

CMPT 280

Tutorial: Dijkstra's Algorithm

Mark Eramian

University of Saskatchewan

Dijkstra's Algorithm

```
1  Algoirthm dijkstra(G, s)
2  Solves the single-source shortest paths problem.
3  G is a weighted graph with non-negative weights.
4  s is the start vertex.
5
6  Let V be the set of vertices in G.
7
8  For each v in V
9      v.tentativeDistance = infinity
10     v.visited = false
11     v.predecessorNode = null
12
13  s.tentativeDistance = 0
14
15  while there is an unvisited vertex
16      cur = the unvisited vertex with the smallest tentative distance.
17      cur.visited = true
18
19      // update tentative distances for adjacent vertices if needed
20      // note that w(i,j) is the cost of the edge from i to j.
21      For each z adjacent to cur
22          if (z is unvisited and z.tentativeDistance >
23              cur.tentativeDistance + w(cur,z) )
24              z.tentativeDistance = cur.tentativeDistance + w(cur,z)
25              z.predecessorNode = cur
```

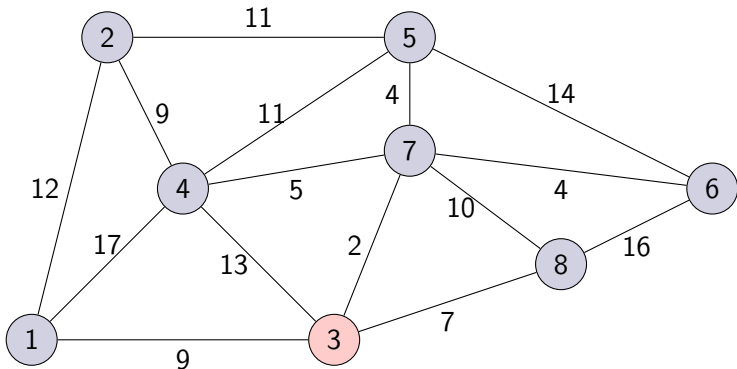
Implementing Dijkstra's Algorithm

- As we saw in class, while the algorithm as presented suggests that tentativeDistance, visited and predecessorNode are properties of nodes, it is not necessary to implement a specialized node object to contain this data.
- Since nodes are always mapped onto integer identifiers, we can store these values in a series of parallel arrays.

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	F	F	F	F	F	F
	0	1	2	3	4	5	6	7	8
Predecessor:	-	-	-	-	-	-	-	-	-
	0	1	2	3	4	5	6	7	8
Tentative Distance:	∞	∞	∞	∞	∞	∞	∞	∞	∞

Tracing Dijkstra's Algorithm

Let's use Dijkstra's algorithm to find the shortest path from node 3 to every other node.



Dijkstra's Algorithm

Initialization for Start Node 3

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	F	F	F	F	F	F

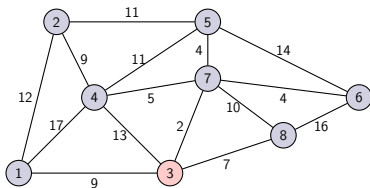
	0	1	2	3	4	5	6	7	8
Predecessor:	-	-	-	-	-	-	-	-	-

	0	1	2	3	4	5	6	7	8
Tentative Distance:	∞	∞	∞	0	∞	∞	∞	∞	∞

Note: Offset 0 of these arrays are not used as we use node IDs as array offsets. Nodes are numbered 1 to n as in lib280.

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	F	F	F	F	F	F
Predecessor:	-	-	-	-	-	-	-	-	-
Tent. Dist.:	∞	∞	∞	0	∞	∞	∞	∞	∞

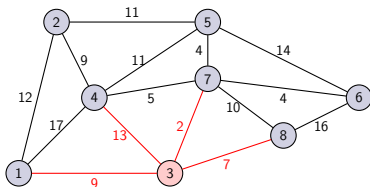


Unvisited node w/ Smallest tent. dist.: 3

```
1 while there is an unvisited vertex
2   cur = the unvisited vertex with the smallest tentative distance.
3   cur.visited = true
4
5   // update tentative distances for adjacent vertices if needed
6   // note that w(i,j) is the cost of the edge from i to j.
7   For each z adjacent to cur
8     if (z is unvisited and z.tentativeDistance >
9         cur.tentativeDistance + w(cur,z) )
10      z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11      z.predecessorNode = cur
```

