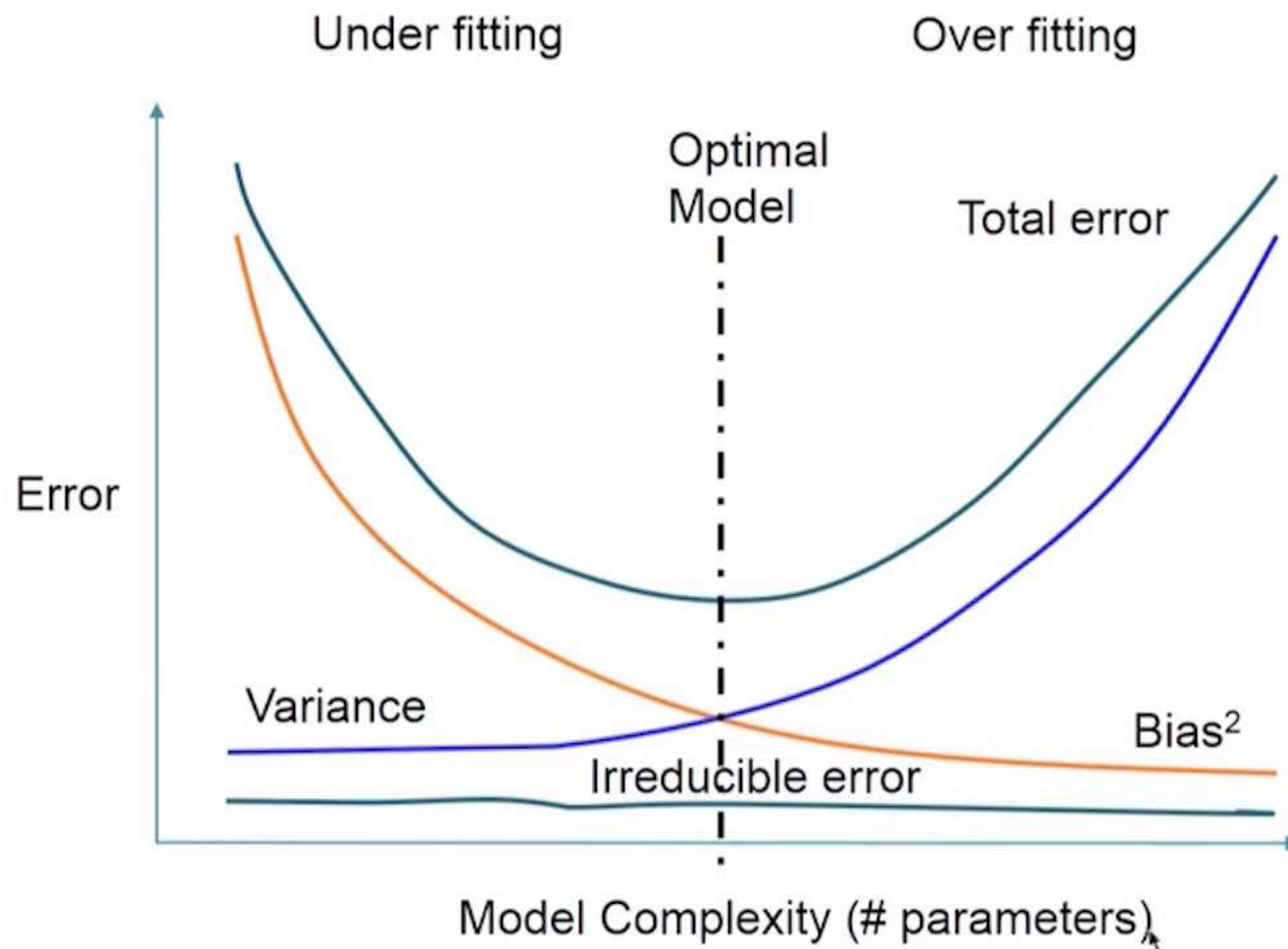


Motivation

youtube.com - To exit full screen, press Esc

- How to select the optimal number of meta or hyper-parameters of a model?
 - Number of principal components in principal components analysis
 - Number of clusters in K-means clustering
 - Number of terms ' n ' in polynomial or nonlinear regression
$$y = \beta_0 + \beta_1 x + \beta_2 x^2 + \dots \beta_n x^n$$
(equivalent to multilinear regression by treating $x, x^2, \dots x^n$ as different variables)
- MSE of **training data set not useful as a measure**
 - MSE will decrease with increasing number of parameters (can be reduced to zero)
- Use cross validation on **a validation data set** to determine optimal number of parameters

Bias-Variance trade-off on test data set



Training and Validation data sets

