# Classification Methods

- Approximating Bayes Decision Rule: (model the likelihood)
  - Linear Discriminant Analysis/ QDA
  - Fisher's linear discriminant
  - **Naïve Bayes**
  - **Bayesian Belief Networks**
- Approximating Bayes Decision Rule: (model the posterior)
  - **Logistic Regression**
  - **Feedforward neural networks, including deep learning**
  - K-Nearest Neighbor
- Focus just on Class Boundaries:
  - Decision trees
  - **Support Vector Machines**

# Quiz (Bayes Rule)

- Suppose 0.01% of Austin's population have cancer. A new test for cancer shows positive 90% of the time when a person actually has cancer, and correctly indicates "negative" 95% of the time when run on someone who do not have cancer.

This test is conducted on an Austinite and the results come out positive.

- What is the probability that this person actually has cancer?

$$p(+ve \mid \text{test } +ve) = \frac{p(C_1)\,p(x \mid C_1)}{p(x)}$$

$$p(x) = p(C_1)\,p(x \mid C_1) + [1 - p(C_1)]\,[1 - p(x \mid C_1)]$$

$C_1$ : $x$

0.01% 90%

# Revisiting Bayes Decision Rule

- Let input **x** have d features or attributes ($x_1, x_2,\ldots,x_d$);
  C is a random variable over class labels.

- **Bayes Decision rule:** Choose value of C that
  **maximizes** $P(x_1, x_2, \ldots, x_d|C)\ P(C)$

- Problem: how to estimate $P(x_1, x_2,\ldots,x_d\,|C)$ for each class?
  - Especially in high dimensions, interacting variables?

# (Conditional) Independence

$P(A,B) = P(A)\,P(B|A)\,P(C|A,B)$

$\Updownarrow$

$P(A)\,P(B)\,P(C)$

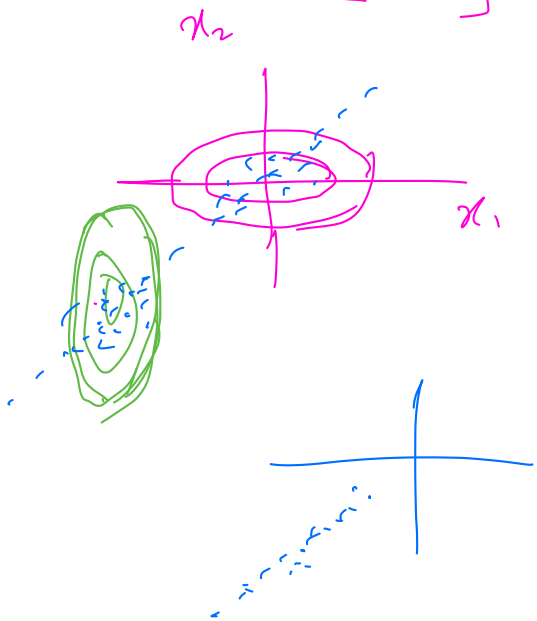
$P(A,B,C,D) = P(A)\,P(B|A)\,P(C|A,B)\,P(D|A,B,C)$

$\Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$

$z = 0$ green

$z = 1$ pink.

$p(x_1, x_2 \mid z)$



# Naïve Bayes Approach

- Conditional Independence:
  - X is cond. Indep of Y given Z if P (X|Y,Z) = P(X|Z)
    - X, Y, Z could be sets of variables too

**Naïve Bayes:**

1. Assume independence among attributes $x_i$ when class is given: ("independence of attributes conditioned on class variable").
   - $P(x_1, x_2, \ldots, x_d|C_j) = P(x_1| C_j)\, P(x_2| C_j) \ldots P(x_d| C_j) = \Pi_i\, P(x_i| C_j)$
   - Note: Conditional independence not equal to attribute independence
2. Estimate probabilities directly from data.

# Estimating Probabilities from Data (Discrete Attributes)

| Tid | Refund | Marital Status | Taxable Income | Evade |
|---|---|---|---|---|
| 1 | Yes | Single | 125K | No |
| 2 | No | Married | 100K | No |
| 3 | No | Single | 70K | No |
| 4 | Yes | Married | 120K | No |
| 5 | No | Divorced | 95K | Yes |
| 6 | No | Married | 60K | No |
| 7 | Yes | Divorced | 220K | No |
| 8 | No | Single | 85K | Yes |
| 9 | No | Married | 75K | No |
| 10 | No | Single | 90K | Yes |

(Example from TSK)

- Class: $P(C) = N_c/N$
  - e.g., P(No) = 7/10,
    P(Yes) = 3/10
- For discrete attributes:

  $P(x_i = v \mid C_k)$ = fraction of examples of class *k* for which attribute $x_i$ takes value *v*.
  - Examples:

    P(Status=Married|No) = 4/7

    P(Refund=Yes|Yes)=0

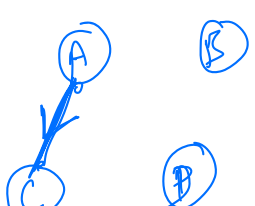
# Naïve Bayes Example

- Worked out in Backup Slides

# Naïve Bayes (Comments)

- Independence assumption often does not hold
  - Poorer estimate of P(C|x), often unrealistically close to 0 or 1
    - but still may pick the right "max"!!
  - If too restrictive, use other techniques such as Bayesian Belief Networks (BBN)
- Somewhat robust to isolated noise points, and irrelevant attributes
- Tries to finesse "curse of dimensionality"
- Most popular with binary or small cardinality categorical attributes
- **Requires only single scan of data; also streaming version is trivial.**

- Notable "Success": Text (bag-of-words representation + multinomial model per class).

