour (2006).

For further discussions regarding MCT techniques with nuisance parameters (e.g., Local/Maximized MCT), see Appendix C.

#### 6.3 Implicit standard error

In this subsection, we show that *implicit standard errors* (ISE) for the components of a parameter vector  $\theta = (\theta_1, ..., \theta_m)'$  can be derived from simulation-based confidence intervals. The asymptotic standard error proposed in Section 4 can be markedly different and may be quite unreliable in finite samples. To construct a more reliable standard error, we derive the ISE in the following way.

- 1. Calculate the (typically restricted) estimate  $\hat{\theta}_0 = (\hat{\theta}_{10}, \dots, \hat{\theta}_{m0})'$  from observed data  $(\mathbb{Y}_0)$ .
- 2. Using  $\hat{\theta}_0$  as parameter value, generate N i.i.d. replications  $\mathbb{Y}(N) = (\mathbb{Y}_1, ..., \mathbb{Y}_N)$  of  $\mathbb{Y}$ , by Monte Carlo methods.

- 3. From  $\mathbb{Y}(N) = (\mathbb{Y}_1, \dots, \mathbb{Y}_N)$ , compute the corresponding parameter estimates.
- 4. For each component  $\theta_i$  of  $\theta$ , the confidence interval  $[C_i(\alpha_L), C_i(\alpha_H)]$ , with coverage  $\alpha = \alpha_L \alpha_H$ , is constructed using the empirical  $\alpha_{iL}$  quantile and the empirical  $\alpha_{iH}$  quantile of  $\hat{\theta}_i(N) = (\hat{\theta}_{i0}, \hat{\theta}_{i1}, \dots, \hat{\theta}_{iN})$ .
- 5. By analogy with usual Gaussian-based confidence intervals, we set  $C_i(\alpha_L) = \hat{\theta}_{i0} z(\alpha/2) \,\hat{\sigma}_{iL}$  and  $C_i(\alpha_H) = \hat{\theta}_{i0} + z(\alpha/2) \,\hat{\sigma}_{iH}$ , where  $z(\alpha/2)$  satisfies  $P[Z \ge z(\alpha/2)] = \alpha/2$  and  $Z \sim N(0,1)$ . This suggests that two numbers could play the role of "standard errors" here:

$$\hat{\sigma}_{iL} = \frac{\hat{\theta}_{i0} - C_i(\alpha_L)}{z(\alpha/2)} := ISE_{iL}, \quad \hat{\sigma}_{iU} = \frac{C_i(\alpha_H) - \hat{\theta}_{i0}}{z(\alpha/2)} := ISE_{iH}. \tag{6.13}$$

6. Finally, a conservative ISE for  $\theta_i$  is given by min{ $ISE_{iL}$ ,  $ISE_{iH}$ } and a liberal ISE is given by the average or max{ $ISE_{iL}$ ,  $ISE_{iH}$ }.

## 7 Simulation study

In this section, we evaluate the properties of our proposed estimators through simulation, focusing specifically on bias and root mean square error (RMSE). Furthermore, we present simulation findings regarding the finite-sample properties of the LR-type test discussed in Section 6. In addition, through simulations, we illustrate the significance of leverage in the context of volatility forecasting.

#### 7.1 Estimation

Now, we assess the statistical performance of our proposed estimators. These estimators include the closed-form ARMA (CF-ARMA) estimator, as well as four winsorized ARMA (W-ARMA) estimators with no intercept regression, where (J = 10, 50, 100, 200). Overall, there is no consistent ranking among the different estimators. However, the Bayesian estimator consistently outperforms other methods in the context of an SV(1) model; refer to Jacquier et al. (1994) for details. Consequently, we compare our proposed estimators with both QML [see Harvey and Shephard (1996)] and Bayesian [see Jacquier et al. (1994), Kim et al. (1998)] estimators. We consider an SVL(1) model with parameter values set at ( $\phi$ ,  $\sigma$ <sub>V</sub>,  $\sigma$ <sub>V</sub>,  $\delta$ ) = (0.95, 0.15, 1, -0.95). These parameter choices are typical in empirical studies focusing on hourly or daily returns. We conduct simulations with 1000 replications and present results for two distinct sample sizes (T = 1000, 2000).

Bayesian estimates based on Markov Chain Monte Carlo methods are computed using mixture sampler of Omori et al. (2007), where the SVL(1) model is reparametrized as  $y_t = \exp(w_t/2)z_t$  and  $w_t = \mu_w + \phi(w_{t-1} - \mu_w) + \sigma_v v_t$ , where  $\sigma_y = \exp(\mu_w/2)$ . Regarding this reparametrization, see also Kim et al. (1998). The priors for  $\mu_w$ ,  $\phi$ ,  $\sigma_v$ , and  $\delta$  are set to:  $\mu_w \sim \mathcal{N}$  (-3,5);  $\sigma_v^2 \sim \mathcal{IG}\left(\frac{5}{2},\frac{0.05}{2}\right)$  with mean 0.0167 and standard deviation 0.0237;  $\phi \in (-1,1)$  with  $\frac{\phi+1}{2} \sim \mathcal{B}$  (20,1.5), giving  $\phi$  a mean of 0.86 and a standard deviation of 0.11;  $\delta \sim \mathcal{U}(-1,1)$ , where  $\mathcal{U}$  denotes the uniform distribution,  $\mathcal{B}$  denotes the beta distribution, and  $\mathcal{IG}$  denotes the inverse gamma distribution. Note that, except

Table 1. Comparison with competing estimators: Bias and RMSE

					В	ias			RM	ISE	
				$\overline{\phi}$	$\sigma_y$	$\sigma_{v}$	δ	φ	$\sigma_y$	$\sigma_v$	δ
							True V	alue			
T	Estimators	RCT	NIV	0.95	0.15	1	-0.95	0.95	0.15	1	-0.95
	Bayes	6.06E+08	0	0.0314	0.1102	-0.5120	0.1608	0.0318	0.1607	0.5128	0.1621
	QML	23063.9	0	-0.0102	0.0087	-0.2139	0.3490	0.0462	0.0521	0.5896	0.3611
	CF-ARMA	1.0	24	-0.0050	0.0087	-0.0259	-0.0290	0.0291	0.0521	0.2579	0.1213
	W-ARMA $(J = 10)$	1.3	0	-0.0060	0.0087	0.0147	-0.0293	0.0155	0.0521	0.0878	0.1185
1000	W-ARMA $(J = 50)$	1.9	0	-0.0069	0.0087	0.0218	-0.0289	0.0168	0.0521	0.1008	0.1197
	W-ARMA ( $J = 100$ )	2.8	0	-0.0040	0.0087	-0.0060	-0.0298	0.0160	0.0521	0.1035	0.1182
	W-ARMA $(J = 200)$	3.9	0	0.0009	0.0087	-0.0544	-0.0310	0.0158	0.0521	0.1241	0.1163
	Bayes	7.84E+08	0	0.0316	0.0543	-0.5115	0.1612	0.0317	0.0728	0.5120	0.1627
	QML	30509.9	0	-0.0051	0.0047	-0.1240	0.3490	0.0171	0.0357	0.2733	0.3542
	CF-ARMA	1.0	1	-0.0026	0.0044	-0.0166	-0.0460	0.0202	0.0355	0.1893	0.0706
	W-ARMA $(J = 10)$	1.1	0	-0.0034	0.0045	0.0077	-0.0461	0.0101	0.0355	0.0613	0.0695
2000	W-ARMA $(J = 50)$	1.5	0	-0.0038	0.0045	0.0108	-0.0461	0.0111	0.0355	0.0755	0.0694
	W-ARMA ( $J = 100$ )	2.2	0	-0.0022	0.0045	-0.0044	-0.0461	0.0107	0.0355	0.0764	0.0692
	W-ARMA $(J = 200)$	3.4	0	0.0007	0.0045	-0.0329	-0.0463	0.0107	0.0355	0.0876	0.0688

Notes: We simulate 1000 samples from each model. W-ARMA (J = 10, 50, 100, 200) is the winsorized ARMA estimator based on OLS and J is the winsorizing parameter. These methods are proposed in Section 3. QML is the quasi-maximum likelihood estimator of Harvey and Shephard (1996). We used mixture sampler for the Bayesian estimation [see Omori et al. (2007)], where the posteriors are based on 2500 draws of the sampler, after discarding 2500 draws. RCT stands for the relative computational time w.r.t. the CF-ARMA estimator. The number of inadmissible values (NIV) of  $\phi$  is also reported, these are out of 1000. Boldface font highlights the smallest bias and RMSE with no NIV. For additional results related to this table, see Appendix Table A1.

for the parameter  $\mu_w$ , for which we use a slightly informative prior, we adopt the priors proposed by Omori et al. (2007). The sampler is initialized by setting  $\mu_w^{(0)} = -4.6$ ,  $\phi^{(0)} = 0.9$ ,  $\sigma_v^{(0)}^2 = 0.9$ , and  $\delta^{(0)} = -0.9$ . We apply this Bayesian method on simulated data sets and draw 5000 observations from the posterior distributions. Bayesian estimators are obtained by averaging the last 2500 draws.

In our simulations, we find the CF-ARMA estimator of  $\phi$  occasionally produced values outside the stationary region. These samples were discarded from calculation. Therefore, the bias and RMSE obtained are thus conditional on the non-occurrence of inadmissible values. Such problems are practically non-existent with the OLS-based W-ARMA estimator. Table 1 presents the estimation outcomes, revealing that the W-ARMA estimator consistently exhibits superior performance in bias and RMSE across all parameter values and sample sizes. Specifically, the winsorized ARMA estimator with J=10 consistently outperforms all other estimators, including QML and the Bayesian estimator, demonstrating significantly lower bias and RMSE. Moreover, winsorized estimators are notably more time-efficient, as evidenced by the considerable margin of time savings compared to alternative methods. These findings offer valuable insights into the relative performance of various estimation techniques for SVL(1) models.

#### 7.2 Testing

Here, we are interested in testing for no leverage and hence consider the following hypothesis

$$H_0: \delta = 0 \quad vs \quad H_1: \delta \neq 0 \tag{7.1}$$

Table 2. Empirical size of tests for no leverage in SVL(1) model (moderate persistence)

		Н	$I_0$ : $\delta = 0$ vs. $H_1$ : $\delta \neq 0$						
	$\phi = 0$	0.90, $\sigma_y = 0.10$ , $\sigma_z$	v = 0.75	$\phi = 0.75$ , $\sigma_y = 0.10$ , $\sigma_v = 1.00$					
T	Asy	LMC	MMC	Asy	LMC	MMC			
500	1.1	5.6	0.8	1.1	4.9	1.3			
1000	1.9	7.0	1.9	0.5	5.2	2.0			
2000	2.3	5.4	1.6	0.4	4.6	1.5			
5000	2.5	4.6	2.7	1.8	5.4	3.6			

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

Table 3. Empirical power of tests for no leverage in SVL(1) model (moderate persistence)

					$H_0$	: $\delta = 0$ vs. $H$	$I_1: \delta \neq 0$					
		$\delta = -0.90$	0		$\delta = -0.70$	)		$\delta = 0.70$			$\delta = 0.90$	)
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	90, $\sigma_y = 0.10$	0, $\sigma_{v} = 0.75$					
500	89.3	90.1	71.2	67.5	69.7	45.1	65.7	66.2	43.9	90.2	90.2	71.0
1000	95.7	96.0	89.2	86.5	86.8	72.4	86.6	86.7	71.8	97.4	97.7	89.6
2000	99.5	99.3	95.0	96.3	95.1	90.0	95.8	96.0	91.1	98.9	98.8	95.9
5000	99.4	99.3	98.2	98.4	98.3	97.0	99.1	99.2	97.0	99.7	99.9	98.3
					$\phi = 0.7$	75, $\sigma_y = 0.10$	$\sigma_v = 1.00$					
500	97.6	97.5	91.1	95.4	94.8	83.2	93.5	93.0	79.0	97.9	97.2	89.2
1000	98.2	98.3	95.8	97.4	98.3	94.2	98.3	98.1	94.4	98.7	98.6	96.4
2000	99.6	99.7	99.1	99.5	99.6	98.5	99.6	99.6	98.7	99.6	99.5	98.8
5000	99.9	99.9	99.8	99.9	99.9	99.9	100.0	99.9	99.9	99.9	99.9	99.9

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N=99 simulations. Asymmetric test results are level-corrected using N=10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

To test the hypothesis of no leverage, we utilize the vector of moment conditions given in equation (6.3) to derive  $g_T(\theta_1)$ , which remains consistent with the unconstrained model. We then simply set  $\delta = 0$  in the final moment condition to derive  $g_T(\theta_0)$ . It is worth noting that all moment conditions, except the last one, are independent of  $\delta$  and remain identical under both the null and alternative hypotheses.

The unrestricted and restricted objective functions are denoted by  $M_T^*(\theta_1) = g_T(\theta_1)'\hat{\Omega}_{1,*}^{-1}g_T(\theta_1)$  and  $M_T^*(\theta_0) = g_T(\theta_0)'\hat{\Omega}_{0,*}^{-1}g_T(\theta_0)$  respectively. Here, the complete parameter vector under  $H_1$  is represented by  $\theta = (\phi_1, ..., \phi_p, \sigma_y, \sigma_v, \delta)'$ , while under  $H_0$ , the vector of nuisance parameters reduces to  $\tilde{\theta} = (\phi_1, ..., \phi_p, \sigma_y, \sigma_v)'$ . Hence, within the framework of LMC tests, the values  $\hat{\theta}_0 = (\hat{\phi}_1^0, ..., \hat{\phi}_p^0, \hat{\sigma}_y^0, \hat{\sigma}_v^0)'$ , obtained from estimating the restricted model using observed data, are used to simulate the null distribution of the test statistic.

When considering MMC tests, we consider the consistent set define by

$$C_{T}^{(1)}(\delta^{0}) = \left\{ \tilde{\theta}_{0} \in \tilde{\Omega}_{0} : \left\| \phi_{k} - \hat{\phi}_{k}^{0} \right\| \leq 0.01, |\phi_{k}| \leq 0.999, \left\| \sigma_{y} - \hat{\sigma}_{y}^{0} \right\| \leq 0.05, |\sigma_{y}| \geq 0.01, \left\| \sigma_{v} - \hat{\sigma}_{v}^{0} \right\| \leq 0.05, |\sigma_{v}| \geq 0.01 \right\} \quad (7.2)$$

for SVL(1) models. For SVL(2) models, we will consider a larger set which includes more values of the variance

Table 4. Empirical size of tests for no leverage in SVL(1) model (high persistence)

		Н	$I_0$ : $\delta = 0$ vs. $H_1$ : $\delta \neq 0$			
	$\phi = 0$	$0.99,  \sigma_{\gamma} = 0.10,  \sigma_{\gamma}$	v = 0.25	$\phi = 0$	$0.95,  \sigma_{\gamma} = 0.10,  \sigma_{\gamma}$	v = 0.50
T	Asy	LMC	MMC	Asy	LMC	MMC
500	0.9	5.7	1.0	1.4	5.0	0.8
1000	1.0	5.2	1.6	1.4	4.4	0.6
2000	1.4	5.1	1.8	1.2	3.7	0.9
5000	2.3	5.8	3.5	2.9	6.5	2.1

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

Table 5. Empirical power of tests for no leverage in SVL(1) model (high persistence)

					$H_0$	: $\delta = 0$ vs. $H_1$	$: \delta \neq 0$					
		$\delta = -0.90$	)		$\delta = -0.70$	0		$\delta = 0.70$			$\delta = 0.90$	)
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	99, $\sigma_{V} = 0.10$ ,	$\sigma_v = 0.25$					
500	17.5	18.8	8.8	11.8	11.7	4.8	12.6	13.6	5.5	20.8	22.7	10.6
1000	30.7	30.0	16.4	19.7	20.5	10.1	19.5	18.6	10.3	31.5	32.6	17.0
2000	50.1	47.2	33.0	32.9	30.1	20.1	33.0	31.3	20.0	50.1	47.3	34.3
5000	78.9	77.7	71.2	55.7	54.1	50.0	56.0	55.7	50.2	79.4	78.4	73.8
					$\phi = 0.9$	$05, \sigma_y = 0.10,$	$\sigma_{v} = 0.50$					
500	65.7	67.9	43.7	42.3	44.2	22.9	42.8	44.9	21.5	66.4	67.8	44.2
1000	86.7	87.6	74.2	64.4	65.8	47.3	64.8	65.1	47.8	88.5	89.6	74.4
2000	97.8	97.8	92.8	86.0	85.8	73.9	86.6	85.8	77.0	98.3	98.2	92.4
5000	99.5	99.4	97.7	97.0	97.2	95.7	98.1	97.9	95.7	99.6	99.6	98.2

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N=99 simulations. Asymmetric test results are level-corrected using N=10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

Table 6. Empirical size of tests for no leverage in SVL(2) model

			$H_0$ : $\delta = 0$ vs. $H_1$ : $\delta \neq 0$							
	$\phi_1 = 0.05$	$\phi_{2} = 0.85,  \sigma_{y} = 0.85$	$\phi_1 = 0.05$ ,	$\phi_1 = 0.05,  \phi_2 = 0.70,  \sigma_V = 1.00,  \sigma_V = 1.00$						
T	Asy	LMC	MMC	Asy	LMC	MMC				
500	1.4	5.1	0.8	1.1	5.9	0.7				
1000	2.1	5.8	1.4	0.9	7.0	0.8				
2000	1.2	3.9	0.7	1.1	3.6	1.1				
5000	1.9	5.9	2.0	2.0	6.6	2.1				

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

Table 7. Empirical power of tests for no leverage in SVL(2) model

					$H_0$	$: \delta = 0 \text{ vs. } I$	$H_1:\delta$	<b>≠</b> 0					
		$\delta = -0.90$			$\delta = -0.70$	1			$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC		Asy	LMC	MMC	Asy	LMC	MMC
				φ	$\phi_1 = 0.05,  \phi_2$	$_{2} = 0.85,  \sigma_{y}$	$_{\prime} = 1.0$	$0,\sigma_{\nu}=1$	.00				
500	97.9	95.3	78.0	91.8	88.2	62.0		91.9	89.0	64.0	98.4	97.1	75.0
1000	98.9	98.3	93.0	97.2	96.1	83.0		97.9	97.2	83.0	99.5	98.8	93.0
2000	99.7	99.4	97.0	99.5	99.0	97.0		99.4	99.0	94.0	99.6	99.4	96.0
5000	99.8	99.6	99.0	99.9	99.7	99.0		99.4	99.6	97.0	99.8	99.8	100.0
				φ	$\phi_1 = 0.05,  \phi_2$	$a_2 = 0.70,  \sigma_y$	<sub>/</sub> = 1.0	$0,\sigma_{v}=1$	.00				
500	100.0	100.0	97.4	99.9	99.8	93.8		99.6	99.4	93.6	99.7	99.7	96.6
1000	100.0	100.0	100.0	99.9	100.0	99.3		99.9	99.9	99.3	99.9	99.9	98.7
2000	100.0	100.0	100.0	100.0	100.0	99.5		100.0	100.0	100.0	100.0	100.0	100.0
5000	100.0	100.0	100.0	100.0	100.0	100.0		100.0	100.0	100.0	100.0	100.0	100.0

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo test uses N=99 simulations. Asymmetric test results are level-corrected using N=10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

parameters. This set is given by

$$C_{T}^{(2)}(\delta^{0}) = \left\{ \tilde{\theta}_{0} \in \tilde{\Omega}_{0} : \left\| \phi_{k} - \hat{\phi}_{k}^{0} \right\| \leq 0.01, |\phi_{k}| \leq 0.999, \left\| \sigma_{y} - \hat{\sigma}_{y}^{0} \right\| \leq 0.10, |\sigma_{y}| \geq 0.01, \left\| \sigma_{v} - \hat{\sigma}_{v}^{0} \right\| \leq 0.10, |\sigma_{v}| \geq 0.01 \right\}. \tag{7.3}$$

We report the rejection frequency of the asymptotic, LMC, and MMC test procedures when testing for no leverage. For the asymptotic test, the critical value is obtained from a  $\chi^2_{(1)}$  distribution rather than from the simulated null distribution. As we show, the asymptotic test tends to under-reject when using  $M_T^*$ . In the appendix we include results where  $M_T^I$  is used instead, and in this setting the asymptotic test performs very poorly as size is not controlled. On the other hand, the LMC and MMC procedures tend to perform consistently well. The only exception is when persistence is high and  $M_T^I$  is used. In that case, the LMC tends to over-reject under the null, but only mildly in comparison to the asymptotic test. All rejection frequencies are obtained using 1,000 replications. In cases where we find that there is evidence of under or over-rejection under the null, the rejection frequencies when the alternative hypothesis is true (*i.e.*, power study) are obtained using critical values that are locally level-corrected. Note that we use the term "locally level-corrected" instead of "size-corrected" because a true size correction would require one to ensure that the probability of rejecting the null hypothesis under all distributions compatible with null hypothesis (*i.e.*, for all values of the nuisance parameters) be less than or equal to the level  $\alpha$ . However, finding the appropriate size-corrected critical values requires a numerical search that was not performed in the experiments.

When needed, the level-corrected critical value is obtained by simulating the test statistic under the null hypothesis with 10,000 replications for asymptotic tests and 1,000 replications for LMC tests. It is worth noting that, as a result, the power results for the asymptotic test shown below are infeasible in practice as they require knowing the true DGP. These are only provided for comparison. On the other hand, the MMC test does not involve the use of level-corrected critical values as it already involves a search over values consistent with the null hypothesis. Further, this test does not display any over-rejection under the null hypothesis. The maximization of MMC tests was done

using a particle swarm algorithm and calculations were performed with the R system [see MaxMC package Dufour and Neves (2018); Bendtsen. (2022)]. For all scenarios, we examine the performance of each test procedure across various sample sizes: T = 500, 1,000, 2,000, 5,000. Our findings can be summarized as follows.

First, we consider testing for leverage in an SVL(1) model. Table 2 reports the empirical size of the asymptotic test, LMC test, and MMC test for no leverage across four different sample sizes and two distinct DGPs. These DGPs possess moderate persistence in the volatility process, characterized by  $\theta = (0.90, 0.10, 0.75, 0.00)$  and  $\theta = (0.75, 0.10, 1.00, 0.00)$ , respectively, consistent with the null hypothesis. As observed, the asymptotic test exhibits some under-rejection. Conversely, the simulation-based Local Monte Carlo procedures outlined here performs well in comparison, achieving a rejection frequency much closer to the nominal test level of  $\alpha = 5\%$ . Given that the MMC procedure searches over a larger set of parameters consistent with the null, its rejection frequency is expected to be lower. Table A5 in the appendix shows results when  $M_T^I$  is used instead and as observed, the asymptotic test exhibits a significant degree of over-rejection, failing to control the test size. However, we note that in this case, the LMC procedure also exhibits some over-rejection, particularly evident in the case where  $\phi = 0.90$ , although showing a decreasing trend as the sample size increases. These findings also indicate that as persistence increases from  $\phi = 0.75$  to  $\phi = 0.90$ , both the asymptotic test and the LMC test demonstrate higher levels of over-rejection. On the contrary, this analysis highlights the effectiveness of the MMC procedure, which successfully controls the test size by maintaining a rejection frequency less than or equal to the nominal level, as prescribed by theory.

Second, to showcase the power of these test procedures we consider DGPs with the same values for  $\phi$ ,  $\sigma_v$ , and  $\sigma_v$ , but consider different values of  $\delta$  that are consistent with the alternative hypothesis. Table 3 contains the rejections frequencies for the two DGPs (moderate persistence) and four different sample sizes when  $\delta = -0.90, -0.70, 0.70, 0.90$ . Although it is commonly the case when considering financial time series that the leverage parameter is negative, the last six columns include test results when leverage is positive to show that the power of these tests appear to be symmetrical, in that they are very comparable to the rejection frequencies when leverage is negative values of the same magnitude. We also consider more values of  $\delta$  and summarize all these results graphically in Appendix Figures A2 and A3. When considering these results, it is important to remember that the rejection frequencies for the asymptotic test are obtained using critical values that are level-corrected as described above. These are used instead of the conventional  $\chi^2_1$  critical values so that they may be more comparable since, as seen from Table A2, using the conventional critical values leads to lower power. Hence, the power results for the asymptotic test shown here are infeasible in practice as we do not typically know the true DGP parameter values under the null hypothesis. In the Appendix, Table A6 shows power results when  $M_T^I$  is used. Here, both the asymptotic and LMC tests are level-corrected. Meanwhile, Table A11 shows the same results except that the LMC test rejection frequencies are no longer level-corrected and here we see that there is not a large difference in terms of power, suggesting that the LMC test still performs quite well, even when  $M_T^I$  is used. The Appendix also provides similar figures as described above when  $M_T^*$  is used but the asymptotic test is not level-corrected and when  $M_T^I$  is used.

Those results are summarized graphically in Appendix Figures A4 and A5 and A14 to A17, respectively. As expected, the power of all test procedures increase as the sample size increases. These results also show that when persistence increases from  $\phi = 0.75$  to  $\phi = 0.90$ , the power of all test procedures decreases slightly. This is especially the case for smaller sample sizes but less prevalent for larger samples sizes.

Third, we consider two more DGPs where we increase the degree of persistence. Specifically, we consider a  $\phi=0.95$  and  $\phi=0.99$ . When considering these DGPs under the null hypothesis, such that  $\delta=0$ , and use  $M_T^*$  in computing the LR test statistic, the results shown in Table 4 are no different than in the moderate persistence case. However, when using  $M_T^I$  in computing the LR test statistic, find that there is a higher degree of over-rejection from both the asymptotic test and the LMC test. However, for the LMC test, the over-rejection decreases as the sample size increases. This can be seen from Table A7. Here, we see once again the benefit of the MMC test procedure. The MMC procedure does not rely on the feasibility of estimating  $\hat{\Omega}_*$  and is able to control the size of the test even for the more difficult cases where persistence is very high (e.g.,  $\phi=0.99$ ) and even does so when considering small sample sizes.

