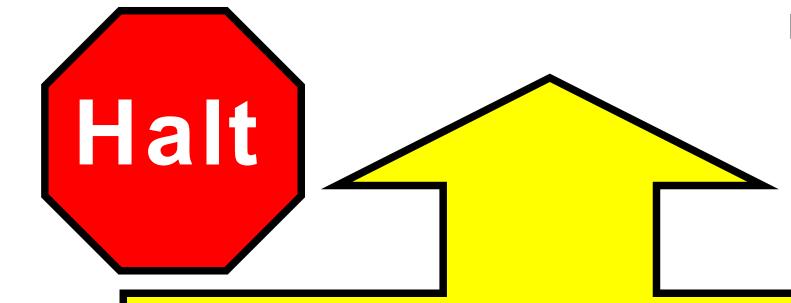




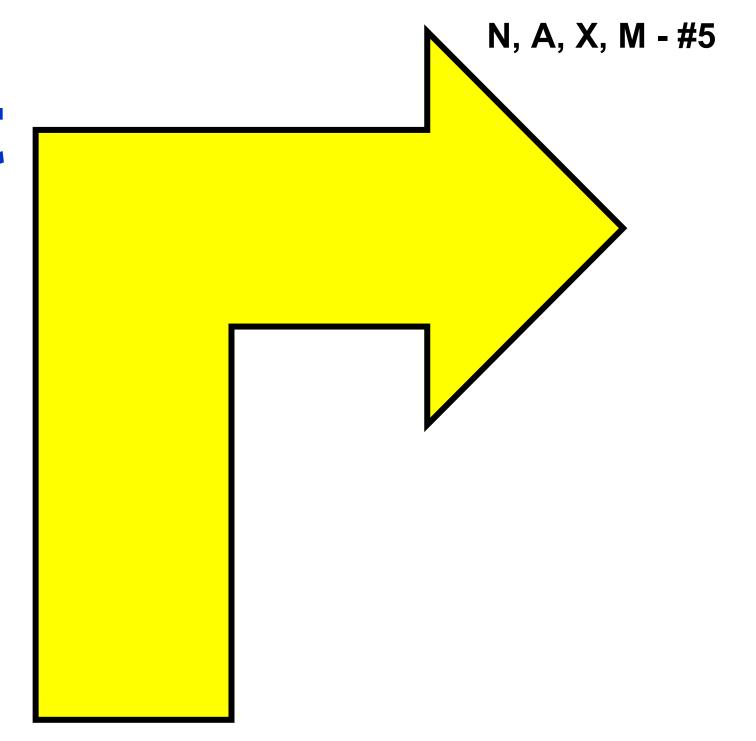


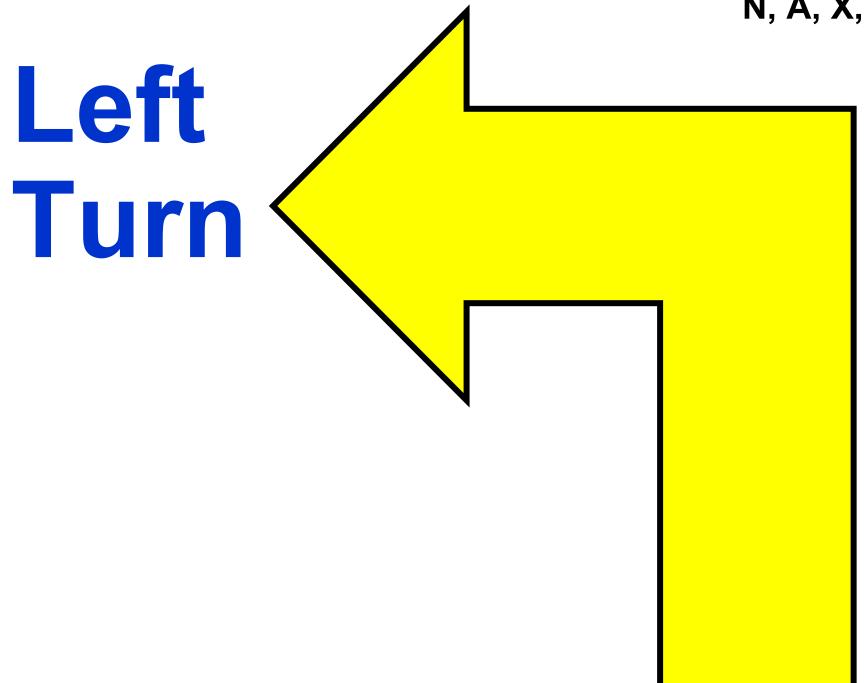
### Sit



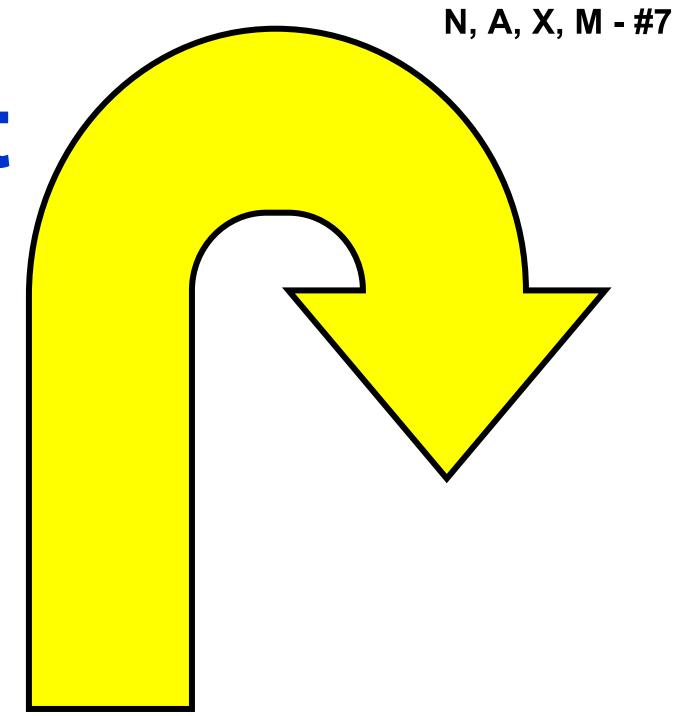
### Down

### Right Turn





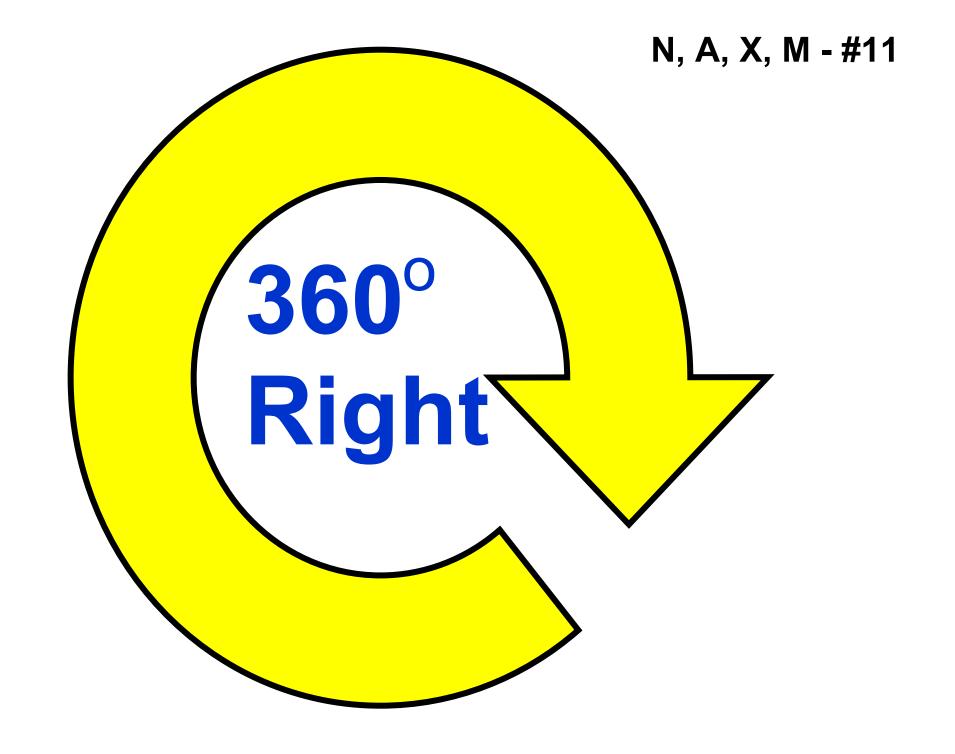
# About Turn Right

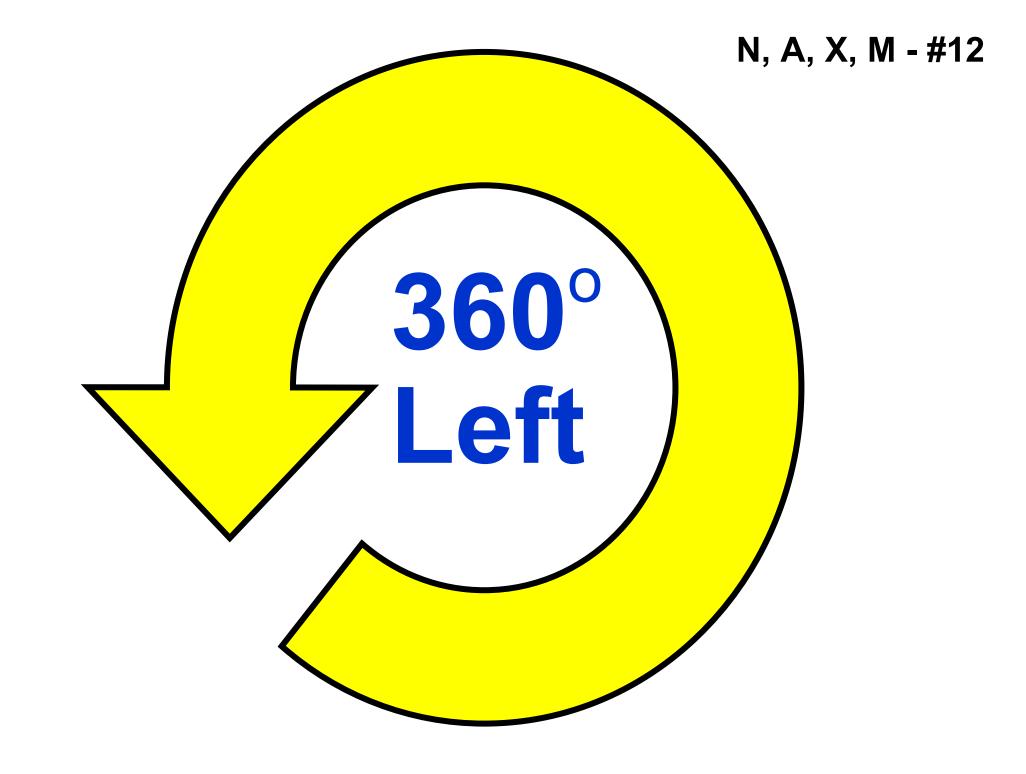






