

TECHNO INDIA UNIVERSITY

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Batch — BCS2B

Subject — Automata Theory

① Transition function for DFA, NFA and epsilon NFA.

→ For deterministic finite approach, (DFA)

transition function:  $Q \times \Sigma \rightarrow Q$

where  $Q \rightarrow$  finite set of state  
 $\Sigma \rightarrow$  set of input alphabet

for NFA,

transition function ( $\delta$ ):  $Q \times (\Sigma \cup \epsilon) \rightarrow 2^Q$

$Q$  and  $\Sigma$  are same as before

$\epsilon \rightarrow$  null move.

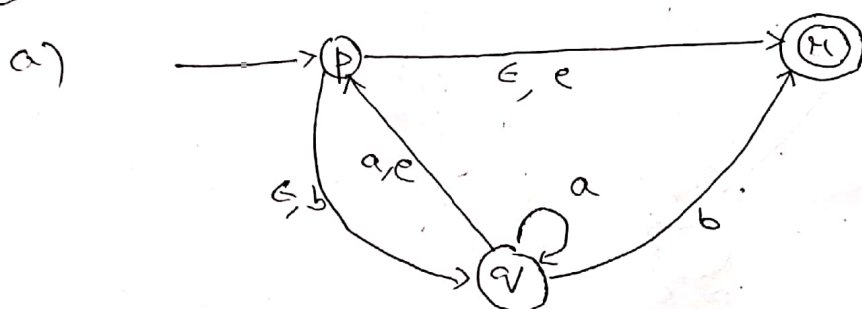
for epsilon NFA,

transition function ( $\delta$ ):  $Q \times \Sigma_{\epsilon} \rightarrow P(Q)$

where  $Q, \Sigma$  and  $\epsilon$  have representation as in case of NFA

and  $\Sigma_{\epsilon}$  denotes  $(\Sigma \cup \epsilon)$

② Convert epsilon NFA to NFA.



Transition table for NFA:-

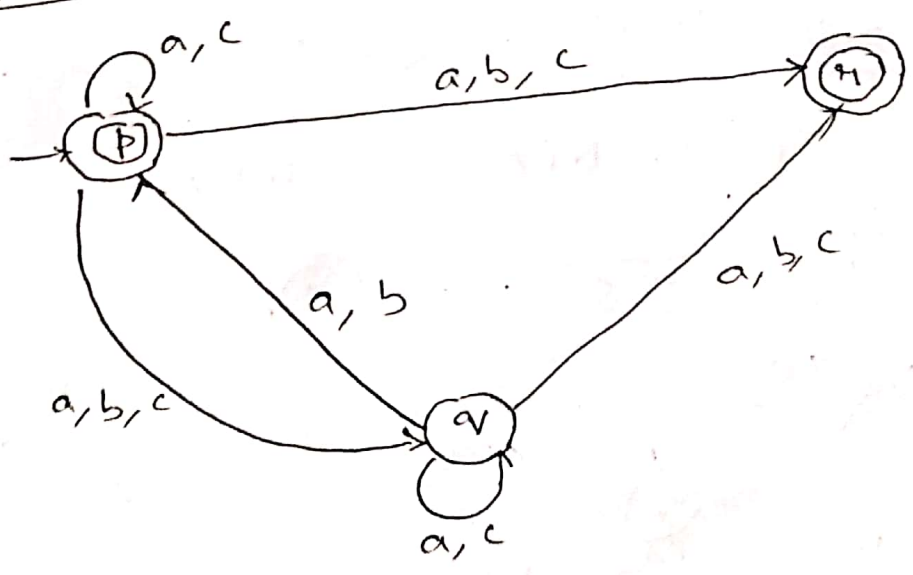
|   | a         | b   | c         |
|---|-----------|-----|-----------|
| p | {p, q}    | {q} | {p, r}    |
| q | {p, q, r} | r   | {p, q, r} |
| r | φ         | φ   | φ         |

|     | $\epsilon^x$ | $a$             | $\epsilon^x$ |
|-----|--------------|-----------------|--------------|
| $p$ | $p, q, r$    | $\phi, p, \phi$ | $p, q, r$    |
| $q$ | $q$          | $p$             | $p, q, r$    |
| $r$ | $r$          | $\phi$          |              |

|     | $\epsilon^x$ | $b$          | $\epsilon^x$ |
|-----|--------------|--------------|--------------|
| $p$ | $p, q, r$    | $q, r, \phi$ | $q, r$       |
| $q$ | $q$          | $r$          | $r$          |
| $r$ | $r$          | $\phi$       |              |