Fourth, Table 5 shows that when persistence is much higher the power of the test is also affected. While the power remains relatively high when  $\phi = 0.95$ , it decreases notably when  $\phi = 0.99$ , such that the power of the LMC test, for instance, is not as substantial. Nevertheless, the power of the LMC test is comparable to the infeasible asymptotic test, which suggest it still performs quite well. As can be seen, the power still increases with the sample size when persistence is high as expected and so we should expect that for cases where persistence is very high, a larger sample size can achieve even better power results. As before, we also provide a table where the asymptotic test is not locally level-corrected; see Appendix Table A3. Similarly, Appendix Tables A8 and A12 present results when  $M_T^I$  is used with level-corrected critical values and without level-corrected critical values for the LMC test respectively. In addition, Appendix Figures A6-A9 and A18-A21 summarize results for more values of  $\delta$  for both DGPs considered here when using  $M_T^*$  without level-correction and when using  $M_T^I$  with and without level-correction.

Fifth, we test the hypothesis of no leverage when the DGP includes an additional lag (i.e., when p=2). Specifically, we consider two DGPs that are similar to the ones considered for the SVL(1) case in the sense that the persistence is similar. Tables 6 and A9 summarize the results of the test procedures under the null hypothesis. The results for the asymptotic and LMC tests are similar to when we considered an SVL(1) model. That is, when using  $M_T^*$  there is some under-rejection for the asymptotic test and when using  $M_T^I$  the asymptotic test displays a very high degree of over-rejection, while the LMC test displays a small degree of over-rejection that appears to decrease for larger sample sizes and is especially smaller for the second DGP where  $\phi_1=0.05$  and  $\phi_2=0.70$ . As previously mentioned, here we expand the consistent set used for the MMC test slightly by considering a wider space for the variance parameters. As before, we find that the MMC test performs remarkably well in controlling the size of the test, highlighting once more the benefit of this test procedure, which is feasible for the computationally simple moment-based estimation procedure proposed here.

Table 8. MSE ratios and DM test for forecasting volatility in SV models with and without leverage.

			SV(1) vs.	. SVL(1)					SV(2) vs.	SVL(2)		
	h =	: 1	h =	= 5	h =	10	h =	: 1	h =	5	h =	10
δ	MSE ratio	DM Stat.	MSE ratio	DM Stat.	MSE ratio	DM Stat.	MSE ratio	DM Stat.	MSE ratio	DM Stat.	MSE ratio	DM Stat.
		$\phi$ =	$= 0.90,  \sigma_y = 0$	0.10, $\sigma_{v} = 0$	).75			$\phi_1 = 0.05$	$\phi_0 = 0.85$	$\sigma_y = 1.00$ ,	$\sigma_v = 1.00$	
-0.9	1.14	7.86***	1.08	8.69***	1.05	8.75***	1.14	7.87***	1.03	7.12***	1.01	7.07***
-0.7	1.06	3.77***	1.04	5.71***	1.03	5.70***	1.08	6.59***	1.02	5.43***	1.01	5.50***
-0.5	1.02	1.75*	1.02	3.64***	1.01	3.57***	1.04	4.86***	1.01	3.94***	1.00	4.00***
0.5	1.02	2.67***	1.01	3.96***	1.01	4.54***	1.04	5.08***	1.01	4.11***	1.00	4.37***
0.7	1.07	5.43***	1.04	6.91***	1.03	7.27***	1.08	6.59***	1.01	5.96***	1.01	6.21***
0.9	1.15	7.94***	1.09	9.13***	1.05	9.11***	1.14	7.97***	1.03	7.86***	1.01	7.95***
		φ=	$= 0.75,  \sigma_y = 0$	0.10, $\sigma_{v} = 1$	.00			$\phi_1 = 0.05$	$\phi_0$ = 0.70,	$\sigma_y = 1.00$ ,	$\sigma_{v} = 1.00$	
-0.9	1.19	8.13***	1.06	8.56***	1.03	8.57***	1.17	7.68***	1.03	7.78***	1.01	7.78***
-0.7	1.10	5.91***	1.04	7.32***	1.02	7.35***	1.09	5.94***	1.02	6.10***	1.01	6.09***
-0.5	1.04	3.42***	1.02	5.51***	1.01	5.54***	1.04	3.73***	1.01	3.98***	1.00	3.97***
0.5	1.03	1.92*	1.01	1.82*	1.00	1.99**	1.04	4.37***	1.01	4.39***	1.00	4.44***
0.7	1.08	4.65***	1.03	5.62***	1.02	5.75***	1.09	6.43***	1.02	6.44***	1.01	6.45***
0.9	1.19	7.92***	1.06	8.69***	1.03	8.70***	1.18	7.98***	1.03	8.12***	1.01	8.12***

Notes: We simulate a process with T=2,010 observations, estimate the model using the first  $T_{est}=2,000$ , and forecast the last 10 observations. This process is repeated B=3,000 times. The MSE ratio is computed by using the MSE of the SV(p) model in the numerator and the MSE of the SVL(p) model in the denominator, so that a value greater than 1 suggests that the model with leverage provides a better forecast. The reported values represent the Mean Squared Error (MSE) ratio for each model at different horizons: h=1 (one day), h=5 (one week), and h=10 (two weeks). The DM statistic is computed as in equation (7.6). The significance level of the DM statistic is indicated using (\*) for 10% significance level, (\*\*) for 5% significance level, and (\*\*\*) for 1% significance level.

Finally, Tables 7 and A10 show results when the test procedures are applied to an SVL(2) model that is consistent with the alternative hypothesis. Specifically, we again report results when  $\delta = -0.90, -0.70, 0.70, 0.90$  and also include results without level-correction in Tables A4 and A13 of the Appendix and graphically summarize all results for more values of  $\delta$  in Appendix Figures A10-A13 and A22-A25. The results shown here are quite similar to the SVL(1) case, though the MMC procedure appears to have even higher power for smaller sample sizes. Overall, we find that the performance of the MC simulation-based tests are favourable under various settings.

#### 7.3 Forecasting

When forecasting, we work with the log of the squared returns, which according to (2.8) and (5.4) is given by  $\log(\hat{y}_{T+h|T}^2) = \mu + H'\hat{\xi}_{T+h|T}$ . Table 8 reports the ratio of the  $MSE_{SV}$  and  $MSE_{SVL}$  where the subscript SV and SVL denotes the MSE from the model with no leverage (*i.e.*,  $\delta = 0$ ) and the MSE from the model with leverage (*i.e.*,  $\delta \neq 0$ ) respectively. Specifically, the MSE of each model is computed as,

$$MSE_{m} = \frac{1}{B} \sum_{i=1}^{B} \left( \sum_{j=1}^{h} \left[ \log(y_{t+j}^{2}) - \log(\hat{y}_{m,t+j|t}^{2}) \right]^{2} \right), \tag{7.4}$$

where  $m = \{SV, SVL\}$  and B is the number of simulations. In practice, we would set B to be the number of out-of-sample observations after t as in the empirical section below. The ratio is then computed as MSE ratio  $= MSE_{SV}/MSE_{SVL}$  and hence, a value greater than 1 suggests the model with leverage performs better. This ratio is provided for values of  $\delta = -0.9, -0.7, -0.5, 0.5, 0.7, 0.9$  along different rows and horizons h = 1,5,10 along different

Table 9. Empirical W-ARMA estimates of SVL(p) models

		SVI	L(1)					SVL(3)							
	$\hat{\phi}$	σ̂y	$\hat{\sigma}_{V}$	$\hat{\delta}$	$\hat{\phi}_1$	$\hat{\phi}_2$	σ̂y	ôν	$\hat{\delta}$	$\hat{\phi}_1$	$\hat{\phi}_2$	$\hat{\phi}_3$	σ̂y	$\hat{\sigma}_{V}$	$\hat{\delta}$
								S&P 500							
est.	0.984	0.848	0.233	-0.922	0.513	0.465	0.848	0.810	-0.004	0.287	0.292	0.394	0.848	0.757	-0.048
SE	(0.001)	(0.071)	(0.004)	(0.040)	(0.066)	(0.064)	(0.160)	(0.104)	(0.508)	(0.064)	(0.108)	(0.042)	(0.131)	(0.104)	(0.366)
								DOWJ							
est.	0.982	0.810	0.233	-0.912	0.576	0.402	0.810	0.736	-0.007	0.369	0.126	0.475	0.810	0.678	-0.101
SE	(0.001)	(0.061)	(0.003)	(0.045)	(0.068)	(0.070)	(0.143)	(0.115)	(0.506)	(0.083)	(0.039)	(0.009)	(0.104)	(0.116)	(0.205)
								NASDQ							
est.	0.989	1.133	0.190	-0.999	0.488	0.497	1.133	0.697	-0.002	0.369	0.427	0.188	1.133	0.684	-0.012
SE	(0.001)	(0.116)	(0.004)	(0.000)	(0.057)	(0.056)	(0.261)	(0.117)	(0.509)	(0.100)	(0.057)	(0.043)	(0.236)	(0.118)	(0.504)

Notes: Sample for each index is from 2000-Jan-04 to 2023-May-31 (T = 5,889). Estimates are obtained using W-ARMA estimator given in (3.22) with J = 100. Standard errors of parameters are obtained using the implicit standard errors procedure described in Section 6.3.

columns. Specifically, we consider some of the same DGPs as in the hypothesis test for no leverage study presented above. Additionally, we use the DM test of Diebold and Mariano (2002) as a means to determine the statistical significance of the difference in the forecast performance of a model with leverage and a model with no leverage. That is, we compute

$$d_{i} = \sum_{j=1}^{h} \left[ \log(y_{t+j}^{2}) - \log(\hat{y}_{SV,t+j|t}^{2}) \right]^{2} - \sum_{j=1}^{h} \left[ \log(y_{t+j}^{2}) - \log(\hat{y}_{SVL,t+j|t}^{2}) \right]^{2}$$
(7.5)

where as before, i denotes the number of the simulations. From here, the DM statistic is computed as

$$DM = \frac{\bar{d}}{\sqrt{(\gamma_d(0) + 2\sum_{k=1}^{B^{1/3}} \gamma_d(k))/B}}$$
(7.6)

where  $\bar{d} = \frac{1}{B} \sum_{i=1}^{B} d_i$  and  $\gamma_d(k)$  is the sample auto-covariance of  $d_i$  at lag k. As described in Diebold and Mariano (2002) this test statistic has a standard normal distribution under the null hypothesis of no statistical difference is the forecast error. That is, we test the null hypothesis  $H_0: \mathrm{DM} = 0$  against an alternative hypothesis  $H_1: \mathrm{DM} \neq 0$ .

From Table 8, we find that when leverage is present, the forecasts of the model with leverage outperforms the forecasts of the model without leverage. This is seen as the MSE ratio is above 1. Specifically, as we should expect, we find that when  $\delta$  is higher, the ratio becomes larger indicating the performance difference is greater. This is also reflected in the DM statistic, which is larger for larger values of  $\delta$ . As previously discussed, we see from the first line of equation (5.4) that  $\delta$  shows up in the forecast but is multiplied by  $F^{(h-1)}$  and so for stable models, as h increases, the effect of  $\delta$  will decay. This feature can be seen in Table 8 since we can see the MSE ratio decrease as h increases. However, we still find that the difference in forecasting performance is still statistically significant and in favour of the model with leverage even at horizon h = 10 (e.g., two weeks ahead if working with daily data).

Table 10. Asymptotic and finite-sample tests for the presence of leverage in SVL(p) models

				$H_0$ : $\delta = 0$ vs. $H_1$ :	$\delta \neq 0$							
	9	SVL(1)			SVL(2)		S	SVL(3)				
	Asymptotic	LMC	MMC	Asymptotic	LMC	MMC	Asymptotic	LMC	MMC			
S&P 500	0.00	0.00	0.01	0.45	0.95	0.95	0.00	0.61	0.70			
DOW Jones	0.00	0.00	0.01	0.31	0.95	0.94	0.00	0.42	0.46			
NASDAQ	0.00	0.00	0.01	0.66	0.92	0.92	0.08	0.88	0.89			

Notes: Sample for each index is from 2000-Jan-04 to 2023-May-31 (T = 5,889). The reported values are p-values for test procedure when testing for leverage (*i.e.*  $H_0: \delta = 0$  vs.  $H_1: \delta \neq 0$ ). When estimating the constrained and unconstrained models we used W-ARMA estimator given in (3.22) with J = 100. We use N = 999 Monte Carlo simulations to simulate the null distribution for LMC and MMC tests. Table A17 extends this table by considering N = 99, N = 299, and J = 200 for both the LMC and MMC test procedures.

Table 11. Empirical volatility forecasting performance with competing conditional volatility models

			S&P 500				Ι	ow Jones					NASDAQ		
Models	h = 1	h = 5	h = 10	$Q_{1,5}$	Q <sub>1,5,10</sub>	h = 1	h = 5	h = 10	$Q_{1,5}$	$Q_{1,5,10}$	h = 1	h = 5	h = 10	$Q_{1,5}$	$Q_{1,5,10}$
ARCH(1)	13.637	65.351	128.308	0.278	0.278	11.982	60.489	121.549	0.778	0.778	14.488	68.342	132.365	0.333	0.556
ARCH(2)	9.516	50.644	105.371	0.294	0.294	9.482	50.428	104.794	0.778	0.778	8.981	47.187	97.012	0.333	0.556
ARCH(3)	8.938	47.549	100.908	0.312	0.312	8.882	47.319	100.274	0.778	0.778	8.690	45.378	94.243	0.333	0.556
GARCH(1,1)	8.298	42.542	87.394	0.333	0.357	8.279	42.450	87.042	0.778	0.778	7.918	40.114	81.538	0.357	0.556
GARCH(2,2)	8.260	42.368	87.177	0.385	0.333	8.260	42.300	86.859	0.778	0.778	7.884	39.989	81.388	0.417	0.556
GARCH(3,3)	8.252	42.316	87.124	0.357	0.385	8.260	42.288	86.883	0.778	0.778	7.889	39.990	81.401	0.385	0.556
EGARCH(1,1)	7.972	40.672	82.886	0.556	0.556	8.006	40.792	83.014	0.778	0.778	7.674	38.928	78.894	0.625	0.556
EGARCH(2,2)	7.879	40.262	82.132	0.625	0.625	7.941	40.486	82.466	0.778	0.778	8.109	40.712	82.045	0.333	0.556
EGARCH(3,3)	7.792	39.904	81.490	0.714	0.714	11.809	59.886	110.933	0.778	0.778	9.856	53.880	161.961	0.625	0.556
GJR(1,1)	8.060	41.541	85.548	0.417	0.417	8.051	41.430	85.102	0.778	0.778	7.723	39.314	79.967	0.455	0.556
GJR(2,2)	8.035	41.422	85.404	0.455	0.455	8.030	41.267	84.842	0.778	0.778	7.702	39.207	79.820	0.500	0.556
GJR(3,3)	8.025	41.361	85.329	0.500	0.500	8.036	41.280	84.912	0.778	0.778	7.690	39.190	79.824	0.556	0.556
SV(1)-NL	6.266	31.721	64.669	0.800	1.000	6.195	31.377	63.869	1.000	1.000	6.087	30.658	62.175	0.750	0.750
SV(2)-NL	6.259	32.830	67.340	0.714	0.833	6.200	32.437	66.467	0.778	0.778	6.027	31.349	63.936	0.625	0.556
SV(3)-NL	6.185	33.041	67.593	0.800	1.000	6.098	32.699	66.794	0.800	0.800	5.974	31.570	64.198	0.625	0.600
SV(1)-WL	6.153	31.520	64.509	1.000	1.000	6.109	31.134	63.590	1.000	1.000	5.956	30.329	61.783	1.000	1.000
SV(2)-WL	6.193	32.685	67.191	0.800	1.000	6.141	32.281	66.303	1.000	1.000	5.939	31.187	63.772	1.000	1.000
SV(3)-WL	6.114	32.912	67.461	1.000	1.000	6.021	32.542	66.634	1.000	1.000	5.874	31.414	64.041	1.000	1.000

Notes: The reported values represent the Mean Squared Error (MSE) for each model at different horizons: h=1 (one day), h=5 (one week), and h=10 (two weeks). The values in bold indicate that the model is part of the Model Confidence Set (MCS) for that horizon and that specific index. The MCS is determined using a 5% significance level. The values in bold red indicate the models in the MCS with the lowest MSE. Sample for each index is from 2000-Jan-04 to 2023-May-31 (T=5,889). Estimates are obtained using W-ARMA estimator given in (3.22) with J=100. Out-of-sample forecasting is performed using a rolling window scheme of size  $T_{est}=1,000$ , where the first estimation window ends at observation 1,000, and the last estimation window starts at observation 4,880 but ends at observation 5,879.

### 8 Application to stock price indices

In this section, we demonstrate the performance of SVL(p) models, when applied to three financial indices: the Standard and Poor's 500 Composite Price Index (S&P500), the Dow Jones Industrial Average Price Index (DOWJ), and the Nasdaq Composite Price Index (NASDAQ), using data sourced from Yahoo Finance. SVL(p) models are fitted to daily demeaned returns of these indices. Specifically, the raw series  $p_t$  are converted to returns by the transformation  $r_t = 100[\log(p_t) - \log(p_{t-1})]$  and then the returns are demeaned by  $y_t = r_t - \hat{\mu}_r$ , where  $\hat{\mu}_r$  is the sample average of returns. We consider a sample from January 4, 2000 to May 31, 2023 (*i.e.*, T = 5,889) so that all indices are available for the same time period and so that we capture various volatile periods.

The Appendix Figure A26 shows plots of  $y_t$  for each index. Additionally, Appendix Table A16 reports summary statistics of the daily residual returns  $y_t$  as well as summery statistics for  $y_t^2$  and  $y_t^*$ , where  $y_t^* = \log(y_t^2) - \mu$  as in equation (2.8), for each financial index. The skewness and kurtosis of  $y_t$  and  $y_t^2$  for each index show some evidence of non-normal distribution, while the distribution of log-transformed residual returns is closer to normal. These findings are consistent with most empirical studies.

Table 9 shows the parameter estimates of the SVL(p) models (where p = 1, 2, 3) using our W-ARMA estimator. For all estimates in this section we use (3.22) with J = 100 with equal weights to estimate  $\phi_p$  and the other expressions in equations (3.14) and (3.15) to obtain estimates of the other parameters. This table also reports implicit standard errors of each parameter, which are obtained using the procedure described in section 6.3. Our results show some persistence in the volatility process for each index during the sample considered here. We also find that leverage (i.e.,  $\delta$ ) is very high when using an SVL(1) model, but very small and in many cases close to 0 when considering an SVL(2) or SVL(3) model. Figures (A27) - (A29) present estimates for  $\hat{\phi}_i$ ,  $\hat{\sigma}_v$ , and  $\hat{\delta}$  for the same models and indices but for different values  $J = \{100, 105, 110, ..., 190, 195, 200\}$  and suggest that these estimates are not very sensitive to the choice of J. Estimates of  $\hat{\sigma}_V$  are not provided as this parameter does not depend on J in any way.

As in the simulation section above, we examine a test for no leverage in SVL(p) models, specifically testing  $H_0$ :  $\delta = 0$  against  $H_1$ :  $\delta \neq 0$ , using the moment-based LR test described in Section 6.1. This entails utilizing the moments provided in (6.3) for both the constrained and unconstrained models to calculate the LR statistic.

The LR test results are reported in Table 10, where we consider the asymptotic test, the LMC test, and the MMC test procedures. Here, J=100 is used and the Monte Carlo test results are obtained using N=999. The asymptotic test appears to reject the null hypothesis of no leverage at a significance level of 10% for the SVL(1) case and even SVL(3) case where  $\delta$  was shown to be very small in Table 9. On the other hand, the LMC test results appear to be more consistently in line with what we should expect given the values of  $\delta$  being closer to 0 when using an SVL(2) or SVL(3) model. That is, we reject the null hypothesis of no leverage when considering an SVL(1) model but fail to reject the null hypothesis when considering an SVL(2) or SVL(3) model. Table A17 reports results for N=99, N=299, and N=999 for J=100 and J=200 and show that our results are consistent for different values of N and different J.

For the MMC test, we use the same confidence set as in (7.2) when searching the nuisance parameter space for a maximum p-value. The reason for choosing this set and not the wider set given in (7.3) is because we see that with the LMC test, only the SVL(1) model appears to reject the null hypothesis of no leverage. As a result we find it suitable to use the same confidence set as in the SVL(1) case shown in the simulation section where we saw this set was large enough to allow the MMC test procedure to control size. In contrast, with the SVL(2) and SVL(3) models, the LMC procedure already fails to reject the null hypothesis and so it is not necessary to search a very wide space.

We find it interesting that including higher-order lags of the volatility process appears to diminish the leverage effect observed when using an SVL(1) model. To explore this further, Tables A14 and A15 present four Monte Carlo simulation experiments. In the first two experiments, we simulate an SV(2) and an SV(3) DGP with no leverage, considering different sample sizes and using parameter values similar to the estimates obtained for the S&P 500 index data in Table 9. We then apply both an SVL(1) model and the corresponding SVL(p) model to the generated data. This process is repeated 1000 times to assess whether the leverage effect in an SVL(1) model could be attributed to misspecification of the lag order. Estimates from the corresponding SVL(p) model are included as a benchmark. These results, shown in Table A14, provide little evidence of a leverage effect arising solely from misspecifying the lag order. In the next two experiments, we simulate an SVL(1) DGP with  $\delta$  = -0.90 and another SVL(1) DGP with  $\delta$  = -0.70. For each DGP, we apply an SVL(1), SVL(2), and SVL(3) model to the generated data. The SVL(1) model serves as a benchmark to confirm the presence of a leverage effect in the data, while the SVL(2) and SVL(3) models are used to examine whether including higher-order lags reduces the leverage effect. These experiments, also repeated 1000 times, and the results are summarized in Table A15. We find that the average estimate of the leverage effect is indeed smaller when using a higher-order model. We believe that further investigation of this result would be valuable and consider it the focus of ongoing research.

Table 11 provides results of a forecast study. Specifically, we consider various different GARCH-type, SV-type and SVL-type models along different rows and report their MSE when forecasting the log squared residual returns of each index at horizon h=1, 5, and 10. Here, for all SV(p) and SVL(p) models, J=100 is used. In order to compute the MSE, we use a fixed estimation window of  $T_{est}=1,000$  and then roll the estimation window forward, while always forecasting the next  $h=1,\ldots,10$  periods. Since we have a total sample size of T=5,889, this results in B=4,880 forecast errors for each horizon. The reason for keeping a short estimation window is based on the premise that very distant observations may contain little useful information for use in forecasting in more recent periods as discussed in Kambouroudis and McMillan (2015). The squared forecast errors are also used to perform the Model Confidence Set (MCS) test of Hansen et al. (2011) using a significance level of 5% in order to determine the set of models that outperform the rest in terms of forecasting performance. When using the MCS test we are testing the following hypothesis

$$H_0: \mu_i = 0 \text{ for all } i \in \mathcal{M} \text{ and } H_1: \mu_i \neq 0 \text{ for some } i \in \mathcal{M}$$
 (8.1)

where  $\mu_i = E[d_i]$ , which is computed as  $\bar{d}_i = m^{-1} \sum_{j \in \mathcal{M}} \bar{d}_{i,j}$  with i, j indexing two different models and  $\mathcal{M}$  is the

set of all models being considered here. In this case, the test statistic of interest is  $MCS_{T_{max},\mathcal{M}} = \max_{i \in \mathcal{M}} t_i$  where  $t_i = \frac{\bar{d}_i}{\sqrt{\hat{\text{Var}}(\bar{d}_i)}}$  and where  $\hat{\text{Var}}(\bar{d}_i)$  is a bootstrap estimate of  $\text{Var}(\bar{d}_i)$ . That is, we consider the  $T_{max}$  version of the test discussed in Hansen et al. (2011). This test is applied using R package 'MCS' (see Bernardi (2017)). The bold values highlight the models that belong to the MCS and have the lowest MSE for that horizon and index. Our results show that the SVL(1) model is the only model that is always included in the MCS at all horizons and for all indices and has the lowest MSE at horizons h = 5 and h = 10 for all indices. From Table 11 we can also see that the SV(1), SV(3) and SVL(2) and SVL(3) model appear in the MCS for specific horizons for all three indices. When considering Dow Jones and NASDAQ data, the SV(2) model also appears in the MCS for specific horizons. Further, for these latter two indices, some EGARCH models also appear in the MCS. The MCS even includes some GJR and GARCH models when considering NASDAQ data.

Further, Table 11 includes results of the multi-horizon model confidence set of Quaedvlieg (2021). Specifically, we consider the uniform superior predictive ability statistic to determine the set of models that provide the best forecasting performance at a horizon of h = 1 and h = 5 jointly and at all three horizons considered here jointly. The p-values for each case are provided. Similar to the single-horizon model confidence set, SV(1), SV(3), and all SVL(p) models appear in these sets though the SVL(p) are more commonly included. For example, for NASDAQ only SVL(p) models are included. The SVL(1) model, however, is included in these sets for all horizons and for all indices, which is consistent with our single-horizon results. Table A18 presents the results when J = 200 and show that our findings remain the same.

We also consider a larger estimation window  $T_{est} = 4,880$  and for which the results are shown in Appendix Table A19 for J = 100 and Table A20 for J = 200. As before, we still find that the SVL(1) model is always part of the MCS but in this case only the SV(1), SV(3) and SVL(3) also appear in the MCS. For the multi-horizon MCS, the higher order models only appear when considering DOW Jones index and all three horizons jointly. The SV(1) model appears in all cases except at horizon h = 1 and h = 5 jointly for the S&P 500 index. Meanwhile, once again, the SVL(1) model appears for all joint horizons and all indices.

### 9 Conclusion

Despite their conceptual appeal, SVL models pose challenges for estimation and inference due to the presence of latent variables, especially when extending beyond the SVL(1) model. To address this, we propose a novel moment-based simple CF-ARMA estimator for SVL(p) models. This estimator offers analytical tractability and computational efficiency, thereby overcoming limitations associated with existing methods. Moreover, we introduce enhancements such as restricted and winsorized versions of the CF-ARMA estimator, which further improve the stability and accuracy of the estimator, particularly in the presence of outliers or small samples. We demonstrate that these simple estimators are especially convenient for use in simulation-based inference techniques, such as Bootstrap or Monte

Carlo tests.

