

# Rohit Bangal

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Savedi, Ahmednagar, MH, IN - 414003

## EDUCATION

**Government College of Engineering & Research, Awasari, Pune, India**  
**Savitribai Phule Pune University**

August 2016 – May 2020

Bachelor of Engineering (BE) - Instrumentation and Control

- CGPA 8.83 with grade 'First Class with Distinction'.
- In the top 5 students in the class for all four years.

## EXPERIENCE

**Tantradnyan Engineers, Project Engineer**

Since April 2020

- Prepare, schedule, coordinate, and monitor the assigned engineering projects.
- Monitor compliance with performance standards and specifications.
- Assign responsibilities and mentor project team.
- Guide PLC and SCADA engineer in programming and designing.
- Design the control and power wiring diagrams.

**Robotics Research Lab, Team Leader**

August 2018-June 2020

Government College of Engineering and Research, Pune

- Led the team which participated in **Asia-Pacific Broadcasting Union Robot Contest (2019 & 2020)** and the team which participated in **Mitsubishi Electric Cup (2019)**.
- Guided the team of approx. 35 students as they complete projects for competition or self-interest.

**Tantradnyan Engineers, Internship**

June 2018-August 2018

- PLC Selection and Ladder Programming (Siemens, Delta, Selec)
- Sensor and Actuator selection and integration with PLC
- Control logic designing

**Robotics Research Lab, Team Member**

August 2016-August 2018

Government College of Engineering and Research, Pune

- Worked on design, modeling, testing and validation of robots in **Asia-Pacific Broadcasting Union Robot Contest (2018)**.
- Worked on designing and programming of robots' control system and electronics in **Asia-Pacific Broadcasting Union Robot Contest (2017)**.

## PATENT & PUBLICATIONS

**Portable, Human-Powered Electrical Energy Source.**

Patent Application Number: - 201721041912 (Published).

**Path Planning and Controlling of Omni-Directional Robot Using Cartesian Odometry and PID Algorithm.**

Issued: - December 26, 2019. Publisher: - IEEE.

**Design and Control of Quadruped Robot with Machine Vision-based Path Planning.**

Issued: - June 2, 2020. Publisher: - IEEE.

## AWARDS

**Special Jury Award**

My role: - Team Leader

Event: - Asia-Pacific Broadcasting Union Robot Contest (2019)

**Commendable Performance Award**

My role: - Team Leader

Event: - Mitsubishi Electric Cup (2019)

**National Engineering Olympiad**

Secured All India Rank 1

**Smart and Simple Robot**

My role: - Design, modeling, testing and validation of robots

Event: - Asia-Pacific Broadcasting Union Robot Contest (2018)

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## WORK PROJECTS

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**Communication between two PLCs at a distance using dish antennas (Wi-Fi).**

**Designing and Programming of 'Graphing and Controlling VB.net software' for Siemens S7 PLC.**

**Switchgear test bench automation.**

**Busbar tinning automation using Pyrometer.**

**Flange drilling automation using Siemens PLC and Encoder.**

**Back flushing control panel.**

**Woolen-sheet press bench automation.**

## ACADEMIC PROJECTS

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**Smart Grid** – Engineering final year project

September 2019-May 2020

- Designed and modelled the scaled version of Smart Grid concept.
- Designed and implemented control logic using Allen Bradley PLC and NodeMCU.
- Designed and Configured the SCADA in FactoryTalk View.
- Designed android application to monitor and control the system remotely with integration to firebase database for data logging.
- Designed basic website to monitor the system remotely.

**Rugby Ball pick-place and kick robots** - Asia-Pacific Broadcasting Union Robot Contest (2020)

August 2019-June 2020

- Worked on designing and validation of robots.

**Pick and Place Automatic Guided Vehicle Scaled Robot** - Mahindra & Mahindra Ltd.

November 2019-December 2019

- Designed the algorithm to follow path using given co-ordinates using encoders as feedback.
- Designed and assembled the Pick and Place arm using linear actuators.

**Smart Street** – Engineering mini-project.

January 2019-March 2019

- Designed and modelled the project using CATIA.
- Designed and implemented control logic and electronics.
- Used Proteus to simulate and test the logic.

**Calendar-based building energy management system** – Mitsubishi Electric Cup 2019.

September 2018-February 2019

- Designed the control logic and worked on wiring diagram.
- Designed and programmed the control logic in Mitsubishi PLC, HMI and NodeMCU.

**Quadruped robot** - Asia-Pacific Broadcasting Union Robot Contest (2019)

August 2018-June 2019

- Worked on designing, testing and validation of control system and electronics of robots.
- Worked on designing, modeling, manufacturing, assembly and validation of leg mechanism of robot.

**Disc landing robot** - Asia-Pacific Broadcasting Union Robot Contest (2017)

August 2016-March 2017

- Worked on designing and implementing of control system and electronics for disk throwing and landing mechanism.
- The mechanism mainly used pneumatics to throw and land multiple soft disks on specified locations.

## TECHNICAL SKILLS

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Process Control, Microsoft Office, AutoCAD, CATIA, Proteus, PLC, HMI and SCADA

## RELEVANT COURSES & TRAININGS

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Digital Circuits, Advanced Programming Paradigms (PLC), Online Industrial Training cum Internship on Automation Technology and Mitsubishi FA Product Training