

# Rohith Pallamreddy

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## EDUCATION

<b>Georgia Institute of Technology</b> <i>Bachelor of Science in Computer Science, GPA: 4.00/4.00</i>	<b>Atlanta, GA</b> <i>May 2027</i>
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## EXPERIENCE

<b>REMAP Lab</b> <i>Undergraduate Research Assistant</i> <ul style="list-style-type: none"><li>Analyzed <b>large-scale spatiotemporal mobility data</b>, including anonymized cellphone tracking and travel-route records</li><li>Applied and evaluated <b>map-matching algorithms</b> to improve trajectory accuracy and analytical usability</li><li>Integrated mobility, census, and environmental data to identify behavioral responses to extreme heat, observing an <b>approximately 25% reduction in trip volume during heatwave periods</b></li></ul>	<b>Atlanta, GA</b> <i>Jan 2025 – Present</i>
<b>No Heat (Vertically Integrated Project)</b> <i>Research Group Member</i> <ul style="list-style-type: none"><li>Analyzed <b>high-resolution geospatial datasets</b> to characterize urban microclimates in Savannah, GA</li><li>Generated raster layers of building height, canopy height, and land elevation using <b>Google Earth Engine, and USGS LiDAR Explorer</b></li><li>Computed <b>Universal Thermal Climate Index (UTCI)</b> using SOLWEIG and UROCK to identify pedestrian routes that <b>reduce thermal exposure by approximately 12°C without increasing route length</b></li></ul>	<b>Atlanta, GA</b> <i>Aug 2025 – Present</i>
<b>System Technology Works</b> <i>Computer Science Intern</i> <ul style="list-style-type: none"><li>Led a team of interns to deploy and optimize <b>LLMs</b> on a humanoid robot (<b>Zeus2Q</b>) using <b>Ollama</b>, improving on-device inference latency</li><li>Enhanced robotic mobility systems to support autonomous cart pushing and robust navigation</li></ul>	<b>Alpharetta, GA</b> <i>May 2024 – Aug 2024</i>
<b>Horror Hacks</b> <i>Chief Organizer</i> <ul style="list-style-type: none"><li>Organized and coordinated an <b>international hackathon</b>, managing logistics and programming for <b>40+ participants</b> across two iterations</li><li>Designed and led beginner-focused tutorials and workshops, increasing participant engagement and accessibility</li></ul>	<b>Alpharetta, GA</b> <i>Oct 2022 – May 2024</i>

## PROJECTS

<b>LADEE Lunar Dust Risk Mapping &amp; Path Optimization</b> <ul style="list-style-type: none"><li>Built predictive models using NASA’s <b>LADEE dataset</b> to quantify lunar dust hazards, implementing a danger coefficient (0 – 10)</li><li>Simulated terrain-level dust accumulation and micrometeoroid impacts with <b>PyBullet Physics Engine</b></li><li>Computed optimized rover routes using weighted <b>Dijkstra’s algorithm</b>, reducing dust exposure by <b>approximately 50%</b> compared to shortest-path navigation while respecting mission windows</li></ul>	<i>Nov 2025 – Dec 2025</i>
<b>Cosmetics Wizard (Full-Stack Ingredient Analyzer)</b> <ul style="list-style-type: none"><li>Developed an AI/ML system for <b>cosmetic safety</b>, leveraging <b>vector embeddings</b> to detect hazardous ingredients</li><li>Built a full-stack interface that generates <b>safety ratings (predicting within 0.3 points)</b> and identifies the top 5 safest and most hazardous ingredients from ingredient input</li></ul>	<i>Sept 2025 – Nov 2025</i>
<b>CounterPunch AI (Computer Vision Defense Analyzer)</b> <ul style="list-style-type: none"><li>Used <b>MediaPipe</b> and computer vision to analyze boxing defense, revealing that simple back-and-forth head movement is insufficient</li><li>Built an <b>interactive dashboard</b> with dynamic graphs and a "Predictability Score," helping beginners improve head movement and reducing their vulnerability score by <b>approximately 70%</b> during training drills</li></ul>	<i>May 2025 – Sept 2025</i>
<b>Motorcycle Simulator Project</b> <ul style="list-style-type: none"><li>Developed a <b>motorcycle racing simulator</b> via Georgia Tech <b>Create-X</b> with realistic controls for the gaming industry</li><li>Designed <b>CAD models</b> in Fusion 360 and integrated with Arduino-based control system for physical input mapping</li></ul>	<i>Aug 2025 – Dec 2025</i>

## CERTIFICATIONS

<b>NVIDIA</b>   AI Infrastructure and Operations Fundamentals	<i>Dec 2025</i>
<b>IBM</b>   GenAI and LLMs: Architecture and Data Preparation	<i>Dec 2025</i>
<b>Microsoft</b>   Generative AI for Data Science	<i>Dec 2025</i>
<b>Google</b>   Bracketology with Google Machine Learning	<i>Dec 2025</i>

## SKILLS

<b>Programming &amp; Data Science:</b> Python (Pandas, NumPy, SciPy, Matplotlib, Seaborn, Plotly, TensorFlow, PyTorch, Keras, PyBullet, MediaPipe, OpenCV, Vector Embeddings, AI/ML, CV, NLP), C, C++, Java, SQL, R, Julia, MATLAB, Bash/Shell Scripting, Julia, GeoSpatial Data (LiDAR, Raster, Vector, SOLWEIG, UMEP, QGIS, ArcGIS, Google Earth Engine), APIs/REST, Docker, Kubernetes
<b>Mathematics &amp; Statistics:</b> Descriptive & Inferential Statistics, Probability, Hypothesis Testing, Linear Algebra, Calculus, Multivariable Calculus, Differential Equations, Discrete Math, Graph Theory, Optimization, Numerical Methods, Proofs, Machine Learning Theory, Bayesian Methods, Time Series Analysis
<b>Tools &amp; Platforms:</b> Git/GitHub, GitLab, Jupyter Notebook, VS Code, IntelliJ, Linux/Unix, PACE ICE, VS Code, Docker, Kubernetes, AWS, GCP, Azure, Postman, Tableau, Power BI
<b>Creative &amp; Design:</b> Drawing (8 yrs), 3D Modeling & Animation (5 yrs), Blender, Maya, Photoshop, Illustrator, CAD, Figma