Our study includes a series of simulation experiments and empirical applications that examine the statistical properties and forecasting performance of the proposed estimators, with a particular focus on the role of leverage in volatility predictions. Overall, our research advances estimation and inference techniques for SVL(p) models, offering valuable insights into the dynamics of volatility in financial markets. By integrating empirical applications with simulation studies, we provide practitioners and researchers with practical tools and methodologies to enhance risk management, option pricing, asset allocation, and volatility forecasting.

In future work, we aim to explore methods for approximating the likelihood function of the SVL model, despite the challenges posed by latent variables and the leverage effect. Such approximations would enable the use of log predictive scores and other likelihood-based evaluation metrics to assess predictive performance, as recommended by Geweke and Amisano (2010). Additionally, developing alternative predictive evaluation criteria compatible with moment-based estimators could provide deeper insights into the forecasting capabilities of our method. Furthermore, extending our methodology to incorporate the general leverage structures proposed by Catania (2022) - which would involve developing new moment conditions and adapting our estimation procedure to handle the additional complexity - could potentially improve the model's ability to capture asymmetric volatility responses to market movements and enhance forecasting performance, and we consider this an interesting and valuable direction for future research. Integrating high-frequency intraday data into our estimation approach is another promising avenue that we are currently exploring in a companion paper Ahsan et al. (2023), as it could enhance the precision of volatility estimates and improve model evaluation and forecasting accuracy, following the insights of Lopez (2001). These future directions hold the potential to further strengthen the utility and robustness of moment-based estimation methods for SVL models in financial econometrics.

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# Estimation and inference for higher-order stochastic volatility models with leverage

# **Supplementary Appendix**

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This online Supplementary Appendix contains additional details and complementary results relevant to the paper.

- A. Proofs.
- B. Additional ARMA-based winsorized estimators.
- C. Monte Carlo tests with nuisance parameters.
- D. Additional simulation results.
- E. Complementary empirical results

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#### A Proofs

PROOF OF PROPOSITION 3.1 From (2.9) - (2.10), we have

$$\phi(B)w_t = v_t, \quad v_t^* = w_t + \epsilon_t \tag{A.1}$$

where  $\phi(B) = (1 - \phi_1 B - \dots - \phi_p B^p)$  and  $v_t = \delta_p z_{t-1} + (1 - \delta_p)^{1/2} \bar{v}_t$ . Furthermore,  $v_t$ 's and  $\epsilon_t$ 's are uncorrelated. This result follows from

$$Cov(v_t, \epsilon_t) = \mathbb{E}\left[v_t(h(z_t) - \mathbb{E}[\epsilon_t])\right] = \mathbb{E}\left[v_t(h(z_t))\right] = \mathbb{E}\left[\mathbb{E}(v_t|z_t)h(z_t)\right],\tag{A.2}$$

where  $h(z_t) = \log(z_t^2)$ . Since  $\mathbb{E}[\mathbb{E}(v_t|z_t)h(z_t)]$  is an odd function of  $z_t$ , and the density of  $z_t$  [ $f(z_t)$ ] is symmetric, its expected value is zero. Thus,  $Cov(v_t, \varepsilon_t) = 0$ .

Now applying  $\phi(B)$  to both sides of (2.10) yields

$$\phi(B)y_t^* = \phi(B)w_t + \phi(B)\varepsilon_t = v_t + \phi(B)\varepsilon_t. \tag{A.3}$$

The right hand side of (A.3) is clearly a covariance stationary process. By the Wold decomposition theorem it must have a moving average representation. Since the autocovariance function cuts off for lags k > p it must be an MA(p) process, say  $\theta(B)\eta_t = (1-\theta_1 B - \cdots - \theta_p B^p)\eta_t$ . Hence,  $y_t^*$  must be an ARMA(p,p) process [see equation (2.1) of Granger and Morris (1976)].

The moving average parameters  $\theta_1, \theta_2, ..., \theta_p$  and the white noise variance  $\sigma_{\eta}^2$  of this ARMA(p, p) process can be found by equating the autocovariance function of the right hand side of (A.3) with that of  $\theta(B)\eta_t$  for lags k=0,1,...,p and solving the p+1 resulting nonlinear equations

$$(1+\theta_1^2+\cdots+\theta_p^2)\sigma_\eta^2 = \sigma_v^2 + (1+\phi_1^2+\cdots+\phi_p^2)\sigma_\epsilon^2,$$

$$(-\theta_1+\theta_1\theta_2+\cdots+\theta_{p-1}\theta_p)\sigma_\eta^2 = (-\phi_1+\phi_1\phi_2+\cdots+\phi_{p-1}\phi_p)\sigma_\epsilon^2,$$

$$\vdots$$

$$(-\theta_{p-1}+\theta_1\theta_p)\sigma_\eta^2 = (-\phi_{p-1}+\phi_1\phi_p)\sigma_\epsilon^2,$$

$$-\theta_p\sigma_\eta^2 = -\phi_p\sigma_\epsilon^2.$$
(A.4)

Note that there may be multiple solutions, only some of which result in an invertible process.

PROOF OF COROLLARY 3.2 From Proposition 3.1, the observed process  $y_t^*$  satisfies the following equation:

$$y_t^* = \sum_{j=1}^p \phi_j y_{t-j}^* + \eta_t - \sum_{j=1}^p \theta_j \eta_{t-j}$$
(A.5)

or

$$y_t^* = \sum_{j=1}^p \phi_j y_{t-j}^* + \nu_t + \epsilon_t - \sum_{j=1}^p \phi_j \epsilon_{t-j}.$$
 (A.6)

Multiply both sides of (A.6) by  $y_{t-k}^*$ , and taking expectation, we get:

$$\gamma_{y^*}(k) = \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + \mathbb{E}[\nu_t y_{t-k}^*] + \mathbb{E}[\epsilon_t y_{t-k}^*] - \sum_{j=1}^p \phi_j \mathbb{E}[\epsilon_{t-j} y_{t-k}^*]. \tag{A.7}$$

For k = 0, we get

$$\begin{split} \gamma_{y^*}(k) &= \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + \mathbb{E}[\nu_t y_t^*] + \mathbb{E}[\epsilon_t y_t^*] - \sum_{j=1}^p \phi_j \mathbb{E}[\epsilon_{t-j} y_t^*] \\ &= \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + \sigma_v^2 + \sigma_\varepsilon^2 - \sum_{j=1}^p \phi_j \mathbb{E}[\epsilon_{t-j} (\phi_j y_{t-j}^* - \phi_j \epsilon_{t-j})] \\ &= \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + \sigma_v^2 + \sigma_\varepsilon^2 - \sum_{j=1}^p \phi_j^2 \mathbb{E}[\epsilon_{t-j} y_{t-j}^* - \epsilon_{t-j}^2] \\ &= \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + \sigma_v^2 + \sigma_\varepsilon^2 - \sum_{j=1}^p \phi_j^2 [\sigma_\varepsilon^2 - \sigma_\varepsilon^2] \\ &= \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + \sigma_v^2 + \sigma_\varepsilon^2. \end{split} \tag{A.8}$$

Setting  $1 \le k \le p$ , we get

$$\begin{split} \gamma_{y^*}(k) &= \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + \mathbb{E}[\nu_t y^*_{t-k}] + \mathbb{E}[\epsilon_t y^*_{t-k}] - \sum_{j=1}^p \phi_j \mathbb{E}[\epsilon_{t-j} y^*_{t-k}] \\ &= \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) + 0 + 0 - \phi_k \mathbb{E}[\epsilon_{t-k} y^*_{t-k}] = \sum_{j=1}^p \phi_j \gamma_{y^*}(k-j) - \phi_k \sigma_\epsilon^2. \end{split} \tag{A.9}$$

Setting k > p, we get

$$\gamma_{y^*}(k) = \sum_{j=1}^{p} \phi_j \gamma_{y^*}(k-j) + \mathbb{E}[\nu_t y_{t-k}^*] + \mathbb{E}[\epsilon_t y_{t-k}^*] - \sum_{j=1}^{p} \phi_j \mathbb{E}[\epsilon_{t-1} y_{t-k}^*]$$

$$= \sum_{j=1}^{p} \phi_j \gamma_{y^*}(k-j) + 0 + 0 - 0 = \sum_{j=1}^{p} \phi_j \gamma_{y^*}(k-j).$$
(A.10)

Combining (A.8), (A.9), and (A.10), we get the autocovariance structure of the observed process that stated in the Corollary.  $\Box$ 

PROOF OF LEMMA 3.3 From Assumptions 2.1 - 2.2, we have

$$\mathbb{E}[|y_t|y_{t-1}] = \sigma_y^2 \mathbb{E}\left[\exp\left(\frac{w_t}{2} + \frac{w_{t-1}}{2}\right) z_{t-1}\right] \mathbb{E}\left[|z_t|\right]. \tag{A.11}$$

For a standard normal random variable,  $z_t$ , it can be shown that

$$\mathbb{E}\Big[|z_t^i|\Big] = \frac{2^{i/2}}{\sqrt{\pi}} \Gamma\bigg(\frac{i+1}{2}\bigg),\tag{A.12}$$

thus for i = 1, we have

$$\mathbb{E}\Big[|z_t|\Big] = \sqrt{2/\pi}.\tag{A.13}$$

Now define  $A := \frac{w_t}{2} + \frac{w_{t-1}}{2}$  and  $B := z_{t-1}$ , we have:

$$\begin{pmatrix} A \\ B \end{pmatrix} \sim N \begin{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \sigma_A^2 & \frac{\delta \sigma_v}{2} \\ \frac{\delta \sigma_v}{2} & 1 \end{pmatrix} \end{pmatrix} \tag{A.14}$$

where

$$\sigma_A^2 = \text{var}\left(\frac{w_t}{2} + \frac{w_{t-1}}{2}\right) = \frac{1}{4}\text{var}(w_t + w_{t-1}) = \frac{1}{2}[\tilde{\gamma}_p],\tag{A.15}$$

$$\tilde{\gamma}_p := \gamma_p(0) + \gamma_p(1), \quad \gamma_p(0) := \text{var}(w_t), \quad \gamma_p(1) := \text{cov}(w_t, w_{t-1}).$$
 (A.16)

The moment generating function for a bivariate mean zero normal random variable is given by

$$M(t_1, t_2) \equiv \mathbb{E}\left[\exp(t_1 A + t_2 B)\right] = \exp\left(\frac{\sigma_A^2 t_1^2 + \sigma_B^2 t_2^2 + 2\rho_{A,B} \sigma_A \sigma_B t_1 t_2}{2}\right). \tag{A.17}$$

Using (A.17) and (A.14), we get:

$$\frac{\partial M}{\partial t_2} \Big|_{t_1 = 1, t_2 = 0} = \mathbb{E}[\exp(A)B] = \rho_{A,B} \sigma_A \sigma_B \exp\left(\frac{\sigma_A^2}{2}\right)$$

$$= \frac{\delta \sigma_v}{2} \exp\left(\tilde{\gamma}_p / 4\right) \tag{A.18}$$

and, on combining (A.11), (A.13) and (A.18),

$$\mathbb{E}[|y_t|y_{t-1}] = \frac{\delta\sigma_v \sigma_y^2}{\sqrt{2\pi}} \exp(\tilde{\gamma}_p/4)$$
(A.19)

where  $\tilde{\gamma}_p$  depends on the order of latent volatility process (p). For  $p=1,\ldots,5$ , this yields the following expressions for  $\tilde{\gamma}_p$ :

$$\tilde{\gamma}_1 = \frac{\sigma_v^2}{1 - \phi_1},\tag{A.20}$$

$$\tilde{\gamma}_2 = \frac{\sigma_v^2}{(1 - \phi_1 - \phi_2)(1 + \phi_2)},\tag{A.21}$$

$$\tilde{\gamma}_3 = \frac{(1 - \phi_3)\sigma_v^2}{(1 - \phi_1 - \phi_2 - \phi_3)(1 + \phi_1\phi_3 + \phi_2 - \phi_3^2)},$$
(A.22)

$$\tilde{\gamma}_{4} = \frac{(1 - \phi_{3} - \phi_{1}\phi_{4} - \phi_{4}^{2})\sigma_{v}^{2}}{(1 - \phi_{1} - \phi_{2} - \phi_{3} - \phi_{4})(1 + \phi_{1}\phi_{3} + \phi_{2} + \phi_{4} + 2\phi_{2}\phi_{4} + \phi_{1}^{2}\phi_{4} + \phi_{2}\phi_{4}^{2} - \phi_{3}^{2} - \phi_{4}^{2} - \phi_{4}^{3} - \phi_{1}\phi_{3}\phi_{4})}, \quad (A.23)$$

$$\tilde{\gamma}_{5} = \frac{(1 - \phi_{3} - \phi_{1}\phi_{4} - \phi_{4}^{2} - \phi_{5} - \phi_{2}\phi_{5} + \phi_{3}\phi_{5} - \phi_{1}^{2}\phi_{5} + \phi_{2}\phi_{5}^{2} - \phi_{5}^{2} + \phi_{5}^{3} - \phi_{1}\phi_{4}\phi_{5})\sigma_{v}^{2}}{(1 - \phi_{1} - \phi_{2} - \phi_{3} - \phi_{4} - \phi_{5})\tilde{\kappa}},$$
(A.24)

where

$$\tilde{\kappa} := 1 + \phi_1 \phi_3 + \phi_2 + \phi_4 + 2\phi_2 \phi_4 + {\phi_1}^2 \phi_4 + \phi_2 {\phi_4}^2 - {\phi_3}^2 - {\phi_4}^2 - {\phi_4}^3 - {\phi_1} \phi_3 \phi_4 + {\phi_1}^3 \phi_5$$

$$- \phi_1^2 \phi_3 \phi_5 - \phi_1^2 \phi_5^2 + \phi_1 \phi_2 \phi_4 \phi_5 + 3\phi_1 \phi_2 \phi_5 + 2\phi_1 \phi_3 \phi_5^2 - \phi_1 \phi_4^2 \phi_5 - 2\phi_1 \phi_4 \phi_5 - \phi_1 \phi_5^3 + \phi_1 \phi_5$$

$$- \phi_2^2 \phi_5^2 - 2\phi_2 \phi_3 \phi_5 + \phi_2 \phi_4 \phi_5^2 - \phi_2 \phi_5^2 + 3\phi_3 \phi_4 \phi_5 - \phi_3 \phi_5^3 + \phi_3 \phi_5 - \phi_4 \phi_5^2 + \phi_5^4 - 2\phi_5^2.$$
(A.25)

PROOF OF COROLLARY 3.4 The estimator of  $\phi_p$  is based on the autocovariance structure of the process  $y_t^*$ . This is the solution of p-system of equations from (3.2) with  $k = p + 1, \dots, 2p$ . Thus

$$\begin{bmatrix} \gamma_{y^{*}}(p) & \gamma_{y^{*}}(p-1) & \cdots & \gamma_{y^{*}}(1) \\ \gamma_{y^{*}}(p+1) & \gamma_{y^{*}}(p) & \cdots & \gamma_{y^{*}}(2) \\ \vdots & \vdots & & \vdots \\ \gamma_{y^{*}}(2p-1) & \gamma_{y^{*}}(2p-2) & \cdots & \gamma_{y^{*}}(p) \end{bmatrix} \cdot \begin{bmatrix} \phi_{1} \\ \phi_{2} \\ \vdots \\ \phi_{p} \end{bmatrix} = \begin{bmatrix} \gamma_{y^{*}}(p+1) \\ \gamma_{y^{*}}(p+2) \\ \vdots \\ \gamma_{y^{*}}(2p) \end{bmatrix},$$
(A.26)

or, equivalently,

$$\Gamma(p,1)\phi_p = \gamma(p,1) \tag{A.27}$$

hence

$$\phi_p = \Gamma(p, 1)^{-1} \gamma(p, 1) \tag{A.28}$$

where  $\phi_p := (\phi_1, \dots, \phi_p)^{'}$ ,  $\gamma(p, 1) = [\gamma_{y^*}(p+1), \dots, \gamma_{y^*}(2p)]^{'}$  are vectors, and  $\Gamma(p, 1)$  is a p-dimensional Toeplitz matrices such that

$$\Gamma(p,1) := \begin{bmatrix}
\gamma_{y^*}(p) & \gamma_{y^*}(p-1) & \cdots & \gamma_{y^*}(1) \\
\gamma_{y^*}(p+1) & \gamma_{y^*}(p) & \cdots & \gamma_{y^*}(2) \\
\vdots & \vdots & & \vdots \\
\gamma_{y^*}(2p-1) & \gamma_{y^*}(2p-2) & \cdots & \gamma_{y^*}(p)
\end{bmatrix}.$$
(A.29)

Note that (A.28) is also valid for any  $j \ge 1$  such that

$$\phi_p = \Gamma(p, j)^{-1} \gamma(p, j), \tag{A.30}$$

where  $\gamma(p,j) := [\gamma_{y^*}(p+j), \dots, \gamma_{y^*}(2p+j-1)]'$  and  $\Gamma(p,j)$  is a p-dimensional Toeplitz matrices such that

$$\Gamma(p,j) := \begin{bmatrix}
\gamma_{y^*}(p+j-1) & \gamma_{y^*}(p+j-2) & \cdots & \gamma_{y^*}(j) \\
\gamma_{y^*}(p+j) & \gamma_{y^*}(p+j-1) & \cdots & \gamma_{y^*}(j+1) \\
\vdots & \vdots & & \vdots \\
\gamma_{y^*}(2p+j-2) & \gamma_{y^*}(2p+j-3) & \cdots & \gamma_{y^*}(p+j-1)
\end{bmatrix}.$$
(A.31)

Now, by (3.2) with k = 0, we have:

$$\gamma_{y^*}(0) = \phi_1 \gamma_{y^*}(1) + \dots + \phi_p \gamma_{y^*}(p) + \sigma_v^2 + \sigma_\varepsilon^2,$$
(A.32)

hence

$$\sigma_{v} = [\gamma_{y^{*}}(0) - \sum_{j=1}^{p} \phi_{j} \gamma_{y^{*}}(j) - \pi^{2}/2]^{1/2} = [\gamma_{y^{*}}(0) - \phi_{p}^{'} \gamma(p) - \pi^{2}/2]^{1/2}, \tag{A.33}$$

where  $\phi_p := (\phi_1, \dots, \phi_p)^{'}$ ,  $\gamma(p) := [\gamma_{y^*}(1), \dots, \gamma_{y^*}(p)]^{'}$  and  $\sigma_{\varepsilon}^2 = \psi^{(1)}(1/2) = \pi^2/2$ . Now by construction,

$$\mu = \mathbb{E}[\log(y_t^2)] = \log(\sigma_y^2) + \mathbb{E}[\log(z_t^2)] = \log(\sigma_y^2) + \bar{\mu}, \tag{A.34}$$

or, equivalently,

$$\sigma_{\gamma}^2 = \exp(\mu - \bar{\mu}). \tag{A.35}$$

Now from Lemma 3.3, we have:

$$\delta_p = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_v \sigma_v^2} \exp\left(-\frac{1}{4}\tilde{\gamma}_p\right),\tag{A.36}$$

where  $\delta_p$  is a function of  $\lambda_y(1) := \mathbb{E}[|y_t|y_{t-1}], \ \tilde{\gamma}_p := \text{var}(w_t) + \text{cov}(w_t, w_{t-1})$  and other parameter estimates of the model  $(\phi_1, \ldots, \phi_p, \sigma_v, \sigma_v)'$ . Expressions of  $\delta_p$  for the lower order SVL(p) models are:

$$\delta_1 = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_v \sigma_v^2} \exp\left(-\frac{1}{4} \frac{\sigma_v^2}{1 - \phi_1}\right),\tag{A.37}$$

$$\delta_2 = \frac{\sqrt{2\pi}\lambda_{\gamma}(1)}{\sigma_{\nu}\sigma_{\gamma}^2} \exp\left(-\frac{1}{4} \frac{\sigma_{\nu}^2}{(1-\phi_1 - \phi_2)(1+\phi_2)}\right),\tag{A.38}$$

$$\delta_3 = \frac{\sqrt{2\pi}\lambda_y(1)}{\sigma_v \sigma_v^2} \exp\left(-\frac{1}{4} \frac{(1-\phi_3)\sigma_v^2}{(1-\phi_1-\phi_2-\phi_3)(1+\phi_1\phi_3+\phi_2-\phi_3^2)}\right),\tag{A.39}$$

$$\delta_4 = \frac{\sqrt{2\pi}\lambda_{\gamma}(1)}{\sigma_{\nu}\sigma_{\gamma}^2} \exp\left(-\frac{1}{4} \frac{(1-\phi_3-\phi_1\phi_4-\phi_4^2)(1-\phi_1-\phi_2-\phi_3-\phi_4)^{-1}\sigma_{\nu}^2}{(1+\phi_1\phi_3+\phi_2+\phi_4+2\phi_2\phi_4+\phi_1^2\phi_4+\phi_2\phi_4^2-\phi_3^2-\phi_4^2-\phi_4^3-\phi_1\phi_3\phi_4)}\right).$$
(A.40)

PROOF OF LEMMA 4.1 Under Under Assumptions 2.1 and 2.2, the observed process  $\{y_t^*\}$  is strictly stationarity and geometrically ergodic with  $\mathbb{E}[y_t^*] < \infty$ ,  $\mathbb{E}[|y_t|y_{t-1}] < \infty$  and  $\mathbb{E}[y_t^*y_{t+k}^*] < \infty$ . So the consistency is a simple application of the Law of Large Numbers for stationary and ergodic processes, *i.e.*, the Ergodic theorem; see Theorem 13.12 and Corollary 13.14 of Davidson (1994).

PROOF OF LEMMA 4.2 To establish the asymptotic normality of empirical moments, we shall use a CLT for dependent processes (see Davidson (1994), Theorem 24.5, p. 385). For that purpose, we first check the conditions under which this CLT holds. We set

$$X_t := \begin{bmatrix} \Psi_t \\ \Lambda_t \\ \bar{\Psi}_t \end{bmatrix}, \quad \Psi_t := \log(y_t^2) - \mu, \quad \Lambda_t := [\Lambda_{t,0}, \Lambda_{t,1}, \dots, \Lambda_{t,m}]', \tag{A.41}$$

$$\Lambda_{t,k} := y_t^* y_{t+k}^* - \gamma_{v^*}(k) = [\log(y_t^2) - \mu][\log(y_{t+k}^2) - \mu] - \gamma_{v^*}(k), \quad k = 0, 1, ..., m,$$
(A.42)

$$\bar{\Psi}_t := [|y_t|y_{t-1}] - \lambda_{\nu}(1), \tag{A.43}$$

$$S_T := \sum_{t=1}^T X_t = \begin{bmatrix} \sum_{t=1}^T \Psi_t \\ \sum_{t=1}^T \Lambda_t \\ \sum_{t=1}^T \bar{\Psi}_t \end{bmatrix}, \tag{A.44}$$

and consider the subfields  $\mathcal{F}_t = \sigma(s_t, s_{t-1}, ...)$  where  $s_t = (y_t, w_t)'$ . We will now show that

$$T^{-1/2} S_T \xrightarrow{d} \mathcal{N} \left( 0, \begin{bmatrix} V_{\mu} & C'_{\mu,\Gamma(m)} & C_{\mu,\lambda_{\gamma}(1)} \\ C_{\mu,\Gamma(m)} & V_{\Gamma(m)} & C_{\Gamma(m),\lambda_{\gamma}(1)} \\ C_{\mu,\lambda_{\gamma}(1)} & C'_{\Gamma(m),\lambda_{\gamma}(1)} & V_{\lambda_{\gamma}(1)} \end{bmatrix} \right), \tag{A.45}$$

which in turn yields (4.2). To do this, we will check the following conditions:

- (i)  $\{X_t, \mathcal{F}_t\}$  is stationary and ergodic;
- (ii)  $\{X_t, \mathcal{F}_t\}$  is a  $L_1$ -mixingale of size -1;
- (iii)  $\limsup_{T\to\infty} T^{-1/2}\mathbb{E}\|S_T\|<\infty$ , where  $\|\cdot\|$  is the Euclidean norm.
- (i) The fact that  $\{X_t, \mathcal{F}_t\}$  is stationary and ergodic follows from Assumptions 2.1-2.2; see discussions in Section 4.
- (ii) (1) A mixing zero-mean process is an adapted  $L_1$ -mixingale with respect to the sub-fields  $\mathcal{F}_t$  provided it is bounded in the  $L_1$ -norm [see Davidson (1994, Theorem 14.2, p. 211)]. To see that  $\{X_t\}$  is bounded in the  $L_1$ -norm, we note that:

$$\mathbb{E}|\log(y_t^2) - \mu| = \mathbb{E}|y_t^*| \le (\mathbb{E}|y_t^*|^2)^{1/2} = (\mathbb{E}[y_t^{*2}])^{1/2} = \sqrt{\gamma_{y^*}(0)} < \infty, \tag{A.46}$$

$$\begin{split} \mathbb{E}|y_t^* y_{t+k}^* - \gamma_{y^*}(k)| &= \mathbb{E}|y_t^* y_{t+k}^*| - |\gamma_{y^*}(k)| \le \mathbb{E}|y_t^* y_{t+k}^*| \\ &\le (\mathbb{E}|y_t^*|^2)^{1/2} (\mathbb{E}|y_{t+k}^*|^2)^{1/2} = (\mathbb{E}[y_t^{*2}])^{1/2} (\mathbb{E}[y_{t+k}^{*2}])^{1/2} \\ &= \mathbb{E}[y_t^{*2}] = \gamma_{y^*}(0) < \infty, \quad \text{for } k = 0, 1, \dots, m, \end{split} \tag{A.47}$$

$$\begin{split} \mathbb{E}||y_{t}|y_{t-1} - \lambda_{y}(1)| &= \mathbb{E}|y_{t}y_{t-1}| - |\lambda_{y}(1)| \le \mathbb{E}|y_{t}y_{t-1}| \\ &\le (\mathbb{E}|y_{t}|^{2})^{1/2} (\mathbb{E}|y_{t-1}|^{2})^{1/2} \\ &= \mathbb{E}[y_{t}^{2}] = \gamma_{v}(0) < \infty, \end{split} \tag{A.48}$$

where the inequality in (A.46) is the application of Lyapunov's inequality and the inequalities in (A.47)-(A.48) follows from the Hölder's inequality.