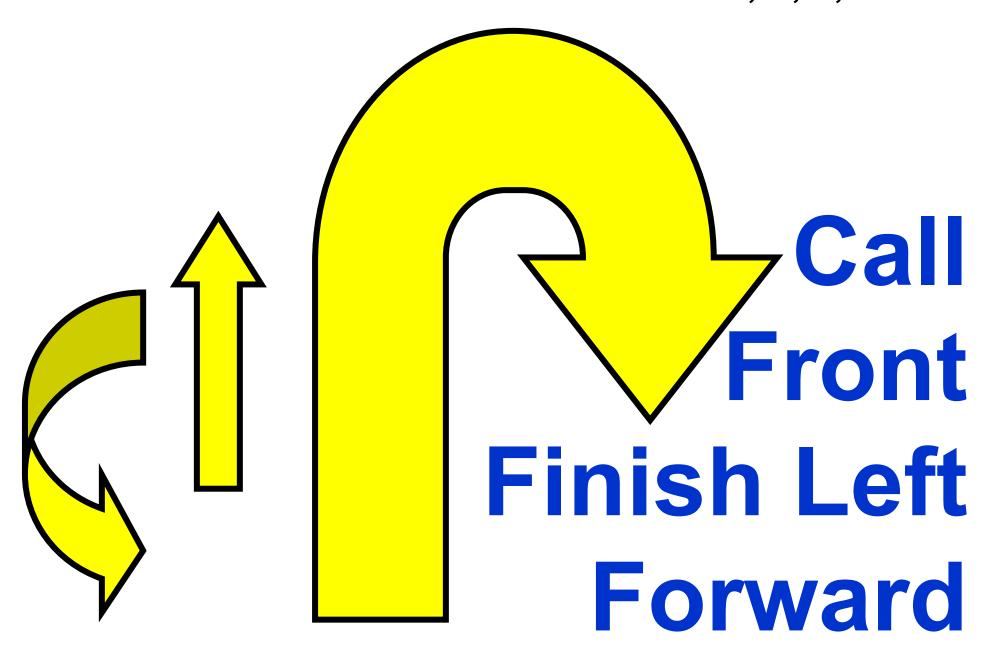






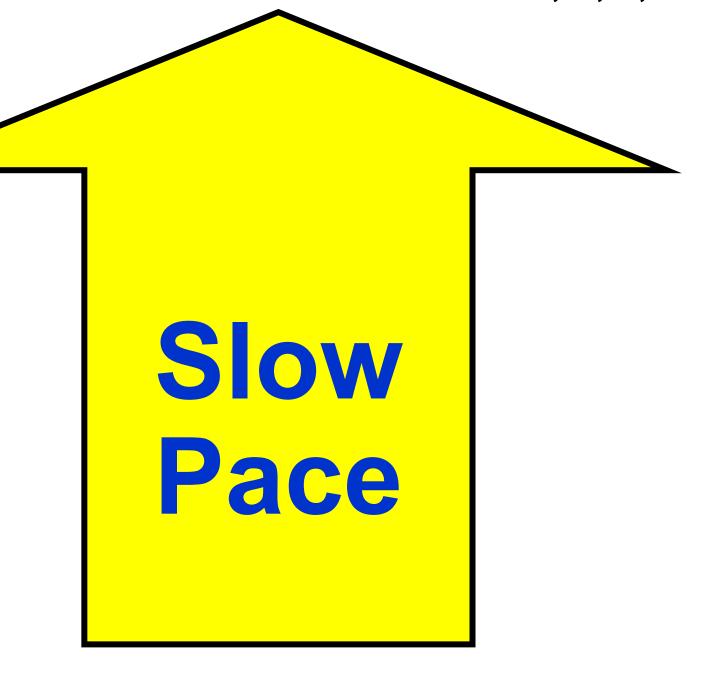
N, A, X, M - #13











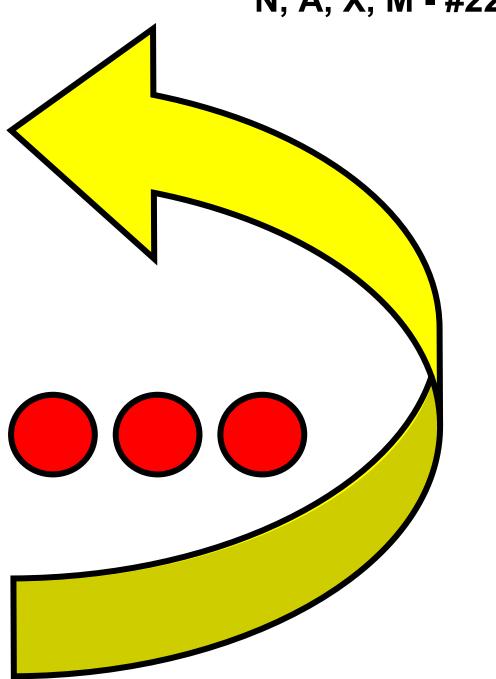


## Normal Pace

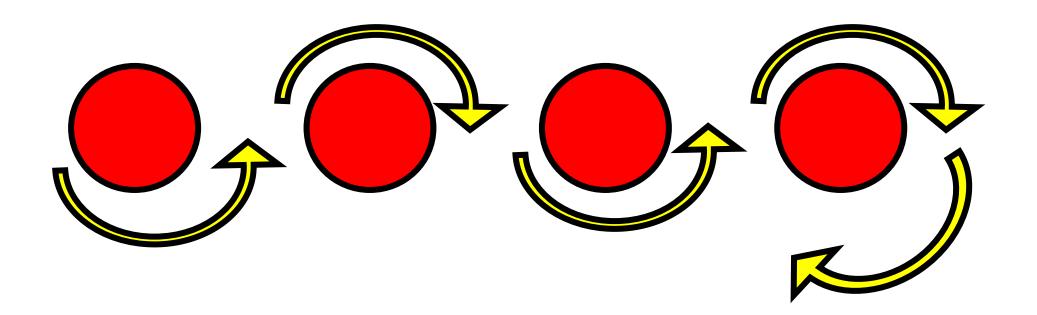


#### Spiral Left

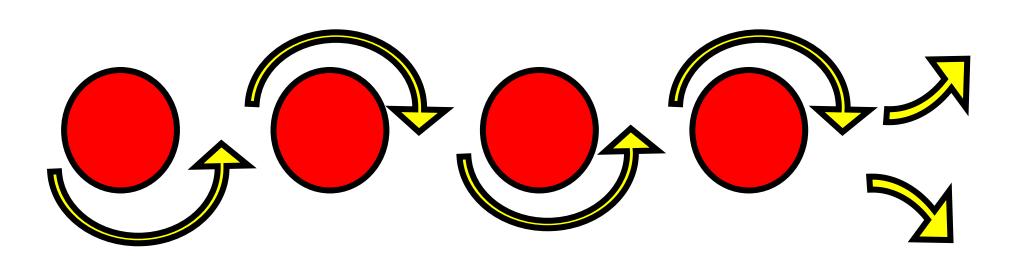
Dog Inside



# Straight Figure 8 Weave Twice



### Serpentine Weave Once



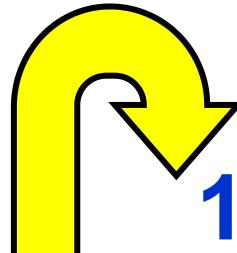
