

Table of Contents

Abstract	vi
Acknowledgements	vii
Chapter 1 Introduction	1
1.1 Motivation	1
1.2 Contributions	4
Chapter 2 Background	5
2.1 Motion Model	5
2.2 Particle Filter	9
2.3 Particle smoothing	12
Chapter 3 Learning the motion model	14
3.1 Introduction	14
3.1.1 Work done so far on learning motion model	14
3.1.2 General Architecture	14
3.2 Particle Filtering and Smoothing	15
3.2.1 Particle Filtering	15
3.2.2 Particle Smoothing	15
3.3 Adapting Motion Model	15
3.3.1 Expectation Maximization	15
3.3.2 Parameter Estimation	15
Chapter 4 Landmarks extraction using Side Sonar Images	18
4.1 Introduction	18
4.1.1 Side Scan Sonar	18
4.1.2 Speeded Up Robust Features	18
4.2 Dynamic Landmarks	18
4.3 Motion Estimation using side sonar images	19

Draft Version – November 14, 2013 13:57

Chapter 5	Results	22
5.1	Adapting Motion Model	22
5.2	Motion estimation using side sonar images	26
Chapter 6	Conclusion	27
Bibliography	28