(ii) - (2) We now show that  $\{X_t, \mathcal{F}_t\}$  is a  $L_1$ -mixingale of size -1. From the discussion in Ahsan and Dufour (2021), we know that  $X_t$  is  $\beta$ -mixing, so it has mixing coefficients of the type  $\beta_T = \psi \rho^T$ ,  $\psi > 0$ ,  $0 < \rho < 1$ . To show that  $\{X_t\}$  is of size -1, its mixing coefficients  $\beta_T$  must be  $O(T^{-\varphi})$ , with  $\varphi > 1$  [see Davidson (1994, Definition 16.1, p. 247)]. Indeed,

$$\frac{\rho^T}{T^{-\varphi}} = T^{\varphi} \exp(T \log \rho) = \exp(\varphi \log T) \exp(T \log \rho) = \exp[\varphi(\log T) + T(\log \rho)]. \tag{A.49}$$

Since  $\lim_{T \to \infty} [\varphi(\log T) + T(\log \rho)] = -\infty$ , we get

$$\lim_{T \to \infty} \exp[\varphi(\log T) + T(\log \rho)] = 0. \tag{A.50}$$

This holds in particular for  $\varphi > 1$ ; see Rudin (1976, Theorem 3.20(d), p. 57).

(iii) To show that  $\limsup_{T\to\infty} T^{-1/2}\mathbb{E}\|S_T\| < \infty$ , we first observe that  $\mathbb{E}(S_T) = 0$  and, using the Cauchy-Schwarz inequality,

$$(T^{-1/2}\mathbb{E}\|S_T\|)^2 \leq \frac{1}{T}\mathbb{E}(\|S_T\|^2) = \frac{1}{T}\mathbb{E}(S_T'S_T) = \frac{1}{T}\operatorname{tr}[\mathbb{E}(S_TS_T')] = \frac{1}{T}\operatorname{tr}[\operatorname{Var}(S_T)]$$

$$= \operatorname{tr}[\operatorname{Var}(T^{-1/2}S_T)]. \tag{A.51}$$

It is thus sufficient to show that

$$\limsup_{T \to \infty} \text{tr}[\text{Var}(T^{-1/2}S_T)] < \infty. \tag{A.52}$$

We now consider separately the components  $\Psi_t$  and  $\Lambda_t$  of  $X_t$ .

(iii) - (1) Set

$$S_{T1} := \sum_{t=1}^{T} \Psi_t, \quad \zeta_{\Psi}(\tau) := \text{cov}(\Psi_t, \Psi_{t+\tau}).$$
 (A.53)

Then

$$\zeta_{\Psi}(\tau) = \mathbb{E}[(\log(y_t^2) - \mu)(\log(y_{t+\tau}^2) - \mu)] = \mathbb{E}[y_t^* y_{t+\tau}^*] = \gamma_{y^*}(\tau), \tag{A.54}$$

$$\operatorname{Var}(T^{-1/2}S_{T1}) = \frac{1}{T} \left[ \sum_{t=1}^{T} \operatorname{Var}(\Psi_t) + \sum_{t \neq s} \operatorname{cov}(\Psi_t, \Psi_s) \right] = \frac{1}{T} \left[ T\zeta_{\Psi}(0) + 2\sum_{\tau=1}^{T} (T - \tau)\zeta_{\Psi}(\tau) \right]$$

$$= \zeta_{\Psi}(0) + 2\sum_{\tau=1}^{T} (1 - \frac{\tau}{T})\zeta_{\Psi}(\tau) = \gamma_{y^*}(0) + 2\sum_{\tau=1}^{T} (1 - \frac{\tau}{T})\gamma_{y^*}(\tau)$$
(A.55)

hence

$$\limsup_{T \to \infty} \text{Var}(T^{-1/2}S_{T1}) = \limsup_{T \to \infty} \left[ \gamma_{y^*}(0) + 2 \sum_{\tau=1}^{T} (1 - \frac{\tau}{T}) \gamma_{y^*}(\tau) \right] 
= \gamma_{y^*}(0) + 2 \sum_{\tau=1}^{\infty} \gamma_{y^*}(\tau) = \sum_{\tau=-\infty}^{\infty} \gamma_{y^*}(\tau) \le \sum_{\tau=-\infty}^{\infty} |\gamma_{y^*}(\tau)| < \infty.$$
(A.56)

This convergence is due to the fact that  $y_t^*$  follows a stationary ARMA(p, p) process. So  $y_t^*$  can be viewed as an MA( $\infty$ ) process with absolutely summable coefficients, which implies the absolute summability of autocovariances [see Hamilton (1994, chapter 3, page 52)]. By the Cauchy-Schwarz inequality, this entails

$$\limsup_{T \to \infty} T^{-1/2} \mathbb{E}|S_{T1}| < \infty. \tag{A.57}$$

(iii) - (2) Set

$$S_{T2} := \sum_{t=1}^{T} \Lambda_t = [S_{T2,0}, S_{T2,1}, \dots, S_{T2,m}]', \tag{A.58}$$

$$S_{T2,k} := \sum_{t=1}^{T} \Lambda_{t,k}, \quad \zeta_{\Lambda_k}(\tau) := \text{cov}(\Lambda_{t,k}, \Lambda_{t+\tau,k}), \quad k = 0, 1, \dots, m.$$
(A.59)

Then, for k = 0, 1, ..., m,

$$\begin{split} \zeta_{\Lambda_k}(\tau) &= & \mathbb{E}[\left(y_t^* \, y_{t+k}^* - \gamma_{y^*}(k)\right) \left(y_{t+\tau}^* \, y_{t+\tau+k}^* - \gamma_{y^*}(k)\right)] = \mathbb{E}[y_t^* \, y_{t+k}^* \, y_{t+\tau}^* \, y_{t+\tau+k}^*] - \gamma_{y^*}(k)^2 \\ &= & \mathbb{E}[y_t^* \, y_{t+k}^*] \mathbb{E}[y_{t+\tau}^* \, y_{t+\tau+k}^*] + \operatorname{cov}(y_t^*, \, y_{t+\tau}^*) \operatorname{cov}(y_{t+k}^*, \, y_{t+\tau+k}^*) \\ &+ \operatorname{cov}(y_t^*, \, y_{t+\tau+k}^*) \operatorname{cov}(y_{t+k}^*, \, y_{t+\tau}^*) - \gamma_{y^*}(k)^2 \\ &= & \gamma_{y^*}(k)^2 + \gamma_{y^*}(\tau)^2 + \gamma_{y^*}(\tau+k) \gamma_{y^*}(\tau-k) - \gamma_{y^*}(k)^2 \end{split}$$

$$= \gamma_{\nu^*}(\tau)^2 + \gamma_{\nu^*}(\tau + k)\gamma_{\nu^*}(\tau - k), \tag{A.60}$$

hence

$$\operatorname{Var}(T^{-1/2}S_{T2,k}) = \frac{1}{T} \left[ \sum_{t=1}^{T} \operatorname{Var}(\Lambda_{t,k}) + \sum_{t \neq s} \operatorname{cov}(\Lambda_{t,k}, \Lambda_{s,k}) \right] = \frac{1}{T} \left[ T\zeta_{\Lambda_k}(0) + 2\sum_{\tau=1}^{T} (T - \tau)\zeta_{\Lambda_k}(\tau) \right]$$
(A.61)

$$= \zeta_{\Lambda_k}(0) + 2\sum_{\tau=1}^{T} (1 - \frac{\tau}{T})\zeta_{\Lambda_k}(\tau)$$
 (A.62)

$$= \gamma_{y^*}(0)^2 + \gamma_{y^*}(k)\gamma_{y^*}(-k) + 2\sum_{\tau=1}^{T} (1 - \frac{\tau}{T})[\gamma_{y^*}(\tau)^2 + \gamma_{y^*}(\tau + k)\gamma_{y^*}(\tau - k)], \tag{A.63}$$

and

$$\limsup_{T \to \infty} Var(T^{-1/2}S_{T2,k}) = \gamma_{y^*}(0)^2 + \gamma_{y^*}(k)\gamma_{y^*}(-k) 
+ \limsup_{T \to \infty} \left[2\sum_{\tau=1}^{T} (1 - \frac{\tau}{T})[\gamma_{y^*}(\tau)^2 + \gamma_{y^*}(\tau + k)\gamma_{y^*}(\tau - k)]\right] 
= \sum_{\tau=-\infty}^{\infty} [\gamma_{y^*}(\tau)^2 + \gamma_{y^*}(\tau + k)\gamma_{y^*}(\tau - k)] 
= \sum_{\tau=-\infty}^{\infty} \gamma_{y^*}(\tau)^2 + \sum_{\tau=-\infty}^{\infty} \gamma_{y^*}(\tau + k)\gamma_{y^*}(\tau - k) 
= \sum_{\tau=-\infty}^{\infty} \gamma_{y^*}(\tau)^2 + \sum_{\tau=-\infty}^{\infty} \gamma_{y^*}(\tau + k) < \infty.$$
(A.64)

This convergence is due to the fact that absolute summability implies square-summability. We deduce that

$$\limsup_{T \to \infty} T^{-1/2} \mathbb{E} \left| S_{T2,k} \right| < \infty, \quad k = 0, 1, \dots, m.$$
(A.65)

(iii) - (3) Set

$$S_{T3} := \sum_{t=1}^{T} \bar{\Psi}_t, \quad \zeta_{\bar{\Psi}}(\tau) := \text{cov}(\bar{\Psi}_t, \bar{\Psi}_{t+\tau}).$$
 (A.66)

Then

$$\zeta_{\bar{\Psi}}(\tau) = \mathbb{E}\left[\left(|y_{t}|y_{t-1} - \lambda_{y}(1)\right)\left(|y_{t+\tau}|y_{t+\tau-1} - \lambda_{y}(1)\right)\right], 
= \mathbb{E}\left[|y_{t}|y_{t-1}|y_{t+\tau}|y_{t+\tau-1}\right] - \lambda_{y}^{2}(1), 
= \mathbb{E}\left[|y_{t}|y_{t-1}\right]\mathbb{E}\left[|y_{t+\tau}|y_{t+\tau-1}\right] + \mathbb{E}\left[|y_{t}||y_{t+\tau}|\right]\underbrace{\mathbb{E}\left[y_{t-1}y_{t+\tau-1}\right]}_{=0} + \mathbb{E}\left[|y_{t}|y_{t+\tau-1}\right]\mathbb{E}\left[y_{t-1}|y_{t+\tau}|\right] - \lambda_{y}^{2}(1), 
= \lambda_{y}^{2}(1) + 0 + \lambda_{y}(1-\tau)\lambda_{y}(1+\tau) - \lambda_{y}^{2}(1) = \lambda_{y}(1-\tau)\lambda_{y}(1+\tau),$$
(A.67)

where  $\lambda_{\gamma}(1-\tau) = 0$  for  $\tau \ge 1$ , hence

$$\operatorname{Var}(T^{-1/2}S_{T3}) = \frac{1}{T} \left[ \sum_{t=1}^{T} \operatorname{Var}(\bar{\Psi}_{t}) + \sum_{t \neq s} \operatorname{cov}(\bar{\Psi}_{t}, \bar{\Psi}_{s}) \right] = \frac{1}{T} \left[ T\zeta_{\bar{\Psi}}(0) + 2\sum_{\tau=1}^{T} (T - \tau)\zeta_{\bar{\Psi}}(\tau) \right]$$

$$= \zeta_{\bar{\Psi}}(0) + 2\sum_{\tau=1}^{T} (1 - \frac{\tau}{T})\zeta_{\bar{\Psi}}(\tau) = \zeta_{\bar{\Psi}}(0) + 0 = \lambda_{y}^{2}(1), \tag{A.68}$$

and

$$\limsup_{T \to \infty} \operatorname{Var}(T^{-1/2}S_{T3}) = \limsup_{T \to \infty} \left[ \lambda_y^2(1) \right] = \lambda_y^2(1) < \infty. \tag{A.69}$$

By the Cauchy-Schwarz inequality, this entails

$$\limsup_{T \to \infty} T^{-1/2} \mathbb{E}|S_{T3}| < \infty. \tag{A.70}$$

Combining (A.57), (A.65) and (A.70), we get, for any  $(m+3) \times 1$  fixed real vector  $a \neq 0$ ,

$$\limsup_{T \to \infty} T^{-1/2} \mathbb{E} \left| a' S_T \right| < \infty. \tag{A.71}$$

It is also clear properties (i) and (ii) also hold if we replace  $S_T$  by  $a'S_T$ . Thus we can apply Theorem 24.5 of Davidson (1994) to  $a'S_T$  to state that  $T^{-1/2}(a'S_T)$  is asymptotically normal. Since this holds for any  $a \neq 0$ , it follows from the Cramér-Wold theorem that  $T^{-1/2}\sum_{t=1}^{T}X_t$  is asymptotically multinormal:

$$T^{-1/2}S_T = T^{-1/2}\sum_{t=1}^T X_t = \sqrt{T} \begin{bmatrix} \hat{\mu} - \mu \\ \hat{\Gamma}(m) - \Gamma(m) \\ \hat{\lambda}_y(1) - \lambda_y(1) \end{bmatrix} \xrightarrow{d} \mathcal{N}(0, V), \tag{A.72}$$

where

$$V = \lim_{T \to \infty} \mathbb{E}\{[T^{-1/2}S_T][T^{-1/2}S_T]'\} = \begin{bmatrix} V_{\mu} & C'_{\mu,\Gamma(m)} & C_{\mu,\lambda_y(1)} \\ C_{\mu,\Gamma(m)} & V_{\Gamma(m)} & C_{\Gamma(m),\lambda_y(1)} \\ C_{\mu,\lambda_y(1)} & C'_{\Gamma(m),\lambda_y(1)} & V_{\lambda_y(1)} \end{bmatrix}.$$
(A.73)

Using (A.56), (A.63) and (A.69), we have:

$$V_{\mu} = \gamma_{y^*}(0) + 2\sum_{\tau=1}^{\infty} \gamma_{y^*}(\tau), \quad V_{\lambda_y(1)} = \text{Var}(\bar{\Psi}_t) + 2\sum_{\tau=1}^{\infty} \text{cov}(\bar{\Psi}_t, \bar{\Psi}_{t+\tau}) = \lambda_y^2(1), \quad (A.74)$$

$$V_{\Gamma(m)} = \text{Var}(\Lambda_t) + 2\sum_{\tau=1}^{\infty} \text{cov}(\Lambda_t, \Lambda_{t+\tau}), \quad C_{\mu, \Gamma(m)} = [C_{\mu 0}, C_{\mu 1}, \dots, C_{\mu m}]', \tag{A.75}$$

$$C_{\mu k} = \sum_{t} \text{cov}(\Psi_{t}, \Lambda_{t, k}) = 2 \sum_{t=1}^{\infty} \mathbb{E}[\Psi_{t}(y_{t}^{*} y_{t+k}^{*} - \gamma_{y^{*}}(k))]$$

$$= 2 \sum_{t=1}^{\infty} \mathbb{E}[y_{t}^{*}(y_{t}^{*} y_{t+k}^{*} - \gamma_{y^{*}}(k))] = 2 \sum_{t=1}^{\infty} [\mathbb{E}(y_{t}^{*2} y_{t+k}^{*}) - \mathbb{E}(y_{t}^{*}) \gamma_{y^{*}}(k)]$$

$$= 2 \sum_{t=1}^{\infty} \mathbb{E}(y_{t}^{*2} y_{t+k}^{*}), \quad k = 0, 1, 2, ..., m.$$
(A.76)

Further, for k = 0, we substitute  $y_t^* = w_t + \epsilon_t$  to get

$$\bar{c} := C_{\mu 0} = 2 \sum_{t=1}^{\infty} \mathbb{E}(y_t^{*3}) = 2 \sum_{t=1}^{\infty} [\mathbb{E}(w_t^3) + \mathbb{E}(\epsilon_t^3)] = 2 \sum_{t=1}^{\infty} \mathbb{E}(\epsilon_t^3). \tag{A.77}$$

Since  $\{z_t\}$  is a sequence of i.i.d.  $\mathcal{N}(0,1)$  random variables, we have  $\mathbb{E}(\epsilon_t^3) = \psi^{(2)}(\frac{1}{2})$  [see (2.7)], which is equal to  $-14\mathcal{Z}(3)$  where  $\mathcal{Z}(\cdot)$  is Riemann's Zeta function with  $\mathcal{Z}(3) = 1.20205.^1$  For k = 1, ..., m, it is easily seen that  $C_{\mu k} = 0$ 

<sup>&</sup>lt;sup>1</sup>The Riemann Zeta function for  $s \in \mathbb{C}$  with Re(s) > 1 is defined as  $\mathcal{Z}(s) = \sum_{n=1}^{\infty} \frac{1}{n^s}$ .

from the MA( $\infty$ ) representation of  $w_t$ . So  $C_{\mu,\Gamma(m)}$  is a  $(m+1)\times 1$  vector given by  $(\bar{c},0_{[m\times 1]})'$ , with  $\bar{c}$  is defined in (A.77). Now

$$\begin{split} C_{\mu,\lambda_{y}(1)} &= \sum_{t} \text{cov}(\Psi_{t}, \Psi_{t}) = 2 \sum_{t=1}^{\infty} \mathbb{E}[Y_{t}^{*}(|y_{t}|y_{t-1} - \lambda_{y}(1))] \\ &= 2 \sum_{t=1}^{\infty} \mathbb{E}[Y_{t}^{*}|y_{t}|y_{t-1}] - \underbrace{\mathbb{E}[Y_{t}^{*}]\lambda_{y}(1)}_{=0} \\ &= 2 \sum_{t=1}^{\infty} [\mathbb{E}[(w_{t} + e_{t})|y_{t}|y_{t-1}] - 2 \sum_{t=1}^{\infty} [\mathbb{E}[w_{t}|y_{t}|y_{t-1}] + \mathbb{E}[e_{t}|y_{t}|y_{t-1}]) \\ &= 2 \sum_{t=1}^{\infty} (\mathbb{E}[|y_{t}||w_{t}y_{t-1}] + \mathbb{E}[|y_{t}|y_{t-1}e_{t}]) \\ &= 2 \sum_{t=1}^{\infty} (2\mathbb{E}[|y_{t}||\cos(w_{t}, y_{t-1}] + \sigma_{y}^{2}\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)|z_{t}|\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}\right] \mathbb{E}[|z_{t}|e_{t}]) \\ &= 2 \sum_{t=1}^{\infty} \left(2\mathbb{E}[|y_{t}||\mathbb{E}[w_{t}, y_{t-1}] + \sigma_{y}^{2}\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}\right] \mathbb{E}[|z_{t}|e_{t}]\right) \\ &= 2 \sum_{t=1}^{\infty} \left(2\mathbb{E}[|y_{t}||\mathbb{E}[w_{t}, y_{t-1}] + \sigma_{y}^{2}\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}\right] \mathbb{E}[|z_{t}|e_{t}]\right) \\ &= 2 \sum_{t=1}^{\infty} \left(2\sigma_{y}\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)\right] \mathbb{E}[|z_{t}||\sigma_{y}\mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}w_{t}\right]\right) \\ &= 2 \sum_{t=1}^{\infty} \left(4\sigma_{y}^{2}\exp\left(\frac{\gamma_{w}(0)}{8}\right)\sqrt{\frac{2}{\pi}}\mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)\right] \frac{\text{cov}(z_{t-1}, w_{t})}{\mathbb{E}[|z_{t}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y}||\sigma_{y$$

where  $\gamma_w(k) = \text{cov}(w_t, w_{t+k})$ ,  $\psi^{(0)}(z)$  is the *digamma function* and  $\gamma^{\epsilon}$  is the Euler-Mascheroni constant.

$$C_{\Gamma(m),\lambda_{\nu}(1)} = [C_{\lambda 0}, C_{\lambda 1}, \dots, C_{\lambda m}]', \tag{A.79}$$

$$\begin{split} C_{\lambda k} &= \sum_{t} \text{cov}(\bar{\Psi}_{t}, \Lambda_{t,k}) = 2 \sum_{t=1}^{\infty} \mathbb{E}[\left(|y_{t}|y_{t-1} - \lambda_{y}(1)\right) \left(y_{t}^{*} y_{t+k}^{*} - \gamma_{y^{*}}(k)\right)] \\ &= 2 \sum_{t=1}^{\infty} \left( \mathbb{E}\left[|y_{t}|y_{t-1} y_{t}^{*} y_{t+k}^{*}\right] - \lambda_{y}(1) \gamma_{y^{*}}(k) \right) \end{split}$$

$$= 2\sum_{t=1}^{\infty} \left( \mathbb{E}[|y_{t}|] \operatorname{cov}(y_{t-1}, y_{t}^{*} y_{t+k}^{*}) + \operatorname{cov}(|y_{t}|, y_{t-1}) \operatorname{cov}(y_{t}^{*}, y_{t+k}^{*}) \right. \\ + \operatorname{cov}(|y_{t}|, y_{t}^{*}) \operatorname{cov}(y_{t-1}, y_{t+k}^{*}) + \operatorname{cov}(|y_{t}|, y_{t+k}^{*}) \operatorname{cov}(y_{t-1}, y_{t}^{*}) - \lambda_{y}(1) \gamma_{y^{*}}(k) \right) \\ = 2\sum_{t=1}^{\infty} \left( \mathbb{E}[|y_{t}|] \mathbb{E}[y_{t-1} y_{t}^{*} y_{t+k}^{*}] + \mathbb{E}[|y_{t}| y_{t-1}] \mathbb{E}[y_{t}^{*}, y_{t+k}^{*}] \right. \\ + \mathbb{E}[|y_{t}|, y_{t}^{*}] \mathbb{E}[y_{t-1}, y_{t+k}^{*}] + \mathbb{E}[|y_{t}| y_{t+k}^{*}] \mathbb{E}[(y_{t-1} y_{t}^{*}) - \lambda_{y}(1) \gamma_{y^{*}}(k) \right) \\ = 2\sum_{t=1}^{\infty} \left( \mathbb{E}[|y_{t}|] \mathbb{E}[y_{t-1}, y_{t}^{*} y_{t+k}^{*}] + \mathbb{E}[|y_{t}| y_{t}^{*}] \mathbb{E}[y_{t-1} y_{t+k}^{*}] \right. \\ + \mathbb{E}[|y_{t}| y_{t+k}^{*}] \mathbb{E}[(y_{t-1}, y_{t}^{*})], \quad k = 0, 1, 2, ..., m.$$

$$(A.80)$$

Now

$$\begin{split} &\mathbb{E}[|y_{t}|]\mathbb{E}[y_{t-1}y_{t}^{*}y_{t+k}^{*}] = \mathbb{E}[|y_{t}|]\mathbb{E}\left[y_{t-1}(w_{t}+\epsilon_{t})(w_{t+k}+\epsilon_{t+k})\right] \\ &= \mathbb{E}[|y_{t}|]\mathbb{E}\left[y_{t-1}w_{t}w_{t+k}\right] = \mathbb{E}[|y_{t}|]\mathbb{E}\left[\sigma_{y}\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}w_{t}w_{t+k}\right] \\ &= \sigma_{y}\mathbb{E}\left[\sigma_{y}\exp\left(\frac{w_{t}}{2}\right)|z_{t}|\right]\left[\mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}\right]\mathbb{E}[w_{t}w_{t+k}] + \mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)w_{t}\right]\mathbb{E}[z_{t-1}w_{t+k}] \\ &+ \mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)w_{t+k}\right]\mathbb{E}[z_{t-1}w_{t}]\right] \\ &= \sigma_{y}^{2}\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)\right]\mathbb{E}[|z_{t}|] \\ &= \exp\left(\frac{y_{w}(0)}{8}\right) = \sqrt{\frac{2}{\pi}} \\ &+ \mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)w_{t+k}\right]\mathbb{E}[z_{t-1}w_{t}] \\ &= \frac{\gamma_{w}(1)}{2}\exp\left(\frac{\gamma_{w}(0)}{8}\right) \\ &= \sigma_{y}^{2}\exp\left(\frac{\gamma_{w}(0)}{8}\right) \sqrt{\frac{2}{\pi}}\left(\delta_{p}\sigma_{v}\bar{\psi}_{k}\frac{\gamma_{w}(1)}{2}\exp\left(\frac{\gamma_{w}(0)}{8}\right) + \delta_{p}\sigma_{v}\frac{\gamma_{w}(k+1)}{2}\exp\left(\frac{\gamma_{w}(0)}{8}\right)\right) \\ &= \delta_{p}\sigma_{v}\sigma_{y}^{2}\sqrt{\frac{1}{2\pi}}\exp\left(\frac{\gamma_{w}(0)}{4}\right)\left(\bar{\psi}_{k}\gamma_{w}(1) + \gamma_{w}(k+1)\right), \end{split} \tag{A.81}$$

where  $\bar{\psi}_k$  is k-th parameter of the MA( $\infty$ ) representation the latent log volatility process,

$$\begin{split} &\mathbb{E}[|y_t|y_t^*]\mathbb{E}[y_{t-1}y_{t+k}^*] = \mathbb{E}[\sigma_y \exp\left(\frac{w_t}{2}\right)|z_t|(w_t + \epsilon_t)]\mathbb{E}[y_{t-1}(w_{t+k} + \epsilon_{t+k})] \\ &= \sigma_y \mathbb{E}\left[\exp\left(\frac{w_t}{2}\right)|z_t|(w_t + \epsilon_t)\right] \left(\mathbb{E}[y_{t-1}w_{t+k}] + \mathbb{E}[y_{t-1}]\mathbb{E}[\epsilon_{t+k})\right] \\ &= \sigma_y^2 \left(\mathbb{E}\left[\exp\left(\frac{w_t}{2}\right)|z_t|w_t\right] + \mathbb{E}\left[\exp\left(\frac{w_t}{2}\right)|z_t|\log(z_t^2)\right] - \mathbb{E}\left[\exp\left(\frac{w_t}{2}\right)|z_t|\right]\mathbb{E}\left[\log(z_t^2)\right]\right) \left(\mathbb{E}[\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}w_{t+k}]\right) \\ &= \sigma_y^2 \underbrace{\left[\mathbb{E}[|z_t|]\mathbb{E}\left[\exp\left(\frac{w_t}{2}\right)w_t\right] + \mathbb{E}\left[\exp\left(\frac{w_t}{2}\right)\right]\mathbb{E}\left[|z_t|\log(z_t^2)\right]}_{=\sqrt{\frac{2}{\pi}}(\log 2 - \gamma^\epsilon)} \\ \end{split}$$

$$-\underbrace{\mathbb{E}[|z_{t}|]}_{=\sqrt{\frac{2}{\pi}}} \underbrace{\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)\right]}_{=\exp\left(\frac{y_{w}(0)}{8}\right)} \underbrace{\mathbb{E}\left[\log(z_{t}^{2})\right]}_{=\psi^{(0)}(0.5)+\log 2} \underbrace{\mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)\right]}_{=\exp\left(\frac{y_{w}(0)}{8}\right)} \underbrace{\exp\left(\frac{w_{t}}{2}\right)}_{=\mathbb{E}\left[z_{t-1}w_{t+k}\right]=\delta_{p}\sigma_{v}\bar{\psi}_{k}}$$

$$= \delta_{p}\sigma_{v}\sigma_{y}^{2}\bar{\psi}_{k}\sqrt{\frac{2}{\pi}}\exp\left(\frac{\gamma_{w}(0)}{4}\right)\left(\frac{\gamma_{w}(0)}{2} - \gamma^{\epsilon} - \psi^{(0)}(0.5)\right),$$

$$\mathbb{E}[|y_{t}|y_{t+k}^{*}]\mathbb{E}[y_{t-1}y_{t}^{*}] = \mathbb{E}[\sigma_{y}\exp\left(\frac{w_{t}}{2}\right)|z_{t}|(w_{t+k} + \epsilon_{t+k})]\mathbb{E}[y_{t-1}(w_{t} + \epsilon_{t})]$$

$$= \sigma_{y}\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)|z_{t}|(w_{t+k} + \epsilon_{t+k})\right]\left(\mathbb{E}[y_{t-1}w_{t}] + \mathbb{E}[y_{t-1}]\mathbb{E}[\epsilon_{t}]\right)$$

$$= \sigma_{y}^{2}\left(\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)|z_{t}|w_{t+k}\right] + \mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)|z_{t}|\right]\mathbb{E}[\epsilon_{t+k}]\right)\left(\mathbb{E}[\exp\left(\frac{w_{t-1}}{2}\right)z_{t-1}w_{t}]\right)$$

$$= \sigma_{y}^{2}\left(\mathbb{E}\left[|z_{t}|\right]\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)w_{t+k}\right] + \mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)\mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)\right] - \mathbb{E}\left[z_{t-1}w_{t}\right] + \mathbb{E}\left[e_{t}\right]\right]$$

$$= \sigma_{y}^{2}\left(\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)w_{t+k}\right] + \mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)\right] - \mathbb{E}\left[z_{t-1}w_{t}\right] + \mathbb{E}\left[e_{t}\right] - \mathbb{E}\left[e_{t-1}w_{t}\right] + \mathbb{E}\left[e_{t}\right]\right]$$

$$= \sigma_{y}^{2}\left(\mathbb{E}\left[\exp\left(\frac{w_{t}}{2}\right)w_{t+k}\right] + \mathbb{E}\left[\exp\left(\frac{w_{t-1}}{2}\right)\right] - \mathbb{E}\left[e_{t-1}w_{t}\right] + \mathbb{E}\left[e_{t}\right] - \mathbb{E}\left[e_{t-1}w_{t}\right] + \mathbb{E}\left[e_{t}\right] - \mathbb{E}\left[e_{t-1}w_{t}\right] + \mathbb{E}\left[e_{t}\right] + \mathbb{E}\left[e_{t}\right]$$