N, A, X, M-#25

Halt 1 Step

Halt

2 Steps Halt

3 Steps Halt



#### Call Front

1 Step Back Halt

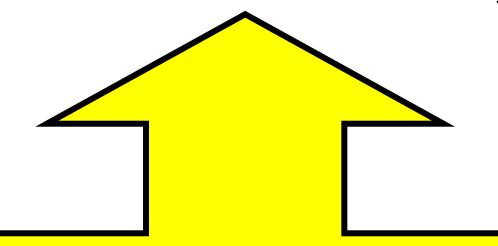


2 Steps Back Halt



3 Steps Back Halt

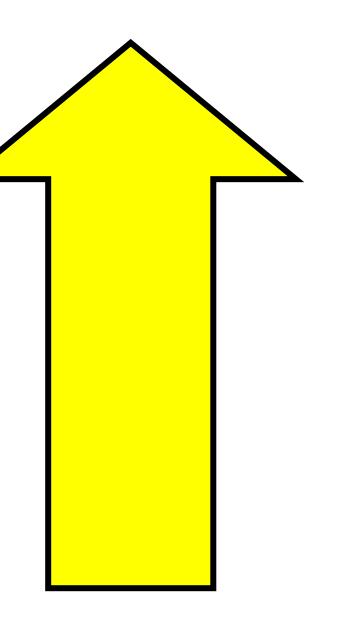




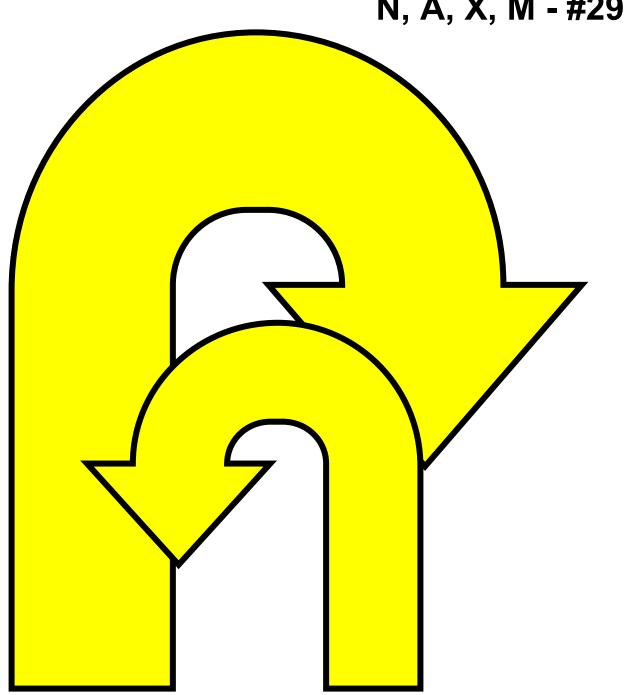
### Moving Down

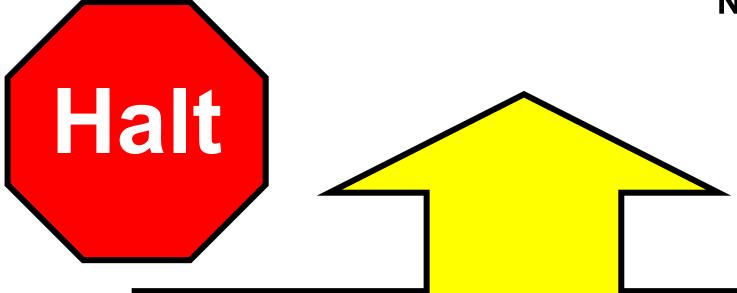


