

# Time Series Analysis

WISE&SOE, XMU

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## **Content**

1. What is the time series?
2. Means, variances and covariances of a time series.
3. Stationarity.

## §1.1 What is the time series?

- ▶ Definition: A time series data is a sequence of observations ordered by time, and they are the observed values of one subject at different time.
- ▶ Exercise: Are the following sequences time series data?
  - (1) Hourly temperature of Chek Lap Kok, Hong Kong from August 13 to 27.
  - (2) Height of Tom: 110cm (age 3), 120cm (age 5), 135cm (age 6).
  - (3) Height of children: George 110cm (age 3), Jack 120cm (age 4), Bill 135 cm (age 5).

## What is the time series

- ▶ All observed time series data (with regular time period) can be denoted by

$$(z_1, z_2, \dots, z_T)$$

It can be considered as a realization of  $T$  random variables:

$$(Z_1, Z_2, \dots, Z_T)$$

- ▶ Definition: A time series is a sequence of random variables, which are ordered by time. It is usually defined as *a doubly infinite sequence of random variables*, and denoted by  $\{Z_t, t \in \mathbb{Z}\}$ , or  $\{Z_t\}$  in short. In this case, time series is a stochastic process with discrete times.

## Time series models

- Recall that, in the linear regression model, there is a response  $Y$  and some predictors  $X$ , and the linear model is

$$Y_i = \beta_0 + \beta_1 X_i + \varepsilon_i.$$

The information for predictors  $X$  are available, and we want to make inference about the response  $Y$ .

- For a time series, the available information includes:
  - (1) the time index  $t$  and
  - (2) the information in the past.

Two typical types of time series models

$$Z_t = a + bt + \varepsilon_t$$

and

$$Z_t = \theta_0 + \phi Z_{t-1} + \varepsilon_t.$$

They correspond to the deterministic model and the stochastic model, and the focus of Chapter 3 is on the latter one.

## §1.2 Means, variances and covariances of a time series

- ▶ **The mean function:** For a time series  $\{Z_t, t \in \mathbb{Z}\}$ , the *mean function* (or mean sequence) is defined by

$$\mu_t = \mathbb{E}(Z_t), \quad t \in \mathbb{Z}.$$

That is,  $\mu_t$  is just the expected value of the process at time  $t$ . In general,  $\mu_t$  can be different at each time  $t$ .

- ▶ **The auto-covariance function:** The *auto-covariance function* (ACVF) is defined as

$$\gamma(t, s) = \text{cov}(Z_t, Z_s), \quad t, s \in \mathbb{Z},$$

where

$$\begin{aligned} \text{cov}(Z_t, Z_s) &= \mathbb{E}[(Z_t - \mu_t)(Z_s - \mu_s)] \\ &= \mathbb{E}(Z_t Z_s) - \mu_t \mu_s. \end{aligned}$$

- ▶ **The variance function:** Especially, when  $s = t$  in the above equation, we have

$$\gamma(t, t) = \text{cov}(Z_t, Z_t) = \text{var}(Z_t),$$

which is the *variance function* of  $\{Z_t\}$ .

- ▶ **The auto-correlation function (ACF):** The *auto-correlation function* (ACF) is given by

$$\rho(t, s) = \text{corr}(Z_t, Z_s), \quad t, s \in \mathbb{Z},$$

where

$$\text{corr}(Z_t, Z_s) = \frac{\text{cov}(Z_t, Z_s)}{\sqrt{\text{var}(Z_t)\text{var}(Z_s)}} = \frac{\gamma(t, s)}{\sqrt{\gamma(t, t)\gamma(s, s)}}.$$



► The ACVF and the ACF have the following properties:

1.  $\gamma(t, t) = \text{var}(Z_t),$   $\rho(t, t) = 1;$
2.  $\gamma(t, s) = \gamma(s, t),$   $\rho(t, s) = \rho(s, t);$
3.  $|\gamma(t, s)| \leq \sqrt{\gamma(t, t)\gamma(s, s)},$   $|\rho(t, s)| \leq 1.$

The first two results are directly from the definitions, and the third one can be derived by Cauchy-Schwarz inequality ( $E|XY| \leq (EX^2)^{1/2}(EY^2)^{1/2}$ ).

- Some useful properties of covariance functions,

$$\text{cov}(aX, Y) = a\text{cov}(X, Y), \quad \text{cov}(X, aY) = a\text{cov}(X, Y),$$

$$\text{cov}(X, aY + bZ) = a\text{cov}(X, Y) + b\text{cov}(X, Z),$$

$$\begin{aligned} \text{cov}(c_1 Y_1 + c_2 Y_2, d_1 Z_1 + d_2 Z_2) &= c_1 d_1 \text{cov}(Y_1, Z_1) \\ &+ c_2 d_1 \text{cov}(Y_2, Z_1) + c_1 d_2 \text{cov}(Y_1, Z_2) + c_2 d_2 \text{cov}(Y_2, Z_2), \end{aligned}$$

and

$$\text{cov} \left[ \sum_{i=1}^m c_i Y_i, \sum_{j=1}^n d_j Z_j \right] = \sum_{i=1}^m \sum_{j=1}^n c_i d_j \text{cov}(Y_i, Z_j).$$

The last formula will be used frequently in this course.

