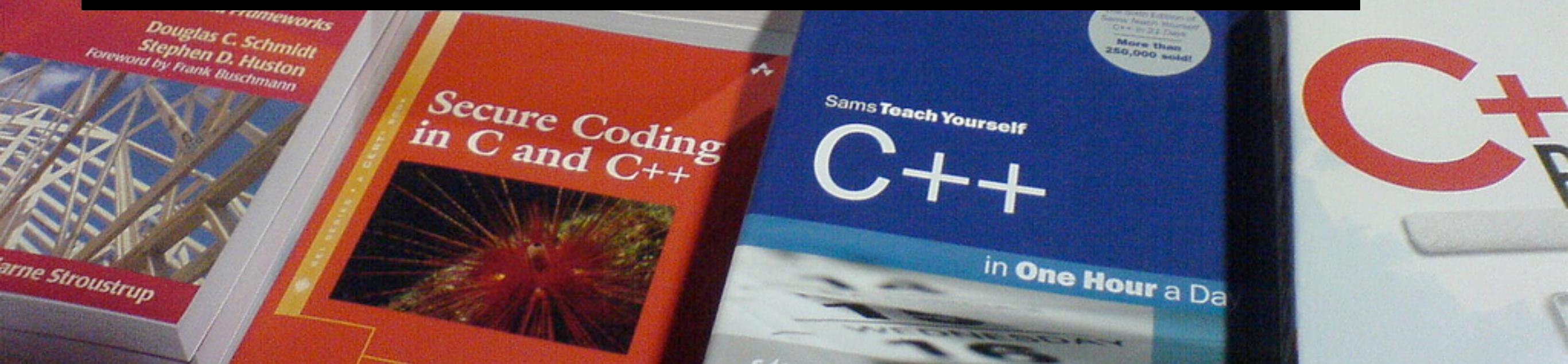


# Imperative and Object-Oriented Languages

Guido Wachsmuth



# Assessment

## last lecture

Explain the properties of language using the examples of English and MiniJava.

- arbitrary
- symbolic
- systematic
- productive
- non-instinctive
- conventional
- modifiable

# Assessment

## last lecture

What is a software language?

- computer-processable artificial language used to engineer software
- piece of software

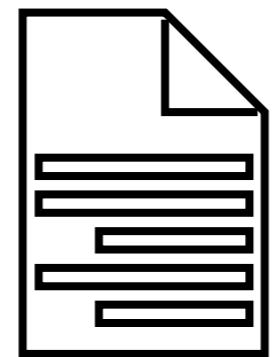
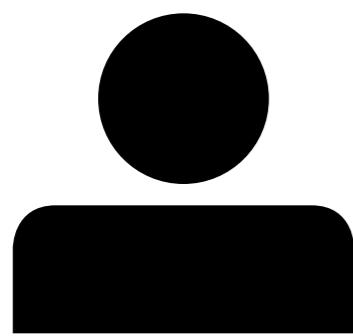
Why is MiniJava a software language?

- computer-processable artificial language
- programming language, can be used to engineer software
- MiniJava compiler = piece of software

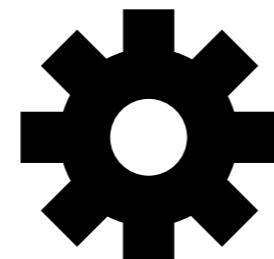
Why is English not a software language?