Combing (A.81)-(A.83), we have

$$C_{\lambda k} = 2 \sum_{t=1}^{\infty} \left( \frac{\delta_p \sigma_v \sigma_y^2}{\sqrt{2\pi}} \exp\left(\frac{\gamma_w(0)}{4}\right) \left( \gamma_w(0) + \bar{\psi}_k \gamma_w(1) + 0.5 \bar{\psi}_k \gamma_w(k) + \gamma_w(k+1) - \frac{\gamma^{\epsilon} + \psi^{(0)}(0.5)}{2} \right) \right),$$

$$k = 0, 1, 2, ..., m. \tag{A.84}$$

where  $\bar{\psi}_k$  is k-th parameter of the MA( $\infty$ ) representation of the latent log volatility process,  $\gamma_w(k) = \text{cov}(w_t, w_{t+k})$ ,  $\psi^{(0)}(z)$  is the *digamma function* and  $\gamma^{\epsilon}$  is the Euler-Mascheroni constant. Finally, (4.2) follows on observing that

$$\sqrt{T} \begin{bmatrix} \hat{\mu} - \mu \\ \hat{\Gamma}(m) - \Gamma(m) \\ \hat{\lambda}_{y}(1) - \lambda_{y}(1) \end{bmatrix} - T^{-1/2} S_{T} \xrightarrow{p} 0.$$
(A.85)

PROOF OF THEOREM 4.3 It is easily seen that  $D_p$  is a continuously differentiable mapping of  $[\mu, \gamma_{y^*}(0), \gamma_{y^*}(1), \dots, \gamma_{y^*}(2p)]'$ . The convergence result stated in (4.9) follows from the standard result for differentiable transformations of asymptotically normally distributed variables together with the application of the multivariate delta method.

In case of an SVL(1) model,

$$D_{1} := D_{1}(\beta) = (D_{\phi_{1}}, D_{\sigma_{y}}, D_{\sigma_{v}}, D_{\delta_{1}})^{'}, \quad \beta := \left[\mu, \gamma_{y^{*}}(0), \gamma_{y^{*}}(1), \gamma_{y^{*}}(2), \lambda_{y}(1)\right]^{'}, \tag{A.86}$$

$$D_{\phi_1} = \gamma_{\nu^*}(2)/\gamma_{\nu^*}(1), \quad D_{\sigma_{\nu}} = \exp(\mu - \bar{\mu})^{1/2}, \quad D_{\sigma_{\nu}} = [1 - (\gamma_{\nu^*}(2)/\gamma_{\nu^*}(1))^2][\gamma_{\nu^*}(0) - \pi^2/2], \tag{A.87}$$

$$D_{\delta_1} = \frac{\sqrt{2\pi}\lambda_{\gamma}(1)}{\sigma_{\nu}\sigma_{\nu}^2} \exp\left(-\frac{1}{4}\frac{\sigma_{\nu}^2}{1-\phi_1}\right),\tag{A.88}$$

$$G(\beta) := \frac{\partial D_1}{\partial \beta'} = \begin{pmatrix} 0 & 0 & -\tilde{A} & \frac{1}{\gamma_{y^*}(1)} & 0\\ \frac{\tilde{B}}{2} & 0 & 0 & 0 & 0\\ 0 & -\frac{\tilde{C}}{2\tilde{F}} & \frac{\gamma_{y^*}(2)^2 \tilde{D}}{\gamma_{y^*}(1)^3 \tilde{F}} & -\frac{\gamma_{y^*}(2) \tilde{D}}{\gamma_{y^*}(1)^2 \tilde{F}} & 0\\ -\frac{\sqrt{2}\lambda_y(1)\sqrt{\pi}e^{-\tilde{E}}e^{-(\mu-\tilde{\mu})}}{\tilde{E}} & \tilde{J} & \tilde{K} & \tilde{L} & \frac{\sqrt{2}\sqrt{\pi}e^{-\tilde{E}}e^{-(\mu-\tilde{\mu})}}{\tilde{E}} \end{pmatrix}, \tag{A.89}$$

where

$$\tilde{A} = \frac{\gamma_{y^*}(2)}{\gamma_{y^*}(1)^2}, \quad \tilde{B} = \sqrt{e^{\mu - \tilde{\mu}}}, \quad \tilde{C} = \frac{\gamma_{y^*}(2)^2}{\gamma_{y^*}(1)^2} - 1, \quad \tilde{D} = \gamma_{y^*}(0) - \frac{\pi^2}{2}, \quad \tilde{E} = \frac{\tilde{C}\tilde{D}}{4(\tilde{A} - 1)}$$
(A.90)

$$\tilde{F} = \sqrt{-\tilde{C}\tilde{D}}, \quad \tilde{G} = \left(\gamma_{V^*}(1)^2 - \gamma_{V^*}(2)^2\right), \quad \tilde{H} = 2\gamma_{V^*}(0) - \pi^2$$
(A.91)

$$\tilde{I} = \gamma_{y^*}(1)^2 \pi^2 - 2\gamma_{y^*}(0)\gamma_{y^*}(1)^2 + 8\gamma_{y^*}(1)\gamma_{y^*}(2) - \gamma_{y^*}(2)^2 \pi^2 + 2\gamma_{y^*}(0)\gamma_{y^*}(2)^2 \tag{A.92}$$

$$\tilde{J} = -\frac{\sqrt{2}\lambda_{y}(1)\sqrt{\pi}e^{-(\mu-\tilde{\mu})-\tilde{E}}\tilde{G}(4\gamma_{y^{*}}(1)+2\gamma_{y^{*}}(0)\gamma_{y^{*}}(1)+2\gamma_{y^{*}}(0)\gamma_{y^{*}}(2)-\gamma_{y^{*}}(1)\pi^{2}-\gamma_{y^{*}}(2)\pi^{2})}{8\gamma_{y^{*}}(1)^{3}\tilde{F}^{3/2}}$$
(A.93)

$$\tilde{K} = -\frac{\sqrt{2}\gamma_{y^*}(2)\lambda_y(1)\sqrt{\pi}e^{-(\mu-\tilde{\mu})-\tilde{E}}\tilde{H}\tilde{I}}{16\gamma_{y^*}(1)^4\tilde{F}^{3/2}}, \quad \tilde{L} = \frac{\sqrt{2}\lambda_y(1)\sqrt{\pi}e^{-(\mu-\tilde{\mu})-\tilde{E}}\tilde{H}\tilde{I}}{16\gamma_{y^*}(1)^3\tilde{F}^{3/2}}.$$
(A.94)

## **B** Additional ARMA-based winsorized estimators

We can achieve better stability and efficiency of the CF-ARMA estimator by using "winsorization". Winsorization substantially increases the probability of getting admissible values. Using (3.21), we propose alternative estimators of  $\phi_p$  and we call these estimators *winsorized ARMA* estimators (or *W-ARMA* estimators). Other (possibly nonlinear) averaging methods, such as the median, may also be used. We consider four types of winsorized estimators based on the expression (3.21) in the simulation section.

1. The first winsorized estimate  $\hat{\phi}_p^{\mathrm{m}}$  is the arithmetic mean of sample ratios (equal weights):

$$\omega_j = 1/J, \quad j = 1, ..., J,$$
 (B.95)

in (3.21). This type of winsorization is also considered by Kristensen and Linton (2006) in the context of the GARCH(1,1) model estimation.

2. The second estimate  $\hat{\phi}_p^{\rm ld}$  is a mean of ratios with linearly declining (LD) weights:

$$\omega_j = (2/J)[1 - (j/(J+1))], \quad j = 1, ..., J.$$
 (B.96)

3. The third estimate is the median-based estimate obtained by taking the median of J estimates of each one of the p components of  $\phi_p$ :

$$\hat{\phi}_{p}^{\text{med}} = [\hat{\phi}_{1}^{\text{med}}, \dots, \hat{\phi}_{p}^{\text{med}}]', \quad \hat{\phi}_{i}^{\text{med}} = \text{med} \{\hat{B}(p, j)_{i} : 1 \le j \le J\}, i = 1, \dots, p.$$
 (B.97)

4. The fourth estimate is obtained by an OLS regression coefficient (without intercept):

$$\hat{\phi}_{p}^{\text{ols}} = [A(p, J)' A(p, J)]^{-1} A(p, J)' e(p, J)$$
(B.98)

where e(p, J) is a  $(pJ) \times 1$  vector and A(p, J) is a  $(pJ) \times p$  matrix defined by

$$e(p, J) = [\hat{\gamma}(p, 1)\omega_1^{1/2}, \dots, \hat{\gamma}(p, J)\omega_J^{1/2}]', \quad A(p, J) = [\hat{\boldsymbol{\Gamma}}(p, 1)\omega_1^{1/2}, \dots, \hat{\boldsymbol{\Gamma}}(p, J)\omega_J^{1/2}]'. \tag{B.99}$$

Clearly, different OLS-based W-ARMA can be generated by considering different weights  $\omega_1, \ldots, \omega_I$ .

All these estimators are depend on J. For J = 1, they are equivalent to the simple CF-ARMA estimator given in (3.14).

## C Monte Carlo tests with nuisance parameters

In this section, we discuss Monte Carlo tests when the distribution of the test statistic depends on nuisance parameters. In other words, we consider a model  $\{(\Xi, \mathbb{A}_{\Xi}, P_{\theta}) : \theta \in \Omega\}$  where we assume that the distribution of S is determined by  $P_{\bar{\theta}}$ , where  $\bar{\theta}$  represents the true parameter vector. To deal with this complication, the MC test procedure can be modified as follows.

1. To test the null hypothesis

$$H_0: \bar{\theta} \in \Omega_0$$

where  $\Omega_0 \subset \Omega$ , we calculate the relevant test statistic  $S_0$  based on data.

- 2. For each  $\theta \in \theta_0$ , by Monte Carlo methods, we generate N i.i.d. replications of  $S: S(N, \theta) = [S_1(\theta), \dots, S_N(\theta)]$ .
- 3. Using these simulated test statistics, we compute the MC p-value

$$\hat{p}_N[S_0|\theta] := p_N[S_0; S(N,\theta)], \tag{C.100}$$

where

$$p_N[x;S(N,\theta)] := \frac{NG_N[x;S(N,\theta)] + 1}{N+1}.$$
 (C.101)

4. The *p*-value function  $\hat{p}_N[S_0|\theta]$  as a function of  $\theta$  is maximized over the parameter values compatible with the  $\Omega_0$  set, *i.e.*, the null hypothesis, and  $H_0$  is rejected if

$$\sup_{\theta \in \Omega_0} \hat{p}_N[S|\theta] \le \alpha. \tag{C.102}$$

If the number of simulated statistics N is chosen so that  $\alpha(N+1)$  is an integer, then we have under  $H_0$ :

$$P[\sup_{\theta \in \Omega_0} \{\hat{p}_N[S|\theta]\} \le \alpha] \le \alpha. \tag{C.103}$$

The test defined by  $\hat{p}_N[S|\theta] \le \alpha$  has size  $\alpha$  for known  $\theta$ . Treating  $\theta$  as a nuisance parameter and  $\Omega_0$  is a nuisance parameter set consistent with null, the test is *exact at level*  $\alpha$ ; for a proof, see Dufour (2006).

Because of the maximization in the critical region (C.102) the test is called a *maximized Monte Carlo* (MMC) test. MMC tests provide valid inference under general regularity conditions such as almost-unidentified models or time series processes involving unit roots. In particular, even though the moment conditions defining the estimator are derived under the stationarity assumption, this does not question in any way the validity of maximized MC tests, unlike the parametric bootstrap whose distributional theory is based on strong regularity conditions. Only the power of MMC tests may be affected. However, the simulated *p*-value function is not continuous, so standard gradient-based methods cannot be used to maximize it. But search methods applicable to non-differentiable functions are applicable, *e.g.* simulated annealing [see Goffe et al. (1994)].

A simplified approximate version of the MMC procedure can alleviate its computational load whenever a consistent point or set estimate of  $\theta$  is available. To do this, we reformulate the setup in order to allow for an increasing sample size, *i.e.*, now the test statistic depends on a sample of size T,  $S = S_T$ .

- 1. Let  $S_{T0}$  be the observed test statistic (based on data) and the distribution of S involves nuisance parameters under the null and  $\bar{\theta} \in \Omega_0$  with  $\Omega_0 \subset \Omega$  and  $\Omega_0 \neq \emptyset$ .
- 2. we have a consistent set estimator  $C_T$  of  $\theta$  (under  $H_0$ ) such that

$$\lim_{T \to \infty} P[\bar{\theta} \in C_T] = 1 \text{ under } H_0. \tag{C.104}$$

- 3. For each  $\theta \in C_T$ , by Monte Carlo methods, we generate N i.i.d. replications of  $S: S_T(N,\theta) = [(S_{T1}(\theta),...,S_{TN}(\theta))].$
- 4. Using these simulations we compute the MC *p*-value  $\hat{p}_{TN}[S_T|\theta] := p_{TN}[S_{T0}; S_T(N,\theta)]$ , where

$$p_{TN}[x; S_T(N, \theta)] := \frac{NG_{TN}[x; S_T(N, \theta)] + 1}{N + 1}.$$
(C.105)

5. The *p*-value function  $\hat{p}_{TN}[S_T|\theta]$  as a function of  $\theta$  is maximized with respect to  $\theta$  in  $C_T$ , and  $H_0$  is rejected if

$$\sup\{\hat{p}_{TN}[S_T|\theta]:\theta\in C_T\}\leq\alpha. \tag{C.106}$$

If the number of simulated statistics N is chosen so that  $\alpha(N+1)$  is an integer, then we have under  $H_0$ :

$$\lim_{T \to \infty} P[\sup{\{\hat{p}_{TN}[S_T | \theta] : \theta \in C_T\}} \le \alpha] \le \alpha, \tag{C.107}$$

*i.e.*, we control for the level asymptotically.

In practice, it is easy to find a consistent set estimate of  $\bar{\theta}$ , whenever a *consistent* point estimate  $\hat{\theta}_T$  of  $\bar{\theta}$  available (e.g. a GMM estimator). For instance, any set of the form

$$C_T = \{\theta : \|\hat{\theta}_T - \theta\| < d\} \tag{C.108}$$

with d a fixed positive constant independent of T, satisfies (C.104). The consistent set estimate MMC (CSEMMC) method is especially useful when the distribution of the test statistic is highly sensitive to nuisance parameters. Here, possible discontinuities in the asymptotic distribution are automatically overcome through a numerical maximization over a set that contains the true value of the nuisance parameter with probability one asymptotically (while there is no guarantee for the point estimate to converge sufficiently fast to overcome the discontinuity). It is worth noting that there is no need to maximize the p-value function with respect to unidentified parameters under the null hypothesis. Thus, parameters which are unidentified under the null hypothesis can be set to any fixed value and the maximization be performed only over the remaining identified nuisance parameters. When there are several nuisance parameters, one can use simulated annealing, an optimization algorithm which does not require differentiability. Indeed, the simulated p-value function is not continuous, so standard gradient based methods cannot be used to maximize it. An example where this is done on a VAR model involving a large number of nuisance parameters, see Dufour and Jouini (2006).

In Dufour and Khalaf (2002), they call the test based on simulations using a point nuisance parameter estimate a *Local Monte Carlo* (LMC) test. The term local reflects the fact that the underlying MC p-value is based on a specific choice for the nuisance parameter. Here if the set  $C_T$  in (C.106) is reduced to a single point estimate  $\hat{\theta}_T$ , *i.e.*  $C_T$  =

$$\{\hat{ heta}_T\}$$
, we get a LMC test 
$$\hat{p}_{TN}[S_T|\hat{ heta}_T] \leq \alpha,$$

which can be interpreted as a parametric bootstrap test. Note that no asymptotic argument on the number N of MC replications is required to obtain this result; this is the fundamental difference between the latter procedure and the parametric bootstrap method.

(C.109)

Even if  $\hat{\theta}_T$  is a consistent estimate of  $\bar{\theta}$  (under the null hypothesis), the set  $C_T = \{\hat{\theta}_T\}$  does not generally satisfy condition (C.104). Additional assumptions are needed to show that the parametric bootstrap procedure yields an asymptotically valid test. It is computationally less costly but clearly less robust to violations of regularity conditions than the MMC procedure; for further discussion, see Dufour (2006). Furthermore, the LMC non-rejections are *exactly* conclusive in the following sense: if  $\hat{p}_N[S | \hat{\theta}_0] > \alpha$ , then the exact MMC test is clearly not significant at level  $\alpha$ .

Since Ahsan and Dufour (2021) consider testing individual parameters of a higher order SV(p) model using t-type statistics briefly described above, we will instead focus on testing for no leverage using the LR-type statistic discussed previously. Consequently, in the description of the simulation-based finite-sample tests above, we set  $S_0 = LR_0$  and  $S(N,\theta) = LR(N,\theta)$ , where  $LR(N,\theta) = [LR_1(\theta),...,LR_N(\theta)]$ . This testing procedure requires estimating the model under both the null hypothesis and the alternative hypothesis using our proposed computationally inexpensive estimators; see Section 3 for computationally simple methods for SVL(p) models. Furthermore, the constrained model utilizes the consistent point estimate  $\hat{\theta}_T$ . We discuss in more detail the test for no leverage in the next section, which also includes other simulation-based results.

## D Additional simulation results

Table A1. Comparison with competing estimators: Bias and RMSE

					В	ias			RM	ISE	
				φ	$\sigma_y$	$\sigma_v$	δ	φ	$\sigma_y$	$\sigma_v$	δ
							True V	/alue			
T	Estimators	RCT	NIV	0.95	0.15	1	-0.95	0.95	0.15	1	-0.95
	Bayes-1	6.06E+08	0	0.0314	0.1102	-0.5120	0.1608	0.0318	0.1607	0.5128	0.1621
	Bayes-2	1.10E+08	0	-0.0233	0.0564	0.0207	0.3405	0.0249	0.0681	0.0477	0.3416
	QML	23063.9	0	-0.0102	0.0087	-0.2139	0.3490	0.0462	0.0521	0.5896	0.3611
	CF-ARMA	1.0	24	-0.0050	0.0087	-0.0259	-0.0290	0.0291	0.0521	0.2579	0.1213
1000	W-ARMA $(J = 10)$	1.3	0	-0.0060	0.0087	0.0147	-0.0293	0.0155	0.0521	0.0878	0.1185
	W-ARMA $(J = 50)$	1.9	0	-0.0069	0.0087	0.0218	-0.0289	0.0168	0.0521	0.1008	0.1197
	W-ARMA ( $J = 100$ )	2.8	0	-0.0040	0.0087	-0.0060	-0.0298	0.0160	0.0521	0.1035	0.1182
	W-ARMA ( $J = 200$ )	3.9	0	0.0009	0.0087	-0.0544	-0.0310	0.0158	0.0521	0.1241	0.1163
	Bayes-1	7.84E+08	0	0.0316	0.0543	-0.5115	0.1612	0.0317	0.0728	0.5120	0.1627
	Bayes-2	1.29E+08	0	-0.0155	0.0346	-0.0151	0.1588	0.1070	0.0573	0.0621	0.1663
	QML	30509.9	0	-0.0051	0.0047	-0.1240	0.3490	0.0171	0.0357	0.2733	0.3542
	CF-ARMA	1.0	1	-0.0026	0.0044	-0.0166	-0.0460	0.0202	0.0355	0.1893	0.0706
2000	W-ARMA ( $J = 10$ )	1.1	0	-0.0034	0.0045	0.0077	-0.0461	0.0101	0.0355	0.0613	0.0695
	W-ARMA ( $J = 50$ )	1.5	0	-0.0038	0.0045	0.0108	-0.0461	0.0111	0.0355	0.0755	0.0694
	W-ARMA ( $J = 100$ )	2.2	0	-0.0022	0.0045	-0.0044	-0.0461	0.0107	0.0355	0.0764	0.0692
	W-ARMA ( $J = 200$ )	3.4	0	0.0007	0.0045	-0.0329	-0.0463	0.0107	0.0355	0.0876	0.0688

## Notes:

- We simulate 1000 samples from each model. W-ARMA (J = 10, 50, 100, 200) is the winsorized ARMA estimator based on OLS and J is the winsorizing parameter. These methods are proposed in Section 3.
- QML is the quasi-maximum likelihood estimator of Harvey and Shephard (1996).
- The Bayes-1 estimator is based on the mixture sampler of Omori et al. (2007), where the SVL(1) model is reparametrized as  $y_t = \exp(w_t/2)z_t$  and  $w_t = \mu_w + \phi(w_{t-1} \mu_w) + \sigma_v v_t$ , where  $\sigma_y = \exp(\mu_w/2)$ . The priors for  $\mu_w$ ,  $\phi$ ,  $\sigma_v$ , and  $\delta$  are set to:  $\mu_w \sim \mathcal{N}(-3,5)$ ;  $\sigma_v^2 \sim \mathcal{IG}\left(\frac{5}{2},\frac{0.05}{2}\right)$  with mean 0.0167 and standard deviation 0.0237;  $\phi \in (-1,1)$  with  $\frac{\phi+1}{2} \sim \mathcal{B}(20,1.5)$ , giving  $\phi$  a mean of 0.86 and a standard deviation of 0.11;  $\delta \sim \mathcal{U}(-1,1)$ , where  $\mathcal{U}$  denotes the uniform distribution,  $\mathcal{B}$  denotes the beta distribution, and  $\mathcal{IG}$  denotes the inverse gamma distribution. We apply this Bayesian method on simulated data sets and draw 5000 observations from the posterior distributions. Bayesian estimators are obtained by averaging the last 2500 draws.
- The Bayes-2 estimator is the efficient MCMC sampler of Kastner (2016) where the parameter vector is sampled using an ancillarity-sufficiency interweaving strategy (ASIS) of Yu and Meng (2011). Independent priors are considered for  $\mu_w$ ,  $\phi$ ,  $\sigma_v$ , and  $\delta$ :  $\mu_w \sim \mathcal{N}(0,1)$ ;  $\sigma_v \in \mathbb{R}^+$  with  $\pm \sqrt{\sigma_v^2} \sim \mathcal{N}(0,1)$ ;  $\phi \in (-1,1)$  with  $(\phi+1)/2 \sim \mathcal{B}(5,15.5)$ ; and  $\delta \in (-1,1)$  with  $(\delta+1)/2 \sim \mathcal{B}(75,1)$ . We apply this Bayesian method on simulated data sets and draw 100,000 observations from the posterior distributions. Bayesian estimators are obtained by averaging the last 50,000 draws.
- RCT stands for the relative computational time w.r.t. the CF-ARMA estimator. The number of inadmissible values (NIV) of  $\phi$  is also reported, these are out of 1000.
- Boldface font highlights the smallest bias and RMSE with no NIV.