Exercise: Suppose  $E(X) = 2$ ,  $\text{var}(X) = 9$ ,  $E(Y) = 0$ ,  $\text{var}(Y) = 4$  and  $\text{cov}(X, Y) = 0.25$ . Find

$\text{var}(X + Y)$ ,  $\text{cov}(X, X + Y)$  and  $\text{corr}(X + Y, X - Y)$ .

Solution:

$$\text{var}(X \pm Y) = \text{var}(X) + \text{var}(Y) \pm 2\text{cov}(X, Y)$$

$$\text{cov}(X, X + Y) = \text{var}(X) + \text{cov}(X, Y)$$

$$\text{cov}(X + Y, X - Y) = \text{var}(X) - \text{var}(Y)$$

- **Example (The random walk):** Let  $\{a_t, t \in \mathbb{N}\}$  be a sequence of *i.i.d.* random variables, each with zero mean and variance  $\sigma_a^2$ . The **random walk** process  $\{Z_t, t \in \mathbb{N}\}$  is defined as

$$Z_t = \sum_{j=1}^t a_j, \quad t \in \mathbb{N}.$$

Alternatively, we can write

$$Z_t = Z_{t-1} + a_t, \quad t \in \mathbb{N},$$

with *initial value*  $Z_0 = 0$ .

1. The mean function of  $\{Z_t\}$  is

$$\mu_t = E(Z_t) = E\left(\sum_{j=1}^t a_j\right) = \sum_{j=1}^t E(a_j) = 0, \quad t \in \mathbb{N}.$$

2. The variance function of  $\{Z_t\}$  is

$$\begin{aligned}\gamma(t, t) &= \text{var}(Z_t) = \text{var}\left(\sum_{j=1}^t a_j\right) \\ &= \sum_{j=1}^t \text{var}(a_j) = t \cdot \sigma_a^2.\end{aligned}$$

Notice that the process variance *increases* linearly with time.

3. For the auto-covariance function (ACVF), it is not difficult to find that for all  $t \leq s$ ,

$$\begin{aligned}\gamma(t, s) &= \text{cov}(Z_t, Z_s) \\&= \text{cov} \left( \sum_{j=1}^t a_j, \sum_{j=1}^s a_j \right) \\&= \text{cov} \left( \sum_{j=1}^t a_j, \sum_{j=1}^t a_j + \sum_{j=t+1}^s a_j \right) \\&= \text{cov} \left( \sum_{j=1}^t a_j, \sum_{j=1}^t a_j \right) \\&= \text{var} \left( \sum_{j=1}^t a_j \right) = t \cdot \sigma_a^2.\end{aligned}$$

4. For the auto-correlation function (ACF), by its definition, we have that

$$\begin{aligned}\rho(t, s) &= \frac{\gamma(t, s)}{\sqrt{\gamma(t, t)\gamma(s, s)}} \\ &= \frac{\sigma_a^2 t}{\sqrt{\sigma_a^2 t \cdot \sigma_a^2 s}} \\ &= \sqrt{t/s}, \quad 1 \leq t \leq s.\end{aligned}$$

When  $s = t + 1$ ,

$$\rho(t, t + 1) = \text{corr}(Z_t, Z_{t+1}) = \sqrt{t/(t + 1)} \approx 1 \text{ as } t \text{ is large.}$$

- **Example (a moving average):** Suppose that  $\{Z_t, t \in \mathbb{Z}\}$  is given by

$$Z_t = a_t - 0.5a_{t-1}, \quad t \in \mathbb{Z},$$

where the  $a$ 's are assumed to be a sequence of *i.i.d.* random variables with zero mean and variance  $\sigma_a^2$ .

1. The mean function of  $\{Z_t\}$  is

$$\mu_t = E(Z_t) = E(a_t) - 0.5E(a_{t-1}) = 0, \quad t \in \mathbb{Z}.$$

2. The variance function of  $\{Z_t\}$  is

$$\text{var}(Z_t) = \text{var}(a_t - 0.5a_{t-1}) = \sigma_a^2 + 0.5^2\sigma_a^2 = 1.25\sigma_a^2.$$