- not computer-processable, not artificial

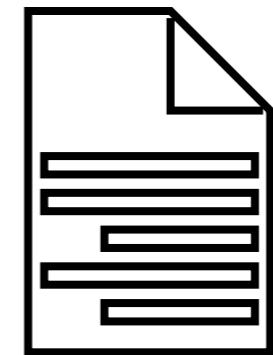
# Recap: Compilers



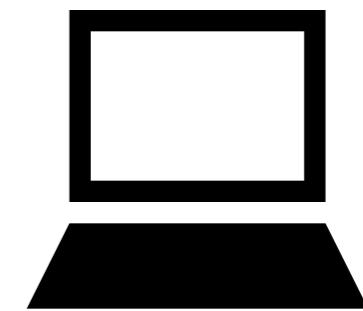
**software  
language**



**compiler**



**machine  
language**



# Overview today's lecture

I  
imperative languages

II  
object-oriented languages

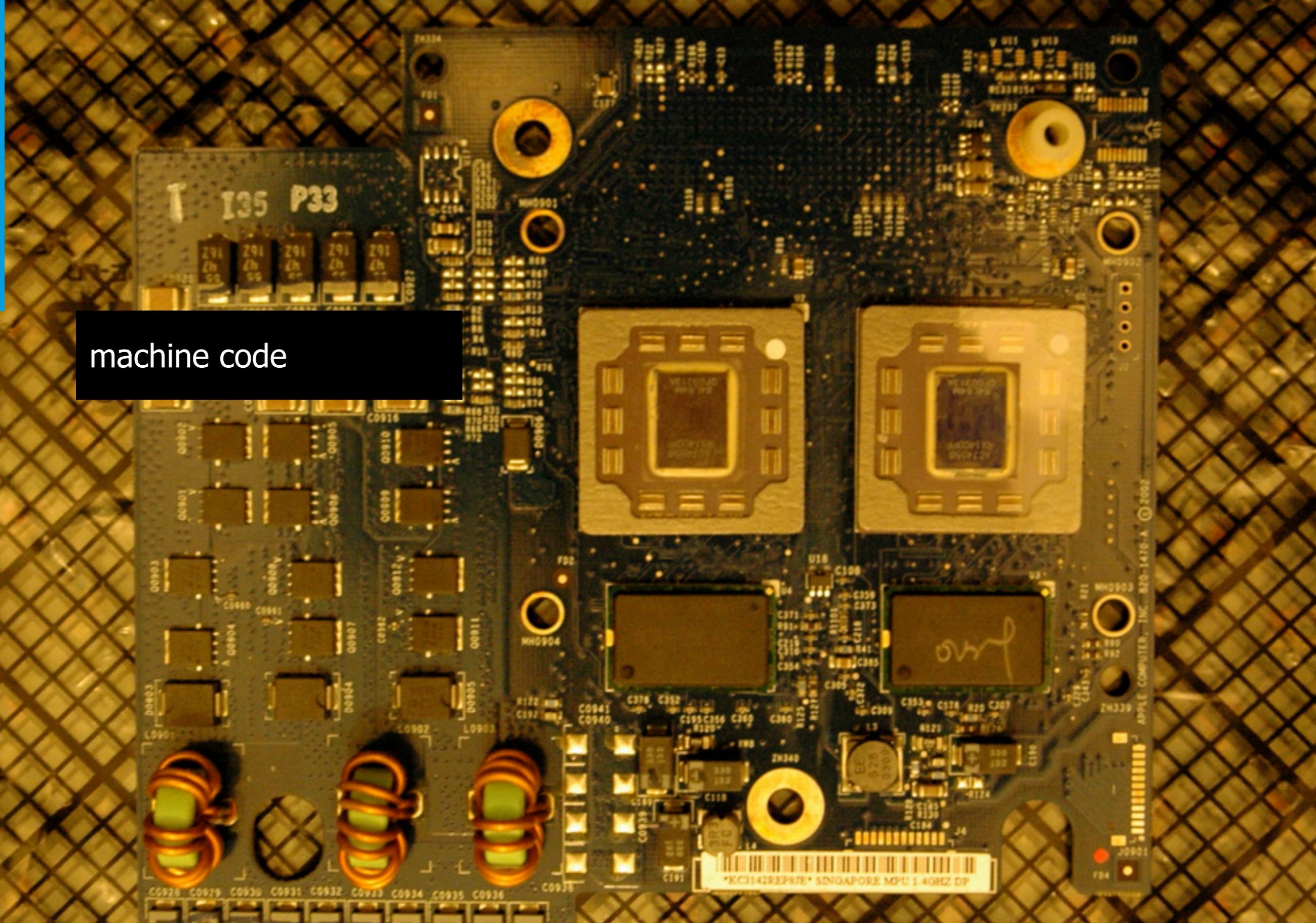
# I

---

## imperative languages

---

machine code



# x86 family registers

## general purpose registers

- accumulator **AX** - arithmetic operations
- counter **CX** - shift/rotate instructions, loops
- data **DX** - arithmetic operations, I/O
- base **BX** - pointer to data
- stack pointer **SP**, base pointer **BP** - top and base of stack
- source **SI**, destination **DI** - stream operations

