

Chance Variation: inherent errors that we cannot control

Assignable Cause: errors caused that we can control

13.2 Control Charts for Average Values: The \bar{X} Control Chart

- When the process is in control, the successive items produced have measurable characteristics that are independent, normal random variables with mean μ and variance σ^2

- if the process is in control throughout the production of subgroup i , then $\frac{(\bar{X}_i - \mu)}{\sigma/\sqrt{n}}$ has a standard normal distribution. \star a standard normal variable Z will almost always be between -3 and $+3$. $\mu - \frac{3\sigma}{\sqrt{n}} < \bar{X}_i < \mu + \frac{3\sigma}{\sqrt{n}}$
lower control limits upper control limits

- Suppose the process has gone out of control by a chance that a shift has occurred in mean, $\mu \rightarrow \mu + \alpha$

$$-3 < \sqrt{n} \frac{(\bar{X} - \mu)}{\sigma} < 3 \rightarrow -3 - \frac{a\sqrt{n}}{\sigma} < \sqrt{n} \frac{(\bar{X} - \mu - \alpha)}{\sigma} < 3 - \frac{a\sqrt{n}}{\sigma}, \text{ hence, since } \bar{X} \text{ is normal}$$

with mean $\mu + \alpha$ and variance $\frac{\sigma^2}{n}$, $\sqrt{n} \frac{(\bar{X} - \mu - \alpha)}{\sigma}$ has a standard normal distribution.

$$\Rightarrow P\left(-3 - \frac{a\sqrt{n}}{\sigma} < Z < 3 - \frac{a\sqrt{n}}{\sigma}\right) = \Phi\left(3 - \frac{a\sqrt{n}}{\sigma}\right) - \Phi\left(-3 - \frac{a\sqrt{n}}{\sigma}\right) \approx \Phi\left(3 - \frac{a\sqrt{n}}{\sigma}\right), \text{ so the probability that it falls outside is approximately } 1 - \Phi\left(3 - \frac{a\sqrt{n}}{\sigma}\right).$$

\star the number of subgroups that will be needed to detect the shift has a geometric distribution with mean $\left[1 - \Phi\left(3 - \frac{a\sqrt{n}}{\sigma}\right)\right]^{-1}$

13.2.1 Case of Unknown μ and σ

- the unbiased estimator of μ is \bar{X} , the average of \bar{X}_i 's.

- the unbiased estimator of σ is $\frac{E(S_i)}{c(n)}$, where $E(S_i) = \frac{\sqrt{2} \Gamma(\frac{n}{2}) \sigma}{\sqrt{n-1} \Gamma(\frac{n-1}{2})}$, $c(n) = \frac{\sqrt{2} \Gamma(\frac{n}{2})}{\sqrt{n-1} \Gamma(\frac{n-1}{2})}$

$$\Rightarrow \text{Lower Control Limits} = \bar{\bar{X}} - \frac{3\bar{S}}{c(n)\sqrt{n}}, \quad \text{Upper Control Limits} = \bar{\bar{X}} + \frac{3\bar{S}}{c(n)\sqrt{n}}, \text{ and check if each of } \bar{X}_i\text{'s falls within these lower and upper limits.}$$

13.3 S-Control Charts

- remember, $E(S_i) = c(n)\sigma$.

$$\begin{aligned} \Rightarrow \text{Var}(S_i) &= E(S_i^2) - \{E(S_i)\}^2 \\ &= \sigma^2 - \{c(n)\}^2 \sigma^2 \\ &= \sigma^2 \{1 - (c(n))^2\} \end{aligned}$$

$$\Rightarrow P\{E(S_i) - 3\sqrt{\text{Var}(S_i)} < S_i < E(S_i) + 3\sqrt{\text{Var}(S_i)}\} = 0.99$$

$$\Rightarrow UCL = \sigma[c(n) + 3\sqrt{1 - c^2(n)}]$$

$$LCL = \sigma[c(n) - 3\sqrt{1 - c^2(n)}], \text{ but if } \sigma \text{ is unknown, it can be estimated from } \frac{\bar{S}}{c(n)}$$

$$UCL = \bar{S} [1 + 3\sqrt{1/c^2(n) - 1}]$$

$$LCL = \bar{S} [1 - 3\sqrt{1/c^2(n) - 1}]$$

13.4 Control Charts For the Fraction Defective

- Let X denote the number of defective items in a subgroup of n items, then $X \sim \text{binom}(n, p)$. If $F = \frac{X}{n}$,

$$\Rightarrow E(F) = \frac{E(X)}{n} = \frac{np}{n} = p$$

$$\Rightarrow \sqrt{\text{Var}(F)} = \sqrt{\frac{\text{Var}(X)}{n^2}} = \sqrt{\frac{np(1-p)}{n^2}} = \sqrt{\frac{p(1-p)}{n}}$$

$$UCL = p + 3\sqrt{\frac{p(1-p)}{n}}, \quad LCL = p - 3\sqrt{\frac{p(1-p)}{n}}$$

↑ to start such a control chart, it is necessary to estimate p .

$$\bar{F} = \frac{1}{K} \sum_{i=1}^K F_i, \quad \text{Var}(\bar{F}) = \sqrt{\frac{\bar{F}(1-\bar{F})}{n}}$$

$$\Rightarrow UCL = \bar{F} + 3\sqrt{\frac{\bar{F}(1-\bar{F})}{n}}, \quad LCL = \bar{F} - 3\sqrt{\frac{\bar{F}(1-\bar{F})}{n}}$$

13.5 Control Charts For Number of Defects

- Let X be a poisson random variable, then $E(X_i) = \lambda = \text{Var}(X_i) \Rightarrow UCL = \lambda + 3\sqrt{\lambda}, \quad LCL = \lambda - 3\sqrt{\lambda}$

$$\Rightarrow \bar{X} = \frac{1}{K} \sum_{i=1}^K X_i = \text{Var}(\bar{X}), \Rightarrow UCL = \bar{X} + 3\sqrt{\bar{X}}, \quad LCL = \bar{X} - 3\sqrt{\bar{X}}$$

...?

13.6 Other Control Charts for Detecting Changes in the Population Mean