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	T	F	F	F	F	F
Predecessor:	-	3	-	-	3	-	-	3	3
Tent. Dist.:	∞	9	∞	0	13	∞	∞	2	7



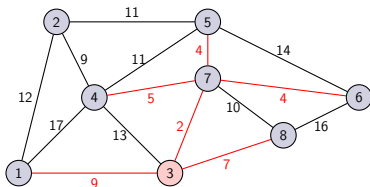
Processed Node 3, Next node to process: 7

```

1  while there is an unvisited vertex
2      cur = the unvisited vertex with the smallest tentative distance.
3      cur.visited = true
4
5      // update tentative distances for adjacent vertices if needed
6      // note that w(i,j) is the cost of the edge from i to j.
7      For each z adjacent to cur
8          if (z is unvisited and z.tentativeDistance >
9              cur.tentativeDistance + w(cur,z) )
10             z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11             z.predecessorNode = cur
    
```

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	T	F	F	F	T	F
Predecessor:	-	3	-	-	7	7	7	3	3
Tent. Dist.:	∞	9	∞	0	7	6	6	2	7



Processed Node 7, Next node to process: 5 or 6 (but we choose 5)

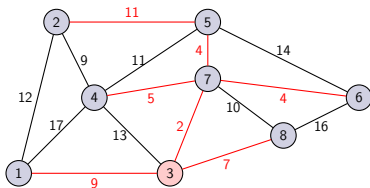
```

1 while there is an unvisited vertex
2   cur = the unvisited vertex with the smallest tentative distance.
3   cur.visited = true
4
5   // update tentative distances for adjacent vertices if needed
6   // note that w(i,j) is the cost of the edge from i to j.
7   For each z adjacent to cur
8     if (z is unvisited and z.tentativeDistance >
9         cur.tentativeDistance + w(cur,z) )
10      z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11      z.predecessorNode = cur

```


Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	T	F	T	F	T	F
Predecessor:	-	3	5	-	7	7	7	3	3
Tent. Dist.:	∞	9	17	0	7	6	6	2	7

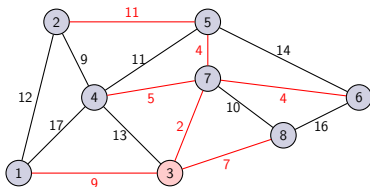


Processed Node 5, Next node to process: 6

```
1 while there is an unvisited vertex
2   cur = the unvisited vertex with the smallest tentative distance.
3   cur.visited = true
4
5   // update tentative distances for adjacent vertices if needed
6   // note that w(i,j) is the cost of the edge from i to j.
7   For each z adjacent to cur
8     if (z is unvisited and z.tentativeDistance >
9         cur.tentativeDistance + w(cur,z) )
10      z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11      z.predecessorNode = cur
```

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	T	F	T	T	T	F
Predecessor:	-	3	5	-	7	7	7	3	3
Tent. Dist.:	∞	9	17	0	7	6	6	2	7

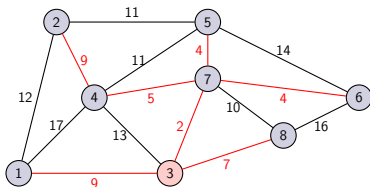


Processed Node 6, Next node to process: 4 or 8 (we choose 4)

```
1 while there is an unvisited vertex
2   cur = the unvisited vertex with the smallest tentative distance.
3   cur.visited = true
4
5   // update tentative distances for adjacent vertices if needed
6   // note that w(i,j) is the cost of the edge from i to j.
7   For each z adjacent to cur
8     if (z is unvisited and z.tentativeDistance >
9         cur.tentativeDistance + w(cur,z) )
10      z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11      z.predecessorNode = cur
```

