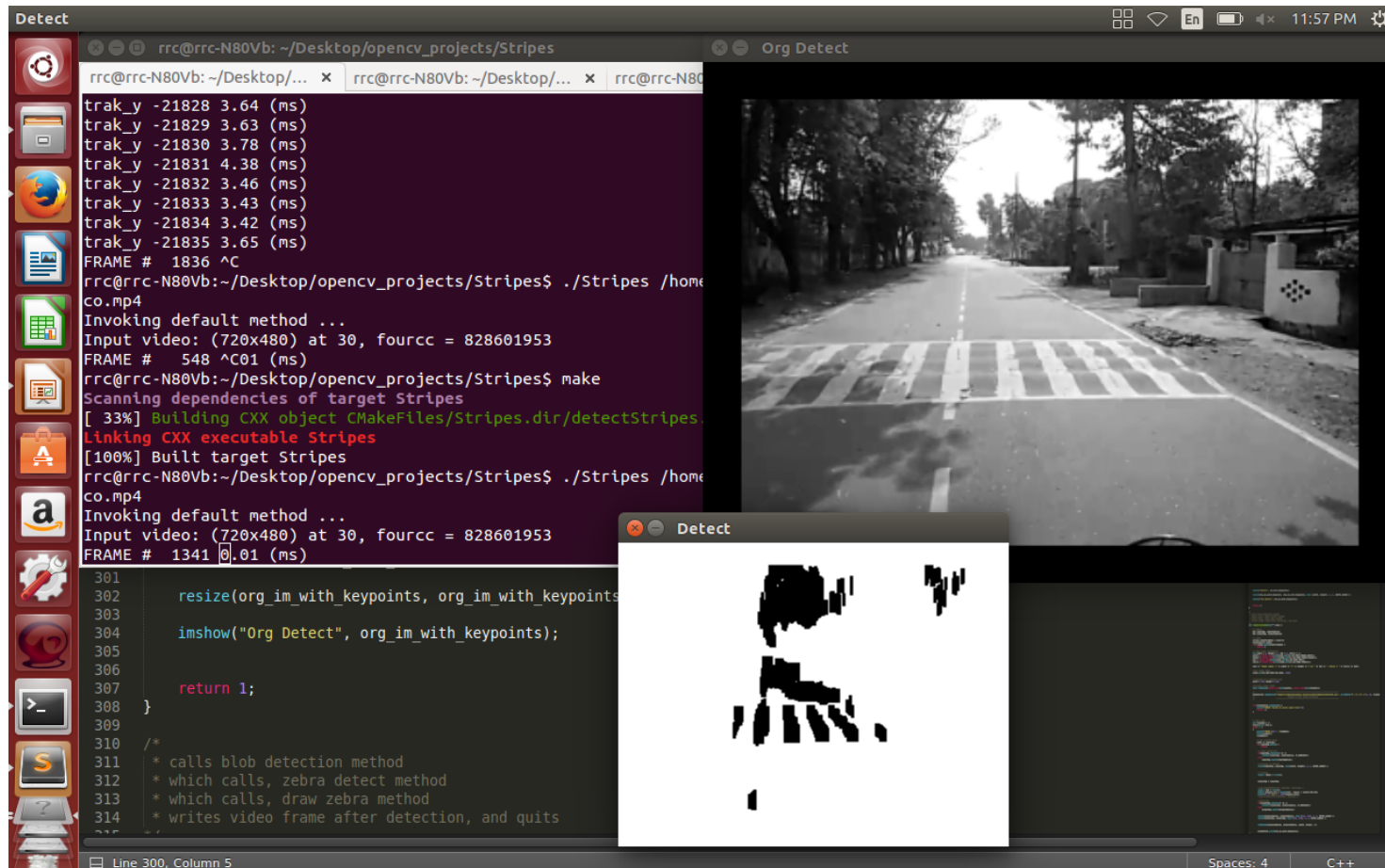


Algo 1 (detectStripes.cpp)

