Rohan Chandra

I am a final year PhD candidate at University of Maryland, College Park advised by Prof. Dinesh Manocha. My research interests lie broadly in autonomous driving and multi-agent systems.

Education

Ph.D. in Computer Science

CGPA: 3.8/4.0

M.S. in Computer Science

CGPA: 3.8/4.0

B.Tech. in ECE

University of Maryland, College Park
August 2018 - Present

University of Maryland, College Park

August 2016 - May 2018

Delhi Technological University, New Delhi

August 2012 - July 2016

Internships

NVIDIA Santa Clara, CA

Applied Research Intern, Autonomous Driving (Prediction)

Summer'21 (Remote)

Improved ego-vehicle trajectory and behavior prediction via ego-goal conditioning by upto 50%. Improved navigation in particularly hard cases like U-turns and left turns—cases that the model struggled with.

Scholarships

- (2021) selected as part of the 2020-2021 cohort (22 selected out of approximately 5,000 doctoral students at UMD) of Future Faculty Fellows.
- o (2020) Awarded the Summer Research Fellowship by The Graduate School, UMD.
- (2018) Recognized as a top writer on Quora with over 1 million views and 385 shares on my posts and answers.

Publications

Autonomous Driving and Multi-Agent Systems

- 1. (In **WACV 2022**) Tianrui Guan, Jun Wang, Shiyi Lan, **Rohan Chandra**, Zuxuan Wu, Larry Davis, Dinesh Manocha. M3DeTR: Multi-representation, Multi-scale, Mutual-relation 3D Object Detection with Transformers.
- 2. (In RAL 2022) Angelos Mavrogiannis, Rohan Chandra, Dinesh Manocha. B-GAP: Behavior-Guided Action Prediction for Autonomous Navigation.
- 3. (In ICRA 2022) Rohan Chandra, Mingyu Wang, Mac Schwager, Dinesh Manocha. Game-Theoretic Planning for Risk-Aware Human Drivers.
- 4. (**Under Review**) Rohan Chandra, Mridul Mahajan, Rahul Kala, Rishitha Palugulla, Chandrababu Naidu, Alok Jain, and Dinesh Manocha. METEOR: A Massive Dense & Heterogeneous Behavior Dataset for Autonomous Driving.
- 5. (In ICRA/RAL 2022) Rohan Chandra, Dinesh Manocha. GamePlan: Game-Theoretic Multi-Agent Planning with Human Drivers at Intersections, Roundabouts, and Merging.
- 6. (In **IEEE Transactions on ITS 2021**) **Rohan Chandra**, Aniket Bera, Dinesh Manocha. Using Graph-Theoretic Machine Learning to Predict Human Driver Behavior.
- 7. (In ICCV 2021) Divya Kothandaraman, Rohan Chandra, Dinesh Manocha. SS-SFDA: Self-Supervised Source-Free Domain Adaptation for Road Segmentation in Hazardous Environments.
- 8. (In ICCV 2021) Divya Kothandaraman, Rohan Chandra, Dinesh Manocha. BoMuDA: Boundless Multi-Source Domain Adaptive Segmentation in Unconstrained Environments.
- 9. (In IROS 2020) Rohan Chandra, Uttaran Bhattacharya, Trisha Mittal, Aniket Bera, Dinesh Manocha. CMetric: A Driving Behavior Measure Using Centrality Functions.
- 10. (In ICRA 2020) Rohan Chandra, Uttaran Bhattacharya, Trisha Mittal, Xiaoyu Li, Aniket Bera, Dinesh Manocha. GraphRQI: Classifying Driver Behaviors Using Graph Spectrums.
- 11. (In IROS/RAL 2020) Rohan Chandra, Tianrui Guan, Srujan Panuganti, Trisha Mittal, Uttaran Bhattacharya, Aniket Bera, Dinesh Manocha. Forecasting Trajectory and Behavior of Road-Agents using Spectral Clustering in Graph-LSTMs.
- 12. (In ICRA 2020) Rohan Chandra, Uttaran Bhattacharya, Tanmay Randhavane, Aniket Bera, and Dinesh Manocha. RoadTrack: Tracking Road Agents in Dense and Heterogeneous Environments.
- 13. (In **RAL/ICRA 2020**) AJ Sathyamoorthy, Jing Liang, Utsav Patel, Tianrui Guan, **Rohan Chandra**, Dinesh Manocha. Densecavoid: Real-time navigation in dense crowds using anticipatory behaviors.
- 14. (In **CSCS 2019**) **Rohan Chandra**, Uttaran Bhattacharya, Christian Roncal, Aniket Bera, Dinesh Manocha. RobustTP: End-to-End Trajectory Prediction for Heterogeneous Road-Agents in Dense Traffic with Noisy Sensor Inputs.

