ANALYSIS REPORT

PSEUDOCODE

```
Functions Used:
   1. readwritefile()
   2. greedy_SeparatingPoints()
   3. checksplitH()
   4. checksplitV()
Create:
   1. List vert
   2. List horz
   3. List solution
   4. int XC[], YC[]
Function readwritefile()
   1. File folder=new File("input")
   2. File[] listofFiles= folder.listFiles()
   3. for(i=0 to listofFiles.length)
   4.
              if(file.isFile())
   5.
                      String filename= file.getName()
              numlines=0
                      br= new BufferedReader(new
   6.
                      FileReader("input/"+filename);
   7.
                      line= br.readLine();
                      numlines: get number of lines from first line of file
   8.
   9.
                      Create array XC[], YC[] of length numlines
                      Read X and Y coordinates line by line into XC, YC
   10.
   11.
                      br.close
              end if
       //output file creation
   12. outfilename= "greedysolution"
   13. if i<10
              outfilename = outfilename + "0" + (i+1)
   14.
       else
   15.
              outfilename = outfilename + (i+1)
       //create file in output_greedy folder
   16. File outfile= new File("output greedy", outfilename)
   17. outfile.createNewFile();
   18. bw: BufferedWriter object to write into files
       //call algorithm to select lines
   19. greedy_SeparatingPoints(XC, YC, 0, XC.length-1)
```

```
//write the number of lines and solution to //file
20. bw.write(solution.size())
21. for z=0 to solution.size()
           bw.write(solution.get(z)+"\n");
    end for
22. bw.close
    end for
    end method
```

Analysis:

- 1. Line 1 and 2 are initialization and takes O(1) time.
- 2. Line 3 has 1 initialization, comparisons up to number of files in folder, say "f".
- 3. Line 4 to 18 will run for "f" times.
- 4. Line 19 is the call to greedy_SeparatingPoints() which will itself take time. The call to this method will be for the number of files in the folder.
- 5. Line 20 to 22 will be executed "f" times.

Method 2

```
greedy_SeparatingPoints(int X[], int Y[], int start, int end)
1. length= X.length
2. boolean splitH= false, splitV= false
3. diff= end- start
4. if diff>0
5.
           vertical=0, horizontal=0
           firstvalue=X[start]
6.
7.
           lastvalue=X[end]
8.
           splitmid= firstvalue+ lastvalue
9.
           if (splitmid%2!=0)
10.
                   vertical= splitmid/2
                   horizontal= splitmid/2
11.
           else
                   vertical= splitmid- 1/2
12.
                   horizontal= splitmid- 1/2
13.
           end if
14.
           if (vert.isEmpty())
15.
                   vert.add= (vertical)
16.
                   solution.add("v" + vertical)
           else
                   splitV = checksplitV(X,Y,vertical)
17.
18.
                   if (splitV== true)
                          vert.add= (vertical)
19.
                          solution.add("v" + vertical)
20.
                   end if
           end if
21.
           splitH= checksplitH(X,Y, horizontal)
22.
           if (splitH== true)
23.
                   horz.add= (horizontal)
                   solution.add("h" + horizontal)
24.
```

```
end if

25. upstart= vertical- 0.5

26. downend= vertical- 1.5

27. greedy_SeparatinfPoints(X, Y, start, downend)

28. greedy_SeparatinfPoints(X, Y, upstart, end)

end if
end
```