## special purpose registers

- segments **SS**, **CS**, **DS**, **ES**, **FS**, **GS**
- flags **EFLAGS**

# Example: x86 Assembler basic concepts

`mov AX [1]` read memory

`mov CX AX`

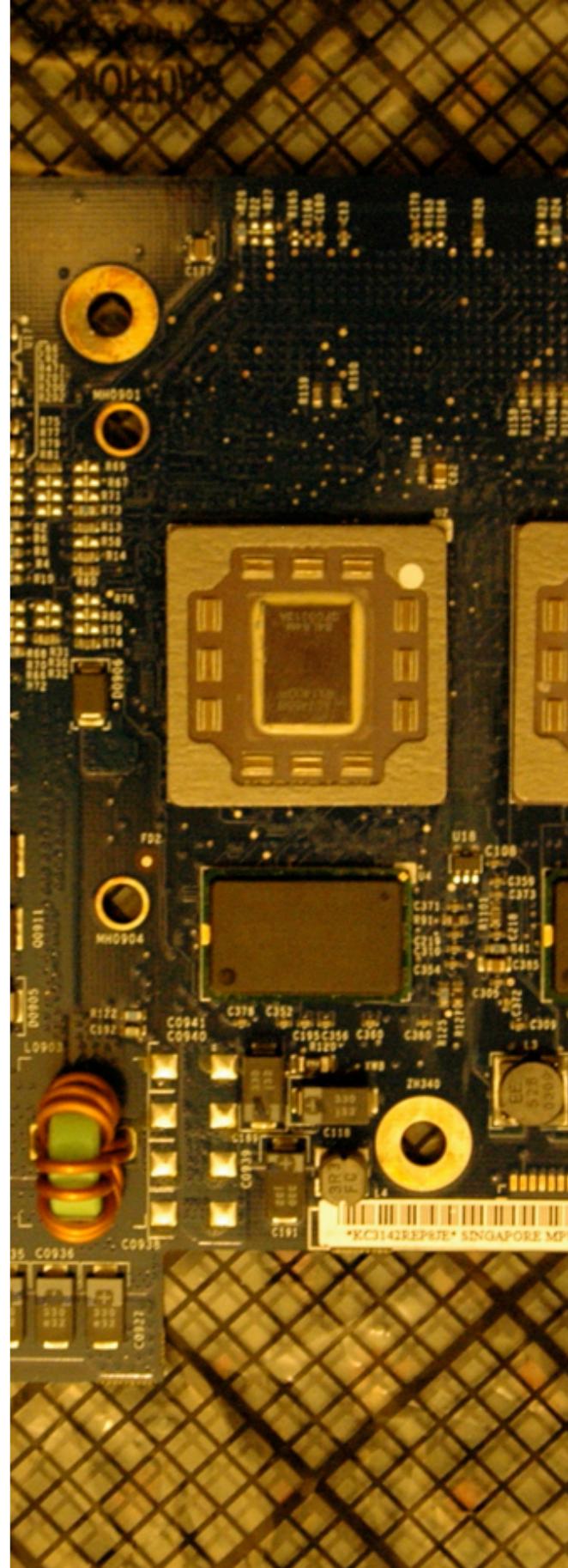
L: `dec CX`

`mul CX` calculation

`cmp CX 1`

`ja L` jump

`mov [2] AX` write memory



# Example: Java Bytecode basic concepts

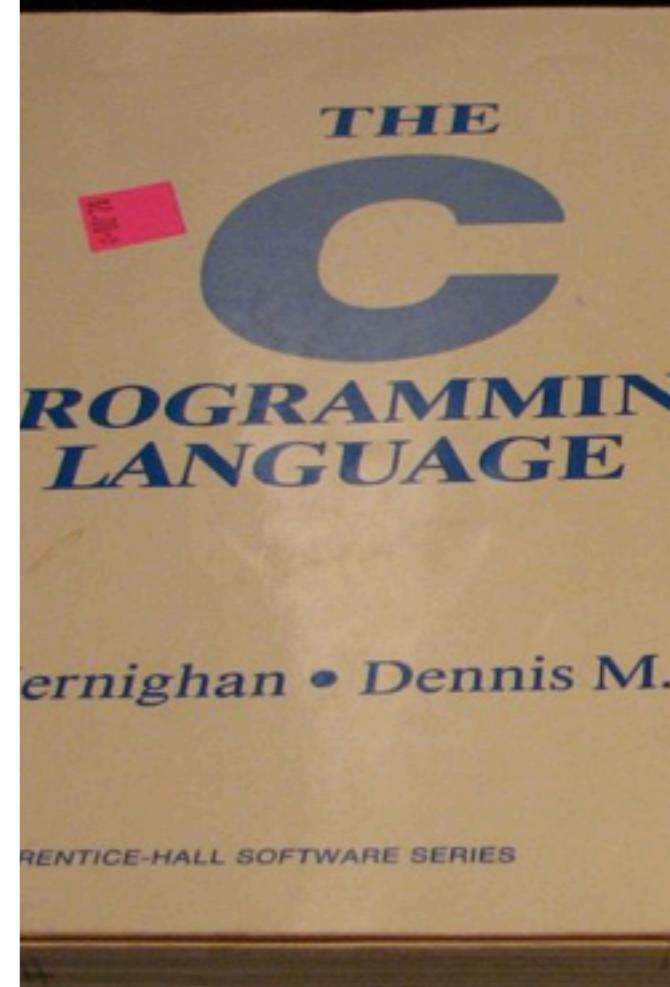
```
.method static public m(I)I
```

```
    iload 1
    ifne else      jump
    iconst_1
    ireturn
```

```
else: iload 1      read memory
      dup
      iconst_1
      isub      calculation
      invokestatic Math/m(I)I
      imul
      ireturn
```

