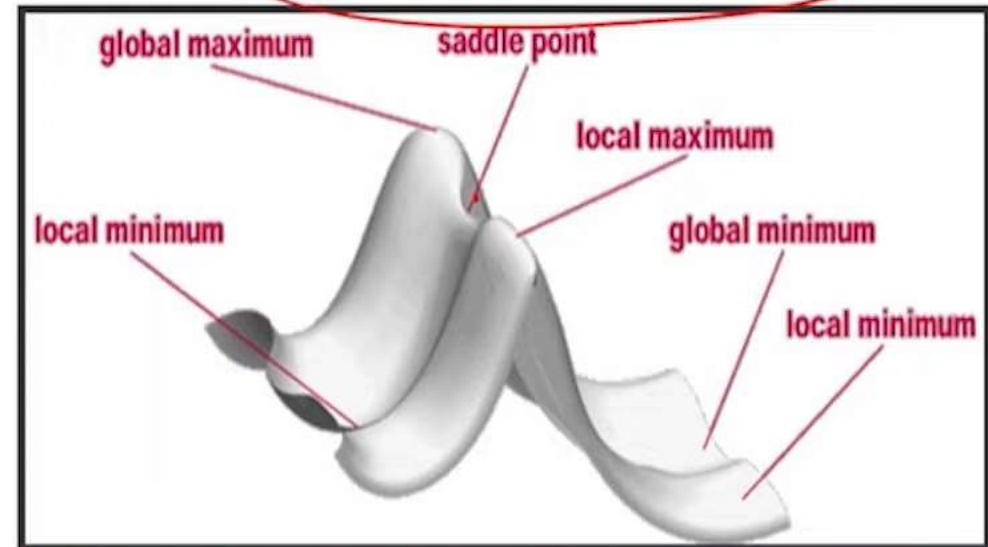


# Unconstrained multivariate optimization - Directional search

- Aim is to reach the bottom most region
- Directions of descent
- Steepest descent
- Sometimes we might even want to climb the mountain for better prospects to get down further



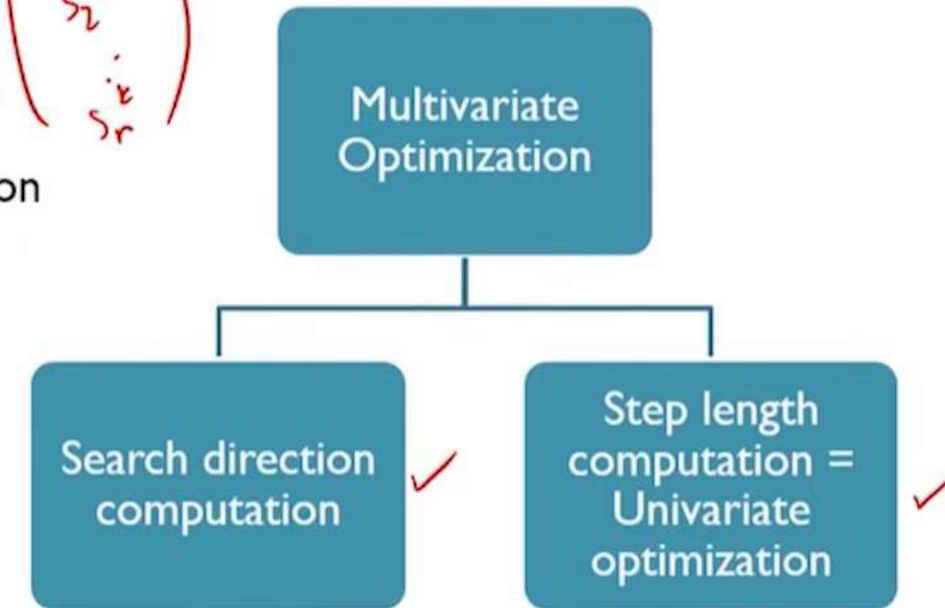
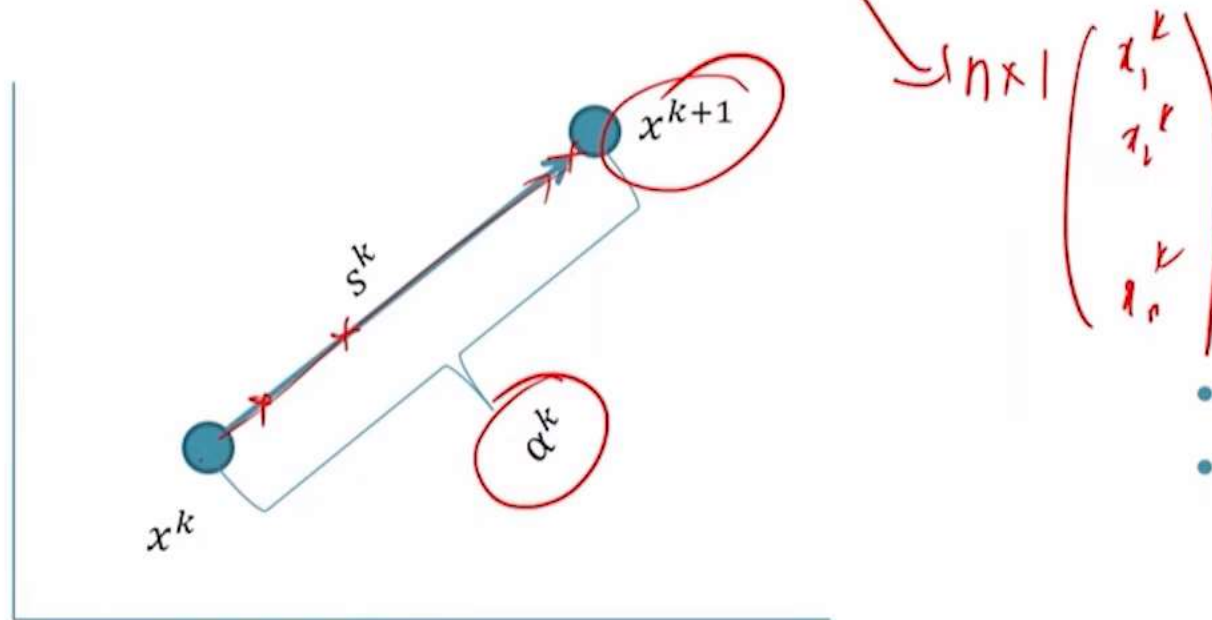
# Unconstrained multivariate optimization - Descent direction and movement