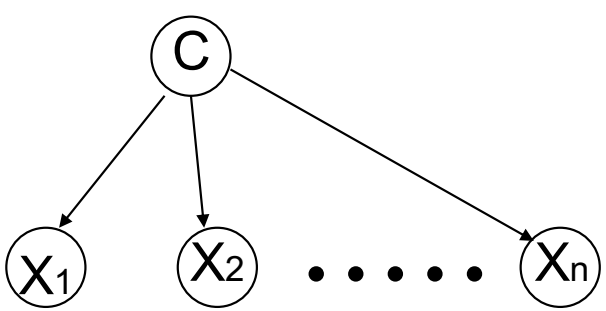


# Graphical Models

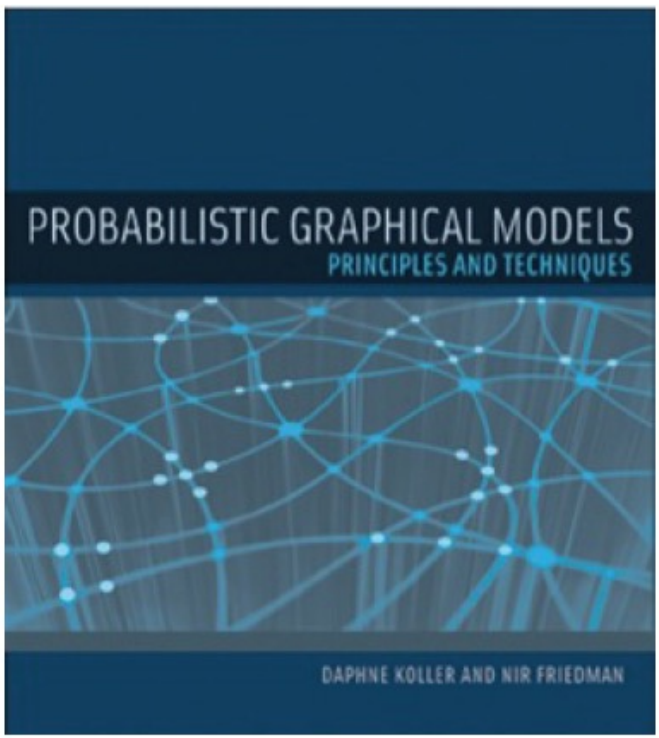
- Graphical models (see Kevin Murphy's survey, 2001) are (directed or undirected) graphs in which nodes represent random variables, and the lack of arcs represent (**assumed**) conditional independences: two sets of nodes are **conditionally independent** given a third set D, if all paths between nodes in A and B are separated by D.
  - Graphical models include mixture models, hidden Markov models, Kalman filters, etc

  **Several R packages**: http://cran.at.r-project.org/web/views/gR.html

- Naïve Bayes is a simple directed graphical model



# (Way Beyond Classification)



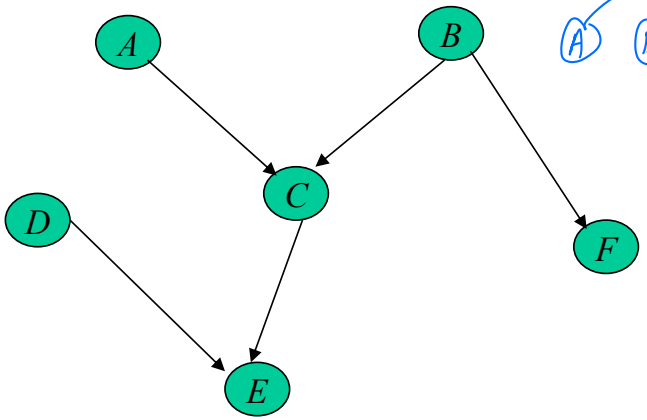

**Daphne Koller**
**Computer Science Dept.**
**Stanford University**

**Nir Friedman**
**School of Computer Science & Engineering**
**Hebrew University**

*MIT Press, 2009, 1231 pages*

# Bayesian (Belief) Networks

- Directed Acyclic Graph on **all** variables.
- Allows combining prior knowledge about (in)dependences among variables with observed training data




1. Any variable is conditionally independent of all non-descendent variables given its parents.
2. Graph also imposes partial ordering, e.g. A,B,C,D,E,F

   From (1) and (2), get P(A,B,C,D,E,F) = P(A)P(B)P(C|A,B)P(D)P(E|C,D)P(F|B)

$= \Pi_i$ P(node i | parents of node i)

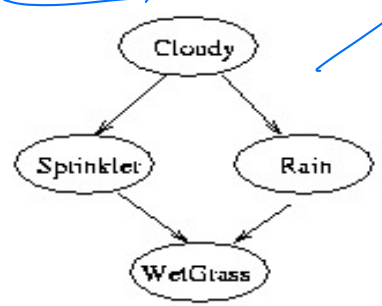
$P(C|D) = \frac{P(C,D)}{P(D)}$

# Example – Wet Grass (Murphy 01)

- See http://www.cs.ubc.ca/~murphyk/Bayes/bnintro.html
- From data, get Conditional Probability Distribution/Table ( CPD or CPT) for each variable.