# Example: C states & statements

<code>int f = 1</code>	variable
<code>int x = 5</code>	
<code>int s = f + x</code>	expression
<code>while (x &gt; 1) {</code>	control flow
<code>f = x * f;</code>	
<code>x = x - 1</code>	assignment
<code>}</code>	



# Example: Tiger states & statements

```
/* factorial function */
```

```
let
```

```
var f := 1
```

variable

```
var x := 5
```

```
var s := f + x
```

expression

```
in
```

```
while x > 1 do (
```

control flow

```
    f := x * f ;
```

```
    x := x - 1
```

assignment

```
)
```

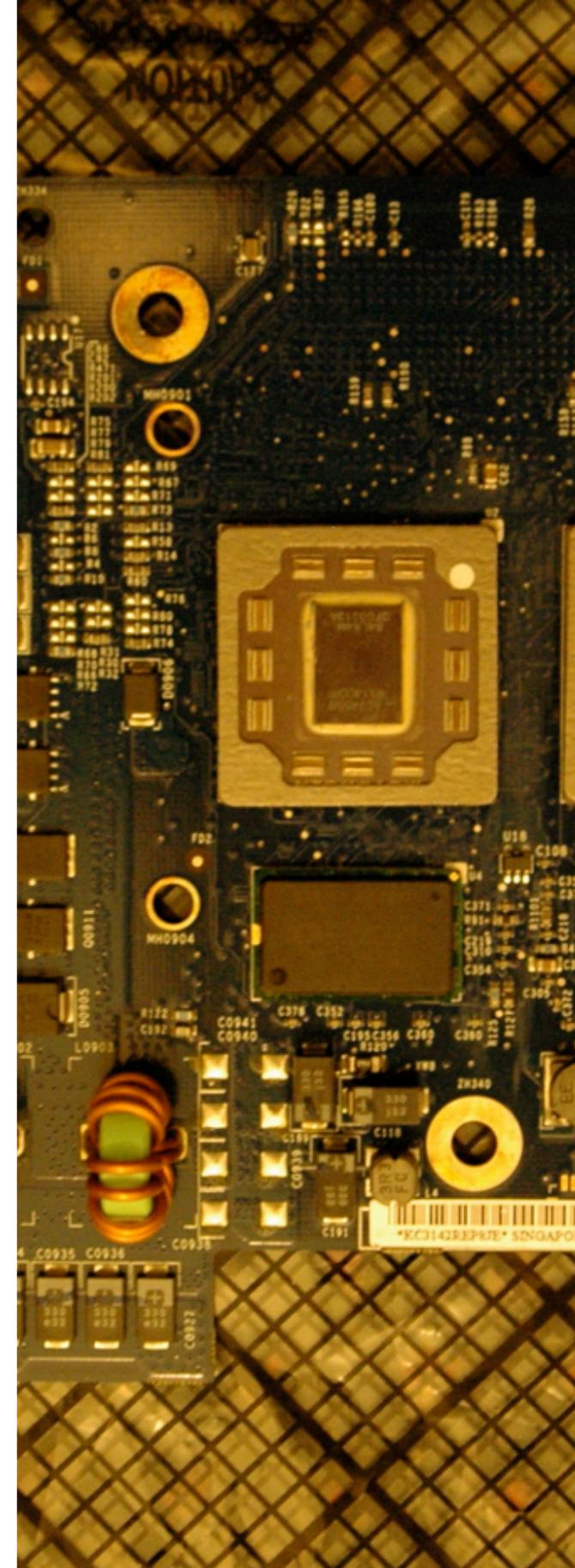
```
end
```



# Example: x86 Assembler modularity

```
push 21          pass parameter  
push 42  
call _f  
add  SP 8       free parameters
```

```
push BP          new stack frame  
mov  BP SP  
mov  AX [BP + 8]  
mov  DX [BP + 12] access parameter  
add  AX DX  
pop  BP          old stack frame  
ret
```

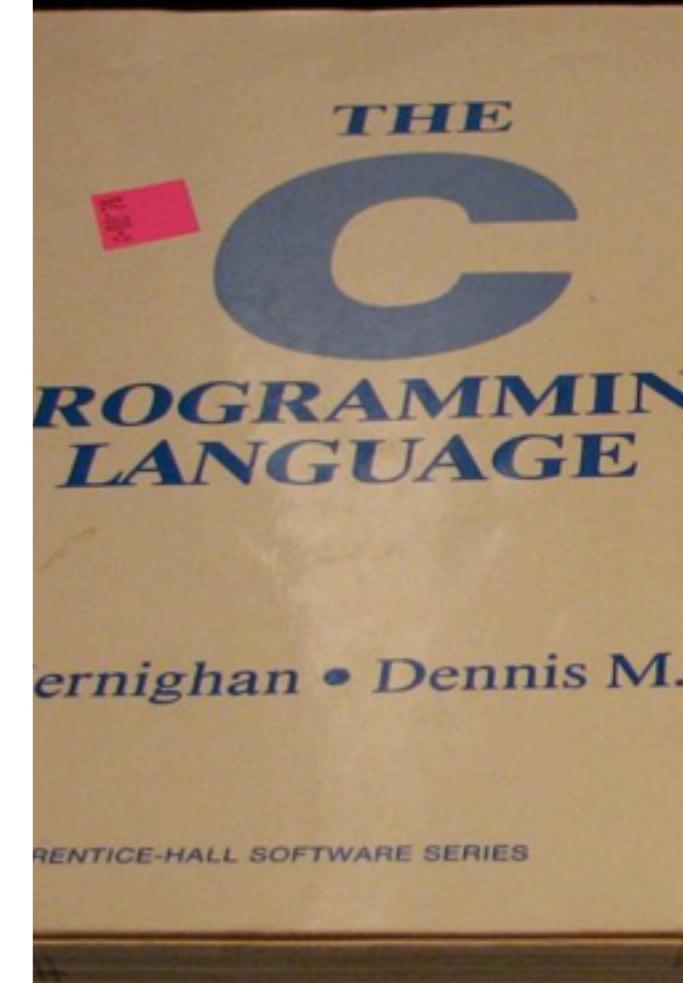


# Example: C procedures

```
#include <stdio.h>

/* factorial function */
int fac(int num) {
    if (num < 1)
        return 1;
    else
        return num * fac(num - 1);    recursive call
}

int main() {
    int x = 10;                      local variable
    int f = fac(x);                 actual parameter
    int x printf("%d! = %d\n", x, f);
    return 0;
}
```



# Example: Tiger procedures

```
/* factorial function */

let
    function fac(n: int) : int = formal parameter
        let