- For large data sets divide data set into training data set ($\sim 70\%$ of the samples) and remaining validation/test data
 - Training set: $\{(\mathbf{x}_1, y_1); (\mathbf{x}_2, y_2); \dots; (\mathbf{x}_n, y_n)\}$
 - Test set: $(\mathbf{x}_{0,i}, y_{0,i}) : i = 1 \dots n_t$ observations

- Training error rate

$$MSE_{Training} = \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{x}_i^T \hat{\beta})^2$$

- Test error rates

$$MSE_{Test} = \frac{1}{n_t} \sum_{i=1}^n (y_{0,i} - \mathbf{x}_{0,i}^T \hat{\beta})^2$$

Validation Set Approach

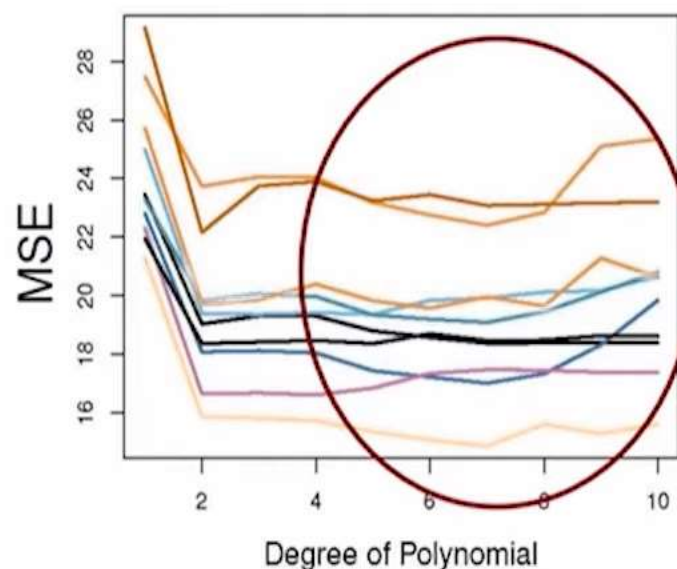
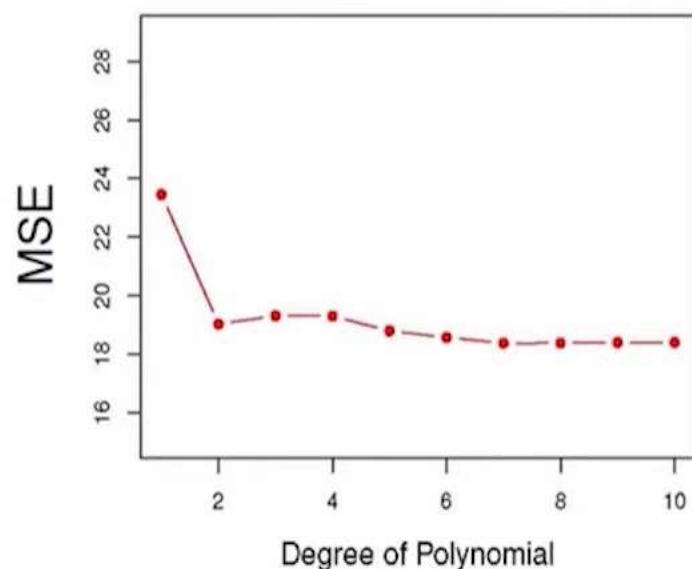
- Enough data: (1) Training set, (2) Validation set, and (3) Test set
- Not enough data: Generate validation sets from a training set
- Validation set approach: Divides (often randomly) the training set into two parts