$P(C,S,R,W) = P(C)\,P(S|C)\,P(R|C)\,P(W|S,R)$

| P(C=F) | P(C=T) |
|---|---|
| 0.5 | 0.5 |




| C | P(S=F) | P(S=T) |
|---|---|---|
| F | 0.5 | 0.5 |
| T | 0.9 | 0.1 |

| C | P(R=F) | P(R=T) |
|---|---|---|
| F | 0.8 | 0.2 |
| T | 0.2 | 0.8 |

| S | R | P(W=F) | P(W=T) |
|---|---|---|---|
| F | F | 1.0 | 0.0 |
| T | F | 0.1 | 0.9 |
| F | T | 0.1 | 0.9 |
| T | T | 0.01 | 0.99 |

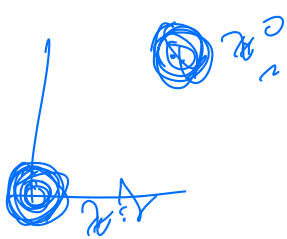
# Takeaways

- Network structure is modeling assumption
  - Exploit domain knowledge
  - Few edges means more independence among variables , so smaller CPTs
- Very flexible: can infer in any direction and involving any subset of variables.
  - Also suggest explanations
- Training data used to fill up the CPTs

# Network Properties and Usage

- Network structure is a modeling assumption, not necessarily unique
  - Some are better than others (good data fit + low complexity)
- If causality is known, make network from root causes …. to end effects.
- Usage: Inferencing
  - Infer the (probabilities of) values of one or more variables given observed values of some others.

**Software:** OpenBUGS http://mathstat.helsinki.fi/openbugs/
Python package
Infer.net http://research.microsoft.com/en-us/um/cambridge/projects/infernet/default.aspx
R packages such as bnlearn



# Inference: Effect to Cause (Bottom Up)

We observe the grass is wet. Is this because of sprinkler or because of rain? (T=1, F=0).

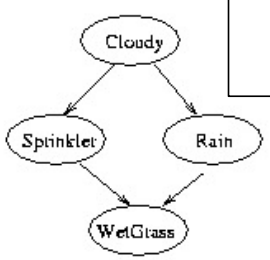
$P(S=1|W=1) =$

$\Sigma_{c,r} P(C=c,S=1, R=r, W=1) / \mathbf{P(W=1) = 0.2781/ .6471 = .43}$

$P(R=1|W=1) =$

$\Sigma c,s P(C=c,S=s, R=1, W=1) / P(W=1) = \mathbf{0.4581/ .6471 = .708}$

So more likely it is because of rain!




| P(C=F) | P(C=T) |
|---|---|
| 0.5 | 0.5 |

| C | P(S=F) | P(S=T) |
|---|---|---|
| F | 0.5 | 0.5 |
| T | 0.9 | 0.1 |

| C | P(R=F) | P(R=T) |
|---|---|---|
| F | 0.8 | 0.2 |
| T | 0.2 | 0.8 |

| S | R | P(W=F) | P(W=T) |
|---|---|---|---|
| F | F | 1.0 | 0.0 |
| T | F | 0.1 | 0.9 |
| F | T | 0.1 | 0.9 |
| T | T | 0.01 | 0.99 |

# Special Types of inference

Diagnostic - B is evidence of A (bottom-up)

previous example

Predictive - A can cause B (top-down)

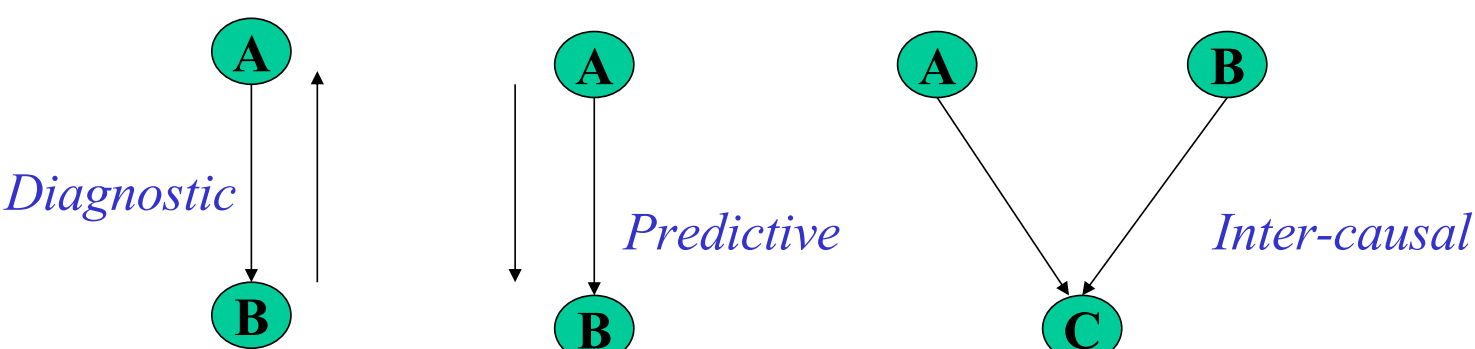
- e.g. P(grass wet | cloudy)