            var f := 1 local variable
        in
            if n < 1 then
                f := 1
            else
                f := (n * fac(n - 1)); recursive call
            f
        end
    var f := 0
    var x := 5
in
    f := fac(x) actual parameter
end
```



# Example: Tiger

## call by value vs. call by reference

```
let
    type vector = array of int

    function init(v: vector) =
        v := vector[5] of 0

    function upto(v: vector, l: int) =
        for i := 0 to l do
            v[i] := i

    var v : vector := vector[5] of 1
in
    init(v) ;
    upto(v, 5)
end
```



# Type Systems

## dynamic & static typing

### machine code

- memory: no type information
- instructions: assume values of certain types

### dynamically typed languages

- typed values
- run-time checking & run-time errors

### statically typed languages

- typed expressions
- compile-time checking & compile-time errors

# Type Systems

## compatibility

### type compatibility

- value/expression: actual type
- context: expected type

### type equivalence

- structural type systems
- nominative type systems

### subtyping

- relation between types
- value/expression: multiple types

# Example: Tiger type compatibility

```
let
  type A = int
  type B = int
  type V = array of A
  type W = V
  type X = array of A
  type Y = array of B

  var a: A := 42
  var b: B := a
  var v: V := V[42] of b
  var w: W := v
  var x: X := w
  var y: Y := x

in
  y
end
```



