

SRI SIDDHARTHA INSTITUTE OF TECHNOLOGY

(A CONSTITUENT COLLEGE OF SSAHE)



LAB MANUAL

**SUBJECT: MICROPROCESSORS AND EMBEDDED
SYSTEMS**

SUBJECT CODE: 18CS408



DEPARTMENT OF INFORMATION SCIENCE AND ENGINEERING, SSIT

Arm Labaratory

Part A : Develop and exercise the following using ARM Assembly Language

1. To perform Arithmetic operations of two integer numbers.

Addition 32-bit :

```
AREA ADDTIN, CODE
```

```
ENTRY
```

```
LDR R0,=VALUE1
```

```
LDR R1,[R0]
```

```
LDR R0,=VALUE2
```

```
LDR R2,[R0]
```

```
ADDS R3,R2,R1
```

```
VALUE1 DCD &BBBBBBBB
```

```
VALUE2 DCD &CCCCCCCC
```

```
END
```

Subtraction 32-bit :

```
AREA SUBTIN, CODE
```

```
ENTRY
```

```
LDR R0,=VALUE1
```

```
LDR R1,[R0]
```

```
LDR R0,=VALUE2
```

```
LDR R2,[R0]
```

```
SUBS R3,R2,R1
```

```
VALUE1 DCD &BBBBBBBB
```

```
VALUE2 DCD &CCCCCCCC
```

```
END
```

Subtraction 16-bit :

```
AREA SUBTIN, CODE
```

```
ENTRY
```

```
LDR R0,=VALUE1
```

```
LDRH R1,[R0]
```

```
LDR R0,=VALUE2
```

```
LDRH R2,[R0]
```

```
SUBS R3,R2,R1
```

```
VALUE1 DCW &BBBB
```

```
VALUE2 DCW &CCCC
```

```
END
```

Subtraction 8-bit :

```
AREA SUBTIN, CODE
```

```
ENTRY
```

```
LDR R0,=VALUE1
```

```
LDRB R1,[R0]
```

```
LDR R0,=VALUE2
```

```
LDRB R2,[R0]
```

```
SUBS R3,R2,R1
```

```
VALUE1 DCB &BB
```

```
VALUE2 DCB &CC
```

```
END
```

<u>Multiplication 32-bit :</u>	<u>Multiplication 16-bit :</u>	<u>Multiplication 8-bit :</u>
<p>AREA MULTIN, CODE</p> <p>ENTRY</p> <p>LDR R0,=VALUE1</p> <p>LDR R1,[R0]</p> <p>LDR R0,=VALUE2</p> <p>LDR R2,[R0]</p> <p>UMULL R4,R3,R2,R1</p> <p>VALUE1 DCD &BBBBBBBB</p> <p>VALUE2 DCD &CCCCCCCC</p> <p>END</p>	<p>AREA MULTIN, CODE</p> <p>ENTRY</p> <p>LDR R0,=VALUE1</p> <p>LDRH R1,[R0]</p> <p>LDR R0,=VALUE2</p> <p>LDRH R2,[R0]</p> <p>UMUL R3,R2,R1</p> <p>VALUE1 DCW &BBBB</p> <p>VALUE2 DCW &CCCC</p> <p>END</p>	<p>AREA MULTIN, CODE</p> <p>ENTRY</p> <p>LDR R0,=VALUE1</p> <p>LDRB R1,[R0]</p> <p>LDR R0,=VALUE2</p> <p>LDRB R2,[R0]</p> <p>UMUL R3,R2,R1</p> <p>VALUE1 DCB &BB</p> <p>VALUE2 DCB &CC</p> <p>END</p>

Addition 64-bit :

```

AREA ADDTIN, CODE
ENTRY
LDR R0,=VALUE1
LDR R1,[R0]
LDR R2,[R0,#4]
LDR R0,=VALUE2
LDR R3,[R0]
LDR R4,[R0,#4]
ADDS R5,R3,R1
ADC R6,R4,R2
LDR R0,=RESULT
STR R4,[R0]
STR R7,[R0,#4]
VALUE1 DCD &12345678,&11111111
VALUE2 DCD &AAAAAAAA,&BBBBBBBB
RESULT DCD 0
END
  
```

Subtraction 64-bit :

AREA SUBTIN, CODE

ENTRY

LDR R0, =VALUE1

LDR R1, [R0]

LDR R2, [R0, #4]

LDR R0, =VALUE2

LDR R3, [R0]

LDR R4, [R0, #4]