Inter-causal - suppose both A and B can cause C

if A "explains" C, it is evidence against B

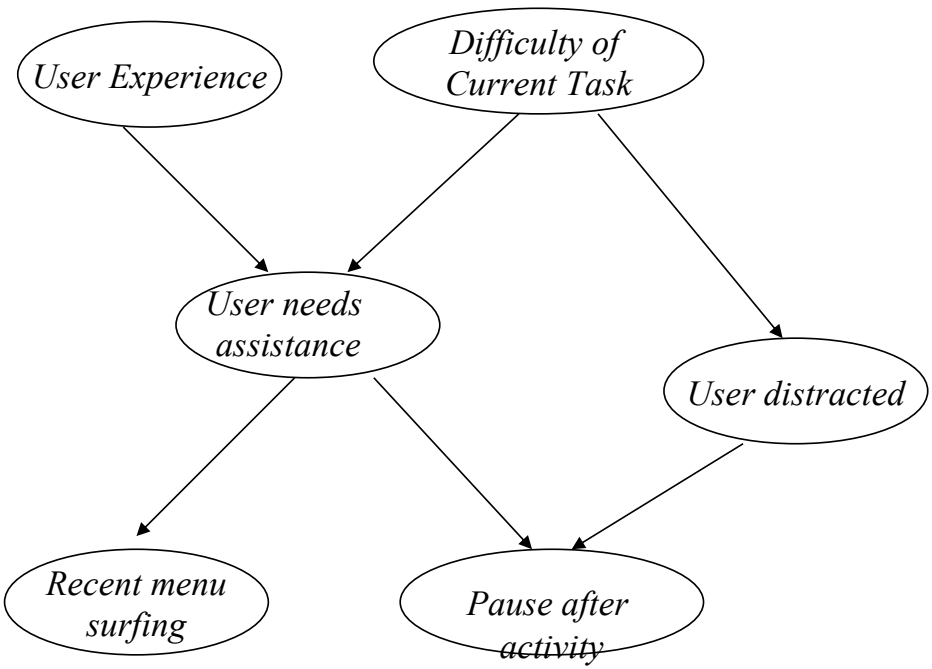
e.g. P(S=1 | W=1, R=1) = 0.1945, i.e. lower chance of sprinkler being ON if one also knows that it rained!

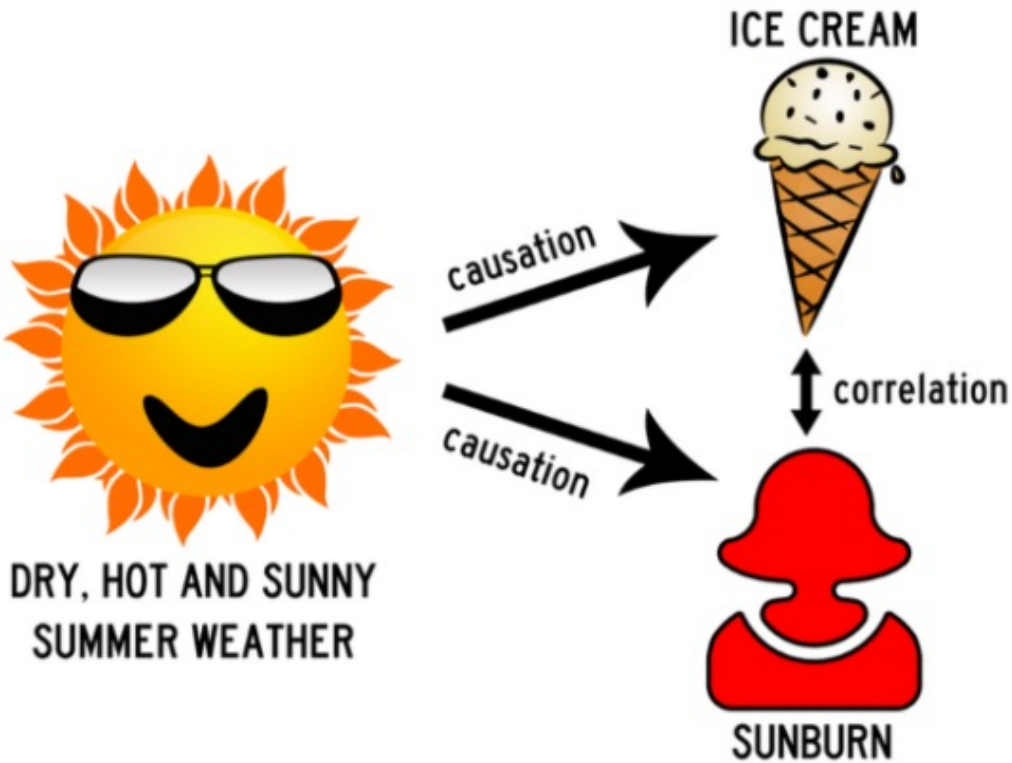
("explaining away","Berkson's paradox", or "selection bias")



# Microsoft Office Assistant

- Only part of Bayesian network shown (Horvitz et al, Lumiere Project)




ICE CREAM
causation
correlation
causation
DRY, HOT AND SUNNY
SUMMER WEATHER
SUNBURN