## • Iterative

$$x^{k+1} = x^k + \alpha^k s^k$$

Starting point      Step length      Search direction

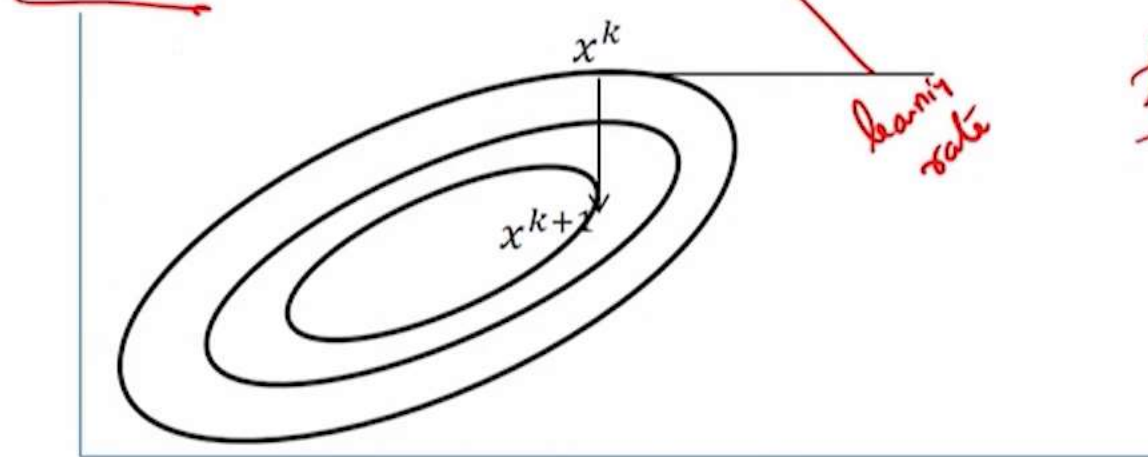
Handwritten notes:  $\alpha^k$  is a scalar,  $s^k$  is an  $n \times 1$  vector.



- In ML techniques, this is called as the learning rule
- In neural networks
  - Back-propagation algorithm
  - Same gradient descent with application of chain rule
- In clustering
  - Minimization of an Euclidean distance norm

# Steepest descent and optimum step size

- Minimize  $f(x_1, x_2, \dots, x_n) = f(x)$
- Steepest descent**
  - At iteration  $k$  starting point is  $x^k$
  - Search direction  $s^k = \text{Negative of gradient of } f(x) = -\nabla f(x^k)$
  - New point is  $x^{k+1} = x^k + \alpha^k s^k$  where  $\alpha^k$  is the value of  $\alpha$  for which  $f(x^{k+1}) = f(\alpha)$  is a minimum (univariate minimization)



$$\nabla f(x) = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix} = \begin{pmatrix} g_1(x) \\ \vdots \\ g_n(x) \end{pmatrix}$$

Handwritten notes:  $\nabla f(x^k) = -\nabla f(x^k)$ ,  $s^k = -\nabla f(x^k)$

$$f(x^k + \alpha s^k)$$

$$x^1 = x^0 + \alpha^0 s^0$$

$$x^2 = x^1 + \alpha^1 s^1$$

Handwritten notes:  $\alpha = \alpha_{\text{fixed}}$ ,  $x^0$ ,  $x^1$ ,  $x^2$