

Computer Project #1

Matlab Program

SDOF Equation of Motion

$$\ddot{x} + 2\zeta\omega\dot{x} + \omega^2x = f_i + \frac{\Delta f_i}{\Delta t}(t - t_i)$$

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Dynamics of Structures

Introduction:

For the computer program number #1, I used the MATLAB program. I generated a step-by-step exact solution of the forced SDOF equation of motion

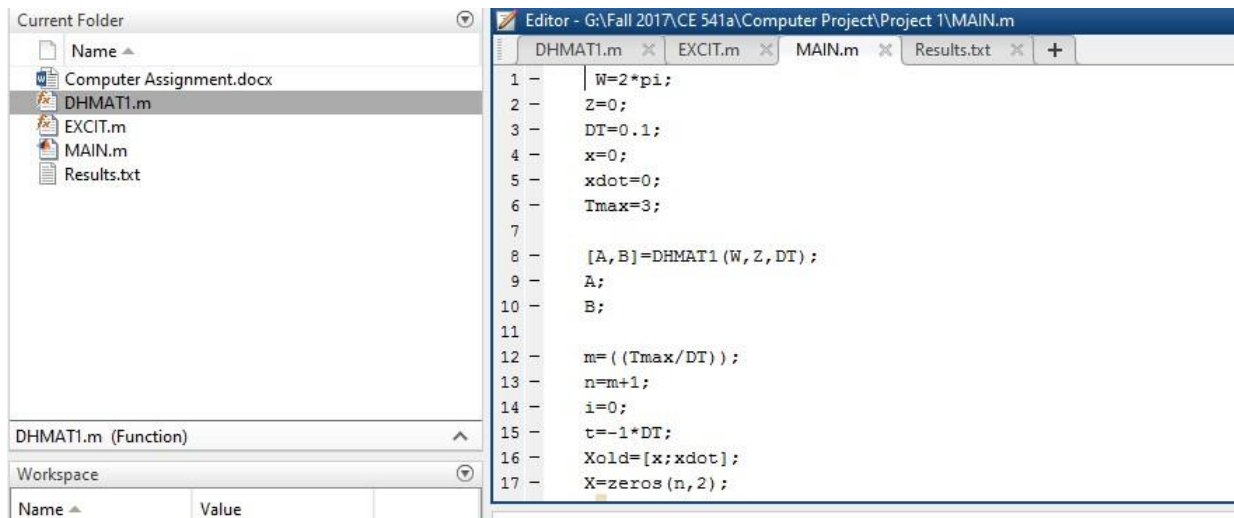
$$\ddot{x} + 2\zeta\omega\dot{x} + \omega^2x = f_i + \frac{\Delta f_i}{\Delta t}(t - t_i)$$

for any arbitrary excitation $f(x)$.

MATLAB:

When creating this program, created multiple files that work in accordance to one another to generate the output desired.

MAIN:



```

16 - Xold=[x;xdot];
17 - X=zeros(n,2);
18 - I=zeros(n,1);
19 - time=zeros(n,1);
20 - results=zeros(n,4);
21
22 - for k=0:m;
23 -     i=i+1;
24 -     t=t+DT;
25 -     [ F ] = EXCIT(t,DT);
26 -     Xnew=(A*Xold)-(B*F);
27
28 -     time(i,1)=t;
29 -     I(i,1)=i;
30 -     X(i,1)=Xold(1);
31 -     X(i,2)=Xold(2);
32

```

```

31 - X(i,2)=Xold(2);
32
33 - Xold(1)=Xnew(1);
34 - Xold(2)=Xnew(2);
35 - end
36
37 - X;
38 - time;
39 - results(:,1)=I;
40 - results(:,2)=time;
41 - results(:,3)=X(:,1);
42 - results(:,4)=X(:,2);
43
44 - Results=results';
45
46 - fileid=fopen('Results.txt','w');
47 - fprintf(fileid, 'Computer Project 1 Results \n \n \n');

```

I then created the Duhamel Integral Matrix Function file. I labeled it DHMAT1. I input all the settings from the given report. This was a new function file which has the code

“

```
function [A,B] = DHMAT1( W,Z,DT )
```

```

Wd=W*sqrt(1-(Z^2));
a11=exp(-Z*W*DT)*((Z/sqrt(1-Z^2))*sin(Wd*DT)+cos(Wd*DT));
a22=exp(-Z*W*DT)*(cos(Wd*DT)-((Z/sqrt(1-Z^2))*sin(Wd*DT)));
a12=((exp(-Z*W*DT))/Wd)*sin(Wd*DT);
a21=(-W/sqrt(1-Z^2))*(exp(-Z*W*DT)*sin(Wd*DT));
b11=exp(-Z*W*DT)*(((2*(Z^2)-1)/((W^2)*DT))+(Z/W)*(sin(Wd*DT)/Wd))+((2*Z/((W^3)*DT))+(1/W^2))*cos(Wd*DT))-((2*Z)/((W^3)*DT));
b12=-exp(-Z*W*DT)*(((2*(Z^2)-1)/((W^2)*DT))*sin(Wd*DT)/Wd)+((2*Z/((W^3)*DT))*cos(Wd*DT))+((2*Z)/((W^3)*DT))-(1/W^2);

```

```

b21=exp(-Z*W*DT)*(((2*(Z^2)-1)/(W^2)*DT)+(Z/W))*(cos(Wd*DT)-(Z/sqrt(1-(Z^2)))*sin(Wd*DT))-
((2*Z)/(W^3)*DT)+(1/W^2))*(Wd*sin(Wd*DT)+(Z*W*cos(Wd*DT)))+(1/(W^2)*DT
));
b22=-exp(-Z*W*DT)*(((2*(Z^2)-1)/(W^2)*DT))*(cos(Wd*DT)-(Z/sqrt(1-(Z^2)))*sin(Wd*DT))-
((2*Z)/(W^3)*DT))*(Wd*sin(Wd*DT)+(Z*W*cos(Wd*DT)))+(1/(W^2)*DT));
A=[a11 a12; a21 a22];
B=[b11 b12; b21 b22];

end    “

```

This function takes my given input (assigned in MAIN.m) and creates an output with the matrices A and B.

