

Rohan Bandaru

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Intro

Computer engineering student with multidisciplinary interests. Internship experience in Robotics, Embedded Systems, Signal Processing, and Data Science. I learn quickly and independently.
Clearance: Inactive Secret

Education

Univ of California, Santa Barbara
B.S. Computer Engineering
B.S. Mathematics
Expected Graduation 2027
Engineering Honors

Skills

Languages

Python	●●●●●
C/C++	●●●●●
CMake	●●●●●
Java	●●●●●
R	●●●●●
MATLAB	●●●●●

Software

Git	●●●●●
Linux	●●●●●
Android	●●●●●
ROS 2	●●●●●
GDB	●●●●●
Arduino	●●●●●
Docker	●●●●●

Hardware

KiCAD	●●●●●
Onshape	●●●●●
Solidworks	●●●●●
Logic Analyzer	●●●●●
Oscilloscope	●●●●●
FDM 3D Printing	●●●●●
Soldering/Reflow	●●●●●
Shop Tools	●●●●●

Work Experience

- MIT Lincoln Labs** · Controls and Autonomy Intern · Lexington, MA Summer 2024
- Developed a high-fidelity simulation environment for UAVs and ground targets to enable rapid SITL testing of GNC and object tracking algorithms. Implemented a camera sensor model and fixed-wing autopilot. Migrated key software to ROS 2
 - Wrote control code for autonomous ground vehicles. Used Motion Capture system
- MITRE** · Embedded Security Intern · Bedford, MA Summer 2023
- Completed an electromagnetic side-channels and sensing project on MIPI CSI bus
 - Learned Digital Signal Processing and Software Defined Radio with little guidance
- CMU AirLab** · Student Researcher · Remote 05/2022 - 02/2023
- Added key features to the [PyPose Python library](#) for integrating state estimation and control algorithms with ML models. Coauthored a [publication in CVPR 2023](#)
- MITRE** · Technical Aide · Bedford, MA Summer 2022
- Improved logic analyzer automation and interoperability by creating internal tools and technical documentation. Gained experience with Python and Rev. Engineering
- Verseau Therapeutics** · Data Science Intern · Bedford, MA Summer 2021
- Analyzed macrophage expression profiles to assess the therapeutic benefit of novel antibodies for Immuno-oncology. Created their histopathology analysis pipeline
- UMass Lab for Perceptual Robotics** · Student Researcher · Remote Summer 2021
- Developed robot simulation tools for Reinforcement Learning experiments with Prof. Rod Grupen. Revamped legacy C codebase and participated in experiment design.

- MSEF (MA Science & Eng. Fair)** · Data Science Intern · Remote Summer 2021
- Informed High-School Science Fair organizers of trends in STEM participation, interest and demographics through [statistical analysis of previous years data](#)

Projects [\(rohanbandaru.github.io/site\)](#)

- DiceGrid CTF Challenge** 04/2024-Present
- Worked with DiceGang to create a [novel hacking challenge](#) where players must design inverters and supply to a small-scale power grid
 - Helped design game infrastructure (PCBs, Transmission Towers) and gameplay
 - Culminated in a 2-day event in NYC where 8 teams generated over 30 Wh
- Deep Learning for Visual Odometry** 2022
- Worked with a friend to create an [improved Deep VO algorithm and a robot test-bed](#)
 - Used AWS Sagemaker and S3 bucket to train on KITTI dataset augmented with virtual Unity game engine data. Evaluated using real robot in adverse conditions
 - Won the Grand Prize at the MA High School Science and Engineering Fair
- Model Rocket Guidance System** 2021-2023
- Created [small-scale inertial guidance capable of somewhat hitting a target apogee](#)
 - Created a custom PCB flight computer, robust actuation mechanism, quaternion orientation, PID controllers with aerodynamic feedforward, and LKF for altitude
 - Won 1st place at the MA Science and Engineering Fair and at the Mass.JAS Symposium. Presented at the 2022 American Junior Academy of Science conference
- FIRST Robotics (FTC 14039 IrRaTiONAl)** 2018-2022
- Software lead on a self-funded [FIRST Tech Challenge team of 7 friends](#)
 - Created custom localization, planning, and control. Implemented PIDF, Pure Pursuit, and Computer Vision algorithms in Java to run in real-time on Android
 - In 2020, we were MA and NJ state champs, with the highest offensive power rating in the world, fourth highest autonomous rating (Worlds cancelled due to COVID-19)

Activities

- IEEE Officer** · Project Lead · Santa Barbara, CA 05/2024 - Present
- Lead students in completing various hardware/software projects.