3. For the auto-covariance function (ACVF), it is not difficult to find that

$$\begin{aligned}\text{cov}(Z_t, Z_{t-1}) &= \text{cov}(a_t - 0.5a_{t-1}, a_{t-1} - 0.5a_{t-2}) \\ &= \text{cov}(a_t, a_{t-1}) - 0.5\text{cov}(a_t, a_{t-2}) \\ &\quad - 0.5\text{cov}(a_{t-1}, a_{t-1}) + 0.5^2\text{cov}(a_{t-1}, a_{t-2}) \\ &= -0.5\text{cov}(a_{t-1}, a_{t-1}),\end{aligned}$$

or

$$\gamma(t, t-1) = -0.5\sigma_a^2, \quad \forall t \in \mathbb{Z}.$$

For any integer  $k \geq 2$ ,

$$\text{cov}(Z_t, Z_{t-k}) = \text{cov}(a_t - 0.5a_{t-1}, a_{t-k} - 0.5a_{t-k-1}) = 0,$$

$$\text{or } \gamma(t, t-k) = 0, \quad \forall k \geq 2, t \in \mathbb{Z}.$$

4. The auto-correlation function (ACF)  $\rho(t, s)$  can then be calculated as follows,

$$\rho(t, s) = \frac{\gamma(t, s)}{\sqrt{\gamma(t, t)\gamma(s, s)}} = \begin{cases} -0.4, & \text{if } |t - s| = 1, \\ 0, & \text{if } |t - s| \geq 2. \end{cases}$$

## §2 Stationarity

- ▶ Why we need the stationarity?
- ▶ The basic idea of stationarity is that the probability laws governing the series do not change with time — that is, the series is in *statistical equilibrium*.

- **Strict stationarity:** A time series  $\{Z_t\}$  is said to be *strictly stationary* if the joint distribution of  $Z_{t_1}, Z_{t_2}, \dots, Z_{t_n}$  is the same as that of  $Z_{t_1-k}, Z_{t_2-k}, \dots, Z_{t_n-k}$  for all choices of natural number  $n$ , all choices of time points  $t_1, t_2, \dots, t_n$  and all choices of time lag  $k$ .

Exercise: Are the following time series  $\{Z_t\}$  strictly stationary?

$\{Z_t\} \sim i.i.d.$  Cauchy distribution with density

$$\pi^{-1}[1+x^2]^{-1} \quad -\infty < x < +\infty.$$

Ans: Yes.

- ▶ **Weak stationarity:** A time series  $\{Z_t\}$  is said to be **weakly (second-order, or covariance) stationary** if
  1. the mean function  $\mu_t$  is constant over time, and
  2.  $\gamma(t, t - k) = \gamma(0, k)$  for all times  $t$  and lags  $k$ .
- ▶ In this course the term *stationary* when used alone will always mean weakly stationary.
- ▶ For a weakly stationary time series, the mean function, the auto-covariance function and the auto-correlation function can be alternatively denoted by
  1.  $\mu = E(Z_t)$ ;
  2.  $\gamma_k = \text{Cov}(Z_t, Z_{t-k})$ ; ( $\gamma_{-k} = \gamma_k$ )
  3.  $\rho_k = \text{Corr}(Z_t, Z_{t-k})$ ; ( $\rho_{-k} = \rho_k$ )

- ▶ The relationship between weak and strict stationarity is as follows,
  1. Strict stationarity + finite second moment  $\Rightarrow$  weak stationarity;
  2. If the joint distributions of a time series are all multivariate normal, then the two definitions coincide;

- **Example (White noise):** A very important example of a stationary process is the so-called **white noise** process, which is defined as a sequence of *i.i.d* random variables  $\{a_t\}$  with zero mean and variance  $\sigma_a^2 > 0$ .

Such a white noise is usually abbreviated as  $WN(0, \sigma_a^2)$ .

1. The fact that  $\{a_t\}$  is strictly stationary is obvious.
2. For the weak stationarity, note that  $\mu_t = E(a_t) = 0$  is a constant and

$$\gamma(t, t - k) = \begin{cases} \sigma_a^2, & \text{if } k = 0, \\ 0, & \text{if } k \neq 0. \end{cases} \quad := \gamma_k$$

Moreover, we have

$$\rho_k = \begin{cases} 1, & \text{if } k = 0, \\ 0, & \text{if } k \neq 0. \end{cases}$$

**Remark:** In some books, the white noise  $\{a_t\}$  is defined to be a sequence of uncorrelated random variables.

- **Example (Random walk) (Cont'd):** The random walk,  $Z_t = a_1 + a_2 + \cdots + a_t$ , is constructed from white noise but is *not* stationary. For example,  $\text{var}(Z_t) = t\sigma_a^2$  is *not* constant; furthermore, the covariance function  $\gamma(t, s) = t\sigma_a^2$  for  $0 \leq t \leq s$  does *not* depend only on time lags. Therefore, the random walk is a **non-stationary** time series.

Let  $\{X_t = \nabla Z_t = Z_t - Z_{t-1}\}$  be the differenced sequence of  $\{Z_t\}$ . Then  $X_t = a_t$ , i.e.  $\{\nabla Z_t\}$  is stationary.



- **Example (A moving average) (Cont'd):** The moving average example,  $Z_t = a_t - 0.5a_{t-1}$ , is an instance of a nontrivial, stationary time series constructed from white noise. In our new notation, we have for the moving average time series that

$$\rho_k = \begin{cases} 1, & \text{for } k = 0, \\ -0.4, & \text{for } k = \pm 1, \\ 0, & \text{for } |k| \geq 2. \end{cases}$$

## **Reference**

Please read Chapter 2 of Cryer & Chan (2008).