## Fast Forward From Sit

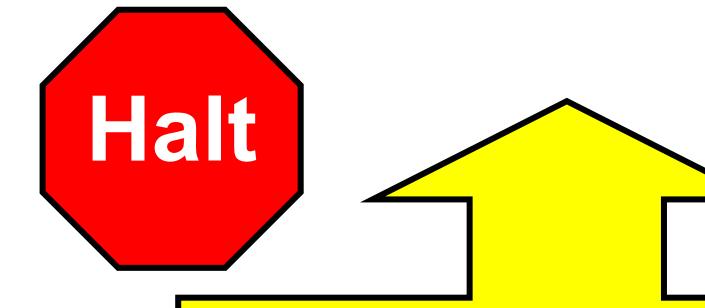


#### Left About Turn



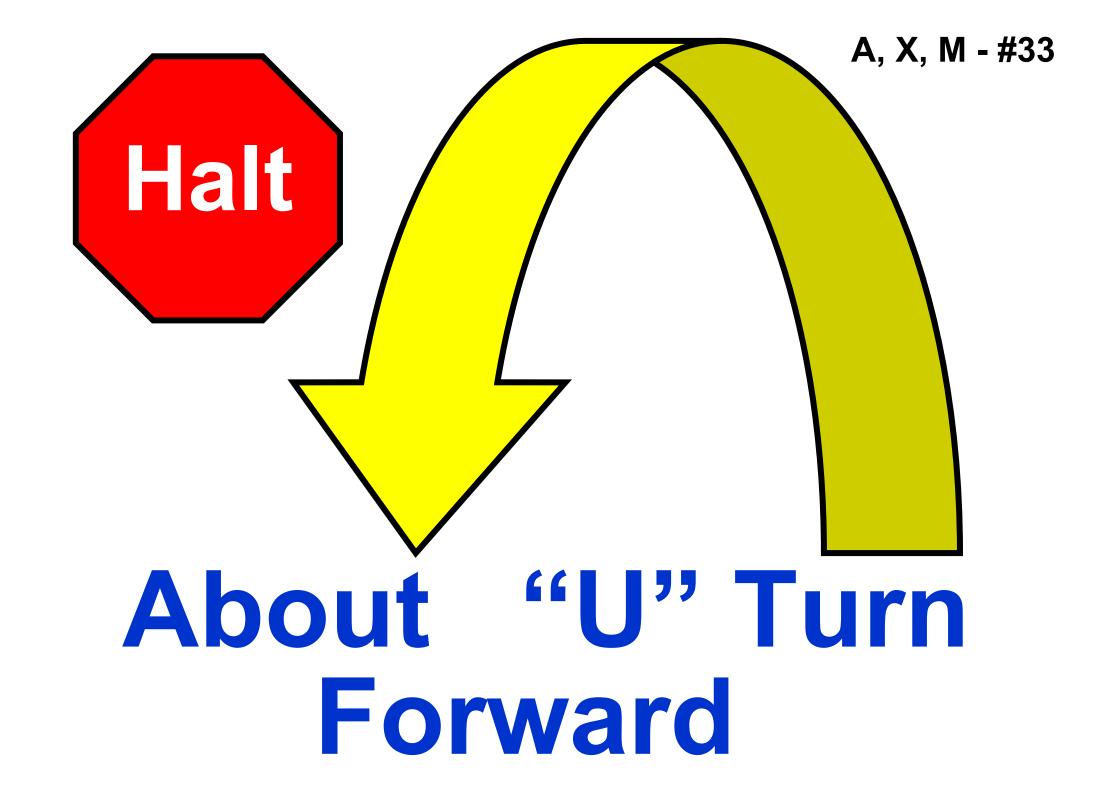


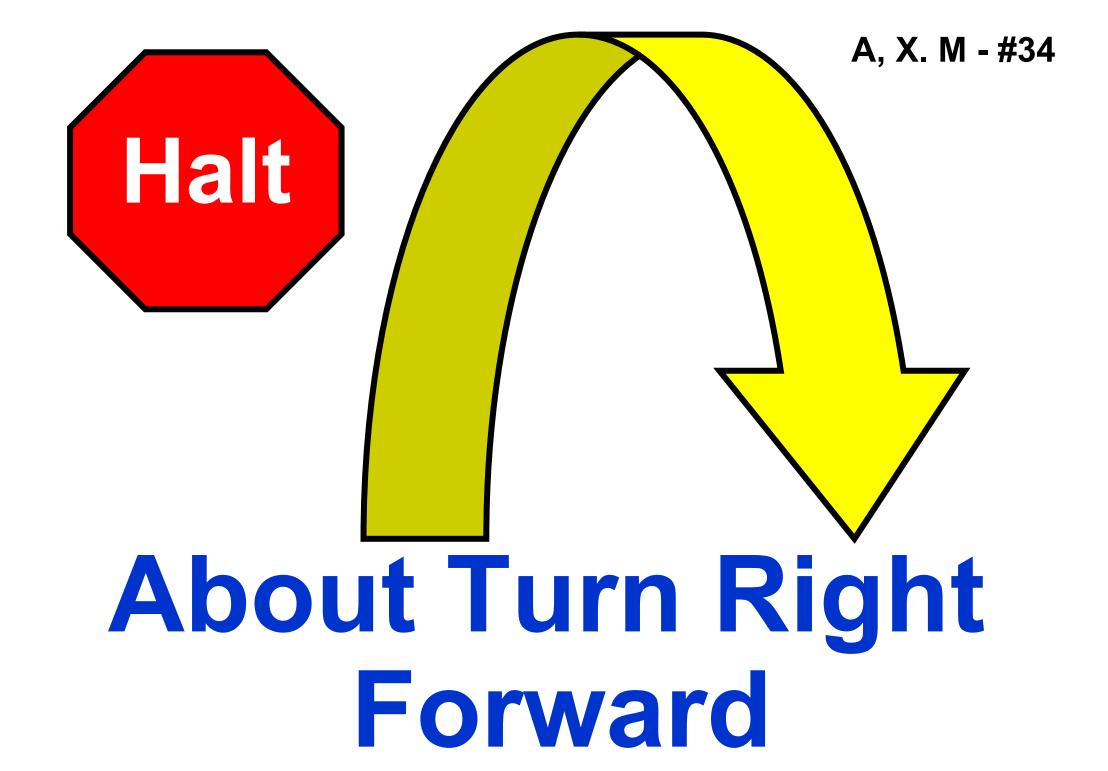
## Walk Around Dog



# Down Walk Around Dog









## Turn Right 1 Step

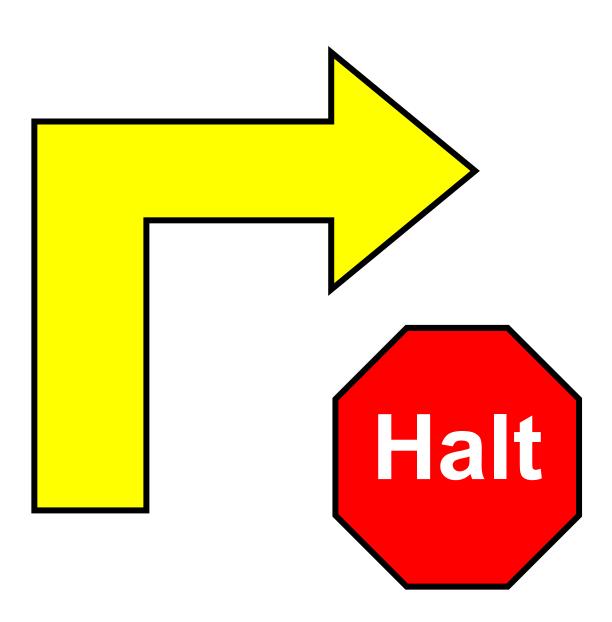




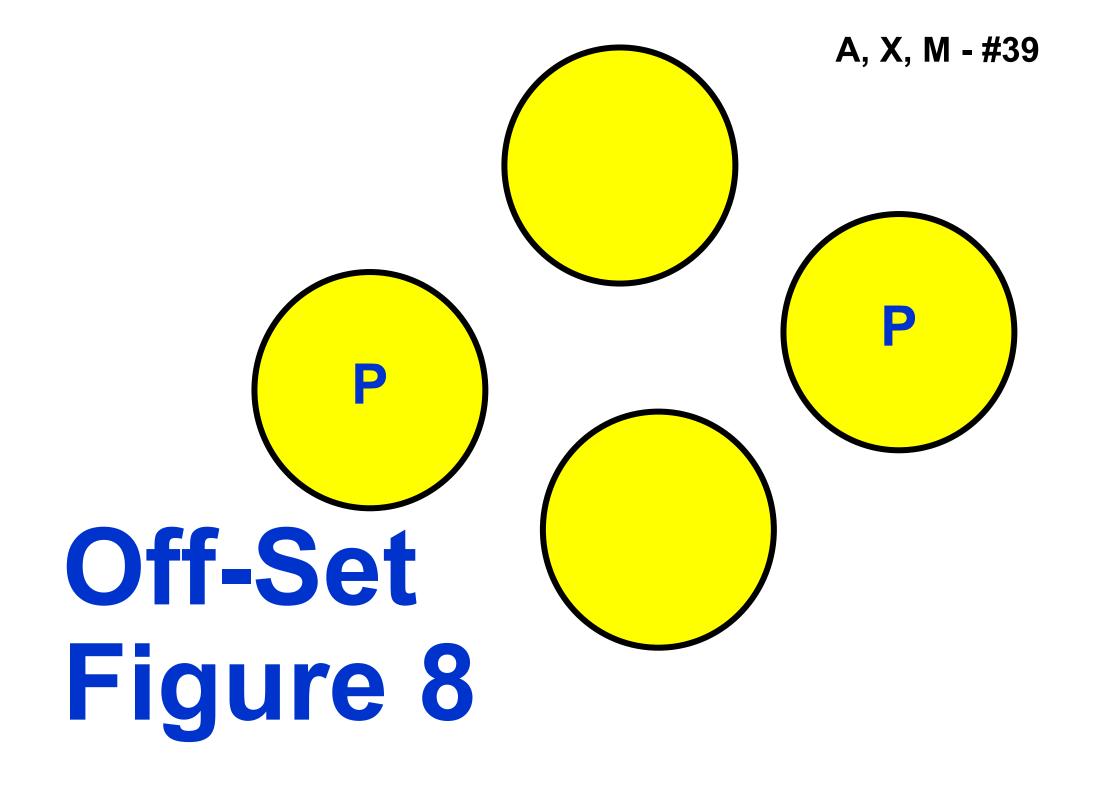