# More Classification Methods

Directly getting to the Posterior: Logistic Regression, Neural Networks

Misc: SVMs

# Logistic Regression (intro)

$y = \{0, 1\}$

$\mu(x) = E[y|x]$ $\quad (0, 1)$ $\quad 0.6$

$\frac{\mu(x)}{1-\mu(x)}$ $\quad (0, \infty)$

$\log \frac{\mu(x)}{1-\mu(x)} = \beta x$ $\quad (-\infty, \infty)$

$\log \frac{0.7}{0.3} = \beta x$

# Logistic Regression

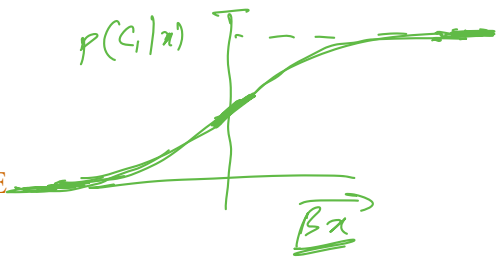
- Models a categorical variable (e.g. class label) as a function of predictors
- Studied extensively and have well-developed theory (variable selection methods, model diagnostic checks, extensions for dealing with correlated data)

Let $y(\mathbf{x}) =$ 0/1 Target variable for binary classification ($C_0$ vs. $C_1$)

- **Then** $\mu = E(y \mid \mathbf{x}) = P(C_1|\mathbf{x})$
  Model: $\ln [\mu / (1-\mu)] = \beta_0 + \beta_1 x_1 + \ldots + \beta_k x_k$
  $= \beta . \mathbf{x}$ (I)
- i.e. model "log-odds ratio" (aka **logit**) as a linear function of predictors

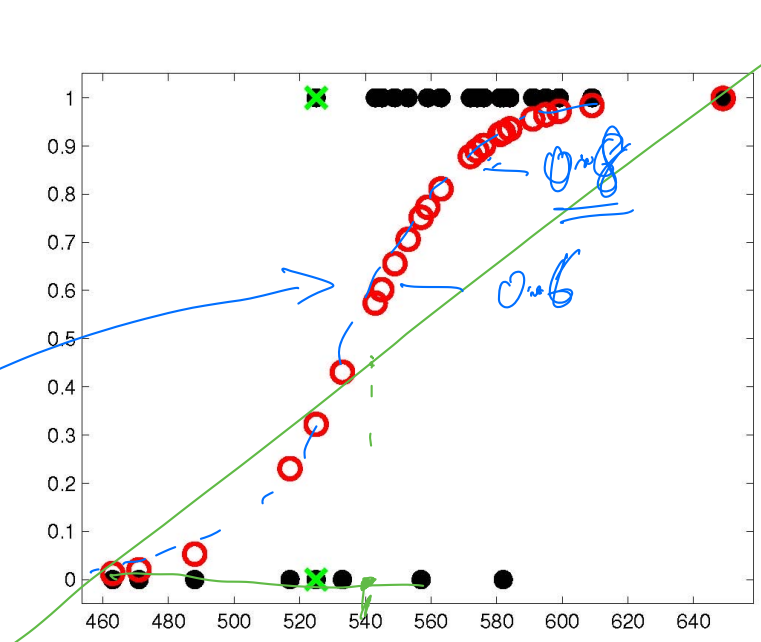
$P(C_1|x) = \mu(\vec{x}) = \dfrac{1}{1+e^{-\beta . x}} = \sigma(\beta \vec{x})$ ← LOGISTIC



# Formulation

- Equivalently: model $\mu = 1/(1+ \exp(-\beta . \mathbf{x})) = \sigma(\beta . \mathbf{x})$
  - $\sigma$ is called **the logistic function**, which is the inverse of logit
  - Rewrite model as
  - $\mu = \exp(\beta . \mathbf{x})/(\exp(\beta . \mathbf{x}) + \mathbf{1})$ and note that 1 = exp(0) to get a hint of how to generalize for more than 2 classes.




*SAT data*
*From KM pg 259.*

# Training

*Minimize Negative Log-Likelihood (NLL) of a suitable probability model*

Implied Stat Model: y's are i.i.d. Bernoulli

- $p(y|\mathbf{x}, \beta) = \text{Bernoulli}(y \mid \sigma(\beta . \mathbf{x}))$
- So $\text{NLL}(\beta) = -\Sigma_i [\, y_i \log \mu_i + (1-y_i) \log(1-\mu_i) \,]$

( cross-entropy error function)

If we use $\tilde{y}_i \in \{-1,1\}$ *then*

$\text{NLL}(\beta) = \Sigma_i \log(1+\exp(-\tilde{y}_i \beta . \mathbf{x}_i))$

Takeaway: a non-linear max-likelihood problem needs to be solved iteratively.

The unknown parameters ($\beta$) are estimated by maximum likelihood. (gradient descent or iterative solutions, e.g. Newton-Raphson, or iterative reweighted least squares see KM 8.3)

# SGD for Logistic Regression

- Loss for *i*th data point (when target is encoded as 0/1)

$$= -[y_i \log \sigma(\boldsymbol{\beta} \cdot x_i + b) + (1 - y_i) \log(1 - \sigma(\boldsymbol{\beta} \cdot x_i + b))]$$

- So gradient is: $\frac{\partial L(\boldsymbol{\beta}, b)}{\partial \boldsymbol{\beta}_j} = [\sigma(\boldsymbol{\beta} \cdot x_i + b) - y] x_{ij}$

  – Where $x_{ij}$ refers to the *j*th feature of $x_i$.

