

Ans! point :- (2,2), (2,5), (5,5) & (5,2)

$$U = \left(0, \frac{1}{4}, \frac{1}{2}, \frac{2}{3}, \frac{3}{4}, 1\right)$$

$$Q(U) = P_0(1-U)^3 + P_1 3U(1-U)^2 + P_2 3U^2(1-U) + P_3 3U^3$$

$$Q(0) = [2,2](1)^3 + [2,5](0) + [5,5](0) + [5,2](0)$$

$$Q(0) = [2,2]$$

$$Q\left(\frac{1}{4}\right) = [2,2] \left(\frac{3}{4}\right)^3 + [2,5] \frac{3}{4} \left(\frac{3}{4}\right)^2 + [5,5] \frac{3}{4^2} \left(\frac{3}{4}\right) + [5,2] 3 \left(\frac{3}{4}\right)$$

$$Q\left(\frac{1}{4}\right) = \left[\frac{27}{32}, \frac{27}{32}\right] + \left[\frac{27}{32}, \frac{135}{64}\right] + \left[\frac{45}{64}, \frac{45}{64}\right] + \left[\frac{405}{64}, \frac{81}{32}\right]$$
$$= \left[\frac{558}{64}, \frac{315}{64}\right]$$

$$Q\left(\frac{1}{2}\right) = [2,2] \frac{1}{8} + [2,5] \frac{3}{2} \left(\frac{1}{2}\right)^2 + [5,5] \left[\frac{1}{4}\right] \left[\frac{1}{2}\right] +$$

$$= \left[\frac{1}{4}, \frac{1}{4}\right] + \left[\frac{3}{4}, \frac{15}{8}\right] + \left[\frac{5}{8}, \frac{5}{8}\right] + [5,2] \left[\frac{1}{2}\right]$$

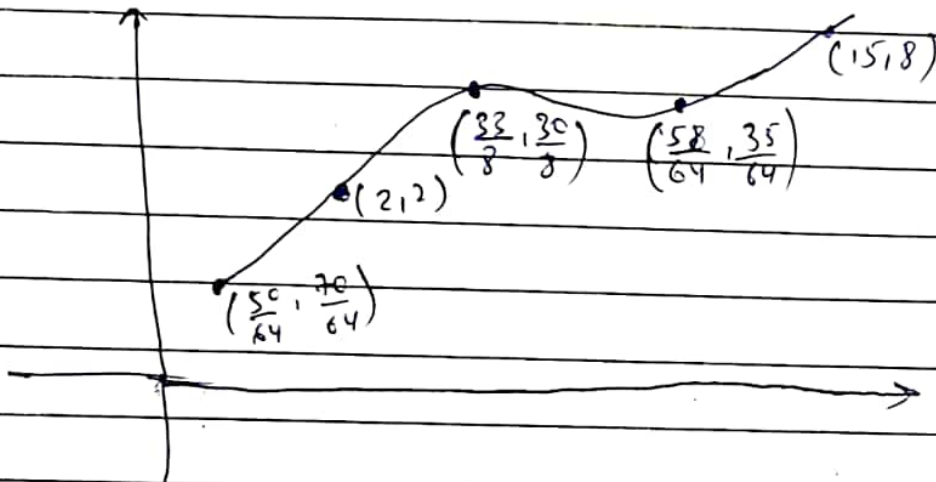
$$+ \left[\frac{5}{2}, 1\right]$$

$$\Rightarrow \left[\frac{33}{8}, \frac{30}{8}\right]$$

$$Q\left(\frac{3}{4}\right) = [2, 2] \left(\frac{1}{4}\right)^3 + [2, 5] \left(\frac{3}{64}\right) + [5, 5] \left(\frac{3}{64}\right) + (5, 2) \left[\frac{3}{64}\right]$$

$$= \left[\frac{50}{64}, \frac{70}{64}\right]$$

$$Q(1) = [5, 2] 3(1)^3 = [15, 8]$$



Ans 2 In analytics geometry sphere with center (x_0, y_0, z_0) & radius or with point (x, y, z)

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$$

For vector

$$\|P - C\|^2 = r^2$$

When ray intersect, intersection point are showed by both equations. Search for point that are on ray and sphere is combining eqn solving for t