# Type Systems

## record types

### record

- consecutively stored values
- fields accessible via different offsets

### record type

- fields by name, type, position in record
- structural subtyping: width vs. depth

```
type R1 = {f1 : int, f2 : int}
type R2 = {f1 : int, f2 : int, f3 : int}
type R3 = {f1 : byte, f2 : byte}
```

# Polymorphism

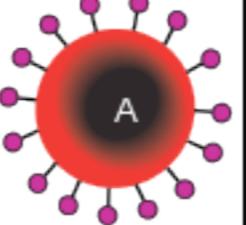
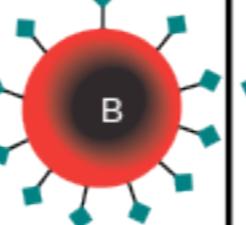
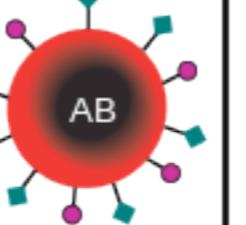
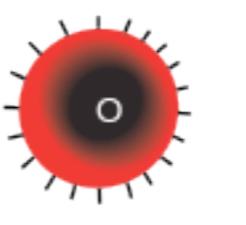
## biology



the occurrence of more than one form

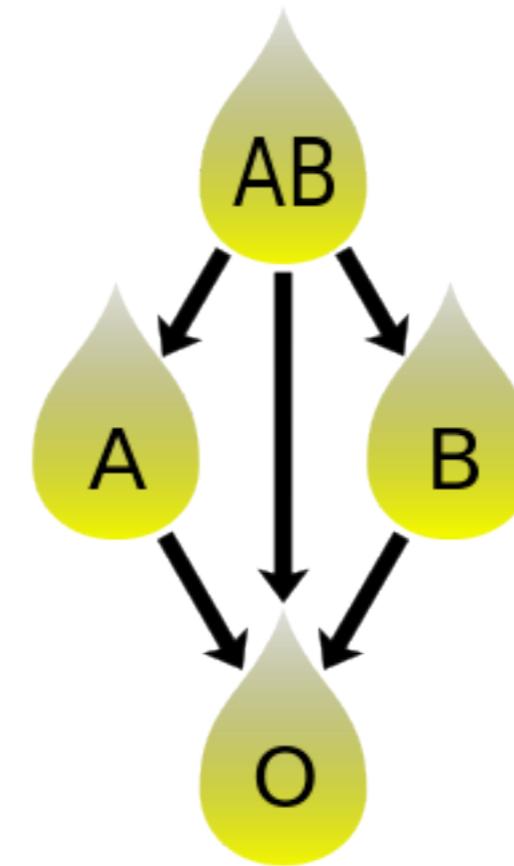
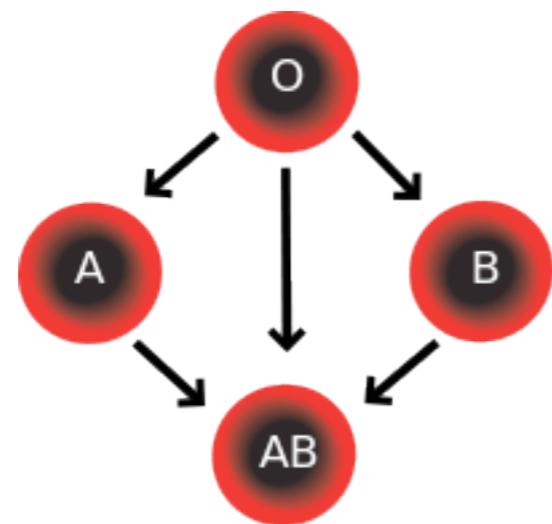
# Polymorphism

## biology

	Group A	Group B	Group AB	Group O
Red blood cell type				
Antibodies in Plasma			None	
Antigens in Red Blood Cell	A antigen	B antigen	A and B antigens	None

# Polymorphism

## biology



# Polymorphism programming languages

21 + 21

21.0 + 21.0

"foo" + "bar"