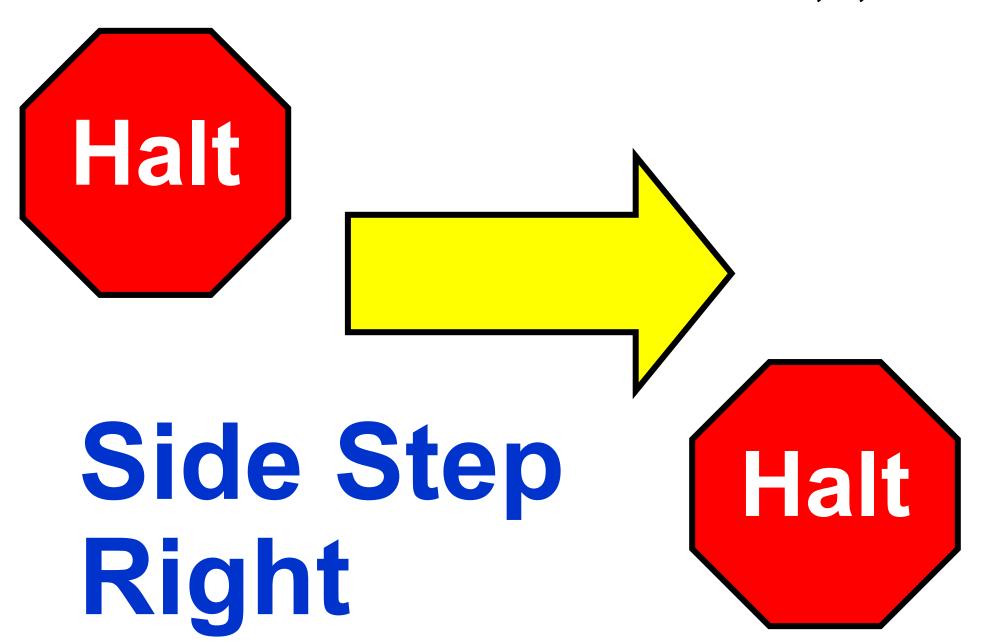


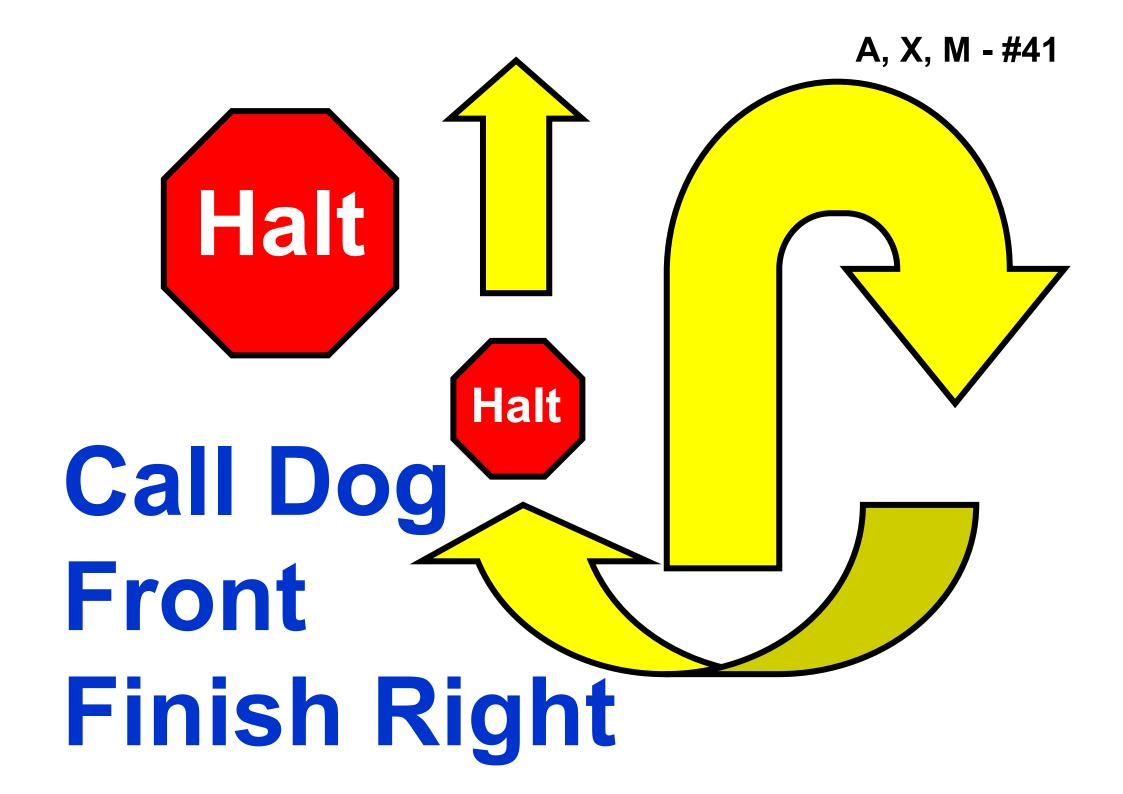
### 90° Pivot Right



A, X, M - #38 Halt 900 Pivot Halt Left



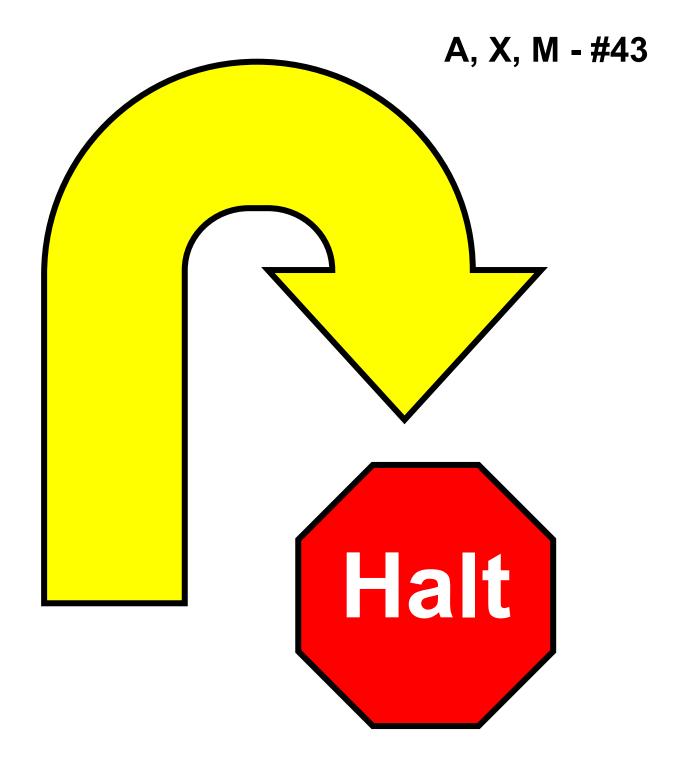






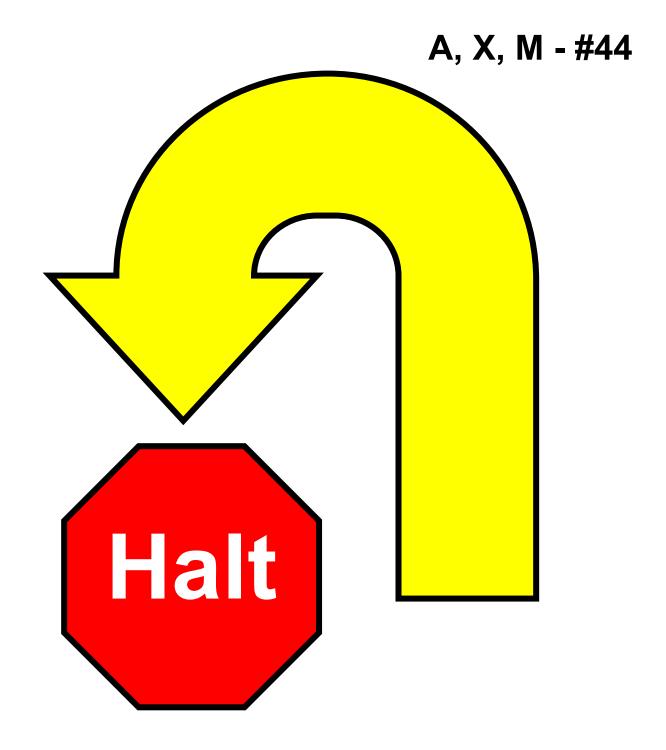


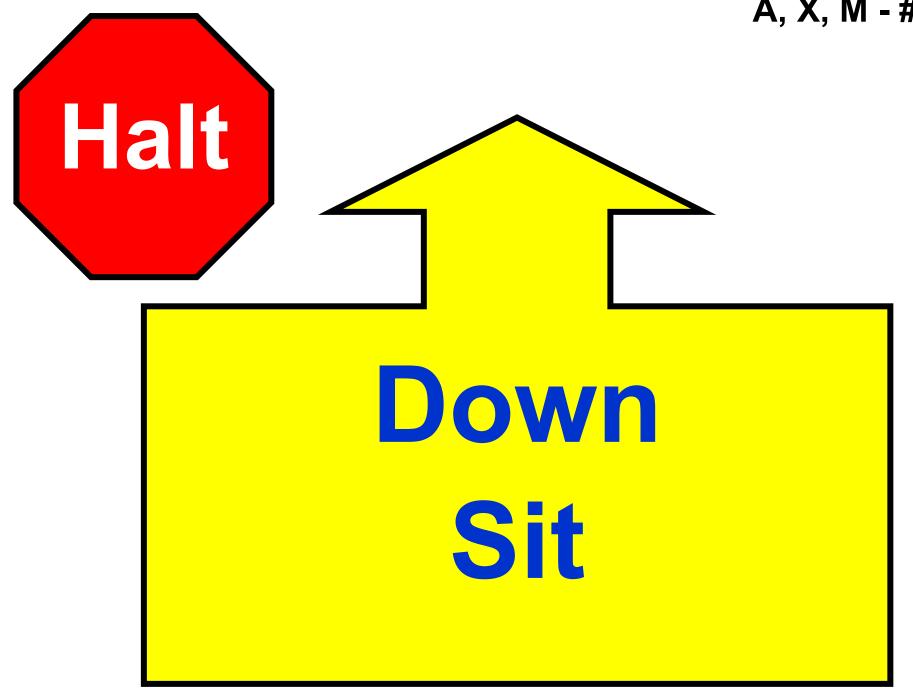
180<sup>0</sup>
Pivot
Right



