

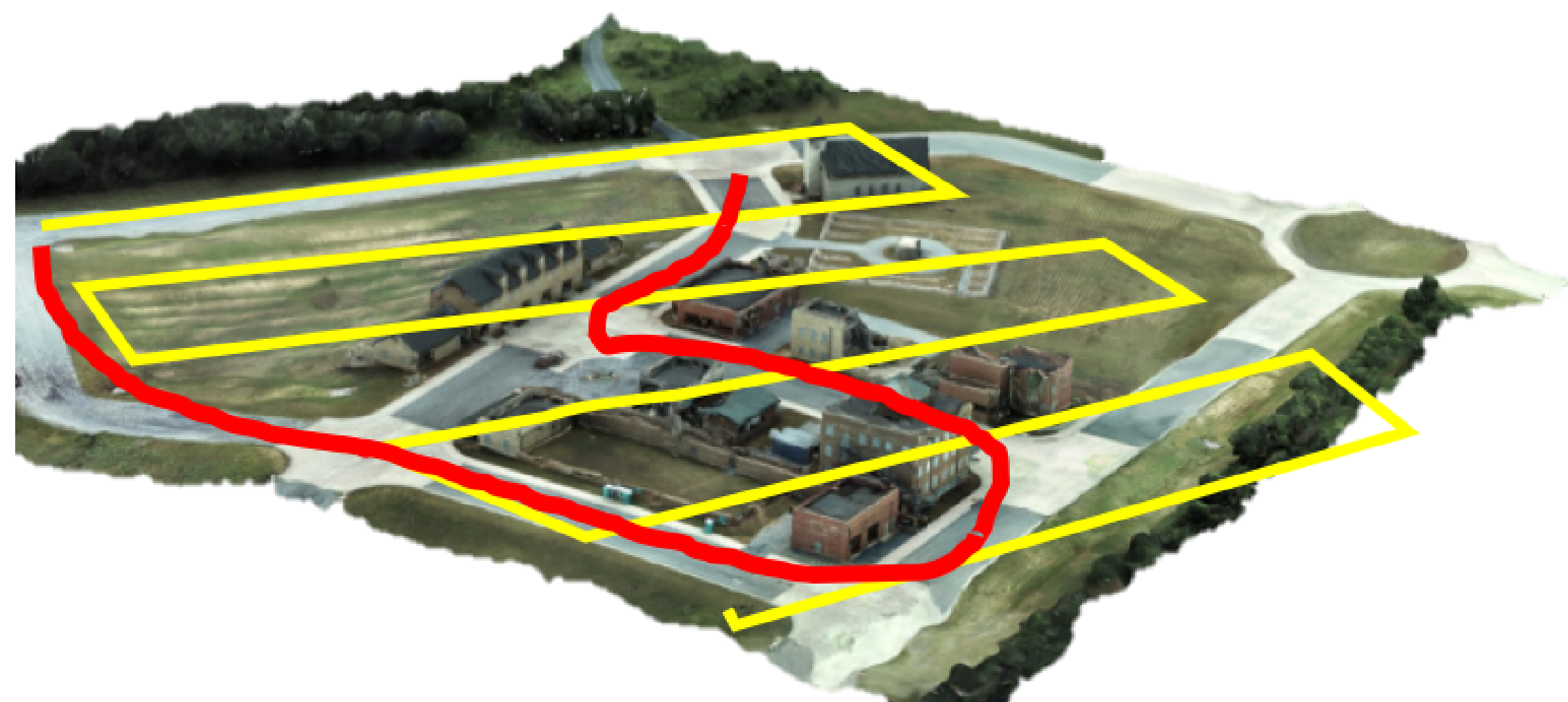
## ABSTRACT

- Exploration: find all cars in a terrain as fast as possible
- Problem: what to do when the object is not in sight?
- Trained car context classifier with 272 aerial images with hand-labeled cars
- Obtained 65.4% and 79.5% accuracy with Neural Net classifier using low (2<sup>nd</sup> layer) and high level (6<sup>th</sup> layer) features extracted from AlexNet

