

Rohin Dhanekar 2301010266  
BTech Cse 'D'

## Operating System Assignment 01

### Part - A

- Ans 1. Modern systems rely on OS because it abstracts hardware complexity, manages resources (CPU, memory, I/O), provides security, multitasking, & ensures user-friendly interaction. Without OS, applications would need to handle hardware directly, making development inefficient.
- Ans 2. A Real-Time Operating System (RTOS) is suitable because it provides fast, predictable responses with low latency, which is critical for health monitoring where timely alerts may save lives.
- Ans 3. Avoid layered structure because its strict layer-by-layer communication introduces overhead & delays, reducing performance. Performance-critical environments need fast, direct communication (e.g., monolithic or optimized microkernel).
- Ans 4. Refute. OS structure impacts performance, reliability, maintainability, & security. Poor structure can cause bottlenecks, debugging difficulties, & vulnerabilities even if processes "run".

- Ans 5) Analysing PCB helps check saved registers, program counter, state flags; errors here reveal misinitialized registers or invalid states
- ii) Context switching involves saving CPU state of the running process into its PCB & loading the next process's state from its PCB.
- iii) Use asynchronous system call because I/O requests shouldn't block execution; it allows the process to continue while I/O completes in the background.

### 'PART-B'

Ans 6a) Total context switching time,

save state = 2 ms

load state = 3 ms

Scheduler overhead = 1 ms

Total time =  $2 + 3 + 1 = 6$  ms

- b) Impact: More context switch time reduces CPU utilization & slows multitasking since more time is spent switching than executing.

Ans 7 • Single-threaded = 40 sec

Assuming 4 threads: Execution =  $40/4 = 10$  sec  
(ideal, ignoring overhead)

- Multithreading improves performance by overlapping computation & I/O, reducing idle CPU cycles, & utilizing multiple cores.

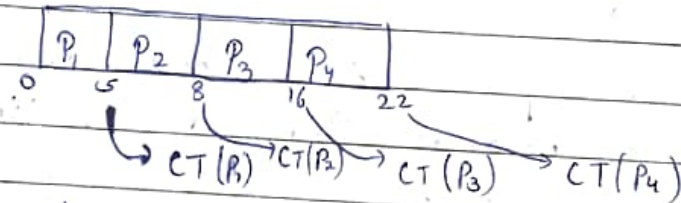
Q no. 8 a) FCFS

Process	Arrival Time (AT)	Burst Time (BT)	Completion Time (CT)	Waiting Time (WT)	TAT
P <sub>1</sub>	0	5	5	5-5=0	5-0=5
P <sub>2</sub>	0	3	8	8-3=5	8-0=8
P <sub>3</sub>	0	8	16	16-8=8	16-0=16
P <sub>4</sub>	0	6	22	22-6=16	22-0=22

$$WT = \text{Turnaround} - \text{Burst} (TAT - BT)$$

$$TAT = \text{Completion} - \text{Arrival} (CT - AT)$$

Grant chart,



$$\text{Avg waiting time} = (0 + 5 + 8 + 16) / 4 = 7.25 \text{ ms}$$

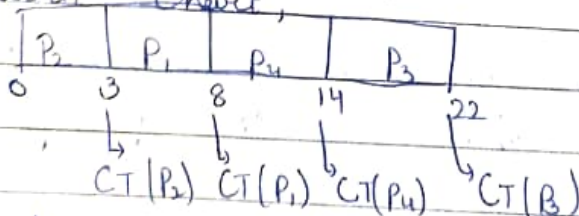
$$\text{Avg turnaround time} = (5 + 8 + 16 + 22) / 4 = 12.75 \text{ ms}$$

b) Non-preemptive SJF

$$TAT = CT - AT$$

$$WT = TAT - BT$$

Grant chart,



$$\text{Avg waiting time} = (3 + 0 + 14 + 8) / 4 = 6.25 \text{ ms}$$

$$\text{Avg turnaround time} = (8 + 3 + 22 + 14) / 4 = 11.75 \text{ ms}$$

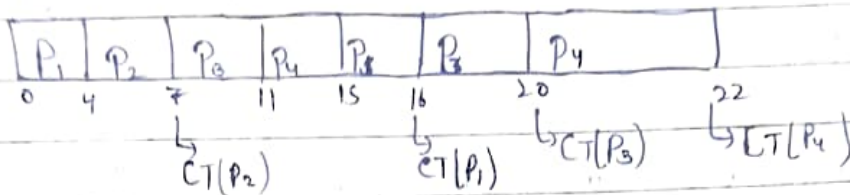


c) Round Robin (Quantum 4ms)

WT: TAT: BT

TAT: CT: AT

Gantt chart,



$$\text{Avg waiting time} = (11 + 4 + 12 + 16) / 4 = 10.75 \text{ ms}$$

$$\text{Avg turnaround} = (16 + 7 + 20 + 22) / 4 = 16.25 \text{ ms}$$

∴ Non Preemptive SJF is "best" algorithm because SJF balances throughput & turnaround best because it minimizes averages waiting & turnaround time.

Ans 9. i) Cloud Migration:

- Choose Micro Kernel for scalability & security (since it isolates services (drivers, file system, etc) in user mode, reducing crashes & improving modularity).
- VMs provide isolation (sandboxing), efficient resources allocation, & easy migration/management.

ii) Smart Home OS:

- OS uses priority-based scheduling + IPC to ensure critical tasks (intrusion detection) preempt less critical ones.
- Suitable algorithms: Priority Scheduling (for critical tasks), Earliest Deadline First (EDF) for real-time responses.