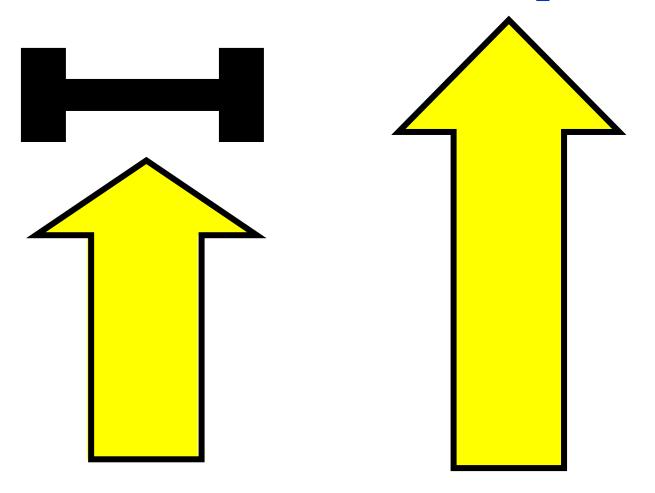


180<sup>0</sup>
Pivot
Left

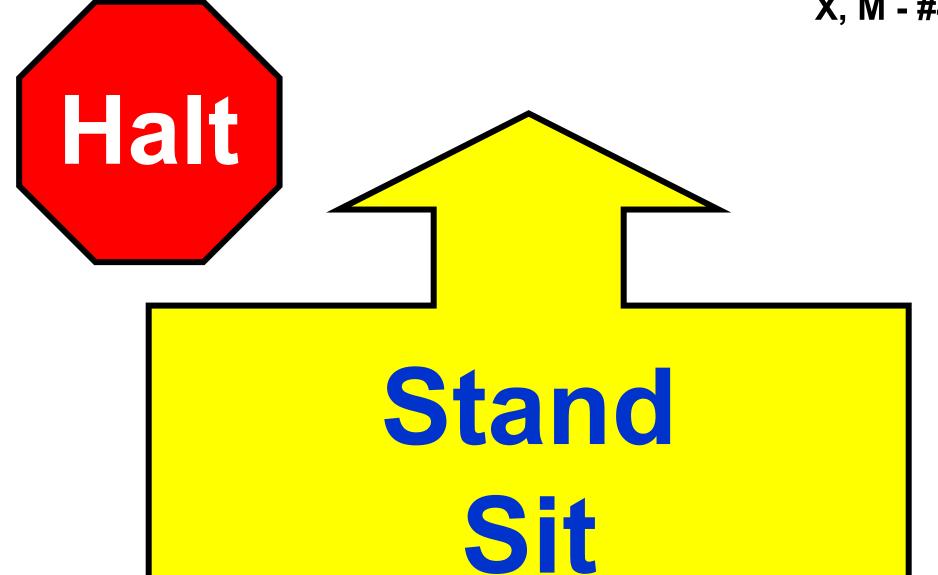


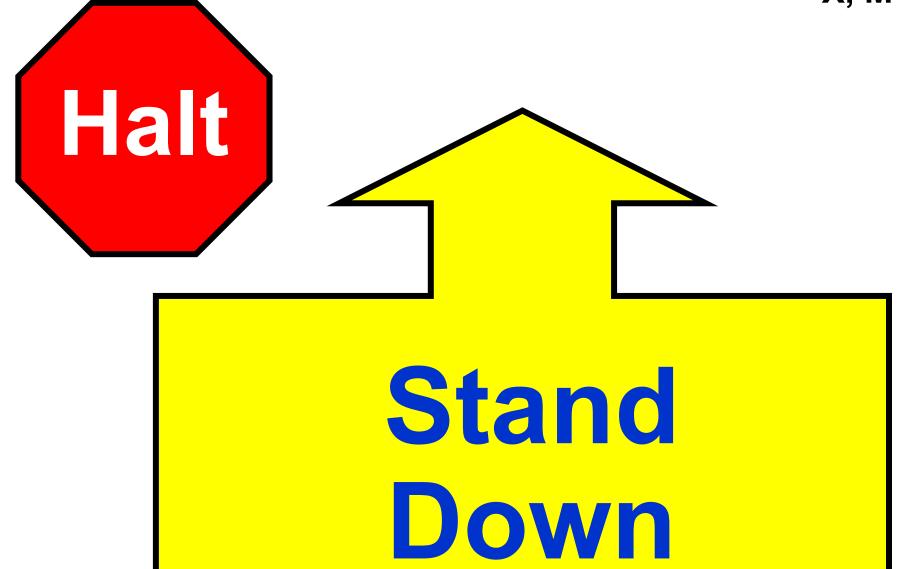


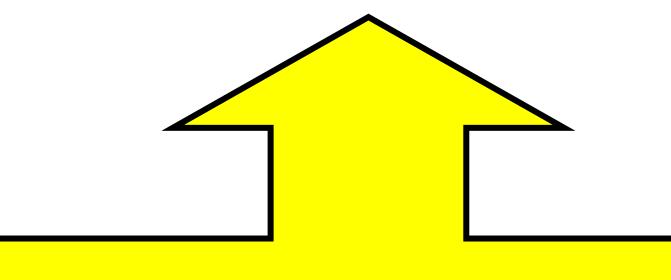
#### Send Over Jump



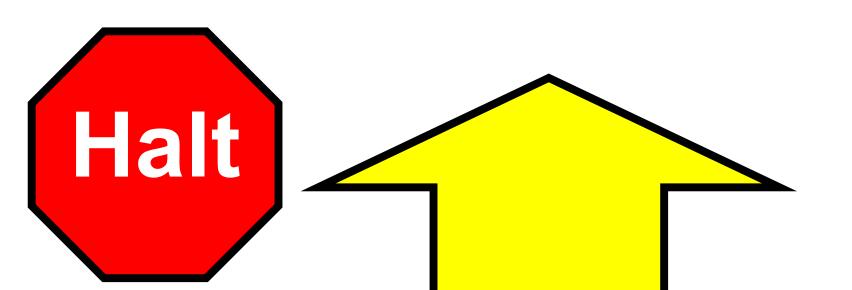
Handler Passes By





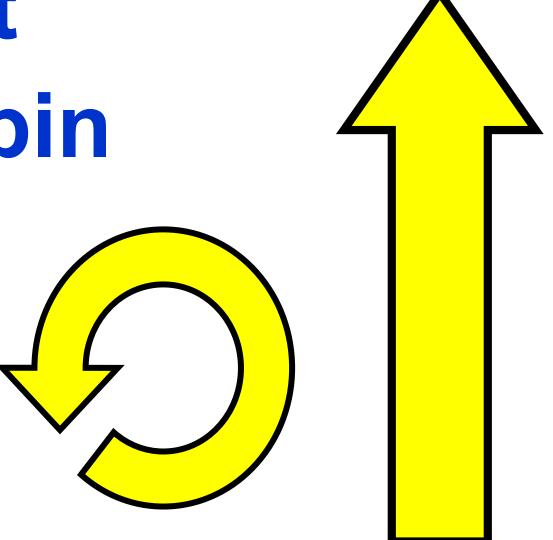


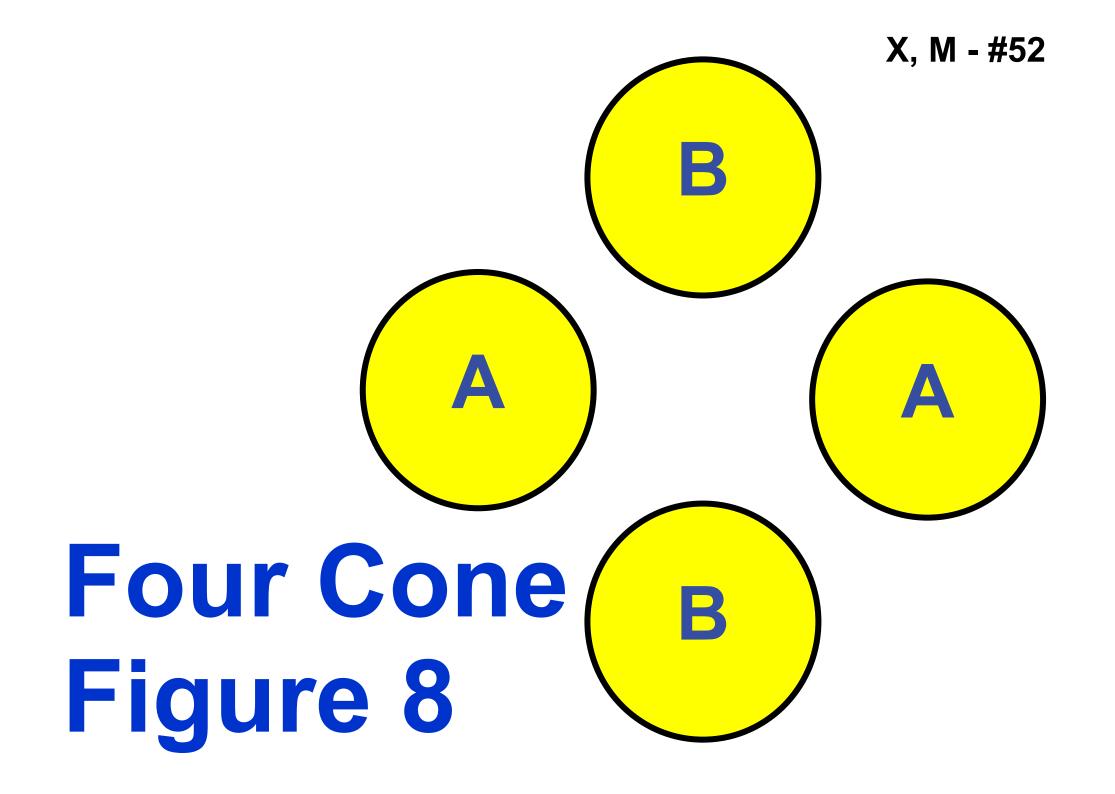
