Results: confusion matrix

```
# confusion matrix.
   > confusionMatrix(crashTest_1_TEST$LogisPred,crashTest_1_TEST$CarType)
   Confusion Matrix and Statistics
              Reference
   Prediction Hatchback SUV
     Hatchback
     SUV
                  Accuracy: 0.95
                    95% CI: (0.7513, 0.9987)
       No Information Rate: 0.5
       P-Value [Acc > NIR] : 2.003e-05
                     Kappa : 0.9
    Mcnemar's Test P-Value : 1
               Sensitivity: 1.0000
               Specificity: 0.9000
            Pos Pred Value: 0.9091
            Neg Pred Value: 1.0000
                Prevalence: 0.5000
            Detection Rate: 0.5000
      Detection Prevalence: 0.5500
         Balanced Accuracy: 0.9500
          'Positive' Class : Hatchback
```



Confusion matrix

		True con	True condition	
	Total population	Condition positive	Condition negative	
Predicted condition	Predicted condition positive	True positive, Power	False positive, Type I error	
	Predicted condition negative	False negative, Type II error	True negative	

Source: https://en.wikipedia.org/wiki/Receiver operating characteristic



Terminology

- $TP \rightarrow \text{true positives}$, $TN \rightarrow \text{true negatives}$,
- ∘ FP → false positives, FN → false negatives N = TP + TN + FP + FN
- TP Correct identification of positive labels
- TN Correct identification of negative labels
- FP Incorrect identification of positive labels
- FN Incorrect identification of negative labels



- Accuracy: Overall effectiveness of a classifier
 - \circ A = $\frac{TP+TN}{N}$
 - Maximum value that accuracy can take is 1
 - This happens when the classifier exactly classifies two groups (i.e, FP = 0 and FN = 0)
- Remember
 - Total number of true positive labels = TP+FN
- Similarly
 - Total number of true negative labels = TN+FP



 Sensitivity: Effectiveness of a classifier to identify positive labels

$$\circ S_e = \frac{TP}{TP + FN}$$

- Specificity: Effectiveness of a classifier to identify negative labels
 - $\circ S_p = \frac{TN}{FP + TN}$
- Both S_e and S_p lie between 0 and 1, 1 is an ideal value for each of them
- Balanced accuracy
 - BA = (sensitivity + specificity)/2



 Prevalence: How often does the yes condition actually occur in our sample

$$P = \frac{TP + FN}{N}$$

 Positive predictive value: Proportion of correct results in labels identified as positive

$$PPV = \frac{(sensitivity * prevalence)}{((sensitivity * prevalence) + ((1-specificity)*(1-prevalence)))}$$

 Negative prediction value: Proportion of correct results in labels identified as negative

$$\circ \ NPV \ = \frac{specificity*(1-prevalence)}{(((1-sensitivity)*prevalence)+((specificity)*(1-prevalence)))}$$

Detection rate:

$$\circ DR = \frac{TP}{N}$$

Detection prevalence: prevalence of predicted events

$$\circ DP = \frac{TP + FP}{N}$$

- The Kappa statistic (or value) is a metric that compares an observed accuracy with an expected accuracy (random chance)
- $Kappa = \frac{observed\ accuracy expected\ accuracy}{1 expected\ accuracy}$



Observed accuracy

$$\circ OA = \frac{a+d}{N}$$

Expected accuracy

$$\circ EA = \frac{(a+c)(a+b)+(b+d)(c+d)}{N}$$

• Kappa =
$$\frac{\frac{(a+d)}{N} - \left(\frac{(a+c)(a+b) + (b+d)(c+d)}{N}\right)}{\left(1 - \left(\frac{(a+c)(a+b) + (b+d)(c+d)}{N}\right)\right)}$$