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	T	T	T	T	T	F
Predecessor:	-	3	4	-	7	7	7	3	3
Tent. Dist.:	∞	9	16	0	7	6	6	2	7

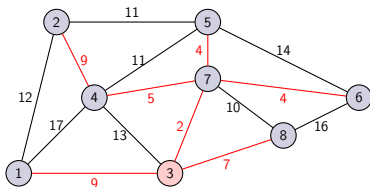


Processed Node 4, Next node to process: 8

```
1 while there is an unvisited vertex
2   cur = the unvisited vertex with the smallest tentative distance.
3   cur.visited = true
4
5   // update tentative distances for adjacent vertices if needed
6   // note that w(i,j) is the cost of the edge from i to j.
7   For each z adjacent to cur
8     if (z is unvisited and z.tentativeDistance >
9         cur.tentativeDistance + w(cur,z) )
10      z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11      z.predecessorNode = cur
```

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	F	F	T	T	T	T	T	T
Predecessor:	-	3	4	-	7	7	7	3	3
Tent. Dist.:	∞	9	16	0	7	6	6	2	7

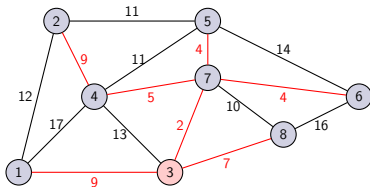


Processed Node 8, Next node to process: 1

```
1 while there is an unvisited vertex
2   cur = the unvisited vertex with the smallest tentative distance.
3   cur.visited = true
4
5   // update tentative distances for adjacent vertices if needed
6   // note that w(i,j) is the cost of the edge from i to j.
7   For each z adjacent to cur
8     if (z is unvisited and z.tentativeDistance >
9         cur.tentativeDistance + w(cur,z) )
10      z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11      z.predecessorNode = cur
```

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	T	F	T	T	T	T	T	T
Predecessor:	-	3	4	-	7	7	7	3	3
Tent. Dist.:	∞	9	16	0	7	6	6	2	7

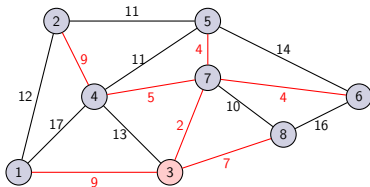


Processed Node 1, Next node to process: 2

```
1 while there is an unvisited vertex
2   cur = the unvisited vertex with the smallest tentative distance.
3   cur.visited = true
4
5   // update tentative distances for adjacent vertices if needed
6   // note that w(i,j) is the cost of the edge from i to j.
7   For each z adjacent to cur
8     if (z is unvisited and z.tentativeDistance >
9         cur.tentativeDistance + w(cur,z) )
10      z.tentativeDistance = cur.tentativeDistance + w(cur,z)
11      z.predecessorNode = cur
```

Dijkstra's Algorithm

	0	1	2	3	4	5	6	7	8
Visited:	F	T	T	T	T	T	T	T	T
Predecessor:	-	3	4	-	7	7	7	3	3
Tent. Dist.:	∞	9	16	0	7	6	6	2	7

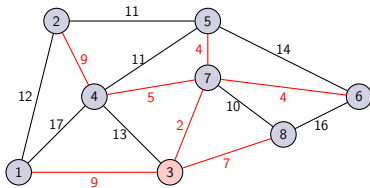
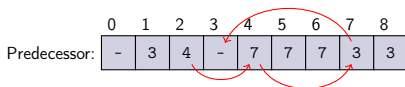


Processed Node 2, no more unvisited vertices, so we're done.
Tentative distance array now contains the final lengths of the shortest paths from 3 to each node.

Dijkstra's Algorithm

Obtaining the Shortest Paths

To recover the shortest path from 3 to a node i , use the predecessor array starting at offset i , and follow the path back.



Recovering the shortest path from 3 to 2:

$2 \leftarrow 4 \leftarrow 7 \leftarrow 3$

Dijkstra's Algorithm

More Examples

For more practice, trace through Dijkstra's algorithm again, but from a different start node, or, for an entirely different graph... maybe a directed one?