### Moving Stand Walk Around Dog

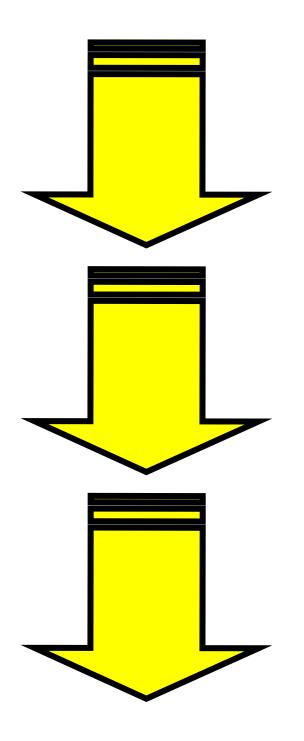


# Leave Dog 5 mtrs About Turn Call Dog to Front Return to Dog

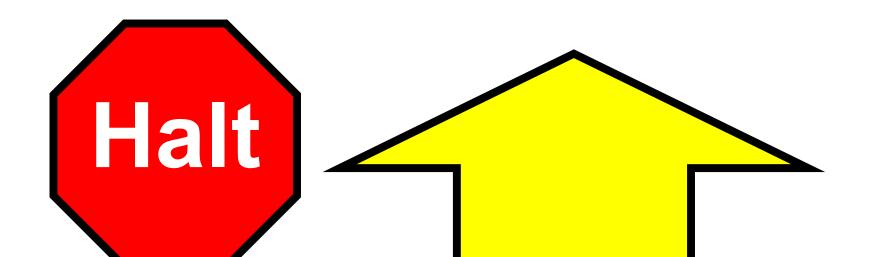
360° Left
Circle Spin
At Heel



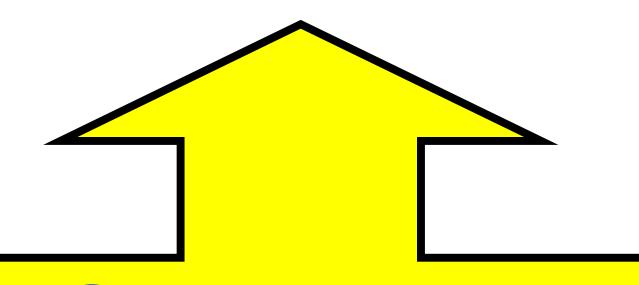




#### Back Up 3 Steps Dog Stays in Position

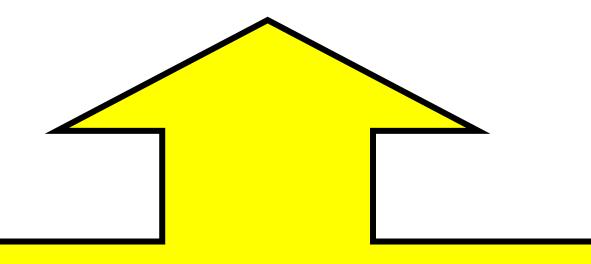


#### Leave Dog 3 mtrs **About Turn** Distance Down - Sit Return Around Dog



#### Stand Dog Leave Dog 3 mtrs Distance Down - Sit Return Around Dog

#### Moving Stand Leave Dog 3 mtrs Distance Down Return Around Dog



## Moving Down Walk Around Dog





# Leave Dog 3 mtrs <sup>2</sup> Call Dog To Heel Without Stopping

