

PES UNIVERSITY

100 Feet Ring Road, BSK 3rd Stage, Bangalore – 560085 Department of Computer Science & Engineering

Course Title: Mobile and Autonomous Robots (UE21CS343BB7)

Semester: 6th Credits: 4 Course Type: Elective

Mini Projects (2024-25)

 Teleoperated Robotic Ar 	rm
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- 2. Autonomous Indoor Navigation for Drone
- 3. Voice-Controlled Robotic Arm
- 4. Gesture-Controlled Robotic Arm
- 5. Drone-based 3D Mapping
- 6. Line tracking along with obstacle detection and avoidance
- 7. Drone-based Fire Detection
- 8. Autonomous Indoor Navigation Robot
- 9. Remote Surveillance Robot
- 10. Warehouse Inventory Management Robot
- 11. Search and Rescue Drone
- 12. Robotics Arm for Precision Tasks
- 13. Environmental Monitoring Robot
- 14. Autonomous Garbage Collection Robot
- 16. Autonomous Delivery Robot
- 17. Space Exploration Rover
- 18. ROS Tic-Tac-Toe Game
- 19. Solar Panel monitoring Drone
- 20. Teleoperation with Haptic Feedback using IMU sensors
- 21. Vision-Guided Pick and Place for real world objects
- 22. Real-Time Object Detection and Tracking
- 23. Autonomous Navigation in GPS-Denied Environments
- 24 Recognize traffic signs from images for Autonomous vehicles
- 25. Stair Climbing Robot
- 26. Radar and ROS Powered Indoor Home Mapping and Positioning Robot
- 27. Hector Slam Mapping and Indoor Positioning ROBOT
- 28. Maze-Solving Robot
- 29. Autonomous Stair Climbing
- 30. Quadruped Balancing on Uneven Surfaces
- 31. Self-Balancing Two-Wheeled Robot
- 32. Swarm Coordination of Ground Robots
- 33. Autonomous Delivery Wheeled Robot
- 34. Autonomous Drone Landing on a Moving Platform
- 35. Aerial Object Tracking and Following
- 36. Gesture-Controlled Mobile Robot