Table A2. Empirical power of tests for no leverage in SVL(1) model (moderate persistence,  $A_T = \hat{\Omega}_*^{-1}$  & Asymptotic not level-corrected)

					$H_0$	: $\delta = 0$ vs. $H$	$I_1: \delta \neq 0$					
		$\delta = -0.90$	)		$\delta = -0.70$	)		$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	$\theta_0$ , $\sigma_y = 0.10$	), $\sigma_{v} = 0.75$					
500	76.2	90.1	71.2	46.3	69.7	45.1	46.4	66.2	43.9	74.6	90.2	71.0
1000	91.9	96.0	89.2	75.1	86.8	72.4	73.8	86.7	71.8	92.3	97.7	89.6
2000	97.4	99.3	95.0	91.6	95.1	90.0	92.1	96.0	91.1	97.0	98.8	95.9
5000	98.7	99.3	98.2	97.5	98.3	97.0	98.3	99.2	97.0	99.1	99.9	98.3
					$\phi = 0.7$	75, $\sigma_y = 0.10$	), $\sigma_{v} = 1.00$					
500	94.0	97.5	91.1	84.2	94.8	83.2	78.6	93.0	79.0	92.7	97.2	89.2
1000	95.6	98.3	95.8	93.2	98.3	94.2	93.6	98.1	94.4	96.4	98.6	96.4
2000	99.1	99.7	99.1	98.0	99.6	98.5	97.9	99.6	98.7	98.6	99.5	98.8
5000	99.8	99.9	99.8	99.9	99.9	99.9	99.9	99.9	99.9	99.9	99.9	99.9

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. Asymmetric test results are not level-corrected. LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

Table A3. Empirical power of tests for no leverage in SVL(1) model (high persistence,  $A_T = \hat{\Omega}_*^{-1}$  & Asymptotic not level-corrected)

					$H_0$	: $\delta = 0$ vs. $H$	$1: \delta \neq 0$					
		$\delta = -0.90$	0		$\delta = -0.70$	0		$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	99, $\sigma_y = 0.10$	$\sigma_{v} = 0.25$					
500	5.4	18.8	8.8	3.5	11.7	4.8	3.8	13.6	5.5	6.2	22.7	10.6
1000	13.3	30.0	16.4	7.8	20.5	10.1	8.0	18.6	10.3	15.7	32.6	17.0
2000	28.8	47.2	33.0	15.6	30.1	20.1	16.0	31.3	20.0	28.7	47.3	34.3
5000	65.8	77.7	71.2	39.2	54.1	50.0	40.9	55.7	50.2	65.1	78.4	73.8
					$\phi = 0.9$	$05, \sigma_y = 0.10$	$\sigma_{v} = 0.50$					
500	42.1	67.9	43.7	22.5	44.2	22.9	20.9	44.9	21.5	42.8	67.8	44.2
1000	74.2	87.6	74.2	46.4	65.8	47.3	46.6	65.1	47.8	75.5	89.6	74.4
2000	94.4	97.8	92.8	76.6	85.8	73.9	75.1	85.8	77.0	95.3	98.2	92.4
5000	98.6	99.4	97.7	95.3	97.2	95.7	95.8	97.9	95.7	99.0	99.6	98.2

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N=99 simulations. Asymmetric test results are not level-corrected. LR test statistic is computed using  $A_T=\hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

Table A4. Empirical power of tests for no leverage in SVL(2) model ( $A_T = \hat{\Omega}_*^{-1}$  & Asymptotic not level-corrected)

					$H_0$	$: \delta = 0 \text{ vs. } I$	$H_1:\delta$	≠ 0					
		$\delta = -0.90$			$\delta = -0.70$	)			$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC		Asy	LMC	MMC	Asy	LMC	MMC
				ф	$\phi_1 = 0.05,  \phi_2$	$_{2} = 0.85,  \sigma_{3}$	y = 1.0	00, $\sigma_v = 1$	.00				
500	92.6	95.3	78.0	81.3	88.2	62.0		80.9	89.0	64.0	93.5	97.1	75.0
1000	95.6	98.3	93.0	92.5	96.1	83.0		93.4	97.2	83.0	97.8	98.8	93.0
2000	98.4	99.4	97.0	98.2	99.0	97.0		97.5	99.0	94.0	98.7	99.4	96.0
5000	99.1	99.6	99.0	98.8	99.7	99.0		98.8	99.6	97.0	99.4	99.8	100.0
				φ	$\phi_1 = 0.05,  \phi_2$	$\sigma_2 = 0.70,  \sigma_3$	, = 1.0	$0, \sigma_{v} = 1$	.00				
500	99.5	100.0	97.4	98.6	99.8	93.8		98.0	99.4	93.6	99.3	99.7	96.6
1000	99.8	100.0	100.0	99.8	100.0	99.3		99.7	99.9	99.3	99.8	99.9	98.7
2000	100.0	100.0	100.0	99.9	100.0	99.5		99.9	100.0	100.0	100.0	100.0	100.0
5000	100.0	100.0	100.0	100.0	100.0	100.0		100.0	100.0	100.0	100.0	100.0	100.0

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo test uses N=99 simulations. Asymmetric test results are not level-corrected. LR test statistic is computed using  $A_T = \hat{\Omega}_*^{-1}$  in (6.2) as in (6.9).

Table A5. Empirical size of tests for no leverage in SVL(1) model (moderate persistence &  $A_T = I_{(p+3)}$ )

		Н	$I_0$ : $\delta = 0$ vs. $H_1$ : $\delta \neq 0$			
	$\phi = 0$	$0.90,  \sigma_y = 0.10,  \sigma_i$	y = 0.75	$\phi = 0$	$0.75,  \sigma_y = 0.10,  \sigma_t$	, = 1.00
T	Asy	LMC	MMC	Asy	LMC	MMC
500	79.3	12.6	3.3	71.1	9.9	1.5
1000	82.8	12.8	2.0	72.8	10.1	1.4
2000	85.0	11.4	1.8	76.7	11.4	1.0
5000	89.0	10.2	1.0	77.9	10.8	1.4

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. LR test statistic is computed using  $A_T = I_{(p+3)}$  in (6.2) as in (6.5).

Table A6. Empirical power of tests for no leverage in SVL(1) model (moderate persistence &  $A_T = I_{(p+3)}$ )

					$H_0$	$\delta = 0 \text{ vs. } I$	$H_1: \delta \neq 0$					
		$\delta = -0.90$			$\delta = -0.70$			$\delta = 0.70$	)		$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	0, $\sigma_y = 0.1$	0, $\sigma_{v} = 0.73$	5				
500	61.9	65.5	20.9	42.3	45.0	12.5	42.	5 43.9	11.4	63.8	66.6	19.5
1000	84.9	81.9	36.8	59.8	57.1	19.7	61.	9 58.2	18.7	85.6	82.7	35.4
2000	99.1	99.3	58.7	85.6	87.3	31.7	85.	6 87.1	31.9	98.7	99.0	60.3
5000	100.0	100.0	94.9	99.8	99.9	70.6	99.	9 99.9	68.4	100.0	100.0	93.9
					$\phi = 0.7$	75, $\sigma_y = 0.1$	0, $\sigma_{v} = 1.00$	)				
500	96.2	95.9	62.3	80.8	80.2	35.8	80.	8 80.3	35.2	96.5	96.4	63.6
1000	100.0	100.0	93.3	99.0	98.7	70.5	98.	8 98.5	72.8	100.0	100.0	92.9
2000	100.0	100.0	99.7	100.0	100.0	94.5	100.	0 100.0	94.4	100.0	100.0	99.9
5000	100.0	100.0	100.0	100.0	100.0	100.0	100.	0 100.0	100.0	100.0	100.0	100.0

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. Asymmetric test results are level-corrected using N = 10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LMC test results are level-corrected using N = 1,000 and true parameters. LR test statistic is computed using  $A_T = I_{(p+3)}$  in (6.2) as in (6.5).

Table A7. Empirical size of tests for no leverage in SVL(1) model (high persistence &  $A_T = I_{(p+3)}$ )

		Н	$I_0$ : $\delta = 0$ vs. $H_1$ : $\delta \neq 0$			
	$\phi = 0$	$0.99,  \sigma_y = 0.10,  \sigma_i$	· = 0.25	$\phi = 0$	.95, $\sigma_y = 0.10$ , $\sigma_t$	y = 0.50
T	Asy	LMC	MMC	Asy	LMC	MMC
500	81.8	19.5	5.3	79.7	13.6	2.5
1000	88.7	17.1	5.2	83.3	13.4	2.3
2000	92.1	16.8	5.4	87.9	11.4	1.6
5000	93.2	13.3	4.8	91.2	10.9	1.4

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. LR test statistic is computed using  $A_T = I_{(p+3)}$  in (6.2) as in (6.5).

Table A8. Empirical power of tests for no leverage in SVL(1) model (high persistence &  $A_T = I_{(p+3)}$ )

					$H_0$	$: \delta = 0 \text{ vs. } H$	$\delta \neq 0$					
		$\delta = -0.90$			$\delta = -0.70$	0		$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	99, $\sigma_y = 0.10$	$\sigma_{v} = 0.25$					
500	23.4	24.1	8.4	19.4	19.8	7.9	22.8	24.1	6.2	25.6	27.0	8.1
1000	34.1	33.4	12.4	26.6	26.4	10.4	23.2	23.1	8.6	29.7	29.6	9.2
2000	43.7	42.7	16.5	30.2	28.7	12.0	30.7	29.7	12.4	44.3	42.4	17.9
5000	68.8	67.2	31.7	46.9	46.1	20.0	44.5	43.8	18.1	66.0	65.0	27.5
					$\phi = 0.9$	$65, \sigma_y = 0.10$	$\sigma_{v} = 0.50$					
500	42.9	40.6	12.8	29.6	27.9	8.0	30.9	28.6	8.1	44.9	41.5	13.2
1000	67.9	67.1	26.2	46.3	45.2	14.6	44.4	43.4	13.0	67.1	65.8	24.1
2000	87.6	87.3	40.1	62.7	62.3	20.3	65.7	65.6	22.7	89.8	89.4	43.9
5000	100.0	100.0	82.3	96.4	96.4	48.0	96.0	96.0	43.7	100.0	100.0	79.9

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. Asymmetric test results are level-corrected using N = 10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LMC test results are level-corrected using N = 1,000 and true parameters. LR test statistic is computed using  $A_T = I_{(p+3)}$  in (6.2) as in (6.5).

Table A9. Empirical size of tests for no leverage in SVL(2) model (with  $A_T = I_{(p+3)}$ )

			$H_0$ : $\delta = 0$ vs. $H_1$ : $\delta \neq 0$			
	$\phi_1 = 0.05$ ,	$\phi_2 = 0.85,  \sigma_y = 1$	1.00, $\sigma_{v} = 1.00$	$\phi_1 = 0.05$ ,	$\phi_2 = 0.70,  \sigma_y = 1$	1.00, $\sigma_{v} = 1.00$
T	Asy	LMC	MMC	Asy	LMC	MMC
500	57.9	13.8	6.7	53.1	8.0	2.7
1000	62.8	10.7	3.9	54.3	6.3	1.7
2000	68.0	8.8	2.4	55.8	7.1	1.5
5000	77.0	8.4	1.9	57.1	6.8	2.5

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N = 99 simulations. LR test statistic is computed using  $A_T = I_{(p+3)}$  in (6.2) as in (6.5).

Table A10. Empirical power of tests for no leverage in SVL(2) model (with  $A_T = I_{(p+3)}$ )

					$H_0$	$: \delta = 0 \text{ vs. } I$	$I_1: \delta \neq 0$					
		$\delta = -0.90$			$\delta = -0.70$	1		$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
				$\phi_1$	$= 0.05, \phi_2$	$a_2 = 0.85,  \sigma_y$	$= 1.00$ , $\sigma_{v} = 1$	1.00				
500	62.4	67.5	47.0	49.4	56.9	34.1	50.0	55.2	34.3	62.1	65.8	45.2
1000	74.3	75.3	52.8	60.1	63.0	39.5	61.5	65.8	40.9	75.5	76.2	53.8
2000	90.3	88.1	67.4	80.9	80.3	52.5	80.9	80.2	49.9	91.0	87.4	66.3
5000	99.8	98.7	88.6	99.1	96.2	77.4	99.4	95.9	78.8	100.0	98.8	87.8
				$\phi_1$	$= 0.05, \phi_2$	$\sigma_2 = 0.70,  \sigma_y$	$= 1.00,  \sigma_{v} = 1$	1.00				
500	97.7	96.7	87.7	90.5	92.8	74.6	90.9	92.3	72.0	97.6	96.5	88.8
1000	100.0	99.2	96.6	99.8	98.7	92.7	99.7	98.7	92.5	100.0	99.4	96.7
2000	100.0	99.9	99.4	100.0	99.9	98.4	100.0	99.9	97.8	100.0	99.9	98.9
5000	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0	99.8	100.0	100.0	100.0

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo test uses N = 99 simulations. Asymmetric test results are level-corrected using N = 10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LMC test results are level-corrected using N = 1,000 and true parameters. LR test statistic is computed using  $A_T = I_{(p+3)}$  in (6.2) as in (6.5).

Table A11. Empirical power of tests for no leverage in SVL(1) model (moderate persistence,  $A_T = I_{(p+3)}$ , & LMC not level-corrected)

					$H_0$	$\delta = 0 \text{ vs. } 1$	$H_1: \delta \neq 0$					
		$\delta = -0.90$			$\delta = -0.70$			$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	00, $\sigma_y = 0.1$	0, $\sigma_{v} = 0.75$					
500	61.9	73.4	20.9	42.3	51.9	12.5	42.5	50.1	11.4	63.8	73.7	19.5
1000	84.9	92.8	36.8	59.8	75.4	19.7	61.9	75.7	18.7	85.6	93.7	35.4
2000	99.1	99.2	58.7	85.6	91.5	31.7	85.6	91.6	31.9	98.7	99.3	60.3
5000	100.0	100.0	94.9	99.8	99.9	70.6	99.9	100.0	68.4	100.0	100.0	93.9
					$\phi = 0.7$	75, $\sigma_y = 0.1$	$0, \sigma_{v} = 1.00$					
500	96.2	98.3	62.3	80.8	87.6	35.8	80.8	87.9	35.2	96.5	98.4	63.6
1000	100.0	99.9	93.3	99.0	99.4	70.5	98.8	99.4	72.8	100.0	100.0	92.9
2000	100.0	100.0	99.7	100.0	100.0	94.5	100.0	100.0	94.4	100.0	100.0	99.9
5000	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0

Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N=99 simulations. Asymmetric test results are level-corrected using N=10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LMC test results are level-corrected using N=1,000 and true parameters. LR test statistic is computed using  $A_T=I_{(p+3)}$  in (6.2) as in (6.5).

Table A12. Empirical power of tests for no leverage in SVL(1) model (high persistence,  $A_T = I_{(p+3)}$ , & LMC not level-corrected)

					$H_0$ :	$\delta = 0 \text{ vs. } H$	$\delta \neq 0$					
T		$\delta = -0.90$			$\delta = -0.70$	0		$\delta = 0.70$			$\delta = 0.90$	
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC
					$\phi = 0.9$	9, $\sigma_{\gamma} = 0.10$	$\sigma_{v} = 0.25$					
500	23.4	26.1	8.4	19.4	21.5	7.9	22.8	25.0	6.2	25.6	29.2	8.1
1000	34.1	40.6	12.4	26.6	31.2	10.4	23.2	29.2	8.6	29.7	35.7	9.2
2000	43.7	50.6	16.5	30.2	35.8	12.0	30.7	37.8	12.4	44.3	50.9	17.9
5000	68.8	73.1	31.7	46.9	52.8	20.0	44.5	50.7	18.1	66.0	72.6	27.5
					$\phi = 0.9$	$\sigma_{v} = 0.10$	$\sigma_{v} = 0.50$					
500	42.9	53.2	12.8	29.6	37.2	8.0	30.9	40.1	8.1	44.9	57.4	13.2
1000	67.9	80.6	26.2	46.3	61.2	14.6	44.4	59.3	13.0	67.1	81.8	24.1
2000	87.6	95.2	40.1	62.7	76.7	20.3	65.7	79.1	22.7	89.8	94.8	43.9
5000	100.0	100.0	82.3	96.4	97.9	48.0	96.0	98.1	43.7	100.0	99.8	79.9

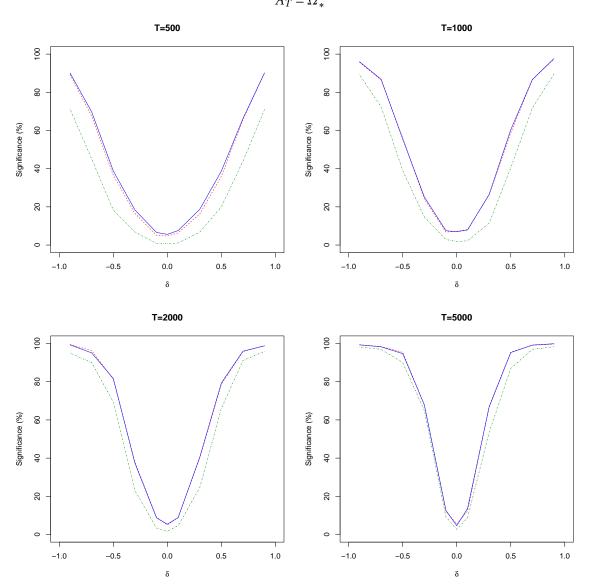
Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N=99 simulations. Asymmetric test results are level-corrected using N=10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LMC test results are level-corrected using N=1,000 and true parameters. LR test statistic is computed using  $A_T=I_{(p+3)}$  in (6.2) as in (6.5).

Table A13. Empirical power of tests for no leverage in SVL(2) model ( $A_T = I_{(p+3)}$  & LMC not level-corrected)

					$H_0$	$\delta = 0 \text{ vs. } H$	$I_1: \delta \neq 0$						
	$\delta = -0.90$				$\delta = -0.70$			$\delta = 0.70$			$\delta = 0.90$		
T	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	Asy	LMC	MMC	
				$\phi_1$	$= 0.05, \phi_2$	$\sigma_2 = 0.85,  \sigma_y$	= 1.00, $\sigma_v = 1$	.00					
500	62.4	67.5	47.0	49.4	56.9	34.1	50.0	55.2	34.3	62.1	65.8	45.2	
1000	74.3	75.3	52.8	60.1	63.0	39.5	61.5	65.8	40.9	75.5	76.2	53.8	
2000	90.3	88.1	67.4	80.9	80.3	52.5	80.9	80.2	49.9	91.0	87.4	66.3	
5000	99.8	98.7	88.6	99.1	96.2	77.4	99.4	95.9	78.8	100.0	98.8	87.8	
				$\phi_1$	$= 0.05, \phi_2$	$\sigma_2 = 0.70,  \sigma_y$	= 1.00, $\sigma_{v}$ = 1	.00					
500	97.7	96.7	87.7	90.5	92.8	74.6	90.9	92.3	72.0	97.6	96.5	88.8	
1000	100.0	99.2	96.6	99.8	98.7	92.7	99.7	98.7	92.5	100.0	99.4	96.7	
2000	100.0	99.9	99.4	100.0	99.9	98.4	100.0	99.9	97.8	100.0	99.9	98.9	
5000	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0	99.8	100.0	100.0	100.0	

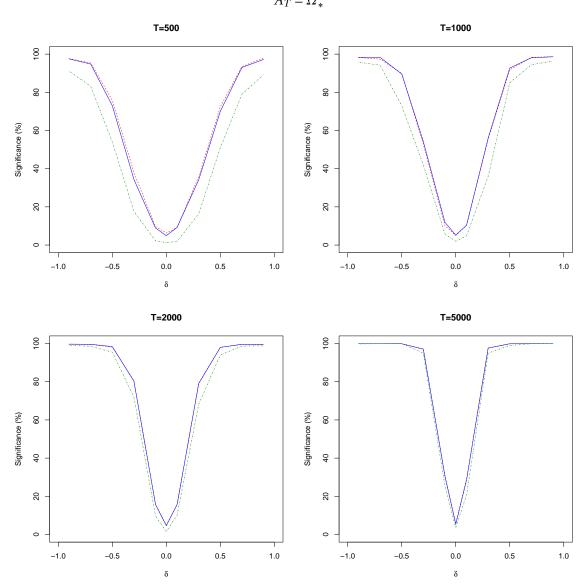
Notes: Rejection frequencies are obtained using 1000 replications. Monte Carlo tests use N=99 simulations. Asymmetric test results are level-corrected using N=10000 and true parameters (*i.e.*, infeasible test in practice as it requires knowing the true DGP). LMC test results are level-corrected using N=1,000 and true parameters. LR test statistic is computed using  $A_T=I_{(p+3)}$  in (6.2) as in (6.5).

Figure A1. Power curves of test for no leverage in SV(1) model when  $\phi=0.90$ ,  $\sigma_y=0.10$ ,  $\sigma_v=0.75$ , &  $A_T=\hat{\Omega}_*^{-1}$ 



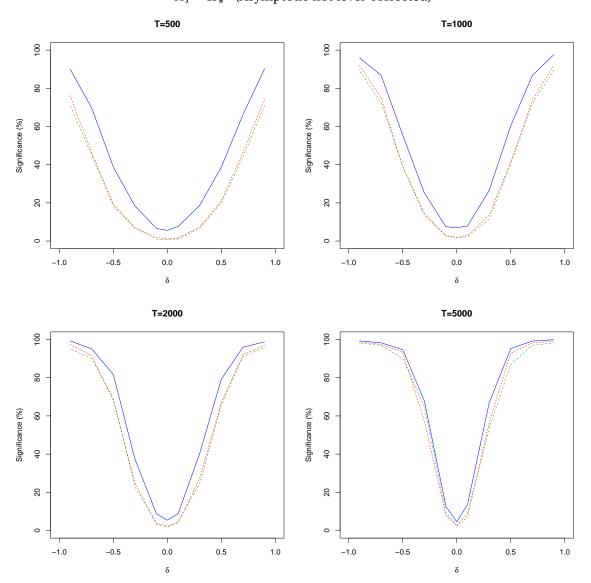
Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A2. Power curves of test for no leverage in SV(1) model when  $\phi=0.75$ ,  $\sigma_y=0.10$ ,  $\sigma_v=1.00$ , &  $A_T=\hat{\Omega}_*^{-1}$ 



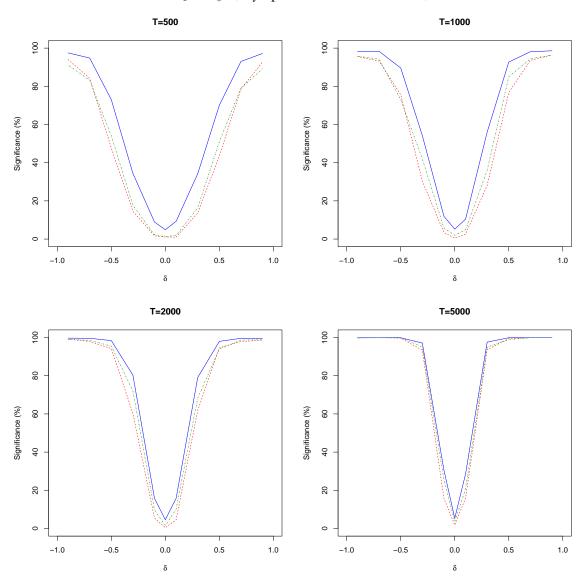
Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A3. Power curves of test for no leverage in SV(1) model when  $\phi=0.90$ ,  $\sigma_y=0.10$ ,  $\sigma_v=0.75$ , &  $A_T=\hat{\Omega}_*^{-1} \text{ (Asymptotic not level-corrected)}$ 



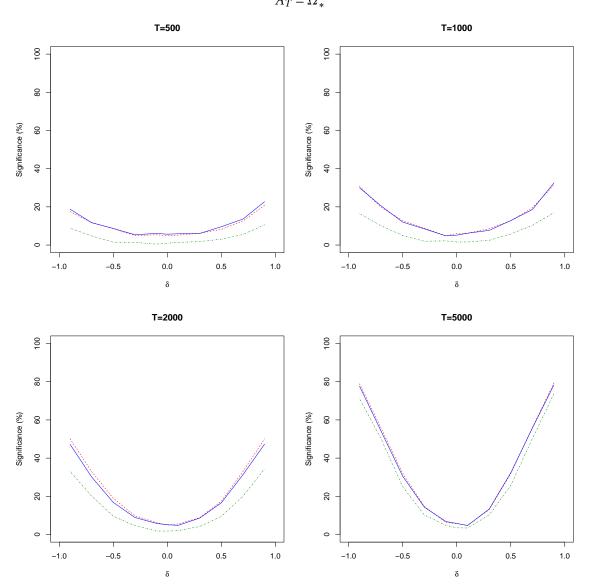
Notes: Red is Asymptotic test, blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A4. Power curves of test for no leverage in SV(1) model when  $\phi=0.75$ ,  $\sigma_y=0.10$ ,  $\sigma_v=1.00$ , &  $A_T=\hat{\Omega}_*^{-1} \text{ (Asymptotic not level-corrected)}$ 



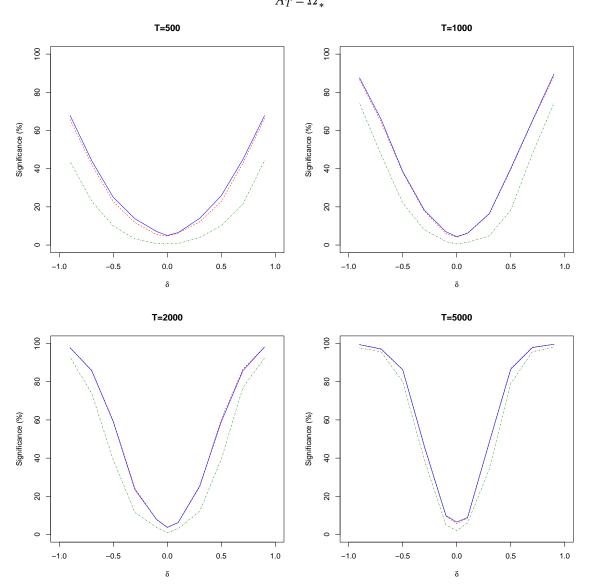
Notes: Red is Asymptotic test, blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A5. Power curves of test for no leverage in SV(1) model when  $\phi=0.99$ ,  $\sigma_y=0.10$ ,  $\sigma_v=0.25$ , &  $A_T=\hat{\Omega}_*^{-1}$ 