- The overall gradient: $\nabla L(f(x; \boldsymbol{\beta}), y)) = \begin{bmatrix} \frac{\partial}{\partial \boldsymbol{\beta}_1} L(f(x; \boldsymbol{\beta}), y) \\ \frac{\partial}{\partial \boldsymbol{\beta}_2} L(f(x; \boldsymbol{\beta}), y) \\ \vdots \\ \frac{\partial}{\partial \boldsymbol{\beta}_n} L(f(x; \boldsymbol{\beta}), y) \end{bmatrix}$

- SGD Update: $\boldsymbol{\beta}_{new} = \boldsymbol{\beta}_{old} - \eta \nabla L\left(f\left(x; \boldsymbol{\beta}_{old}\right), y\right)$

# SGD for Logistic Regression

- Loss for *i*th data point (when target is encoded as -1/1)

$$= \log\left(1 + e^{-y_i \boldsymbol{\beta}\cdot\mathbf{x}_i}\right)$$

- So gradient is: $\dfrac{\partial L(\boldsymbol{\beta}, b)}{\partial \boldsymbol{\beta}_j} = \left(\dfrac{-y_i \mathbf{x}_{ij}}{1 + e^{y_i \boldsymbol{\beta}\cdot\mathbf{x}_i}}\right)$

  –Where $x_{ij}$ refers to the *j*th feature of $x_i$.

- The overall gradient: $\nabla L(f(x;\boldsymbol{\beta}), y)) = \begin{bmatrix} \frac{\partial}{\partial \boldsymbol{\beta}_1} L(f(x;\boldsymbol{\beta}), y) \\ \frac{\partial}{\partial \boldsymbol{\beta}_2} L(f(x;\boldsymbol{\beta}), y) \\ \vdots \\ \frac{\partial}{\partial \boldsymbol{\beta}_n} L(f(x;\boldsymbol{\beta}), y) \end{bmatrix}$

- SGD Update: $\boldsymbol{\beta}_{new} = \boldsymbol{\beta}_{old} - \eta \nabla L\left(f\left(x; \boldsymbol{\beta}_{old}\right), y\right)$

# Properties

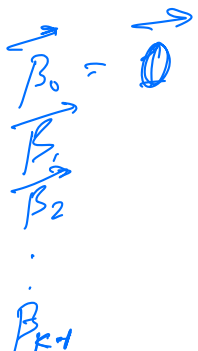
- Logistic regression is an example of a generalized linear model (GLM), with canonical link function = logit, corresponding to Bernoulli (see glmnet in R)

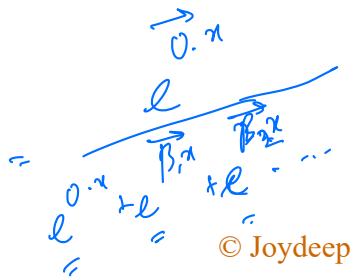
- Disadvantages:
  - Solution not simple closed form, but still reasonably fast
- Advantages:
  - Have parameters with useful interpretations
    - the effect of a unit change in $x_i$ is to increase the odds of a response multiplicatively by the factor $\exp(\beta_i)$
  - Quite robust, well developed

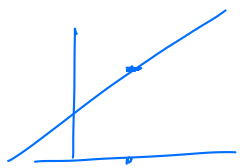
# Multiclass Logistic Regression

- Extension to K classes: use K-1 models
  - one each for $\ln [P(C_i|x)/P(C_k|x)]$
  - Set all coefficients for class K to 0 (to make the system **identifiable;** this choice is arbitrary)

- Put them together to get posteriors.
  - $P(C_i|\mathbf{x}) = \exp(\beta_{i0} + \beta_{i1}x_1 ..) / (1 + \Sigma_j \exp(\beta_{j0} + \beta_{j1}x_1 ..)$ , $i \neq k$
  - $P(C_K|\mathbf{x}) = ….$



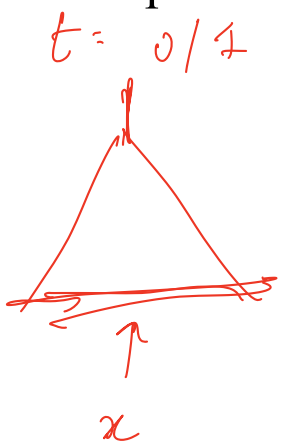


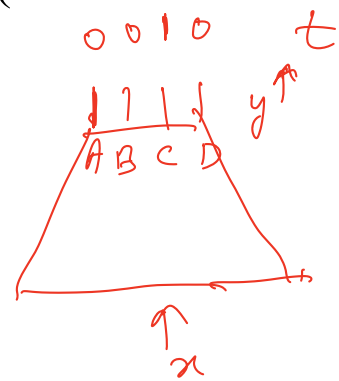


# Visit to SAS

# Multilayered Feedforward Networks for Classification

- choose sufficiently large network (no. of hidden units)
- trained by "1 of M" desired output values
  - ("one-hot coding")
- use validation set to determine when to stop training
- try several initializations, training regimens
- + powerful, nonlinear, flexible
- - interpretation? (Needs extra effort); slow ?




