

Subarray Largest Sum

<https://www.youtube.com/watch?v=5WZl3MMT0Eg>

Here are the key concepts you'd encounter (and learn) while tackling the Maximum Subarray problem:

1. Brute-Force Enumeration

- Enumerating every possible contiguous subarray using three nested loops.
- Understanding index ranges (start = i , end = j , and summing from i to j).
- Learning how summing from scratch each time costs $O(n^3)$.
- Realizing why such a naïve approach doesn't scale.

2. Incremental (Prefix) Summation Trick

- Instead of recomputing the entire sum for each new end index, keep a "running sum" as you extend the subarray.
- For a fixed start i , you compute

```
curr = 0
for j in i...n-1:
    curr += nums[j]
// now curr is the sum of nums[i..j]
```
- This removes the innermost loop and drops the time complexity to $O(n^2)$.
- Teaches you how storing partial results can save repeated work.

3. Time-Complexity Analysis

- Summing up: three loops $\rightarrow O(n^3)$; two loops with running sum $\rightarrow O(n^2)$.
- Learning how to count iterations (e.g. $\sum_{i=0}^{n-1} \sum_{j=i}^{n-1} 1 = O(n^2)$), and how removing one loop changes the big-O.

4. Handling Negative Prefixes (Greedy/Pruning Idea)

- Observing that if your running sum ever goes below zero, adding it to a future positive stretch can only hurt.
- Learning the "if current_sum < 0, reset to 0" heuristic.
- Understanding why "throwing away" a negative prefix is safe when looking only for the maximum contiguous sum.

5. Kadane's Algorithm (Linear DP/GREEDY)

- Recognizing that at each index i , the best subarray ending exactly at i is either:
 - Just $\text{nums}[i]$ (if the previous running sum was negative), or
 - Previous running sum + $\text{nums}[i]$ (if that prefix was ≥ 0).
- Translating that into a one-pass loop that keeps two variables:
 - $\text{currSum} = \max(\text{nums}[i], \text{currSum} + \text{nums}[i])$ (or the equivalent "reset if negative, then add"),
 - $\text{maxSoFar} = \max(\text{maxSoFar}, \text{currSum})$.
- Internalizing the "maximum-ending-here" vs. "maximum-so-far" dynamic-programming idea.

6. Edge-Case Handling

- Why you initialize $\text{maxSoFar} = \text{nums}[0]$ instead of 0 (so you handle all-negative arrays correctly).
- Ensuring you never accidentally return 0 when every element is negative.
- Confirming that the array is nonempty before you begin.

7. Divide-and-Conquer Approach ($O(n \log n)$)

- Splitting the array into two halves, recursively finding:

- The maximum subarray entirely in the left half.
 - The maximum subarray entirely in the right half.
 - The maximum subarray that crosses the midpoint (find best suffix on left + best prefix on right).
 - Learning how to combine those three cases to get the overall maximum.
 - Analyzing why this yields $T(n) = 2 T(n/2) + O(n) \Rightarrow O(n \log n)$.
 - Gaining comfort with “divide, conquer, and merge” recursion patterns.
8. **Space-Complexity Trade-Offs**
- Brute-force and $O(n^2)$ methods use $O(1)$ extra space (just a few counters).
 - A divide-and-conquer recursion uses $O(\log n)$ stack space.
 - Kadane’s uses strictly $O(1)$ extra space, which is optimal.
9. **Understanding “Local” vs. “Global” Maximum**
- Local maximum: best sum ending at the current index.
 - Global maximum: best sum seen anywhere so far.
 - Seeing how local decisions (resetting when negative) affect the global answer.
10. **Practical Implementation Details**
- Iterating through arrays in Python (or any language).
 - Using `max()` to update the global best.
 - Handling off-by-one errors when summing subarrays.
 - Translating pseudocode into clean, production-ready code.

By working through these steps—starting from brute-force, then prefix-sum optimization, then Kadane’s linear solution, and optionally the divide-and-conquer—you’ll cover a spectrum of algorithmic thinking:

- **Brute-force enumeration** (time complexity reasoning),
- **Incremental summation** (prefix-sum optimization),
- **Greedy/DP pruning** (Kadane’s algorithm),
- **Divide & Conquer recursion** (splitting and merging subproblems),
- **Edge-case robustness** (handling all-negative arrays),
- **Space/time trade-offs** (understanding $O(1)$, $O(n \log n)$, $O(n^2)$, $O(n^3)$ behaviors).

All of these concepts show up in many other array/DP problems too, so you build a toolkit you can reuse on other coding-interview questions.