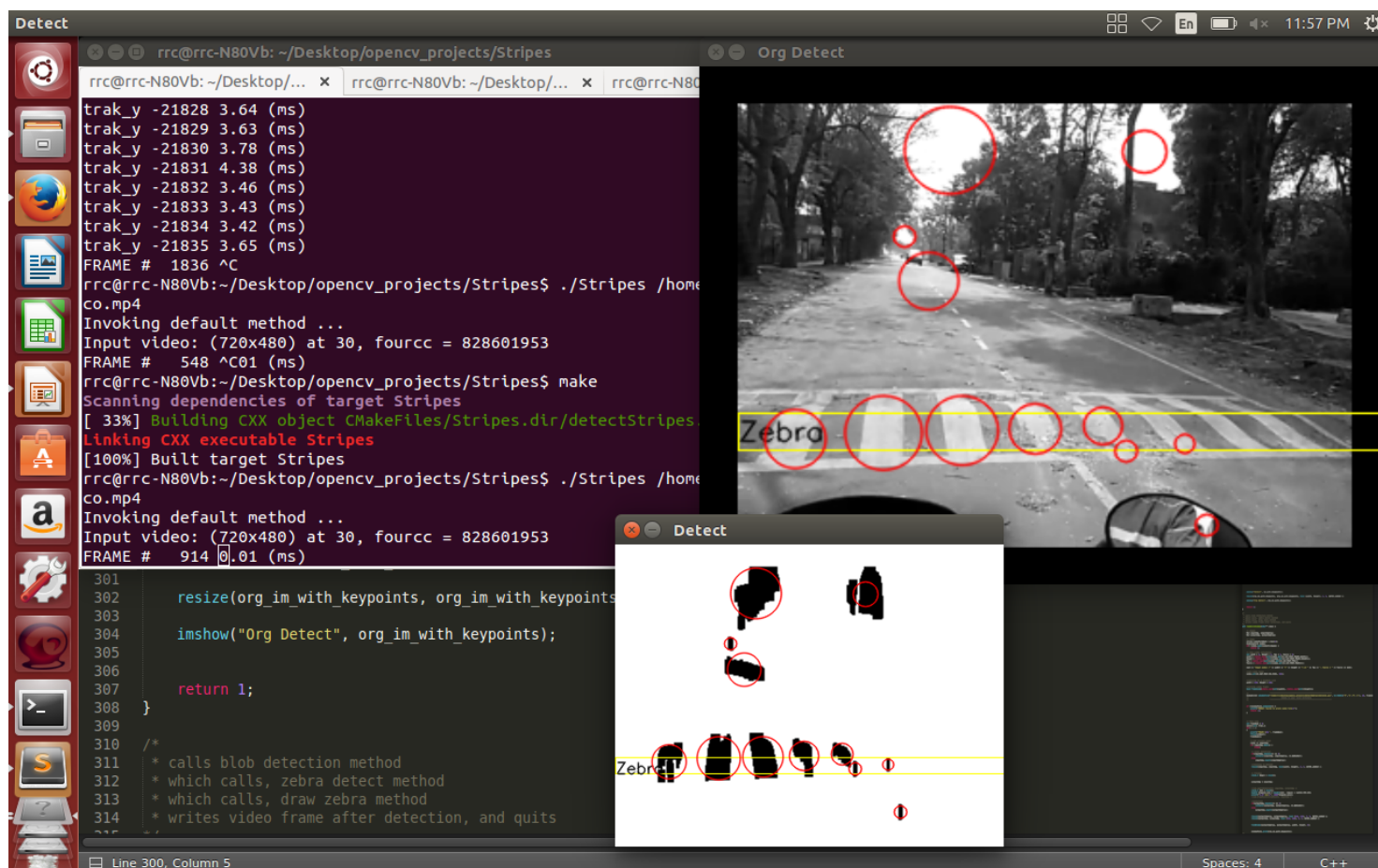
- > read a video frame
- > resize frame to 320x240
- > get homography matrix using 4 fixed points, set heuristically
- > histogram equalization
- > binary global thresholding
- > erode and dilate with vertical structuring element
- > blob detection
- > applying stripe detection using y-location, blob diameter, inter-blob distance in x and y, inter-blob diameter
- > reverse y-location using inverse homography matrix
- > draw yellow rectangle, write black "Zebra", and draw red circles around blobs at y-location with ± 10 precision