MSE

$$= \sum_{n} \sum_{i} \left[ y_{ni} - P(C_i|x_n) \right]^2 \frac{\partial f(x)}{\partial x}$$

+ IRREDUCIBLE TERM

# MLPs as Approximate Bayes Classifiers

- Output of "universal" Feedforward neural nets (MLP, RBF, deep nets) trained by "1 of M" desired output values, estimate Bayesian *a posteriori* probabilities if the cost function is

  mean square error OR cross-entropy

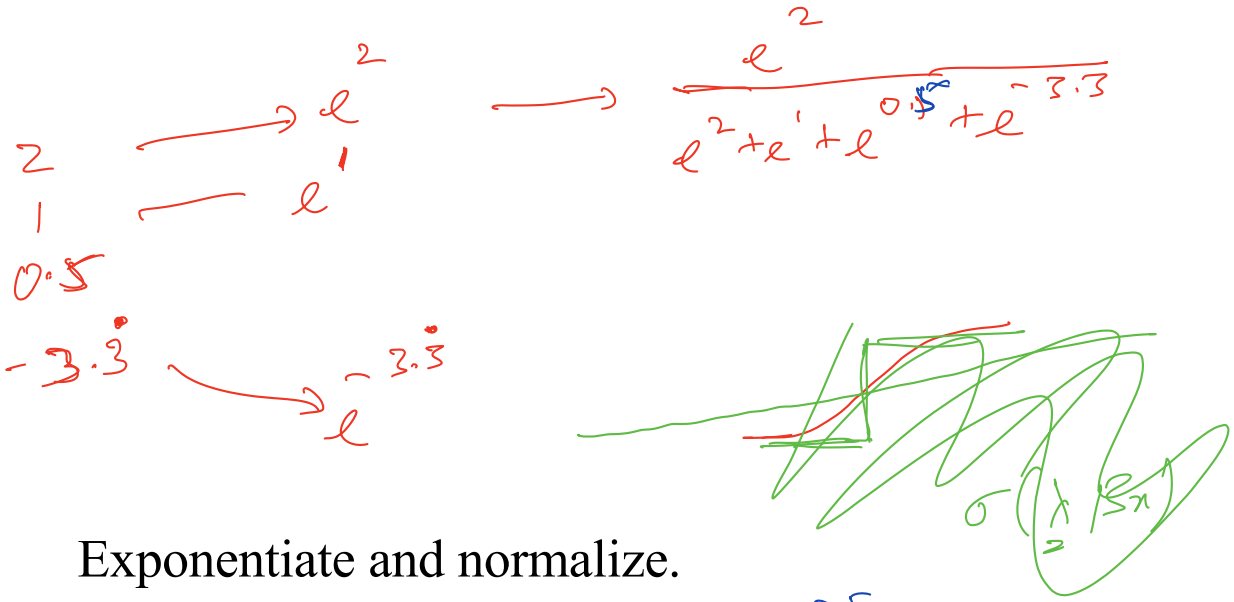
1990

Nowadays some packages use softmax, but often not needed.

- Significance:
  - interpretation of outputs; quality of results
  - setting of thresholds for acceptance/rejection
  - can combine outputs of multiple networks

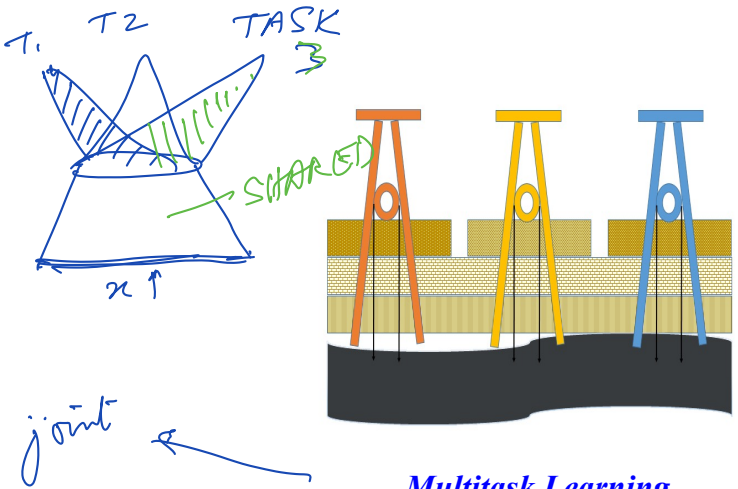
# Softmax

» Monotonic transformation of a set of numbers: x → t(x)
  – All t(x) are non-negative
  – Sum to one
  – Potential for interpretation as discrete probabilities.



Exponentiate and normalize.