• Where a, b, c and d are TP, FP, FN and TN respectively



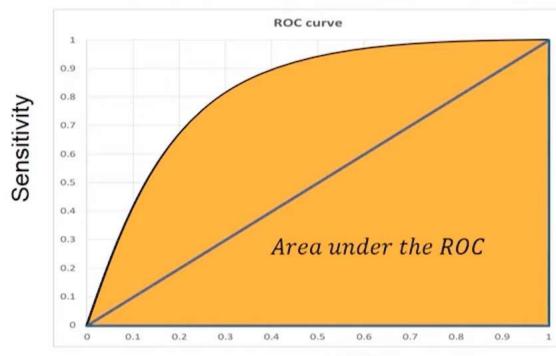
Results: confusion matrix

```
# confusion matrix.
   > confusionMatrix(crashTest_1_TEST$LogisPred,crashTest_1_TEST$CarType)
   Confusion Matrix and Statistics
              Reference
   Prediction Hatchback SUV
     Hatchback
     SUV
                  Accuracy: 0.95
                    95% CI: (0.7513, 0.9987)
       No Information Rate: 0.5
       P-Value [Acc > NIR] : 2.003e-05
                     Kappa : 0.9
    Mcnemar's Test P-Value : 1
               Sensitivity: 1.0000
               Specificity: 0.9000
            Pos Pred Value: 0.9091
            Neg Pred Value : 1.0000
                Prevalence: 0.5000
            Detection Rate: 0.5000
      Detection Prevalence: 0.5500
         Balanced Accuracy: 0.9500
          'Positive' Class : Hatchback
```



ROC

- ROC –An acronym for Receiver Operating Characteristics
- Originally developed and used in signal detection theory
- ROC graph:
 - Sensitivity as a function of specificity
 - sensitivity (Y-axis) and
 1 -specificity (X-axis)



1 -specificity

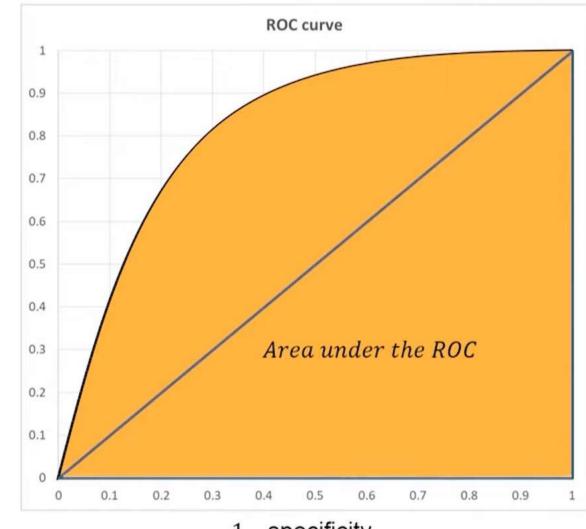




- ROC can be used to
 - See the classifier performance at different threshold levels (from 0 to 1)
 - AUC- Area under the ROC
 - An area of 1 represents a perfect test; an area of 0.5 represents a worthless model.

Sensitivity

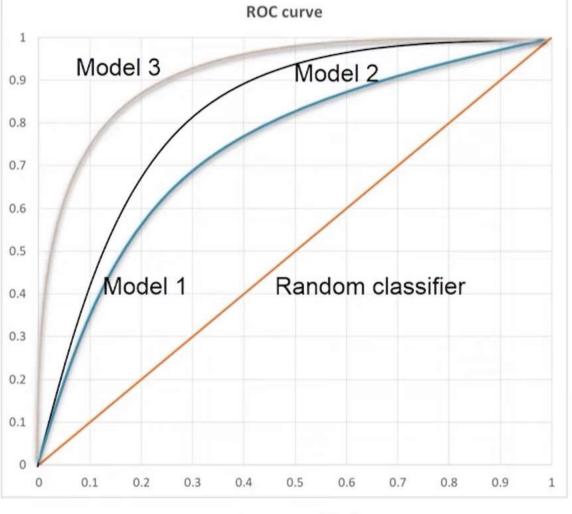
- $\cdot .90 1 = excellent$
- .80 .90 = good
- .70 .80 = fair
- .60 .70 = poor
- AUC < 0.5, check whether your labels are marked in opposite





- ROC can be used to
 - Compare different classifiers at one threshold or overall threshold levels
 - Performance
 - Model 3 > Model 2 > Model 1





1 -specificity