# Polymorphism programming languages

print(42)

print(42.0)

print("foo")

# Polymorphism programming languages

$21 + 21$

$21.0 + 21.0$

$21 + 21.0$

$21 + \text{"bar"}$

# Type Systems

## polymorphism

### ad-hoc polymorphism

#### overloading

- same name, different types, same operation
- same name, different types, different operations

#### type coercion

- implicit conversion

### universal polymorphism

#### subtype polymorphism

- substitution principle

#### parametric polymorphism

```
21 + 21
21.0 + 21.0
print(42)
print(42.0)
"foo" + "bar"
21 + "bar"
```

coffee break



# II

---

## object-oriented languages

---

# Modularity

## objects & messages

### objects

- generalisation of records
- identity
- state
- behaviour

### messages

- objects send and receive messages
- trigger behaviour
- imperative realisation: method calls

# Modularity

## classes

### classes

- generalisation of record types
- characteristics of objects: attributes, fields, properties
- behaviour of objects: methods, operations, features

### encapsulation

- interface exposure
- hide attributes & methods
- hide implementation

```
public class C {  
    public int f1;  
    private int f2;  
    public void m1() { return; }  
    private C m2(C c) { return c; }  
}
```

# Modularity inheritance vs. interfaces

## inheritance

- inherit attributes & methods
- additional attributes & methods
- override behaviour
- nominative subtyping

## interfaces

- avoid multiple inheritance
- interface: contract for attributes & methods
- class: provide attributes & methods
- nominative subtyping

```
public class C {  
    public int f1;  
    public void m1() {...}  
    public void m2() {...}  
}  
  
public class D extends C {  
    public int f2;  
    public void m2() {...}  
    public void m3() {...}  
}  
  
public interface I {  
    public int f;  
    public void m();  
}  
  
public class E implements I {  
    public int f;  
    public void m() {...}  
    public void m'() {...}  
}
```

# Type Systems

## polymorphism

ad-hoc polymorphism

overloading

- same method name, independent classes
- same method name, same class, different parameter types

overriding

- same method name, subclass, compatible types

universal polymorphism

subtype polymorphism

- inheritance, interfaces

parametric polymorphism

# Type Systems

## static vs. dynamic dispatch

### dispatch

- link method call to method

### static dispatch

- type information at compile-time

### dynamic dispatch

- type information at run-time
- single dispatch: one parameter
- multiple dispatch: more parameters

# Example: Java single dispatch

```
public class A {} public class B extends A {} public class C extends B {}

public class D {
    public A m(A a) { System.out.println("D.m(A a)"); return a; }
    public A m(B b) { System.out.println("D.m(B b)"); return b; }
}

public class E extends D {
    public A m(A a) { System.out.println("E.m(A a)"); return a; }
    public B m(B b) { System.out.println("E.m(B b)"); return b; }
}

A a = new A(); B b = new B(); C c = new C(); D d = new D(); E e = new E();
A ab = b;           A ac = c;           D de = e;

d. m(a); d. m(b); d. m(ab); d. m(c); d. m(ac);
e. m(a); e. m(b); e. m(ab); e. m(c); e. m(ac);
de.m(a); de.m(b); de.m(ab); de.m(c); de.m(ac);
```

# Type Systems

## variance

$A <: B$

$C ? D$

# Type Systems

## covariance

$$A <: B$$
$$C <: D$$

# Type Systems

## contravariance

$$A <: B$$
$$C :> D$$

# Type Systems

## invariance

$$A <: B$$
$$C = D$$

# Type Systems

## overriding

### methods

- parameter types
- return type

### covariance

- method in subclass
- return type: subtype of original return type

### contravariance

- method in subclass
- parameter types: supertypes of original parameter types

# Example: Java overloading vs. overriding

```
public class F {  
    public A m(B b) { System.out.println("F.m(B b)"); return b; }  
}  
  
public class G extends F {  
    public A m(A a) { System.out.println("G.m(A a)"); return a; }  
}  
  
public class H extends F {  
    public B m(B b) { System.out.println("H.m(B b)"); return b; }  
}  
  
A a = new A(); B b = new B(); F f = new F(); G g = new G(); H h = new H();  
A ab = b;  
  
f.m(b);  
g.m(a); g.m(b); g.m(ab);  
h.m(a); h.m(b); h.m(ab);
```

