## **CS684: Embedded System Course**

## **Rulebook: [1] Theme Description**

- Figure 1 shows the arena design for this theme.
- The arena is an abstraction of a parking area made up of black lines with **START** position marked.

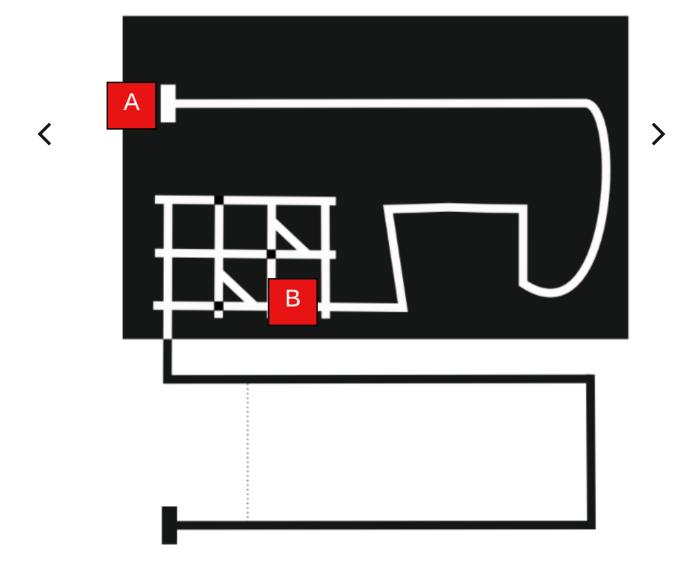


Figure 1: Arena design

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## 1. Arena Components

- Arena consists of two parts traversal area and parking area.
- Thermocol cubes are used to depict the dummy cars.
- Dummy cars can be placed on the line or in the parking area and will act as an obstacle. Robot has to avoid the obstacle and bypass it.

## 2. Theme Run Sequence

- The robot will start from the **START** position of the arena.
- It must traverse around the arena avoiding obstacles.
- It has to detect the parking area.
- Once robot enters into the parking area, it has to detect sufficient space to park itself.
- If space is not available for the parking, robot should stop at the **EXIT** position marked on the arena.

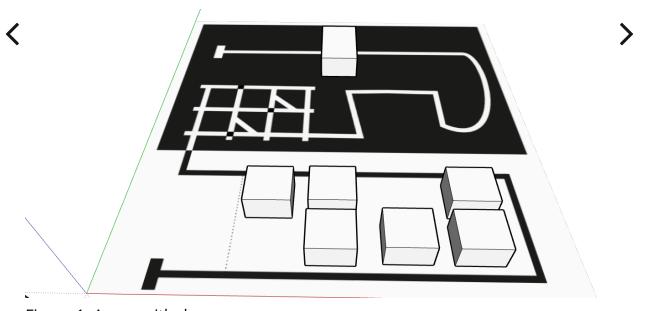


Figure 1: Arena with dummy cars

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