Sphere: $\text{dot}((P - C), (P - C)) = r^2$

Ray: $P(t) = A + tB$

Combined: $\text{dot}(A + tB - C, A + tB - C) = r^2$

eq: $a t^2 + b t + c = 0$

$$a = \text{dot}(B, B)$$

$$b = 2 \cdot \text{dot}(B, A - c)$$

$$c = \text{dot}(A - c, A - c) - R^2$$

$$\therefore t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$D = b^2 - 4ac$$

$D < 0 \Rightarrow$ mod intersect

$D = 0 \Rightarrow$ ray touches sphere

$D > 0 \Rightarrow$ Touch sphere at 2 points

Ans 2: Transparency Shadow

A transparency surface produces both reflected and transmitted light the relative contribution of transmitted light depends on degree of transparency of surface

$$I = (1 - k) I_1 + k I_2$$

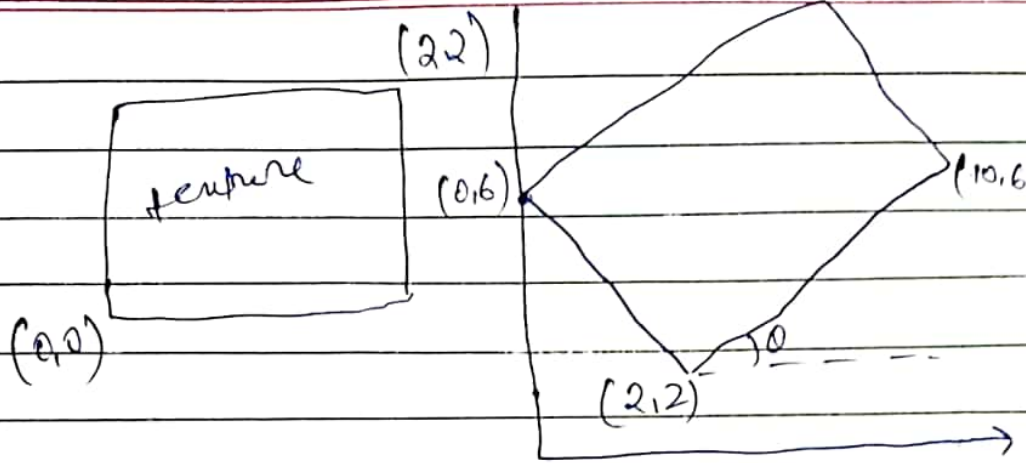
* Gouraud shading is an interpolation method used in computer graphics to produce continuous shading of surface represented by polygon meshes

Ex:- match Bands that appear on surface

* Phong shading:- it is an interpolation method for surface shading in 3D computer graphics. Also referred as normal vector interpolation shading

Ex:- mirror, highly polished metal

Ans 4



(1) Scaling

$$S_x = \sqrt{(10-2)^2 + (6-2)^2} = 4.4721$$

$$S_y = \sqrt{(10-2)^2 + (6-2)^2} = 2.2360$$

~~Scaling~~

$$[S_{sx}] = \begin{bmatrix} 4.4721 & 0 & 0 \\ 0 & 2.2360 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(2) Anticlockwise Rotation

$$\sin \theta = \frac{6-2}{\sqrt{(10-2)^2 + (6-2)^2}} = 0.4472$$

$$\cos \theta = \frac{10-2}{\sqrt{64+16}} = 0.8944$$

$$[R_\theta] = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.8944 & -0.4472 & 0 \\ 0.4472 & 0.8944 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(3) Translation to bring (0,0) \rightarrow (2,2)

$$[T_{2,2}] = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

Final composite matrix $[X]$

$$[X] = [T_{2,2}] \times [R_0] = [S_{xy}]$$

$$= \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0.8944 & -0.4472 & 0 \\ 0.4472 & 0.8944 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 4.4721 & 0 & 0 \\ 0 & 2.2360 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 3.99 & -0.99 & 2 \\ 1.99 & 1.99 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

Fractal Geometry \rightarrow There are very complex pictures generated by computers from a single formula. They are created using iteration. This means one formula is repeated with slightly different value over and over again taking in account result from previous iteration.

Hidden line Elimination \rightarrow It is the method of computing which edge are not hidden by four or more for a specified view & display of parts in projection of machine into 2-D plane. It is utilized by CAD to display virtual lines.