	1 2 3 4	n
• A training set	1 2 3 4	n_t
• A validation set (or hold-out set)	1 2 3 4	n_v

- Use training set, to fit the model
- Use validation set, to predict validation set errors
Provides an estimate of test error rates

Validation Set Approach: Example

- Example: $\text{mileage} \sim \text{horsepower}^1$ (> 300 data points on horsepower of automobiles and mileage)
- Polynomial Model: $\text{mileage} \sim f(\text{horsepower})$



High variability in estimates of test error

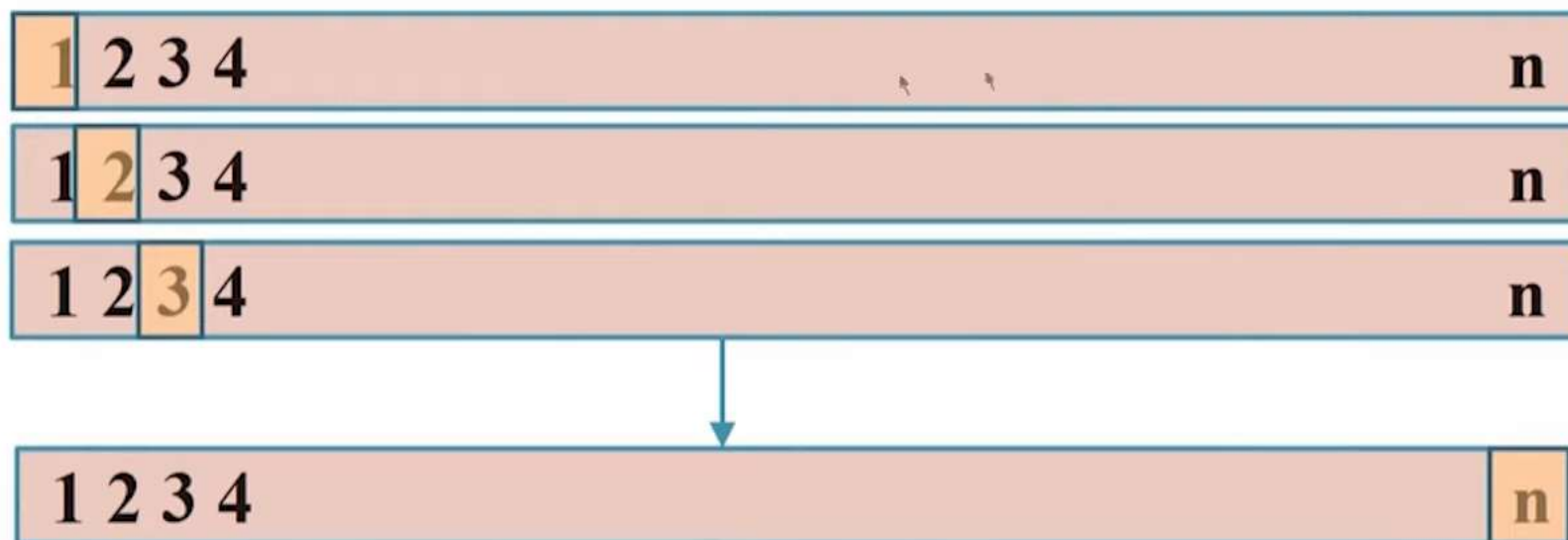
¹Tibshirani et al (2013)

Sampling for small data sets

- Validation of models by repeatedly drawing random samples from a training set
 - Validation set (random sampling)
 - K-fold cross validation
 - Bootstrap
- Objective: Predict the performance of model(s) on the validation/test sets (drawn from training data)
- Resampling methods useful for data scarce situations

