

# Rohan Banerjee

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## EDUCATION

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### Massachusetts Institute of Technology (MIT)

Cambridge, MA

Candidate for M.Eng. in Electrical Engineering and Computer Science, GPA: 5.0/5.0

June 2019

S.B. in Electrical Engineering and Computer Science, GPA: 4.9/5.0

June 2018

*Relevant Coursework:* Statistical Learning Theory and Applications, Robotics: Science and Systems, Bayesian Modeling and Inference, Machine Learning, Inference and Information, Design and Analysis of Algorithms, Computational Cognitive Science, Discrete-Time Signal Processing, Elements of Software Construction, Computation Structures

## EXPERIENCE

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### Massachusetts Institute of Technology

Cambridge, MA

*M.Eng. Researcher*

March 2018 – present

- Conducting research as a member of the DRL (Distributed Robotics Laboratory) group at CSAIL (Computer Science and Artificial Intelligence Laboratory)
- Developing learning algorithms for LIDAR-based rural road detection and intersection topology inference
- Developing rural environment simulation platform based on CARLA open-source driving simulator

### Autoliv

Lowell, MA

*Intern, Advanced Sensing Group*

June – August 2017

- Developed mapping algorithm for Lidar data (Velodyne VLP-64) using point cloud registration to maintain coherent point cloud history and advance lane/object tracking algorithms
- Investigated mapping/registration techniques with lower-resolution (Velodyne VLP-32) Lidar data to improve point cloud data resolution
- Investigated ego-motion estimation techniques with VLP-64 data to support vehicle localization

### Massachusetts Institute of Technology

Cambridge, MA

*SuperUROP Advanced Undergraduate Research Program*

September 2016 – May 2017

- Conducted research as member of the SLS (Spoken Language Systems) group at CSAIL (Computer Science and Artificial Intelligence Laboratory)
- Contributed to the development of a conversational robotic system that can acknowledge speaking subjects
- Converted offline Voice Activity Detector module into real-time streaming module
- Researched techniques for integrating visual face detection and audio source localization

### Northrop Grumman

San Diego, CA

*Intern, Systems Integration, Test & Evaluation*

June – August 2016

- Supported Systems Integration, Test & Evaluation for the Triton UAV (Unmanned Aerial Vehicle) program
- Developed Python test automation script for Triton test-bench landing test
- Co-developed SQL database for automated processing of Triton System Test Requests
- Improved upon Excel database for tracking flight requirements and test points
- Researched test automation methods for future modular hot-bench

## PROJECTS

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### MIT Unmanned Aerial Vehicle Team

Cambridge, MA

*Student Participant*

September 2014 – September 2017

- Developed refined 2D simulator of competition arena and agent dynamics for the International Aerial Robotics Competition as simulation team lead
- Managed development of computer vision gridline and circle detection Python programs as computer vision team lead
- Co-developed Python simulator of competition arena and contributed to UAV path planning algorithms as member of artificial intelligence team

## SKILLS

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**Programming languages:** Python, C++, Java, C, MATLAB, C#, Mathematica

**Other software:** Microsoft SQL Server, Microsoft Excel (VBA)