- 15. (In **IROS 2019**) **Rohan Chandra**, Uttaran Bhattacharya, Aniket Bera, and Dinesh Manocha. DensePeds: Pedestrian Tracking in Dense Crowds Using Front-RVO and Sparse Features.
- 16. (In **CVPR 2019**) **Rohan Chandra**, Uttaran Bhattacharya, Aniket Bera, and Dinesh Manocha. TraPHic: Predicting Trajectories of Road-Agents in Dense and Heterogeneous Traffic.
- 17. (**Under Review**) Tianrui Guan, Divya Kothandaraman, **Rohan Chandra**, Dinesh Manocha. GANav: Group-wise Attention Network for Classifying Navigable Regions in Unstructured Outdoor Environments.

Affective Computing

- 1. (In (ACM'MM), 2020) Trisha Mittal, Uttaran Bhattacharya, Rohan Chandra, Aniket Bera, Dinesh Manocha. "Emotions Don't Lie: An Audio-Visual Deepfake Detection Method Using Affective Cues".
- 2. (In **ECCV 2020**) Uttaran Bhattacharya, Christian Roncal, Trisha Mittal, **Rohan Chandra**, Aniket Bera, Dinesh Manocha. "Take an Emotion Walk: Perceiving Emotions from Gaits Using Hierarchical Attention Pooling and Affective Mapping".
- 3. (In **AAAI 2020**(oral)) Trisha Mittal, Uttaran Bhattacharya, **Rohan Chandra**, Aniket Bera, Dinesh Manocha. "M3ER: Multiplicative Multimodal Emotion Recognition Using Facial, Textual, and Speech Cues."
- 4. (In **AAAI 2020**) Uttaran Bhattacharya, Trisha Mittal, **Rohan Chandra**, Tanmay Randhavane, Aniket Bera, Dinesh Manocha. "STEP: Spatial Temporal Graph Convolutional Networks for Emotion Perception from Gaits."
- 5. (In **CVPR 2020**) Trisha Mittal, Pooja Guhan, Uttaran Bhattacharya, **Rohan Chandra**, Aniket Bera, Dinesh Manocha. "EmotiCon: Context-Aware Multimodal Emotion Recognition using Frege's Principle".

Teaching Experience

CMSC 250: Discrete Mathematics

Taught by Jason Filippou

CMSC 131: Introduction to Programming

Taught by Fawzi Emad

CMSC 417: Computer Networks

Taught by Ashok Agrawala

University of Maryland, College Park Fall'17 and Spring'18

University of Maryland, College Park

Spring'17

University of Maryland, College Park

Fall'16

Professional Activities

- Invited Talks:
 - Georgia Tech
 - UPenn
 - WACV'22: Hazard Perception in Intelligent Vehicles (HPIV) Workshop.
 - RSS'21: Perception and Control for Autonomous Navigation in Crowded, Dynamic Environments Workshop.
 - Maryland Robotics Center Student Seminar.
- Invited to serve on the program committee of the ICCV'21 Workshop on Multi-Agent Interaction and Relational Reasoning.
- Served as a reviewer for the following conferences and journals: CVIU'18 -'20, IJCAI'19, CoRL'19, CVPR'20 -'21, AAAI'20 -'21, ICRA'20 -'21, IROS'19 -'20, RAL'20 -'21, NeurIPS'20, ICLR'21, ICML'21, ICCV'21, RSS'22.
- o 2017-2018: Served as a reviewer on the UMD CS graduate admissions committee.

Diversity and Inclusion

- Al4ALL 2021: Led a 2 week project for 5-6 high school students. Introduced them to various aspects of machine learning and artificial intelligence.
- **NYU AI School 2021:** Teaching basic machine learning and programming and discussing a career in machine learning research with students from underrepresented minorities.
- AI4ALL 2020: Teaching basic machine learning and programming and discussing a career in machine learning research with students from underrepresented minorities.