SUBS R5, R3, R1

SBC R6, R4, R2

LDR R0, =RESULT

STR R4, [R0]

STR R7, [R0, #4]

VALUE1 DCD &12345678, &11111111

VALUE2 DCD &AAAAAAAA, &BBBBBBBB

RESULT DCD 0

END

Multiplication 64-bit :

AREA MULTIN, CODE

ENTRY

LDR R0, =VALUE1

LDR R1, [R0]

LDR R2, [R0, #4]

LDR R0, =VALUE2

LDR R3, [R0]

LDR R4, [R0, #4]

UMULL R6, R5, R3, R1

UMLAL R8, R7, R4, R2

LDR R0, =RESULT

STR R4,[R0]

STR R9,[R0,#4]

VALUE1 DCD &12345678,&11111111

VALUE2 DCD &AAAAAAAA,&BBBBBBBB

RESULT DCD 0

END

2. To perform Logical,shift,Rotate and Compare instructions of two integer numbers.

AREA Program,CODE, READONLY

ENTRY

LDR R0,=VALUE1

LDR R1,[R0]

LDR R0,=VALUE2

LDR R2,[R0]

AND R3,R2,R1

OR R4,R2,R1

EOR R5,R2,R1

LOOP LDR R6,R5,R5,LSL,#2

LDR R7,R5,R5,LSR,#2

LDR R8,R5,R5,ROR,#2

CMP R6,R7

BNE LOOP

VALUE1 DCD &BBBBBBBB

VALUE2 DCD &CCCCCCCC

END

2. To perform the following operation:

I. To move a block of data from one memory segment to another.

II. To exchange block of data between two memory segments.

<pre> AREA Block, CODE, READONLY num EQU 20 ; set number of words to be copied ENTRY ; mark the first instruction called start LDR r0, =src ; r0 = pointer to source block LDR r1, =dst ; r1 = pointer to destination block MOV r2, #num ; r2 = number of words to copy MOV sp, #0x400 ; Set up stack pointer (sp) blockcopy MOVS r3,r2, LSR #3 ; Number of eight word multiples BEQ copywords ; Fewer than eight words to move? PUSH {r4-r11} ; Save some working registers octcopy LDM r0!, {r4-r11} ; Load 8 words from the source STM r1!, {r4-r11} ; and put them at the destination SUBS r3, r3, #1 ; Decrement the counter BNE octcopy ; ... copy more POP {r4-r11} ; Don't require these now - restore ; originals copywords ANDS r2, r2, #7 ; Number of odd words to copy BEQ stop ; No words left to copy? wordcopy LDR r3, [r0], #4 ; Load a word from the source and STR r3, [r1], #4 ; store it to the destination SUBS r2, r2, #1 ; Decrement the counter BNE wordcopy ; ... copy more stop AREA BlockData, DATA, READWRITE src DCD 1,2,3,4,5,6,7,8,1,2,3,4,5,6,7,8,1,2,3,4 </pre>	<pre> 1. AREA PROGRAM, CODE ENTRY LDR R2, =0X0A LDR R0, =SOURCE1 LDR R1, =DEST UP LDR R3, [R0], #4 STR R3, [R1], #4 SUBS R2, #1 BNE UP STOP B STOP AREA SOURCE1, DATA, READONLY DCD 0X20, 0X10, 0X30, 0X40, 0X50, 0X60, 0X70, 0X80, 0X90, 0X0A AREA DEST, DATA, READWRITE SPACE 0X28 ALIGN END </pre>
---	--

STOP B STOP

```

20.      AREA SOURCE,DATA,READONLY
21.      DCD 0X12,0X34,0X05,0X25,0X10
22.      AREA RESULT,DATA,READWRITE
23.      SPACE 0X0A
24.      END
    
```

4. To sort a set of 8-bit numbers.

```

      AREA PROGRAM,CODE,READONLY
      ENTRY
      LDR R3,=0X0A
      SUB R3,#1
ABOVE MOV R4,R3
      LDR R0,=SOURCE
UP     LDRB R1,[R0],#01
      LDRB R2,[R0]
      CMP R1,R2
      BCC DOWN
      STRB R1,[R0],#-1
      STRB R2,[R0],#1
DOWN  SUBS R4,#01
      BNE UP
      SUBS R3,#01
      BNE ABOVE
STOP B STOP
      AREA SOURCE,DATA,READWRITE
      SPACE 0X0A
      END
    
```