Leave-one-out-cross-validation (LOOCV)

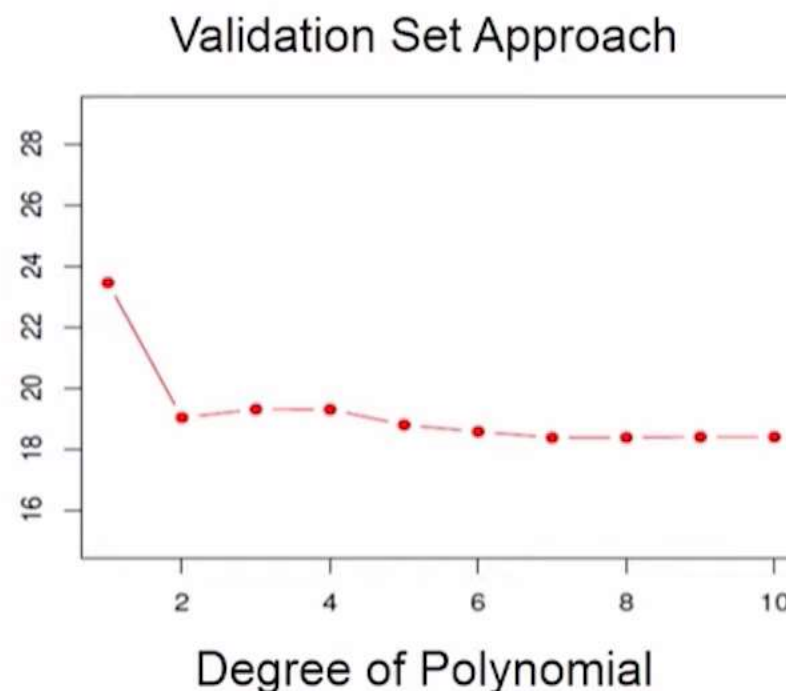
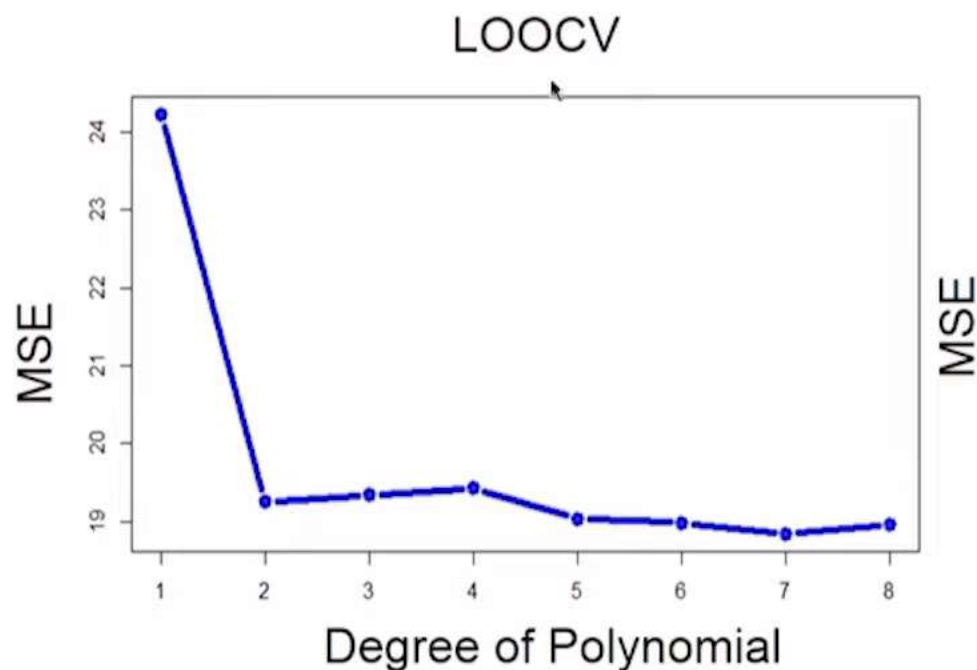
- Build model using $(n-1)$ samples and predict the response (y_i) for *the remaining sample*



$$CV_1 = \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{x}_i^T \hat{\boldsymbol{\beta}}^{(1)})^2$$