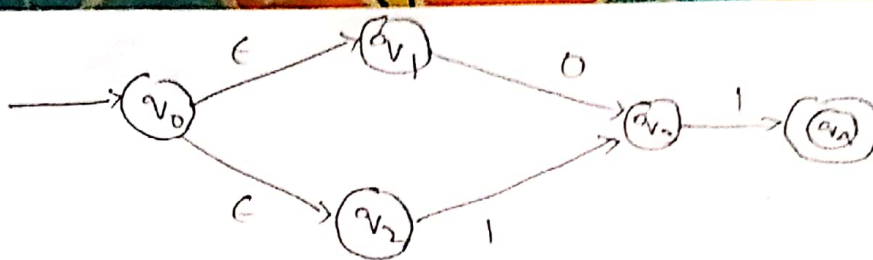
|     | $\epsilon^x$ | $c$             | $\epsilon^x$          |
|-----|--------------|-----------------|-----------------------|
| $p$ | $p, q, r$    | $r, p, q, \phi$ | $r, p, q, r, q, \phi$ |
| $q$ | $q$          | $p-q$           | $p, q, r, q$          |
| $r$ | $r$          | $\phi$          |                       |

Finally NFA  $\rightarrow$



Final stacks:  $p, r$

b)



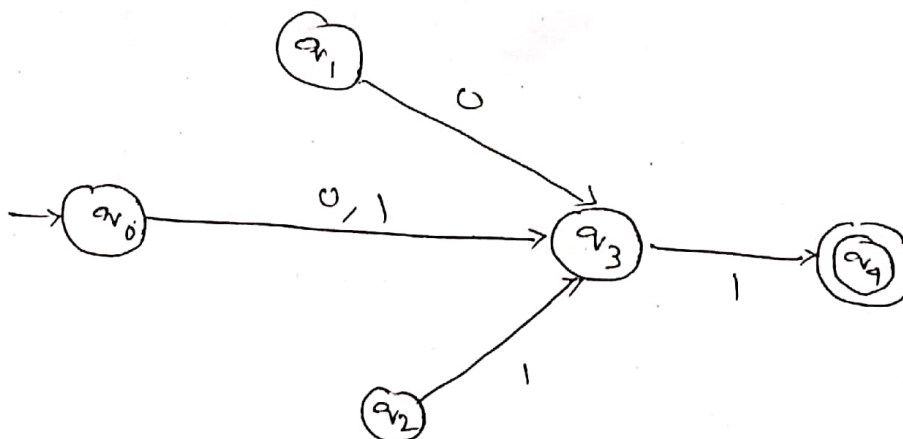
Transition state for NFA

|       | 0      | 1      | $\epsilon^*$ | 0               | $\epsilon^*$      |
|-------|--------|--------|--------------|-----------------|-------------------|
| $q_0$ | $q_3$  | $q_3$  | $q_0$        | $q_0, q_1, q_2$ | $\phi, q_3, \phi$ |
| $q_1$ | $q_3$  | $\phi$ | $q_1$        | $q_1$           | $q_3$             |
| $q_2$ | $\phi$ | $q_3$  | $q_2$        | $q_2$           | $\phi$            |
| $q_3$ | $\phi$ | $q_4$  | $q_3$        | $q_3$           | $\phi$            |
| $q_4$ | $\phi$ | $\phi$ | $q_4$        | $q_4$           | $\phi$            |

|       | $\epsilon^*$    | 1                 | $\epsilon^*$ |
|-------|-----------------|-------------------|--------------|
| $q_0$ | $q_0, q_1, q_2$ | $\phi, \phi, q_3$ | $q_3$        |
| $q_1$ | $q_1$           | $\phi$            |              |
| $q_2$ | $q_2$           | $q_3$             | $q_3$        |
| $q_3$ | $q_3$           | $q_4$             | $q_4$        |
| $q_4$ | $q_4$           | $\phi$            |              |

Transition diagram →



final state:  $q_4$