5.To search for a given element in a set of 32-bit numbers

```

      AREA PROGRAM,CODE,READONLY
      ENTRY
      MOV R4,#0X00
      MOV R5,#0XFF
BACK  LDR R3,=0X05
      LDR R6,=RES
      LDR R0,=SOURCE
      MOV R1,#040
      LDR R2,[R0],#4
      BEQ EXIT
      SUBS R3,R3,#1
      BNE BACK
      STR R4,[R6]
STOP B STOP
EXIT  STR R5,[R6]
      B STOP
      AREA SOURCE,DATA,READONLY
      DCD 0X10,0X20,0X30,0X40,0X50
      AREA KEY,DATA,READONLY
      DCD 0X05
      AREA RES,DATA,READWRITE
      SPACE 0X04
      END
    
```


Part B: Develop and execute the following using c :**6. To interface LED and realize Ring and Johnson counter.****Ring counter:**

```
#include<LPC21XX.h>

unsigned int delay,i,k;

int main(void)
{
IO0DIR = 0x00FF0000;

while(1)
{
k= 0x00010000;
for(i=0;i<8;i++)
{
IO0SET=0x00FF0000;
for(delay=0;delay<50000;delay++);
IO0CLR = k;
for(delay=0;delay<50000;delay++);
k=k<<1;
}
}
```

Johnson counter:

```
#include<LPC21XX.h>

unsigned int delay,i,k;

int main(void)
{
IO0DIR = 0x00FF0000;

while(1)
{
k= 0x00010000;
for(i=0;i<8;i++)
{
IO0SET=0x00FF0000;
```

```
for(delay=0;delay<50000;delay++);
IO0CLR = k;
for(delay=0;delay<50000;delay++);
k=(k<<1)|k;
}
}
```

7.To realize BCD up/down counter using 7-segment display.

```
#include <LPC21xx.h>

signed int delay, count=0, Switchcount=0;
unsigned int Disp[10]={0x003F0000, 0x00060000, 0x005B0000, 0x004F0000, 0x00660000,0x006D0000,0x007D0000,
0x00070000, 0x007F0000, 0x006F0000 };
#define ALLDISP 0x10000000

int main (void)
{
    PINSEL0 = 0x00000000;
    IO0DIR = 0xF0FF0000;
    IO0SET |= ALLDISP;
    while(1)
    {
        for(Switchcount=0;Switchcount<=9;Switchcount++)
        {
            IO0CLR = 0x00FF0000;
            for(delay=0;delay<100;delay++)
                IO0SET = Disp[Switchcount];
            for(delay=0;delay<1000000;delay++)
            {}
        }
        for(Switchcount=9;Switchcount>=0;Switchcount--)
        {

            IO0CLR = 0x00FF0000;
            for(delay=0;delay<100;delay++)
                IO0SET = Disp[Switchcount];
            for(delay=0;delay<1000000;delay++)
```

```
        {}  
    }  
}
```

8.To generate the waveforms using DAC.

1.Sinewave 2.Squarewave 3.Trianglewave

Sinewave:

```
int count=0,sinevalue,value;  
unsigned char sine_tab[49]=  
{0x80,0x90,0xA1,0xB1,0xC0,0xCD,0xDA,0xE5,0xEE,0xF6,0xFB,0xFE,0xFF,0xFE,0xFB,0xF6,0xEE,0xE5,0xDA,0xC  
D,0xC0,0xB1,0xA1,0x90,0x80,0x70,0x5F,0x4F,0x40,0x33,0x26,0x1B,0x12,0x0A,0x05,0x02,0x00,0x02,0x05,0x0A,0x  
12,0x1B,0x26,0x33,0x4F,0x5F,0x70,0x80};  
int main(void)  
{  
    PINSEL0=0x00000000;  
    IO0DIR = 0x00FF0000;  
    Ccount=0;  
    While(1)  
    {  
        for(count=0;count<48;count++)  
        {  
            sinevalue=sine_tab[count];  
            value= 0x00FF0000&(sinevalue<<16);  
            IO0PIN=value;  
        }  
    }  
}
```

Square wave:

```
#include<LPC21XX.h>  
void delay(void);  
int main()  
{  
    PINSEL0 = 0x00000000;
```

```
PINSEL1 = 0x00000000;
IO0DIR = 0x00FF0000;

While(1)
{
    IO0PIN = 0x00000000;
    delay();
    IO0PIN = 0x00FF0000;
    delay();
}
}
```