LOOCV: Example

- Example: $\text{mileage} \sim \text{horsepower}^1$
- Nonlinear Model: $\text{mileage} \sim f(\text{horsepower})$

¹Tibshirani et al (2013)

LOOCV

- Leave-one-out-cross-validation (LOOCV)
- Advantages
 - Far less bias comparison to the validation set approach
Training set contains $(n-1)$ observations each iteration
 - Yield the same results
No randomness in the training/validation set splits
 - Does not overestimate the test error rate as much as the validation set approach
- Disadvantages
 - Expensive to implement due to fitting happens n times
 - It may select a model of excessive size (more variables) than the optimal model

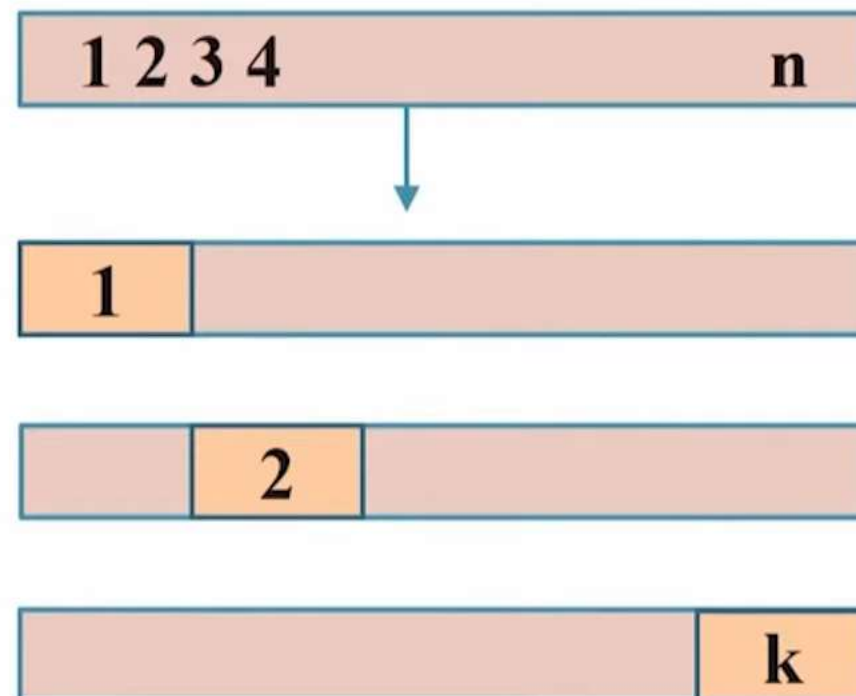
k-Fold Cross Validation

- Training data into k disjoint samples of equal size,

$$Z_1, Z_2, \dots, Z_k$$

- For each validation sample Z_i
 - Use remaining data to fit the model
 - Predict the response for the validation sample Z_i and compute mean square error (MSE_i),
 - Repeat for all k samples
 - The k -fold CV