Method 3:

```
boolean checksplitH(X1,Y1,splitpoint)
1. flagsplit=0
2. for i=0 to Y1.length
           for j=i+1 to Y1.length
3.
                  if flagsplit==0
4.
5.
                          if ((Y1[i]>splitpoint && Y1[j]<splitpoint) ||
                   (Y1[i]<splitpoint && Y1[j]>splitpoint))
6.
                                  x1=X1[i]
7.
                                  x2=X1[j]
8.
                                  y1=Y1[i]
9.
                                  y2=Y1[j]
                                  splitvertfound=0
10.
                                  for k=0 to vert.size()
11.
                                         if splitvertfound=0
12.
13.
                                                 vertical= vert.get(k)
14.
                                                 if (x1<vertical && x2>vertical)
                                                         splitvertfound=1
15.
                                                 end if
                                         end if
                                  end for
                                  if splitvertfound=0
16.
17.
                                         if horz.isEmpty()
                                                 flagsplit=1
18.
                                         end if
                                  flagcount=0
19.
                                  for l=0 to horz.size()
20.
```

```
21.
                                            if flagcount=0
                                                   horzval=horz.get(1)
   22.
                                                   if ((y1>horzval && y2<horzval)||
   23.
                                            (y1<horzval && y2>horzval))
                                                           flagcount=1
   24.
                                                   end if
                                            end if
                                     end for
   25.
                                     if flagcount=1
   26.
                                            flagsplit=0
                                     else
                                            flagsplit=1
   27.
                                     end if
                                     end if
                             end if
                      end if
              end for
       end for
   28. if flagsplit=0
   29.
              return false
       else
   30.
              return true
       end method
Method 4:
       boolean checksplitV(X1[], Y1[], splitpoint)
   1. flagsplit=0
   2. x1=splitpoint-1.5
   3. x2=splitpoint-0.5
   4. for k=0 to horz.size()
   5.
              if flagspit=0
                      betweenline= horz.get(k)
   6.
   7.
                      if((Y1[x1]>betweenline && Y1[x2]<betweenline) ||
              (Y1[x1]<betweenline && Y1[x2]>betweenline))
   8.
                             flagsplit=1
                      else
   9.
                             flagsplit=0
                      end if
              end if
       end for
   10. if flagsplit=1
   11.
              return false
       else
              return true
   12.
       end method
```

Analysis of the procedures: greedy_SeparationPoints()

- 1. The greedy_SeparationPoints() executes for each file in the folder (f times).
- 2. It also executes recursively for every split.
- 3. Since the split is done from 0 to 9 it is called n times, i.e. number of coordinate points.
- 4. The function List.add() has time complexity O(1).
- 5. Also isEmpty() has constant time.

checksplitH()

- 1. The checksplitH() function is called for every horizontal splitpoint to check whether it should be added to solution.
- 2. Line 1 takes O(1).
- 3. The two for loops are nested hence every line in this loop takes n^2.
- 4. Line 11 is a for loop, will execute till size of the vertical list. Hence say if size is n. Every statement in this loop will execute for n^3 times.
- 5. Line 16to 20 runs n^2 times.
- 6. Line 20 is for loop, hence statement 21 to 24 runs n^3 times.
- 7. Line 25 to 27 runs n² times.
- 8. Line 28 to 30 takes O(1) time.
- 9. The list's get()takes O(1) time. Hence complexity of this function is O(n^3).

checksplitV()

This function checks whether vertical split line is to be added in the solution.

- 1. Line 1 to 3 takes O(1).
- 2. The for loop in line 4 has 1 initialization comparisons equal to number of points in horz solution say n.
- 3. Line inside for runs O(n) times (Line 5 to 10).
- 4. Line 10 to 12 runs O(1) times.

This function takes O(n) times.

The overall complexity of the algorithm goes to n^4 , as separating points function i.e. greedy_SeparatingPoints() takes O(n) and checksplitH() takes O(n^3). Therefore total time is O(n^4).

If we also consider number of files say n, then complexity rises to $O(n^5)$.

| > | Algorithm analysis using instance Points 5 |
|---|---|
| | Input: 5 1 |
| | The algorithm gives optimum solution. Output: 3 V 2.5 h 2.5 h 3.5 |
| > | Algorithm fails for The algorithm does not give optimum solution for 10 points. It gives one split point extra. |
| | Input: 10 1 |
| | The algorithm gives following output: 7 v 5.5 h 5.5 v 2.5 v 1.5 h 4.5 h 7.5 |
| | The above solution is not optimal. The number of lines that can be used to split the above 10 points is |

6 v

h h 5.5 4.5 6.5 v 7.5 v 1.5 v 4.5

This above solution is better. This happens because my algorithm first visited lower half, i.e. points on X coordinate 0 to 5. Hence the horizontal line 2.5and 4.5 is drawn first.

When 6-10 points are visited and when v 7.5 is selected, we find that the points are already splitted and line is not drawn or selected in solution.