## MOTIVATION



**Figure 1:** Exploration of objects such as cars or animals in an open environment, or search-and-rescue missions



**Figure 2:** Focused exploration leads to more relevant information

## REFERENCES

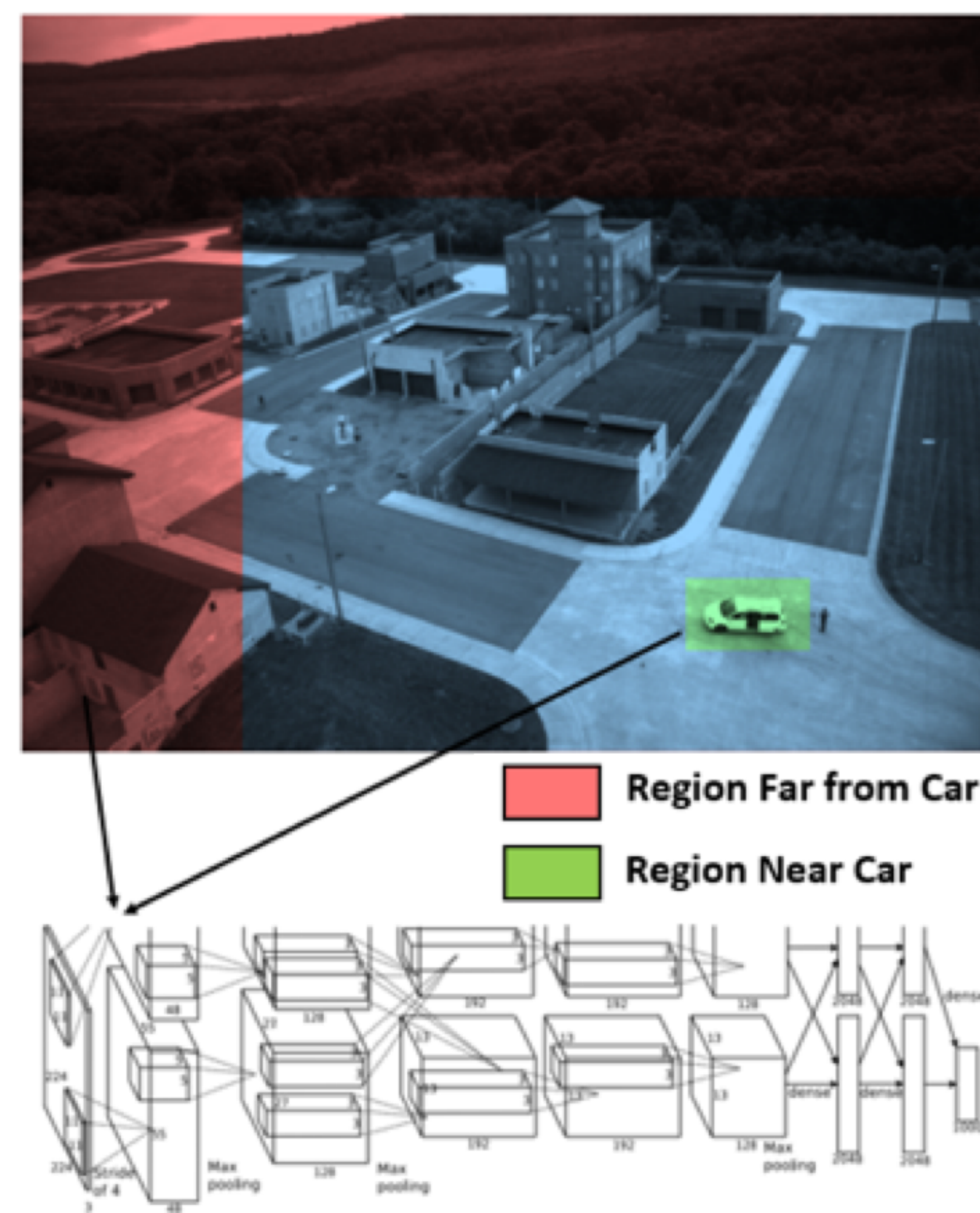
- [1] Ben Athiwaratkun and Keegan Kang. Feature representation in convolutional neural networks. *arXiv preprint arXiv:1507.02313*, 2015.
- [2] Joshua Gleason, Ara V Nefian, Xavier Bouysseounousse, Terry Fong, and George Bebis. Vehicle detection from aerial imagery. In *Robotics and Automation (ICRA), 2011 IEEE International Conference on*, pages 2065–2070. IEEE, 2011.
- [3] Liang Zheng, Yali Zhao, Shengjin Wang, Jingdong Wang, and Qi Tian. Good practice in cnn feature transfer. *arXiv preprint arXiv:1604.00133*, 2016.

## METHODS

We extracted features from regions close and far away from cars in 272 manually labeled examples.