Void delay(void)

```
{
    unsigned int i=0;
    for(i=0;i<=95000;i++);
}
```

Triangle wave :

```
#include<LPC21XX.h>
int main()
{
    unsigned long int temp = 0x00000000;
    unsigned int i=0;
    IO0DIR=0x00FF0000;
    while(1)
    {
        for(i=0;i!=0xFF;i++)
        {
            temp= i;
            temp = temp<<16;
            IO0PIN = temp;
        }
        for(i=0xFF;i!=0;i--)
        {
            temp= i;
            temp = temp<<16;
            IO0PIN = temp;
        }
    }
}
```

9. To interface and rotate stepper motor clockwise and anticlockwise direction.

```
#include<LPC21XX.h>
void clockwise(void);
void anticlockwise(void);
```

```
unsigned long int v1,v2;
unsigned int i=0;j=0,k=0;
int main(void)
{
    PINSEL0 = 0x00FFFFFF;
    IO0DIR = 0x0000F000;
    while(1)
    {
        for(j=0;j<50;j++);
        clockwise();
        for(k=0;k<6500;k++);

        for(j=0;j<50;j++);
        anticlockwise();
        for(k=0;k<6500;k++);
    }
}

void clockwise(void);
{
    v1= 0x00000800;
    for(i=0;i<=3;i++)
    {
        v1=v1<<1;
        v2 = v1;
        v2 = v2 & 0x0000F000;
        IO0PIN = v2;
        for(k=0;k<3000;k++);
    }
}

void anticlockwise(void);
{
    v1= 0x00010000;
    for(i=0;i<=3;i++)
    {
        v1=v1>>1;
        v2 = v1;
        v2 = v2 & 0x0000F000;
        IO0PIN = v2;
        for(k=0;k<3000;k++);
    }
}
```

Part C: Develop and execute the following using the Genuine Aurdino UNO board

12. Build a motion detector using a PIR sensor and display appropriate messages.

```
void setup()
{
  pinMode(2,OUTPUT)
  pinMode(3,INPUT)
}
void loop()
{
  if(digitalRead(2)==HIGH)
  {
    digitalWrite(3,HIGH);
    delay(100);
    digitalWrite(3,LOW);
    delay(100);
  }
}
```

13. Traffic light simulation using Breadboard, LED's,Resistors.

```
void setup()
{
  pinMode(8,OUTPUT);
  pinMode(9,OUTPUT);
  pinMode(10,OUTPUT);
}
void loop()
{
  digitalWrite(8,HIGH);
  digitalWrite(9,LOW);
  digitalWrite(10,LOW);
  delay(100);
  digitalWrite(9,HIGH);
  digitalWrite(8,LOW);
  digitalWrite(10,LOW);
  dealy(100);
  digitalWrite(10,HIGH);
  digitalWrite(8,LOW);
  digitalWrite(9,LOW);
  delay(100);
}
```

14. Program to test the UART Function

```
#include <lpc214x.h>

void uart_interrupt(void) __irq;

unsigned char temp;
unsigned char rx_flag=0, tx_flag=0;

int main(void)
{
    PINSEL0=0X00000005;           /
    IODIR1 = 0X00ff0000;

    U0LCR = 0X00000083;
    U0DLM = 0X00;
    U0DLL = 0x13;
    U0LCR = 0X00000003;
    U0IER = 0X03;

    VICVectAddr0 = (unsigned long)uart_interrupt;
    VICVectCntl0 = 0x20|6;
    VICIntEnable = 0x00000040;

    rx_flag = 0x00;
    tx_flag = 0x00;

    while(1)
    {
        while(rx_flag == 0x00);
        rx_flag = 0x00;
        while(tx_flag == 0x00);
        tx_flag = 0x00;
    }
}

// Do this forever
void uart_interrupt(void) __irq
{
    temp = U0IIR;
    temp = temp & 0x06;

    if(temp == 0x02)
    {
        tx_flag = 0xff;
        VICVectAddr=0;
    }

    else if(temp == 0x04)
    {
        U0THR = U0RBR;
        rx_flag = 0xff;
    }
}
```

```
    VICVectAddr=0;
  }
}
```

15. Rain indicator using rain sensor and water resource

```
void setup()
{
  pinMode(12,INPUT);
  pinMode(13,OUTPUT);
}
Void loop()
{
  if(digitalRead(12)==LOW)
  {
    digitalWrite(13,HIGH);
    delay(100);
    digitalWrite(13,LOW);
    delay(500);
  }
}
```