# Multi-Task & Transfer Learning*



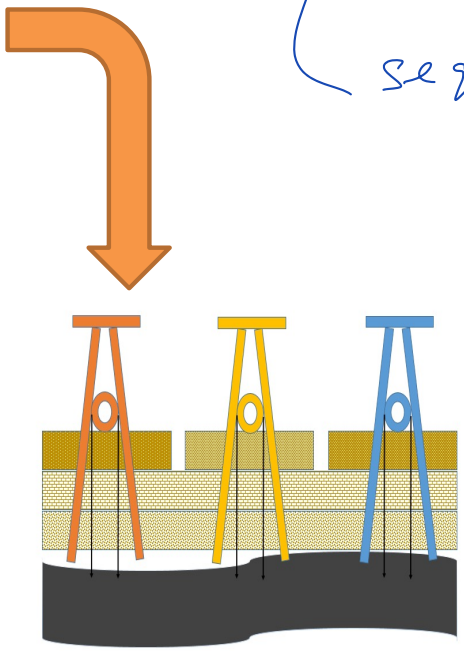

***Multitask Learning***

*Simultaneously learning multiple (related) tasks*

*Code leaders*

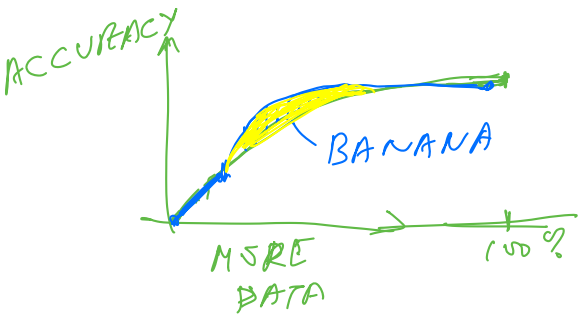
***Transfer Learning***

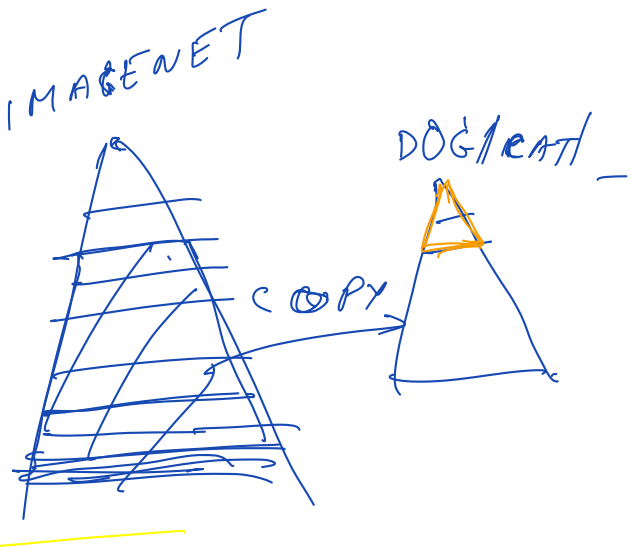
make use of the knowledge gained while solving one problem and applying it to a different but related problem.



*Active Learning*: *incrementally recruiting labelled points based on analysis of model on existing training set. Usually evaluated using a "banana" plot.*

# Extras



# Naïve Bayes Example

*Step 1: Estimating Univariate Probabilities for each variable-class combination*

Discrete Probabilities: (Binary/Categorical)

See tax evasion example in main slides.

Continuous variables:

- Discretize the range into bins
  - one ordinal attribute per bin
  - violates independence assumption
- Binarize: (may lose substantial info)
- Probability density estimation:
  - (usually assuming Normal distribution)

# How to Estimate Probabilities from Data?

| Tid | Refund | Marital Status | Taxable Income | Evade |
|---|---|---|---|---|
| 1 | Yes | Single | 125K | No |
| 2 | No | Married | 100K | No |
| 3 | No | Single | 70K | No |
| 4 | Yes | Married | 120K | No |
| 5 | No | Divorced | 95K | Yes |
| 6 | No | Married | 60K | No |
| 7 | Yes | Divorced | 220K | No |
| 8 | No | Single | 85K | Yes |
| 9 | No | Married | 75K | No |
| 10 | No | Single | 90K | Yes |

- Normal distribution:

$$P(x_j \mid c_j) = \frac{1}{\sqrt{2\pi\sigma_{ij}^2}} e^{-\frac{(x_j-\mu_{ij})^2}{2\sigma_{ij}^2}}$$

  - One for each $(x_i, c_i)$ pair

- For (Income, Class=No):
  - If Class=No
    - sample mean = 110
    - sample variance = 2975

$$P(Income = 120 \mid No) = \frac{1}{\sqrt{2\pi}\,(54.54)} e^{-\frac{(120-110)^2}{2(2975)}} = 0.0072$$

# Example of Naïve Bayes Classifier

**Given a Test Record:**

$$X = (\text{Refund} = \text{No}, \text{Married}, \text{Income} = 120\text{K})$$

naive Bayes Classifier:

P(Refund=Yes|No) = 3/7
P(Refund=No|No) = 4/7
P(Refund=Yes|Yes) = 0
P(Refund=No|Yes) = 1
P(Marital Status=Single|No) = 2/7
P(Marital Status=Divorced|No)=1/7
P(Marital Status=Married|No) = 4/7
P(Marital Status=Single|Yes) = 2/7
P(Marital Status=Divorced|Yes)=1/7
P(Marital Status=Married|Yes) = 0

For taxable income:
If class=No: sample mean=110
sample variance=2975
If class=Yes: sample mean=90
sample variance=25

- P(X|Class=No) = P(Refund=No|Class=No)
  × P(Married| Class=No)
  × P(Income=120K| Class=No)
  = 4/7 × 4/7 × 0.0072 = 0.0024

- P(X|Class=Yes) = P(Refund=No| Class=Yes)
  × P(Married| Class=Yes)
  × P(Income=120K| Class=Yes)
  = 1 × 0 × 1.2 × $10^{-9}$ = 0

Since P(X|No)P(No) > P(X|Yes)P(Yes)

Therefore P(No|X) > P(Yes|X)

=> Class = No

# Smoothing Naïve Bayes

- Avoids zero probablity due to one attribute-value/class combo being absent in training data.
  - Zeroes entire product term
- Probability estimation:

$$\text{Original}: P(x_i \mid C) = \frac{N_{ic}}{N_c}$$

$$\text{m-estimate}: P(x_i \mid C) = \frac{N_{ic} + mp_i}{N_c + m}$$

c: number of classes

p: prior probability

m: weight of prior (i.e. # of virtual samples)

e.g. in text analysis, add a "virtual document that has one instance of every word in the vocabulary (Laplace smoothing): $(N_{ic} + 1) / (Nc + |vocab|)$