We trained a binary classifier to distinguish between our two classes: positive for being close to a car and negative for being distant from a car. We implemented two approaches:

Step	Description
Region selection	Select patches in blobs close and far away to the labeled car
Feature extraction	(1) Extract features from the 2 <sup>nd</sup> layer of AlexNet — 100K samples with 96 features each (2) Extract features from the 6 <sup>th</sup> layer of AlexNet — 3K samples with 4096 features each
Training	Train a binary neural network classifier to output probability of patch being close to a car
Quantitative test	Evaluate performance of classifier on test set
Qualitative test	Break down an entire image in patches and evaluate qualitatively its heat map

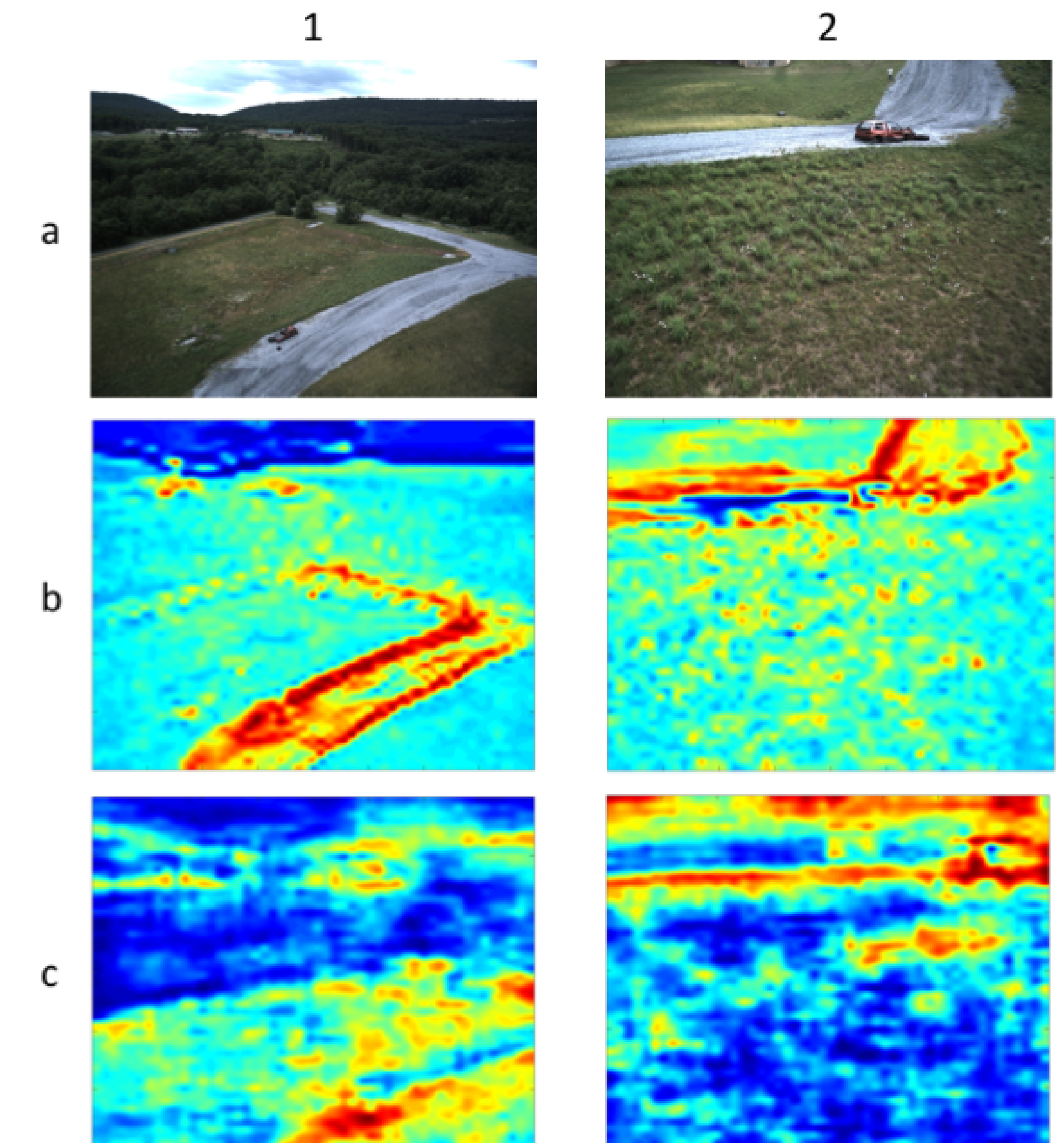


**Figure 3:** Feature extraction from candidate regions of an image

## FUTURE WORK

- Employ a combination of high and low level features to identify context (hypercolumns)
- Test different network architectures for both feature extraction and classification
- Use larger dataset and train a convolutional neural network for end-to-end classification

## HEAT MAPS OF CAR CONTEXT



**Figure 4:** Heat maps generated for two sample images in column 1 and column 2. Row "a" contains the original image, row "b" has the heat map based on low-level features and row "c" has the heatmap based on high-level features from AlexNet

Qualitative evaluation of the images:

- Low-level features from AlexNet identify edges and texture well, as expected
- High-level features generate a more diffuse representation of context
- Images in extremes of scales are not well represented using either method

## ACKNOWLEDGEMENTS

The authors would like to thank Daniel Maturana from CMU for providing the dataset of aerial images used in this project.