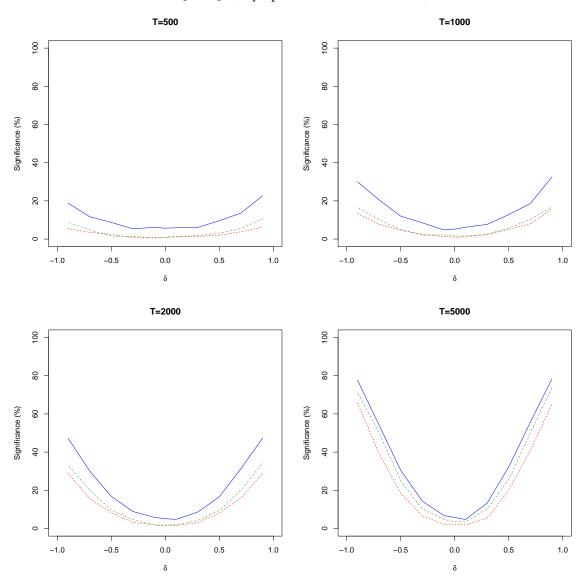
Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A6. Power curves of test for no leverage in SV(1) model when  $\phi=0.95$ ,  $\sigma_y=0.10$ ,  $\sigma_v=0.50$ , &  $A_T=\hat{\Omega}_*^{-1}$ 



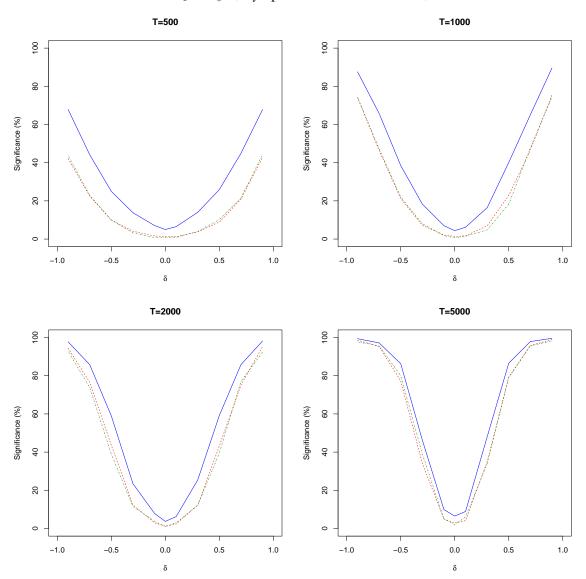
Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A7. Power curves of test for no leverage in SV(1) model when  $\phi=0.99$ ,  $\sigma_y=0.10$ ,  $\sigma_v=0.25$ , &  $A_T=\hat{\Omega}_*^{-1} \text{ (Asymptotic not level-corrected)}$ 



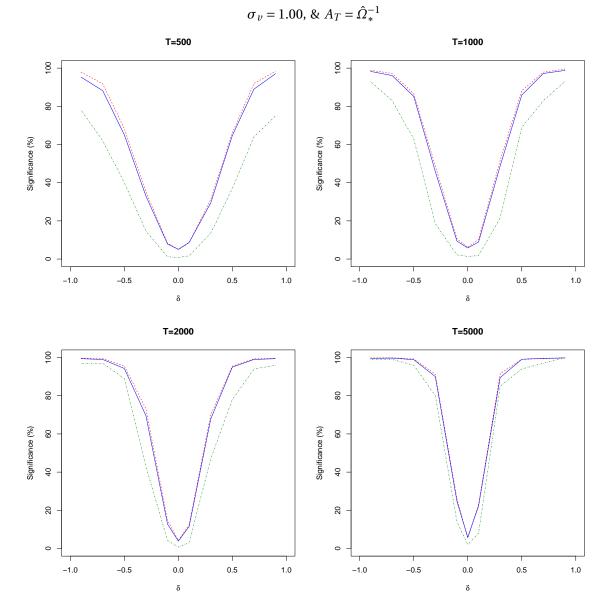
Notes: Red is Asymptotic test, blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A8. Power curves of test for no leverage in SV(1) model when  $\phi=0.95$ ,  $\sigma_y=0.10$ ,  $\sigma_v=0.50$ , &  $A_T=\hat{\Omega}_*^{-1} \mbox{ (Asymptotic not level-corrected)}$ 



Notes: Red is Asymptotic test, blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

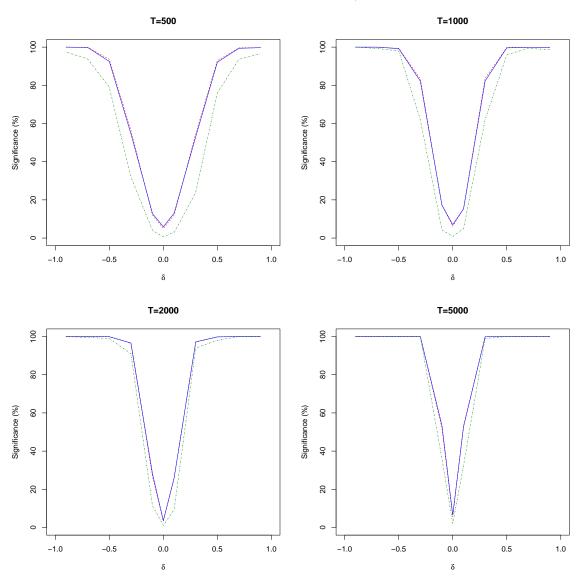
Figure A9. Power curves of test for no leverage in SV(2) model when  $\phi_1=0.05$ ,  $\phi_2=0.85$ ,  $\sigma_y=1.00$ ,



Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

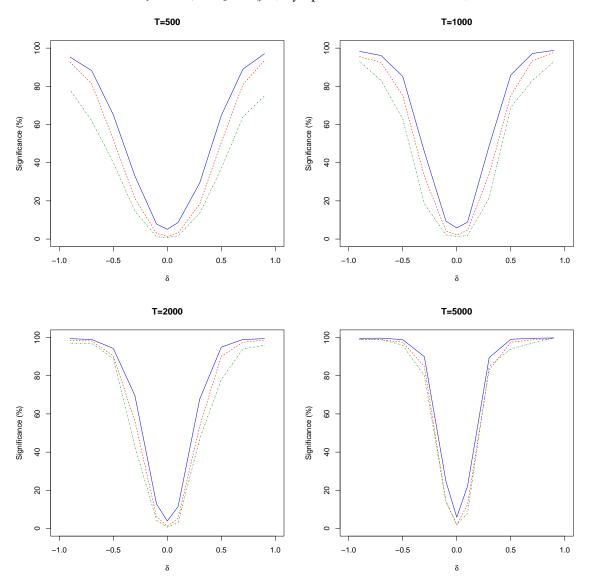
Figure A10. Power curves of test for no leverage in SV(2) model when  $\phi_1=0.05$ ,  $\phi_2=0.70$ ,  $\sigma_y=1.00$ ,

$$\sigma_v = 1.00, \, \& \, A_T = \hat{\Omega}_*^{-1}$$



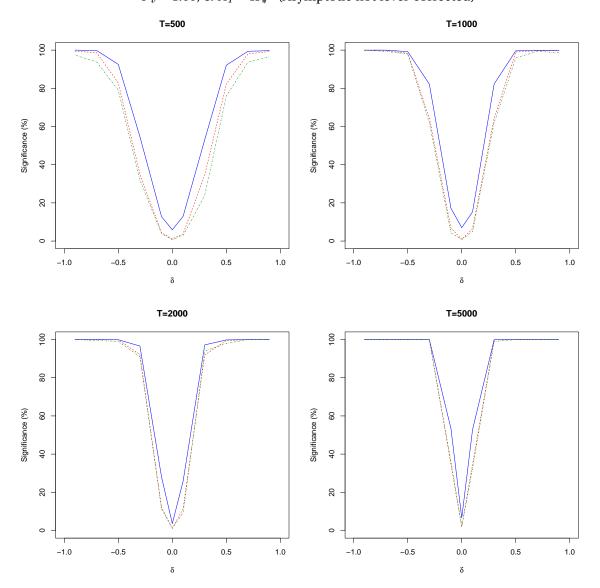
Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A11. Power curves of test for no leverage in SV(2) model when  $\phi_1=0.05$ ,  $\phi_2=0.85$ ,  $\sigma_y=1.00$ ,  $\sigma_v=1.00, \&\ A_T=\hat\Omega_*^{-1} \ (\text{Asymptotic not level-corrected})$ 



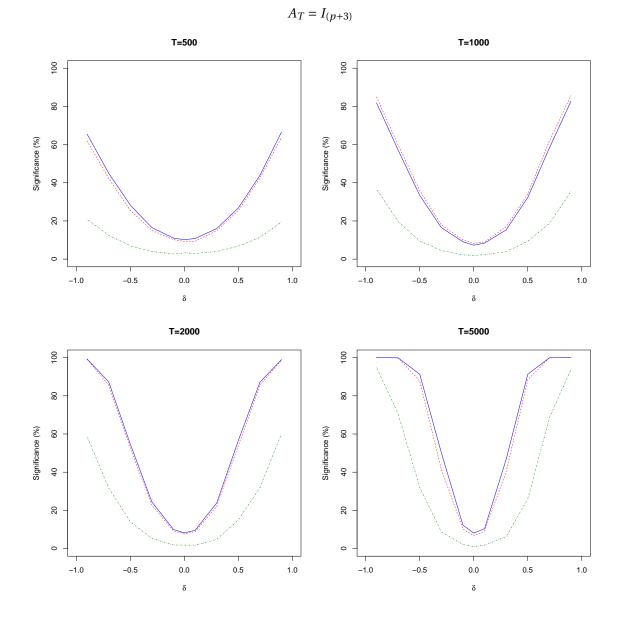
Notes: Red is Asymptotic test, blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A12. Power curves of test for no leverage in SV(2) model when  $\phi_1=0.05$ ,  $\phi_2=0.70$ ,  $\sigma_y=1.00$ ,  $\sigma_v=1.00, \&\ A_T=\hat\Omega_*^{-1} \ (\text{Asymptotic not level-corrected})$ 



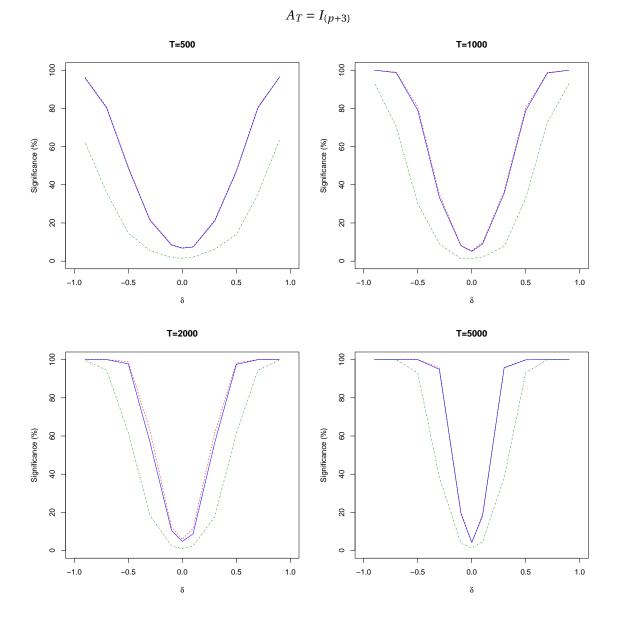
Notes: Red is Asymptotic test, blue is the Local Monte Carlo test, and green is the Maximized Monte Carlo test.

Figure A13. Power curves of test for no leverage in SV(1) model when  $\phi$  = 0.90,  $\sigma_y$  = 0.10,  $\sigma_v$  = 0.75, &



Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test (level corrected), and green is the Maximized Monte Carlo test.

Figure A14. Power curves of test for no leverage in SV(1) model when  $\phi$  = 0.75,  $\sigma_y$  = 0.10,  $\sigma_v$  = 1.00, &



Notes: Red is Asymptotic test (level corrected), blue is the Local Monte Carlo test (level corrected), and green is the Maximized Monte Carlo test.

Figure A15. Power curves of test for no leverage in SV(1) model when  $\phi = 0.90$ ,  $\sigma_y = 0.10$ ,  $\sigma_v = 0.75$ , &  $A_T = I_{(p+3)}$  (LMC not level-corrected)

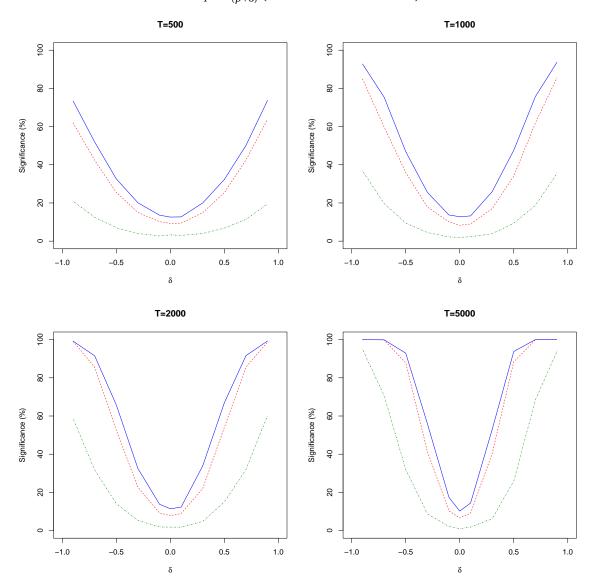


Figure A16. Power curves of test for no leverage in SV(1) model when  $\phi = 0.75$ ,  $\sigma_y = 0.10$ ,  $\sigma_v = 1.00$ , &  $A_T = I_{(p+3)}$  (LMC not level-corrected)

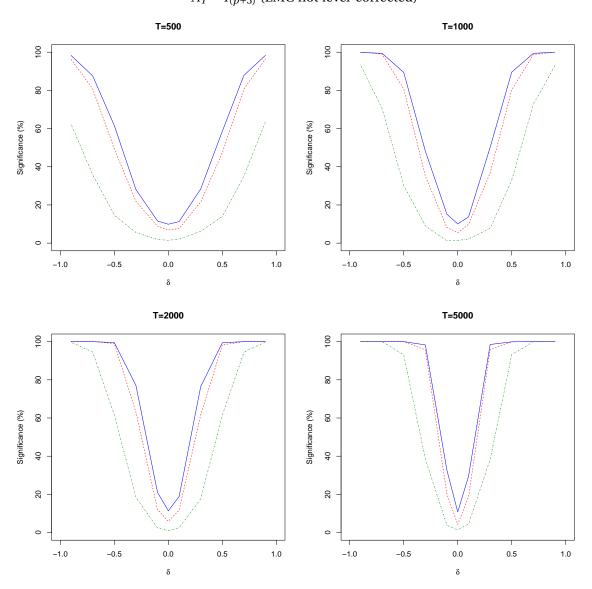


Figure A17. Power curves of test for no leverage in SV(1) model when  $\phi$  = 0.99,  $\sigma_y$  = 0.10,  $\sigma_v$  = 0.25, &

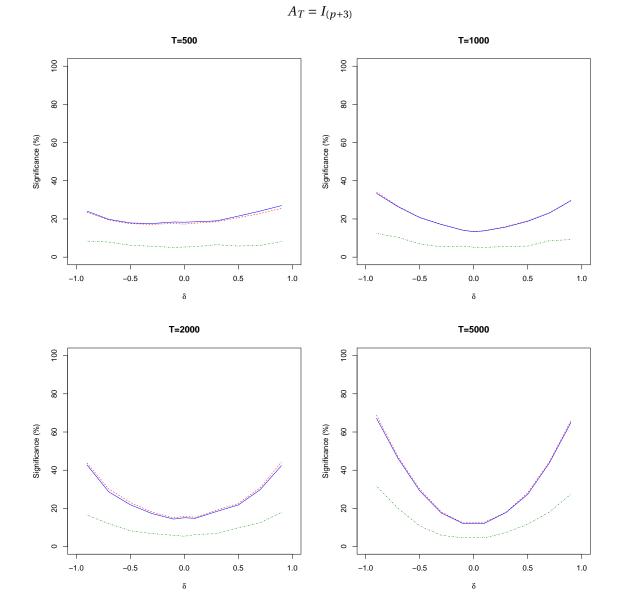


Figure A18. Power curves of test for no leverage in SV(1) model when  $\phi$  = 0.95,  $\sigma_y$  = 0.10,  $\sigma_v$  = 0.50, &

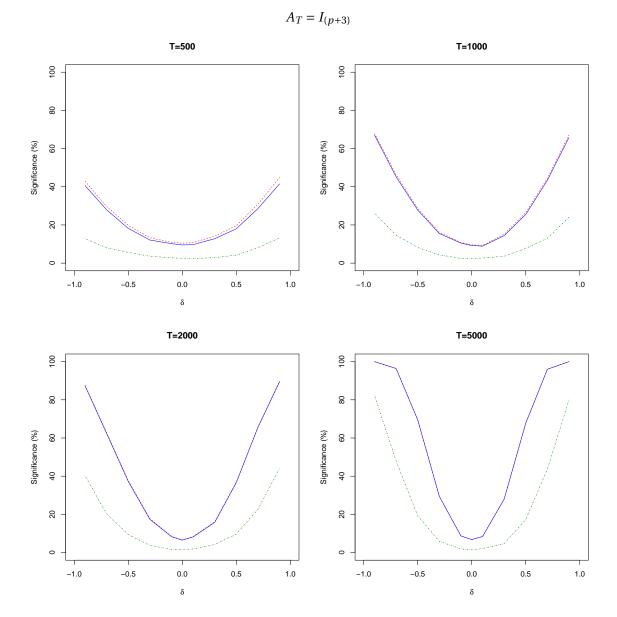


Figure A19. Power curves of test for no leverage in SV(1) model when  $\phi = 0.99$ ,  $\sigma_y = 0.10$ ,  $\sigma_v = 0.25$ , &  $A_T = I_{(p+3)}$  (LMC not level-corrected)

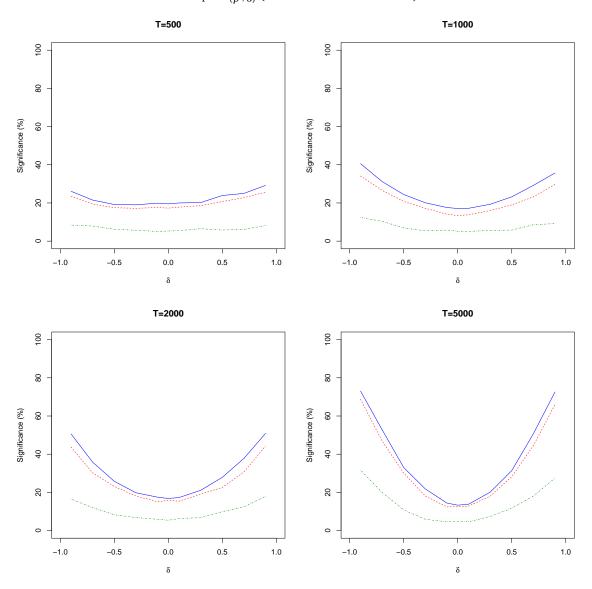


Figure A20. Power curves of test for no leverage in SV(1) model when  $\phi = 0.95$ ,  $\sigma_y = 0.10$ ,  $\sigma_v = 0.50$ , &  $A_T = I_{(p+3)}$  (LMC not level-corrected)

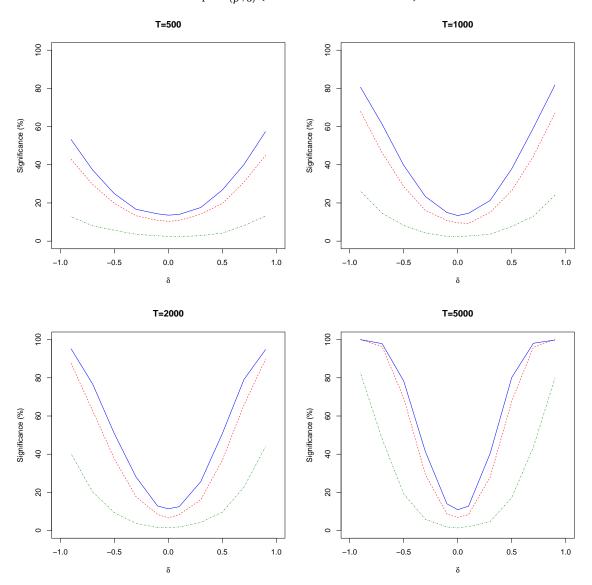


Figure A21. Power curves of test for no leverage in SV(2) model when  $\phi_1$  = 0.05,  $\phi_2$  = 0.85,  $\sigma_y$  = 1.00,

$$\sigma_v = 1.00$$
, &  $A_T = I_{(p+3)}$ 

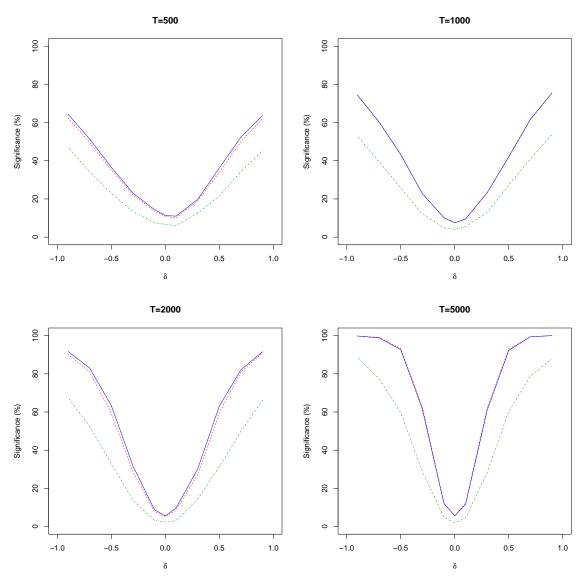


Figure A22. Power curves of test for no leverage in SV(2) model when  $\phi_1$  = 0.05,  $\phi_2$  = 0.70,  $\sigma_y$  = 1.00,

$$\sigma_v = 1.00$$
, &  $A_T = I_{(p+3)}$ 

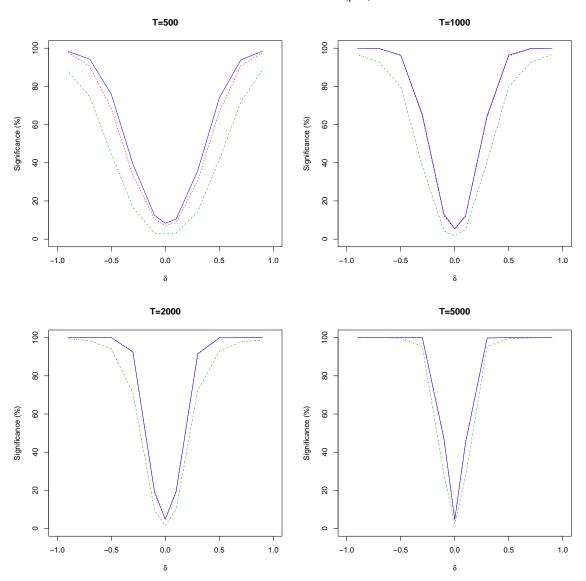


Figure A23. Power curves of test for no leverage in SV(2) model when  $\phi_1=0.05$ ,  $\phi_2=0.85$ ,  $\sigma_y=1.00$ ,  $\sigma_v=1.00, \&\ A_T=I_{(p+3)} \ (\text{LMC not level-corrected})$ 

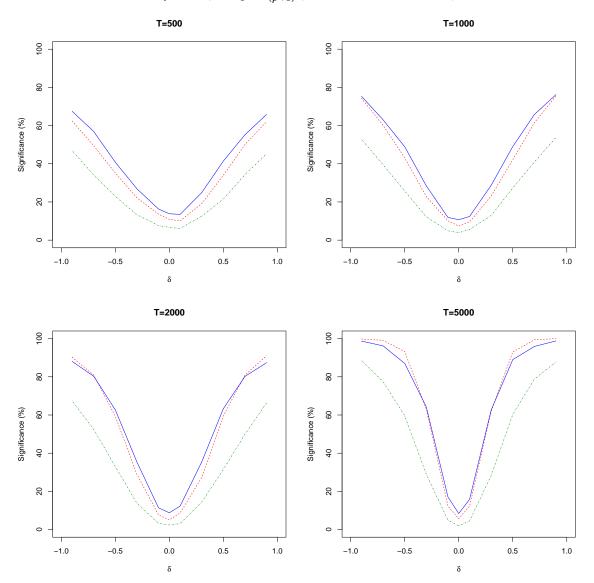


Figure A24. Power curves of test for no leverage in SV(2) model when  $\phi_1=0.05$ ,  $\phi_2=0.70$ ,  $\sigma_y=1.00$ ,  $\sigma_v=1.00, \&\ A_T=I_{(p+3)} \ (\text{LMC not level-corrected})$ 

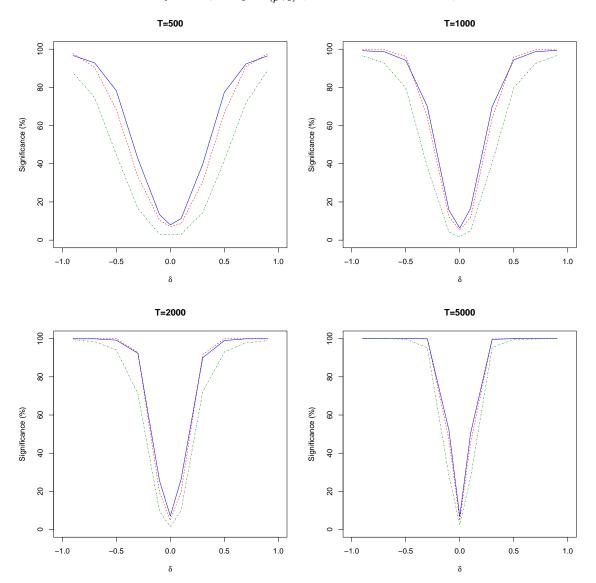


Table A14. Estimating SVL(1) on SV(2) and SV(3) DGP

	T	$\phi_1$	$\phi_2$	$\phi_3$	$\sigma_y$	$\sigma_{v}$	δ
		DGP is SV(2):	$\phi_1 = 0.51,  \phi_2 = 0.4$	$47,  \sigma_y = 0.85,  \sigma_v =$	$= 0.81,  \delta = 0.00$		
	500	0.969			1.238	0.670	-0.014
SVL(1)	1000	0.980			0.999	0.592	0.007
	2000	0.984			0.893	0.570	0.000
	5000	0.986			0.886	0.555	-0.001
	500	0.559	0.406		1.238	1.026	-0.002
SVL(2)	1000	0.542	0.431		0.999	0.945	0.002
	2000	0.539	0.438		0.893	0.905	-0.001
	5000	0.539	0.440		0.886	0.858	-0.001
		DGP is SV(3): $\phi_1$ =	$= 0.29,  \phi_2 = 0.29,  \phi_3$	$\sigma_y = 0.40, \ \sigma_y = 0.85,$	$\sigma_{v} = 0.76,  \delta = 0.00$	)	
	500	0.945			1.191	0.604	-0.006
SVL(1)	1000	0.980			0.977	0.445	0.003
	2000	0.987			0.910	0.396	0.000
	5000	0.990			0.873	0.373	-0.005
	500	0.362	0.284	0.303	1.191	0.986	-0.001
SVL(2)	1000	0.355	0.307	0.308	0.977	0.895	0.000
	2000	0.349	0.314	0.313	0.910	0.846	-0.001
	5000	0.351	0.315	0.314	0.873	0.802	-0.003

Notes: This table presents the average estimate over N = 1000 replications of the DGP.

