

## Geodesics

In Euclidean space, the shortest distance between two points is a straight line. A geodesic is a generalization of straight lines extended to curved spaces such as surface meshes. Crane et al. introduced the heat method in [1] to compute geodesic distances in an efficient and robust manner on any geometric discretization such as regular grids, polygonal meshes and point clouds.

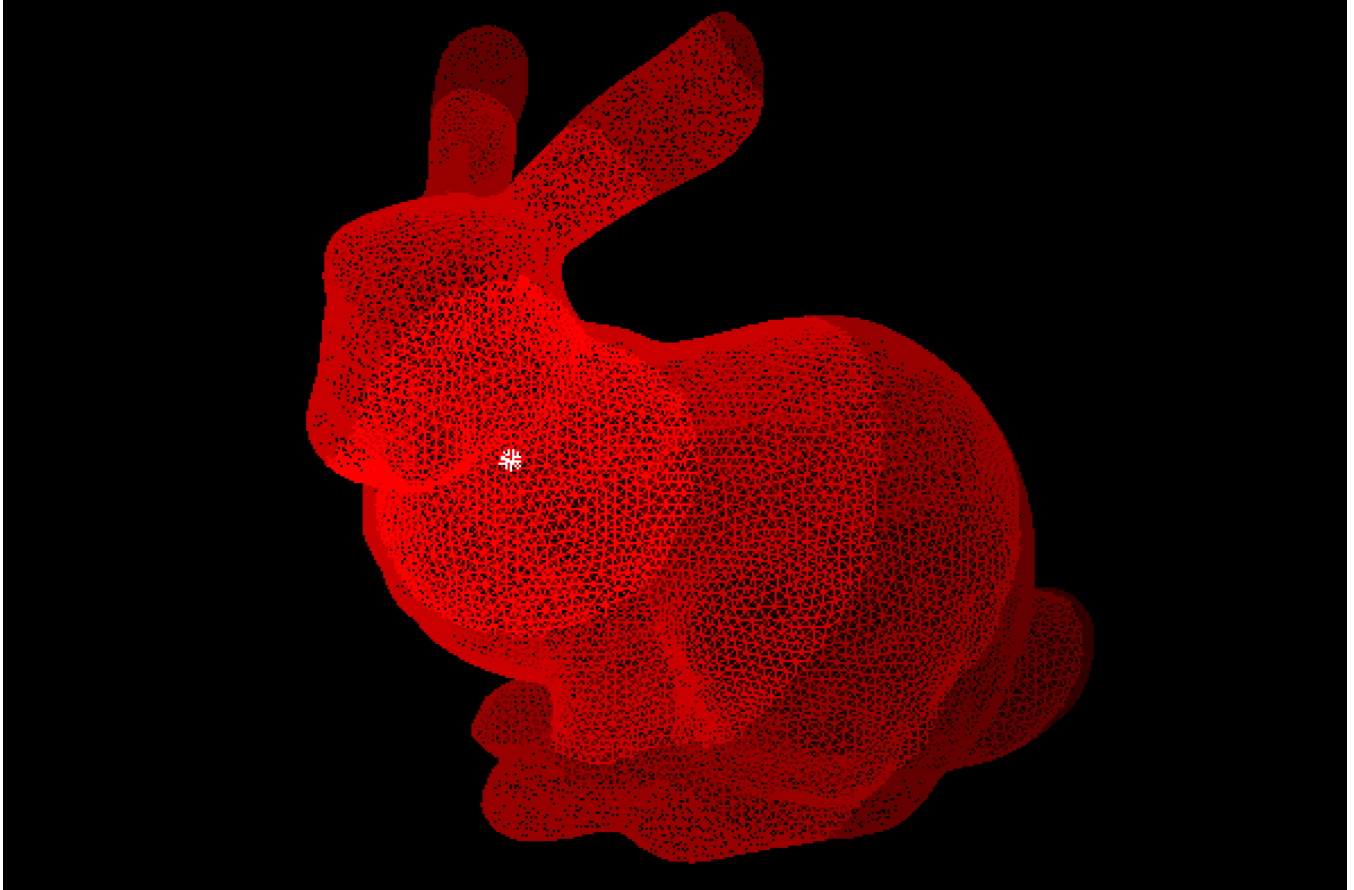


Figure 1. Geodesic distance from a single point on a surface

The method works in three steps:

1. Integrate the heat flow  $\mathbf{v}_t = \Delta \mathbf{v}$  for a fixed time  $t$ . The heat equation can be discretized as:

$$(\mathbf{Id} - t\Delta)\mathbf{v}(t + h) = \mathbf{v}(t)$$

where  $\mathbf{Id}$  is the identity matrix and  $\Delta$  is the Laplace Beltrami operator.  $\mathbf{v}(t)$  is initialized to zero except for the source vertex which is set to 1.  $t$  is chosen to be the square of the average edge length.

2. Compute the vector field  $\mathbf{X} = -\nabla \mathbf{v} / |\nabla \mathbf{v}|$  where  $\nabla \mathbf{v}$  is discretized as:

$$\nabla \mathbf{v} = (\sum_i \mathbf{v}_i (\mathbf{n} \times \mathbf{e}_i)) / 2A_f$$

Here  $A_f$  is the area of the face,  $\mathbf{n}$  is its unit normal,  $\mathbf{e}_i$  is the  $i$ th edge vector and  $\mathbf{v}_i$  is the value of  $\mathbf{v}$  at the opposite vertex (Figure 2).

3. Solve the Poisson equation  $\Delta \phi = \nabla \cdot \mathbf{X}$  where  $\nabla \cdot \mathbf{X}$  is computed as:

$$\nabla \cdot \mathbf{X} = (\sum_j \cot \theta_1 (\mathbf{e}_1 \cdot \mathbf{X}_j) + \cot \theta_2 (\mathbf{e}_2 \cdot \mathbf{X}_j)) / 2$$

See Figure 3.

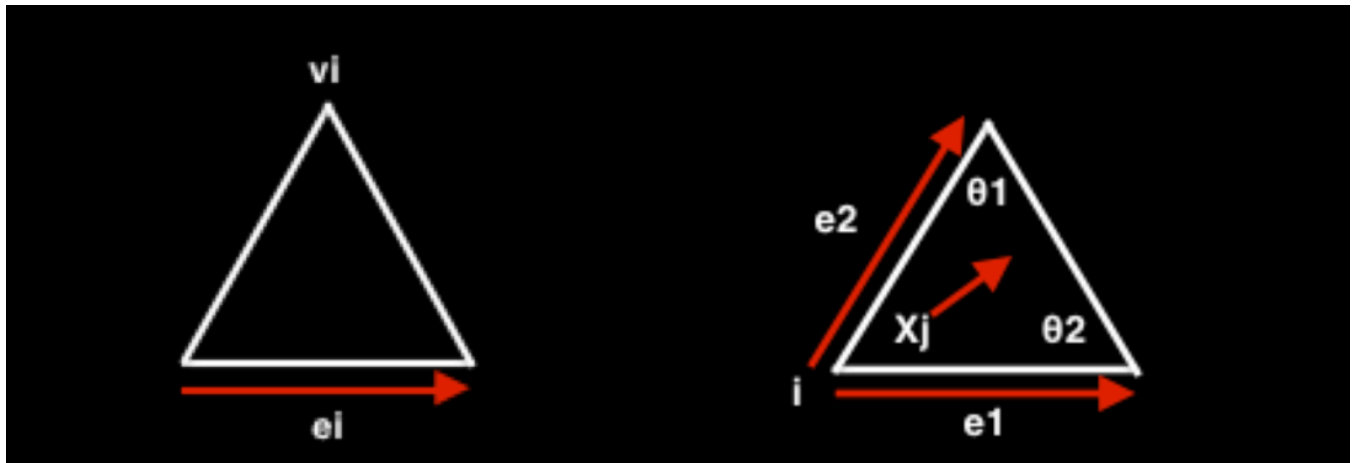


Figure 2

Figure 3

Implementation: <https://github.com/rohan-sawhney/geodesics>

[1] Crane et al. Geodesics in Heat: A New Approach to Computing Distance Based on Heat Flow