# Example: Java invariance

```
public class X {  
    public A a;  
    public A getA() { return a; }  
    public void setA(A a) { this.a = a; }  
}  
  
public class Y extends X {  
    public B a;  
    public B getA() { return a; }  
    public void setA(B a) { this.a = a; }  
}  
  
A a = new A(); B b = new B(); X y = new Y();  
  
y.getA(); y.setA(b); y.setA(a);  
  
String[] s = new String[3]; Object[] o = s; o[1] = new A();
```

# III

---

## summary

---

# Summary lessons learned

## imperative languages

- state & statements
- abstraction over machine code
- control flow & procedures
- types

## object-oriented languages

- objects & messages
- classes
- inheritance
- types

# Literature

[learn more](#)

## Imperative Languages

Carl A. Gunter: Semantics of Programming Languages: Structures and Techniques. MIT Press, 1992

Kenneth C. Louden: Programming Languages: Principles and Practice. Course Technology, 2002

## Object-Oriented Languages

Martin Abadi, Luca Cardelli: A Theory of Objects. Springer, 1996.

Kim B. Bruce: Foundations of Object-Oriented Programming Languages: Types and Semantics. MIT Press, 2002.

Timothy Budd: An Introduction to Object-Oriented Programming. Addison-Wesley, 2002.

# Outlook

## coming next

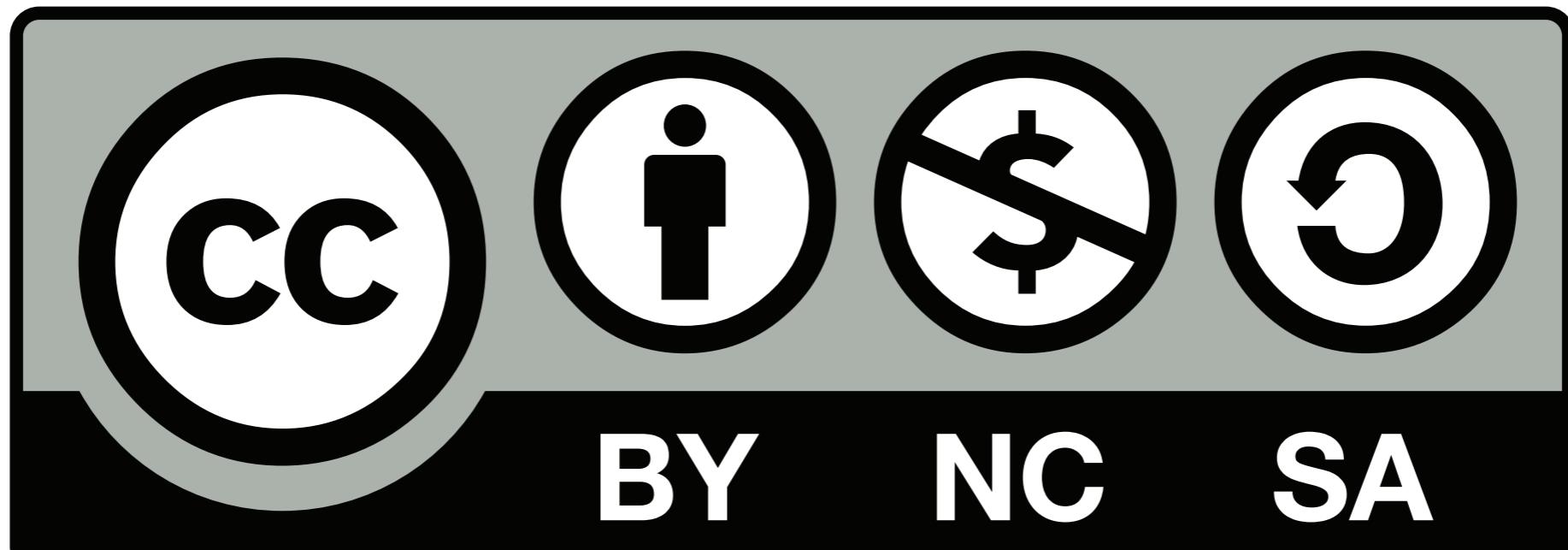
declarative language definition

- Lecture 1: Grammars and Trees
- Lecture 2: SDF and ATerms
- Lecture 3: Name Binding and Type Systems
- Lecture 4: Term Rewriting
- Lecture 5: Static Analysis and Error Checking
- Lecture 6: Code Generation

Lab Sep 12

- get used to Eclipse, Spoofax, and MiniJava





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