Table A15. Estimating SVL(2) and SVL(3) on SVL(1) DGP

	T	$\phi_1$	$\phi_2$	$\phi_3$	$\sigma_y$	$\sigma_v$	δ
		DGP is S	$VL(1)$ : $\phi_1 = 0.98$ , $\sigma_2$	$y = 0.85,  \sigma_{v} = 0.23,$	$\delta = -0.90$		
	500	0.874			0.895	0.478	-0.879
SVL(1)	1000	0.949			0.875	0.414	-0.883
	2000	0.962			0.859	0.346	-0.879
	5000	0.971			0.855	0.286	-0.877
	500	0.479	0.422		0.895	0.643	-0.440
SVL(2)	1000	0.496	0.462		0.875	0.610	-0.374
	2000	0.498	0.466		0.859	0.530	-0.398
	5000	0.497	0.470		0.855	0.443	-0.472
	500	0.347	0.265	0.297	0.895	0.637	-0.563
SVL(3)	1000	0.347	0.294	0.316	0.875	0.613	-0.507
	2000	0.347	0.298	0.315	0.859	0.541	-0.533
	5000	0.344	0.300	0.316	0.855	0.462	-0.589
		DGP is S	$VL(1)$ : $\phi_1 = 0.98$ , $\sigma_2$	$y = 0.85,  \sigma_{\nu} = 0.23,$	$\delta = -0.70$		
	500	0.823			0.878	0.552	-0.674
SVL(1)	1000	0.934			0.870	0.441	-0.678
	2000	0.955			0.858	0.357	-0.677
	5000	0.970			0.854	0.291	-0.676
	500	0.457	0.407		0.878	0.647	-0.485
SVL(2)	1000	0.492	0.457		0.870	0.589	-0.398
	2000	0.488	0.472		0.858	0.507	-0.396
	5000	0.489	0.477		0.854	0.431	-0.431
	500	0.327	0.254	0.296	0.878	0.634	-0.589
SVL(3)	1000	0.347	0.292	0.308	0.870	0.593	-0.490
	2000	0.336	0.305	0.313	0.858	0.516	-0.495
	5000	0.331	0.306	0.320	0.854	0.449	-0.514

Notes: This table presents the average estimate over N = 1000 replications of the DGP.

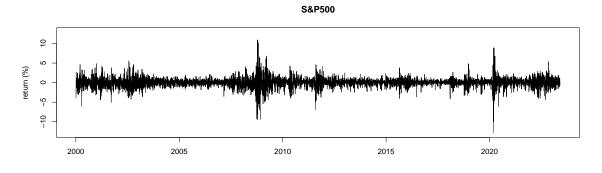
## **E** Complementary empirical results

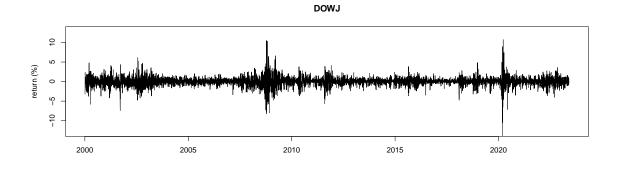
Table A16. Summary statistics

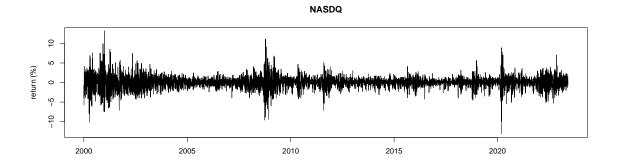
			Sa	mple from 2000-	Jan-04 to 202	23-May-31 (T =	= 5,889)			
	Series	Mean	SD	Kurtosis	SK	Range	Min	Max	LB(10)	
S&P500	$y_t$	0.00	1.25	10.16	-0.37	23.72	-12.78	10.94	97.32	
(T = 5,889)	$y_t^2$	1.56	5.43	271.31	13.58	163.41	0.00	163.41	5741.49	
	$y_t^*$	0.00	2.58	2.47	-1.07	25.33	-18.64	6.70	1636.99	
DOWJ	$y_t$	0.00	1.19	12.53	-0.37	24.61	-13.86	10.75	110.28	
(T = 5,889)	$y_t^2$	1.41	5.39	411.54	16.55	192.10	0.00	192.10	5809.00	
	$y_t^*$	0.00	2.54	1.82	-0.98	22.37	-15.42	6.95	1551.33	
NASDQ	$y_t$	0.00	1.60	6.06	-0.13	26.40	-13.17	13.24	63.06	
(T = 5,889)	$y_t^2$	2.56	7.26	161.34	10.04	175.17	0.00	175.17	4230.10	
	$y_t^*$	0.00	2.56	2.37	-1.07	24.46	-18.28	6.19	1979.06	

Notes: 1.  $y_t = r_t - \mu$  is the residual return,  $y_t^2$  is the squared of residual return and  $y_t^*$  is the residual of log squared of residual return. 2. LB(10) is the heteroskedasticity-corrected Ljung-Box statistics with 10 lags. The critical values for LB(10) are: 15.99 (10%), 18.31 (5%), and 23.21 (1%).

Figure A25. Time series of stock indices from 2000-Jan-04 to 2023-May-31 (T = 5,889)

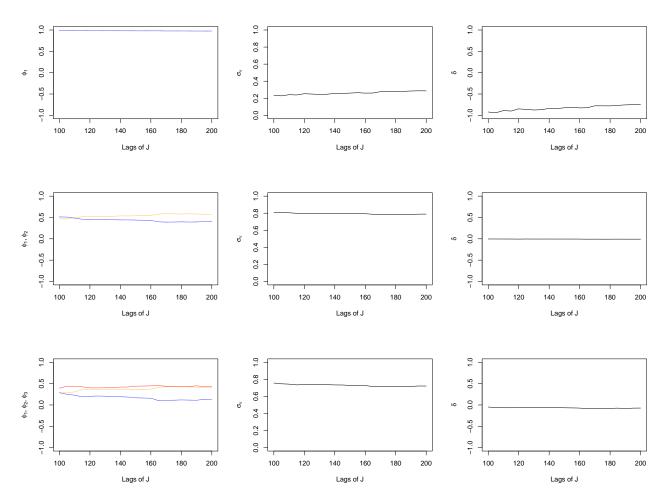






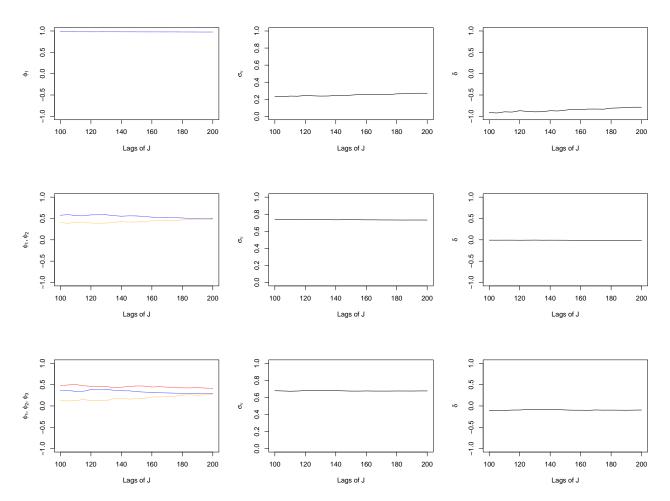
Notes: Demeaned returns are shown (*i.e.*,  $y_t = r_t - \mu$ ) for each stock index.

Figure A26. Empirical parameter estimates of  $\phi_i$ ,  $\sigma_v$ , &  $\delta$  for S&P 500 index using different values of J



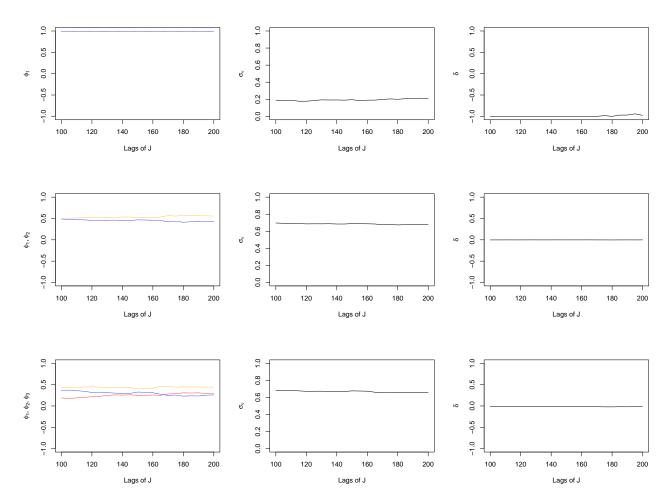
**Notes:** First row corresponds to the estimates of a SVL(1) model, second row corresponds to the estimates of a SVL(2) model, and the third row corresponds to the estimates of a SVL(3) model. Values for  $\sigma_y$  are not shown because they do not depend on  $\phi_i$  and hence do not change with J. The sample used is from 2000-Jan-04 to 2023-May-31 (T = 5,889)

Figure A27. Empirical parameter estimates of  $\phi_i$ ,  $\sigma_v$ , &  $\delta$  for Dow Jones index using different values of J



**Notes:** First row corresponds to the estimates of a SVL(1) model, second row corresponds to the estimates of a SVL(2) model, and the third row corresponds to the estimates of a SVL(3) model. Values for  $\sigma_y$  are not shown because they do not depend on  $\phi_i$  and hence do not change with J. The sample used is from 2000-Jan-04 to 2023-May-31 (T = 5,889)

Figure A28. Empirical parameter estimates of  $\phi_i$ ,  $\sigma_v$ , &  $\delta$  for NASDAQ index using different values of J



**Notes:** First row corresponds to the estimates of a SVL(1) model, second row corresponds to the estimates of a SVL(2) model, and the third row corresponds to the estimates of a SVL(3) model. Values for  $\sigma_y$  are not shown because they do not depend on  $\phi_i$  and hence do not change with J. The sample used is from 2000-Jan-04 to 2023-May-31 (T = 5,889)

Table A17. Asymptotic and finite-sample tests for the presence of leverage in SVL(p) models (with N = 99, N = 299, & N = 999)

				į				$H_0: \delta = 0 \text{ vs. } H_1: \delta \neq 0$	vs. $H_1$ :	0≠0							3			
			SVL(1)	(1)						SVL(2)						SVL(3)	(3)			
	Asymptotic		LMC			MMC		Asymptotic	Ι	LMC		MMC		Asymptotic	Ι	LMC		N	MMC	
		N = 99	299	N = 99  299  999  N	N = 99	299	666		N = 99	299 99	999 N = 99	99 299	666		N = 99	536	666	999 N = 99	299	666
								I						'						
										J = 100										
$S\&P500 \ (T = 5889)$	0.00	0.01	0.00	0.01 0.00 0.00	0.05	0.01 0.01	0.01	0.45	0.92	0.94 0.95	95 0.92		0.93 0.95	0.00	0.55	0.61 0.61	0.61	96.0	0.65	0.7
DOW Jones $(T = 5889)$	0.00	0.01	0.01 0.00 0.00	0.00	0.01	0.01	0.01	0.31	0.93	0.94 0.	0.95   0.93	3 0.94	0.94	0.00	0.41	0.46	0.42	0.92	92.0	0.46
NASDAQ $(T = 5889)$	0.00	0.01	0.01 0.00 0.00	0.00	0.01	0.00	0.01	99.0	0.92	0.91 0.92	92 0.91	1 0.90	0.92	0.08	0.81	0.83	0.88	0.81	0.89	0.89
										J = 200										
$S\&P500 \ (T = 5889)$	0.00	0.01	0.01 0.01 0.00	0.00	0.03	0.03	0.02	0.15	0.81	0.86 0.	0.86 0.84	4 0.86	0.85	0.00	0.37	0.39	0.37	69.0	0.74	0.72
DOW Jones $(T = 5889)$	0.00	0.01		0.00 0.00	0.02	0.01	0.00	0.07	0.82	0.87 0.	0.86  0.95	5 0.86	0.30	0.00	0.42	0.49	0.45	0.90	0.70	8.0
NASDAQ $(T = 5889)$	0.00	0.01	0.00	0.00 0.00	0.01	0.00	0.00	0.75	0.88	0.89 0.	0.90 0.90	0 0.89	0.90	0.04	0.72	0.73	0.77	0.89	0.85	0.87

Notes: 1. The reported values are p-values for test procedure when testing for leverage (i.e.  $H_0: \delta = 0$  vs.  $H_1: \delta \neq 0$ ). 2. The value N is the number of Monte Carlo simulations used to simulate the null distribution.

Table A18. Empirical volatility forecasting performance with competing conditional volatility models

			S&P 500				I	Dow Jones					NASDAQ		
Models	h = 1	h = 5	h = 10	$Q_{1,5}$	$Q_{1,5,10}$	h = 1	h = 5	h = 10	$Q_{1,5}$	$Q_{1,5,10}$	h = 1	h = 5	h = 10	$Q_{1,5}$	$Q_{1,5,10}$
ARCH(1)	13.637	65.351	128.308	0.278	0.278	11.982	60.489	121.549	0.833	0.833	14.488	68.342	132.365	0.444	0.500
ARCH(2)	9.516	50.644	105.371	0.294	0.294	9.482	50.428	104.794	0.833	0.833	8.981	47.187	97.012	0.444	0.500
ARCH(3)	8.938	47.549	100.908	0.312	0.312	8.882	47.319	100.274	0.833	0.833	8.690	45.378	94.243	0.467	0.500
GARCH(1,1)	8.298	42.542	87.394	0.333	0.357	8.279	42.450	87.042	0.833	0.833	7.918	40.114	81.538	0.583	0.500
GARCH(2,2)	8.260	42.368	87.177	0.357	0.333	8.260	42.300	86.859	0.833	0.833	7.884	39.989	81.388	0.538	0.500
GARCH(3,3)	8.252	42.316	87.124	0.385	0.385	8.260	42.288	86.883	0.833	0.833	7.889	39.990	81.401	0.500	0.500
EGARCH(1,1)	7.972	40.672	82.886	0.444	0.556	8.006	40.792	83.014	0.833	0.833	7.674	38.928	78.894	0.700	0.500
EGARCH(2,2)	7.879	40.262	82.132	0.500	0.625	7.941	40.486	82.466	0.833	0.857	8.109	40.712	82.045	0.444	0.500
EGARCH(3,3)	7.792	39.904	81.490	0.571	0.714	11.809	59.886	110.933	0.833	0.833	9.856	53.880	161.961	0.700	0.500
GJR(1,1)	8.060	41.541	85.548	0.385	0.417	8.051	41.430	85.102	0.833	0.833	7.723	39.314	79.967	0.636	0.500
GJR(2,2)	8.035	41.422	85.404	0.385	0.455	8.030	41.267	84.842	0.833	0.833	7.702	39.207	79.820	0.700	0.500
GJR(3,3)	8.025	41.361	85.329	0.400	0.500	8.036	41.280	84.912	0.833	0.833	7.690	39.190	79.824	0.700	0.500
SV(1)-NL	6.363	32.307	65.806	0.600	0.800	6.290	31.954	65.023	0.833	1.000	6.160	31.092	63.068	0.750	0.750
SV(2)-NL	6.256	32.924	67.439	0.571	0.714	6.215	32.634	66.697	0.833	0.857	6.037	31.457	64.052	0.700	0.600
SV(3)-NL	6.171	33.079	67.638	0.750	0.800	6.117	32.825	66.930	0.833	1.000	5.983	31.623	64.253	0.700	0.500
SV(1)-WL	6.247	32.082	65.588	1.000	1.000	6.205	31.718	64.740	1.000	1.000	6.037	30.800	62.733	1.000	1.000
SV(2)-WL	6.185	32.774	67.286	1.000	1.000	6.152	32.482	66.541	1.000	1.000	5.937	31.276	63.870	1.000	1.000
SV(3)-WL	6.097	32.949	67.506	1.000	1.000	6.039	32.676	66.780	1.000	1.000	5.871	31.456	64.085	1.000	1.000

Notes: The reported values represent the Mean Squared Error (MSE) for each model at different horizons: h = 1 (one day), h = 5 (one week), and h = 10 (two weeks). The values in bold indicate that the model is part of the Model Confidence Set (MCS) for that horizon and that specific index. The MCS is determined using a 5% significance level. The values in bold red indicate the models in the MCS with the lowest MSE. Sample for each index is from 2000-Jan-04 to 2023-May-31 (T = 5,889). Estimates are obtained using W-ARMA estimator given in (3.22) with J = 200. Out-of-sample forecasting is performed using a rolling window scheme of size  $T_{est} = 1,000$ , where the first estimation window ends at observation 1,000, and the last estimation window starts at observation 4,880 but ends at observation 5,879.

Table A19. Empirical volatility forecasting performance with competing conditional volatility models

			S&P 500				I	Dow Jone	es				NASDAÇ	)	
Models	h = 1	h = 5	h = 10	Q <sub>1,5</sub>	Q <sub>1,5,10</sub>	h=1	h = 5	h = 10	Q <sub>1,5</sub>	Q <sub>1,5,10</sub>	h = 1	h = 5	h = 10	Q <sub>1,5</sub>	Q <sub>1,5,10</sub>
ARCH(1)	8.101	43.040	88.250	0.111	0.111	8.862	47.620	96.701	0.222	0.333	8.035	40.910	81.936	0.111	0.111
ARCH(2)	7.327	39.415	82.705	0.118	0.118	8.222	43.817	90.654	0.235	0.353	7.409	38.567	79.519	0.118	0.125
ARCH(3)	7.063	37.745	80.925	0.125	0.125	7.962	42.174	88.263	0.250	0.375	7.311	37.653	77.798	0.125	0.118
GARCH(1,1)	6.865	35.276	73.095	0.143	0.133	7.832	39.922	80.865	0.267	0.429	7.073	35.651	72.351	0.133	0.133
GARCH(2,2)	6.824	35.080	72.780	0.133	0.154	7.810	39.725	80.544	0.333	0.500	7.031	35.480	72.035	0.143	0.143
GARCH(3,3)	6.818	35.046	72.744	0.167	0.167	7.809	39.724	80.540	0.364	0.667	7.022	35.435	71.988	0.167	0.167
EGARCH(1,1)	6.568	33.881	69.999	0.182	0.250	7.636	38.723	78.100	0.571	0.857	6.827	34.425	69.701	0.250	0.286
EGARCH(2,2)	6.530	33.753	69.805	0.182	0.200	7.628	38.705	78.067	0.400	0.750	6.775	34.323	69.523	0.286	0.250
EGARCH(3,3)	6.641	34.434	71.390	0.154	0.143	7.665	38.878	78.530	0.500	0.462	6.878	34.982	71.085	0.182	0.154
GJR(1,1)	6.614	34.206	70.984	0.182	0.182	7.668	39.194	79.525	0.444	0.400	6.875	34.744	70.518	0.200	0.182
GJR(2,2)	6.585	34.073	70.791	0.182	0.286	7.662	39.128	79.404	0.286	0.600	6.846	34.619	70.326	0.222	0.200
GJR(3,3)	6.574	34.087	70.854	0.182	0.222	7.645	39.058	79.279	0.308	0.545	6.854	34.740	70.566	0.154	0.222
SV(1)-NL	5.247	26.972	56.134	0.500	1.000	5.936	29.981	60.446	1.000	1.000	5.551	27.787	56.464	1.000	1.000
SV(2)-NL	5.351	28.811	60.772	0.333	0.667	6.111	31.094	63.421	0.800	1.000	5.706	29.606	61.157	0.400	0.400
SV(3)-NL	5.250	29.543	61.608	0.200	0.400	5.960	31.470	63.923	0.800	1.000	5.618	30.035	61.662	0.500	0.667
SV(1)-WL	4.981	26.248	55.372	1.000	1.000	5.782	29.525	60.238	1.000	1.000	5.427	27.49	56.244	1.000	1.000
SV(2)-WL	5.350	28.808	60.768	0.250	0.500	6.109	31.090	63.416	0.667	1.000	5.703	29.596	61.146	0.333	0.333
SV(3)-WL	5.232	29.513	61.578	0.182	0.333	5.928	31.408	63.860	0.800	1.000	5.609	30.013	61.641	0.667	0.500

Notes: The reported values represent the Mean Squared Error (MSE) for each model at different horizons: h=1 (one day), h=5 (one week), and h=10 (two weeks). The values in bold indicate that the model is part of the Model Confidence Set (MCS) for that horizon and that specific index. The MCS is determined using a 5% significance level. The values in bold red indicate the models in the MCS with the lowest MSE. Sample for each index is from 2000-Jan-04 to 2023-May-31 (T=5,889). Estimates are obtained using W-ARMA estimator given in (3.22) with J=100. Out-of-sample forecasting is performed using a rolling window scheme of size  $T_{est}=4,880$ , where the first estimation window ends at observation 4,879, and the last estimation window starts at observation 1,001 but ends at observation 5,879.

Table A20. Empirical volatility forecasting performance with competing conditional volatility models

			S&P 500				I	Dow Jone	es				NASDAÇ	)	
Models	h=1	h = 5	h = 10	$Q_{1,5}$	Q <sub>1,5,10</sub>	h=1	h = 5	h = 10	$Q_{1,5}$	Q <sub>1,5,10</sub>	h=1	h = 5	h = 10	$Q_{1,5}$	Q <sub>1,5,10</sub>
ARCH(1)	8.101	43.040	88.250	0.056	0.111	8.862	47.620	96.701	0.222	0.333	8.035	40.910	81.936	0.111	0.111
ARCH(2)	7.327	39.415	82.705	0.059	0.118	8.222	43.817	90.654	0.235	0.353	7.409	38.567	79.519	0.125	0.118
ARCH(3)	7.063	37.745	80.925	0.062	0.125	7.962	42.174	88.263	0.250	0.375	7.311	37.653	77.798	0.118	0.125
GARCH(1,1)	6.865	35.276	73.095	0.071	0.133	7.832	39.922	80.865	0.308	0.545	7.073	35.651	72.351	0.143	0.133
GARCH(2,2)	6.824	35.080	72.780	0.077	0.143	7.810	39.725	80.544	0.400	0.600	7.031	35.480	72.035	0.133	0.143
GARCH(3,3)	6.818	35.046	72.744	0.067	0.154	7.809	39.724	80.540	0.267	0.500	7.022	35.435	71.988	0.154	0.167
EGARCH(1,1)	6.568	33.881	69.999	0.111	0.250	7.636	38.723	78.100	0.444	0.857	6.827	34.425	69.701	0.250	0.286
EGARCH(2,2)	6.530	33.753	69.805	0.091	0.182	7.628	38.705	78.067	0.333	0.750	6.775	34.323	69.523	0.286	0.250
EGARCH(3,3)	6.641	34.434	71.390	0.083	0.167	7.665	38.878	78.530	0.286	0.400	6.878	34.982	71.085	0.167	0.154
GJR(1,1)	6.614	34.206	70.984	0.125	0.200	7.668	39.194	79.525	0.500	0.667	6.875	34.744	70.518	0.222	0.222
GJR(2,2)	6.585	34.073	70.791	0.143	0.222	7.662	39.128	79.404	0.571	0.462	6.846	34.619	70.326	0.182	0.182
GJR(3,3)	6.574	34.087	70.854	0.100	0.250	7.645	39.058	79.279	0.364	0.429	6.854	34.740	70.566	0.200	0.200
SV(1)-NL	5.238	26.922	56.111	0.500	0.500	5.935	29.960	60.398	1.000	1.000	5.572	27.881	56.708	1.000	1.000
SV(2)-NL	5.323	28.750	60.684	0.333	0.333	6.082	31.219	63.623	0.800	1.000	5.690	29.562	61.100	0.333	0.400
SV(3)-NL	5.242	29.353	61.396	0.167	0.250	5.955	31.658	64.134	1.000	1.000	5.599	30.059	61.692	0.667	0.500
SV(1)-WL	4.985	26.163	55.130	1.000	1.000	5.797	29.500	60.048	1.000	1.000	5.449	27.556	56.374	1.000	1.000
SV(2)-WL	5.321	28.744	60.678	0.200	0.250	6.078	31.210	63.614	0.667	1.000	5.688	29.553	61.090	0.400	0.333
SV(3)-WL	5.218	29.314	61.357	0.250	0.250	5.925	31.606	64.082	1.000	1.000	5.592	30.041	61.674	0.500	0.667

Notes: The reported values represent the Mean Squared Error (MSE) for each model at different horizons: h=1 (one day), h=5 (one week), and h=10 (two weeks). The values in bold indicate that the model is part of the Model Confidence Set (MCS) for that horizon and that specific index. The MCS is determined using a 5% significance level. The values in bold red indicate the models in the MCS with the lowest MSE. Sample for each index is from 2000-Jan-04 to 2023-May-31 (T=5,889). Estimates are obtained using W-ARMA estimator given in (3.22) with J=200. Out-of-sample forecasting is performed using a rolling window scheme of size  $T_{est}=4,880$ , where the first estimation window ends at observation 4,879, and the last estimation window starts at observation 1,001 but ends at observation 5,879.

## **Appendix References**

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