I then had to create a new function file which I called EXCIT, representing the exciting forces in this problem. The assignment required a unit step input where $f(t) = 1$; $0 \leq t$. So my code looks like this,

```

“
function [ F ] = EXCIT(t,DT)

F=zeros(2,1);
%fi is at time t
%fil is at t +dt
fi=1;
fil=1;
F=[fi;fil];

end    “

```

After creating these files, I created a MAIN file that runs all these files together. I labeled this file MAIN. This file takes the matrices created in DHMAT1, due to the original inputs from MAIN.m file and creates the equation to satisfy delta T in intervals all the way to Tmax. This code requires a loop; it also requires a way to stop, so when $T \geq T_{max}$ the loop ends. Here is my code,

```

“
%Input
W=2*pi;
Z=0;
DT=0.1;
x=0;
xdot=0;
Tmax=3;

[A,B]=DHMAT1(W,Z,DT);
A;
B;

m=(Tmax/DT);
n=m+1;

```

```

i=0;
t=-1*DT;
Xold=[x;xdot];
X=zeros(n,2);
I=zeros(n,1)
time=zeros(n,1);
results=zeros(n,4)

for k=0:m;
    i=i+1;
    t=t+DT;
    [ F ] = EXCIT(t,DT);
    Xnew=(A*Xold)-(B*F)

    time(i,1)=t;
    I(i,1)=i;
    X(i,1)=Xold(1);
    X(i,2)=Xold(2);

    Xold(1)=Xnew(1);
    Xold(2)=Xnew(2);
end

X;
time;
results(:,1)=I;
results(:,2)=time;
results(:,3)=X(:,1);
results(:,4)=X(:,2);

Results=results';

fileid=fopen('Results.txt','w');
fprintf(fileid, 'Computer Project 1 Results \n \n \n');
fprintf(fileid, 'I= %f \n T= %f \n Xi= %f \n Xdoti= %f \n \n ',Results);
fclose(fileid); ``

```

At the end of this file I created a new output file to open labeled Results.txt. This file arranges all the exact answers in I,T,Xi,Xdoti. This is what the output setting looks like,

Computer Project 1 Results

I= 1.000000	Xdoti= 0.093549
T= 0.000000	I= 3.000000
Xi= 0.000000	T= 0.200000
Xdoti= 0.000000	Xi= 0.017503
	Xdoti= 0.151365
I= 2.000000	
T= 0.100000	I= 4.000000
Xi= 0.004838	T= 0.300000

Xi= 0.033158
Xdoti= 0.151365

I= 5.000000
T= 0.400000
Xi= 0.045823
Xdoti= 0.093549

I= 6.000000
T= 0.500000
Xi= 0.050661
Xdoti= 0.000000

I= 7.000000
T= 0.600000
Xi= 0.045823
Xdoti= -0.093549

I= 8.000000
T= 0.700000
Xi= 0.033158
Xdoti= -0.151365

I= 9.000000
T= 0.800000
Xi= 0.017503
Xdoti= -0.151365

I= 10.000000
T= 0.900000
Xi= 0.004838
Xdoti= -0.093549

I= 11.000000
T= 1.000000
Xi= -0.000000
Xdoti= -0.000000

I= 12.000000
T= 1.100000
Xi= 0.004838
Xdoti= 0.093549

I= 13.000000
T= 1.200000
Xi= 0.017503
Xdoti= 0.151365

I= 14.000000
T= 1.300000
Xi= 0.033158
Xdoti= 0.151365

I= 15.000000
T= 1.400000
Xi= 0.045823
Xdoti= 0.093549

I= 16.000000
T= 1.500000
Xi= 0.050661
Xdoti= 0.000000

I= 17.000000
T= 1.600000
Xi= 0.045823
Xdoti= -0.093549

I= 18.000000
T= 1.700000
Xi= 0.033158
Xdoti= -0.151365

I= 19.000000
T= 1.800000
Xi= 0.017503
Xdoti= -0.151365

I= 20.000000
T= 1.900000
Xi= 0.004838
Xdoti= -0.093549

I= 21.000000
T= 2.000000
Xi= -0.000000
Xdoti= -0.000000

I= 22.000000
T= 2.100000
Xi= 0.004838
Xdoti= 0.093549

I= 23.000000
T= 2.200000
Xi= 0.017503
Xdoti= 0.151365

I= 24.000000
T= 2.300000
Xi= 0.033158
Xdoti= 0.151365

I= 25.000000
T= 2.400000
Xi= 0.045823
Xdoti= 0.093549

I= 26.000000
T= 2.500000
Xi= 0.050661
Xdoti= 0.000000

I= 27.000000
T= 2.600000

Xi= 0.045823
Xdoti= -0.093549

I= 28.000000
T= 2.700000
Xi= 0.033158
Xdoti= -0.151365

I= 29.000000
T= 2.800000
Xi= 0.017503
Xdoti= -0.151365

I= 30.000000
T= 2.900000
Xi= 0.004838
Xdoti= -0.093549

I= 31.000000
T= 3.000000
Xi= -0.000000
Xdoti= -0.000000