$$CV_{(k)} = \frac{1}{k} \sum_{i=1}^k MSE_i$$



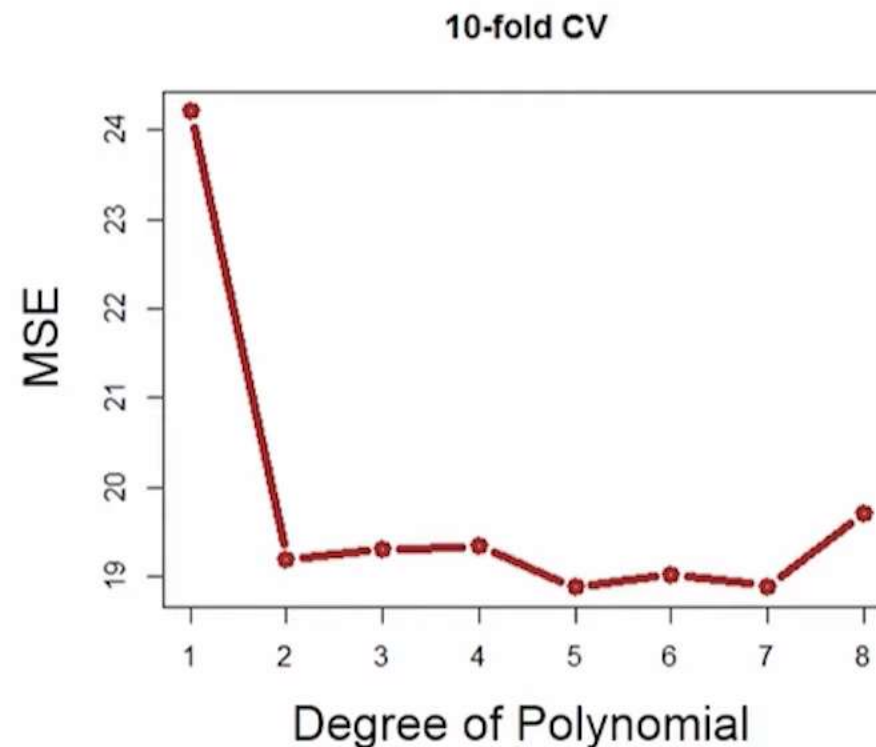
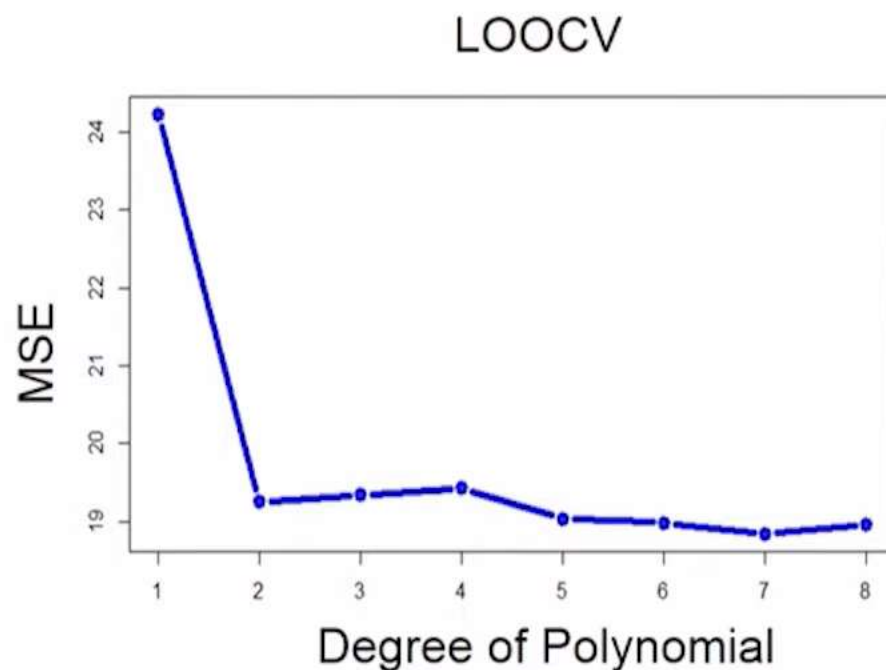
k-fold Validation

- For $k=n$, Leave-one-out-cross-validation (LOOCV)
- In practice, $k=5$ or 10 is taken,
- Less computation cost
- For computationally intensive learning methods
 - LOOCV fits the model n times
 - k -fold CV fits the model k times



k-fold CV: Example

- Example: $\text{mileage} \sim \text{horsepower}^1$
- Nonlinear Model: $\text{mileage} \sim f(\text{horsepower})$

¹Tibshirani et al (2013)