Algo 1



NALCO dataset showing white stripes with bars

Algo 1

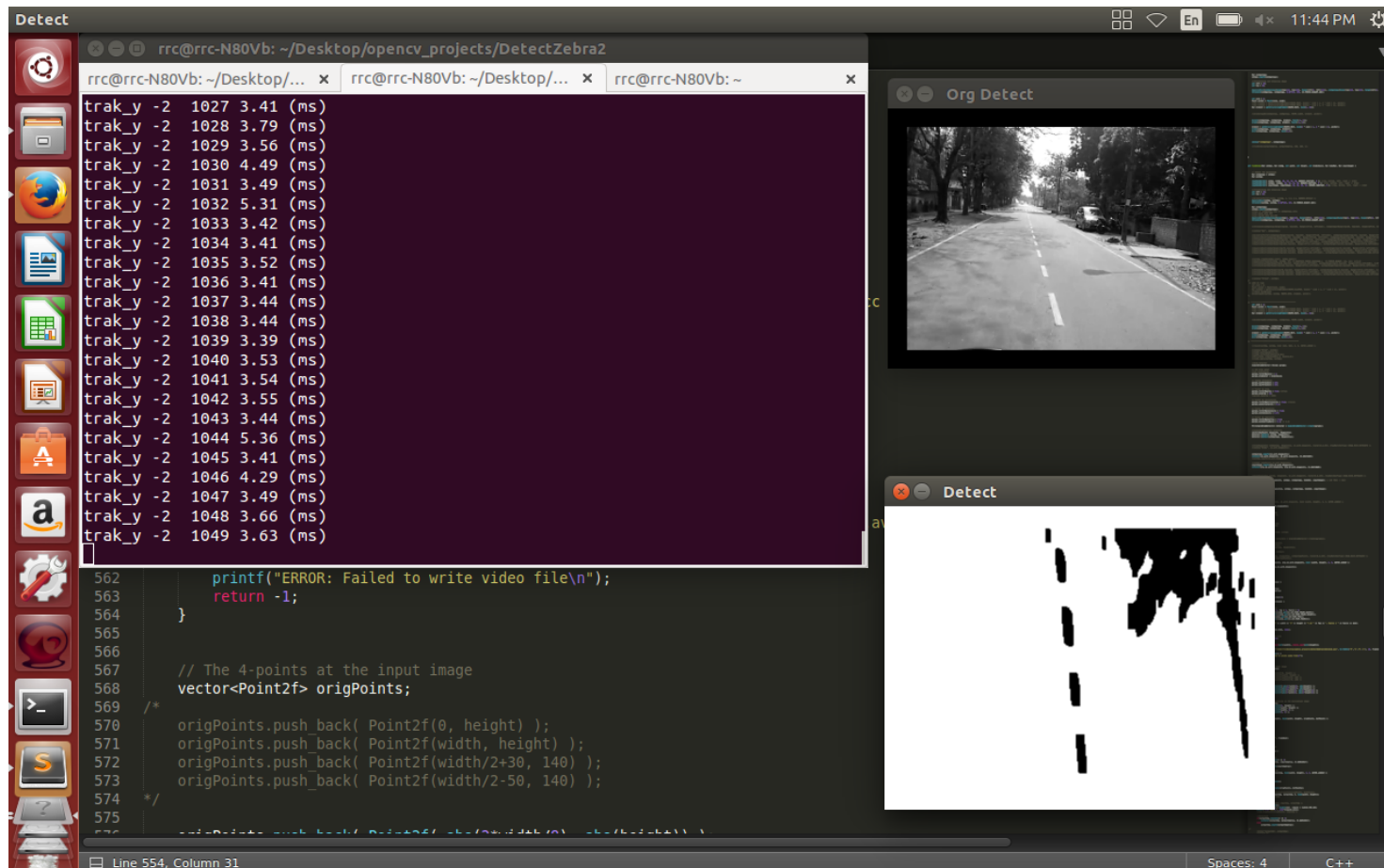


NALCO dataset showing TRUE detection of white stripes with bars

Algo 2 (detectStripeBars.cpp)

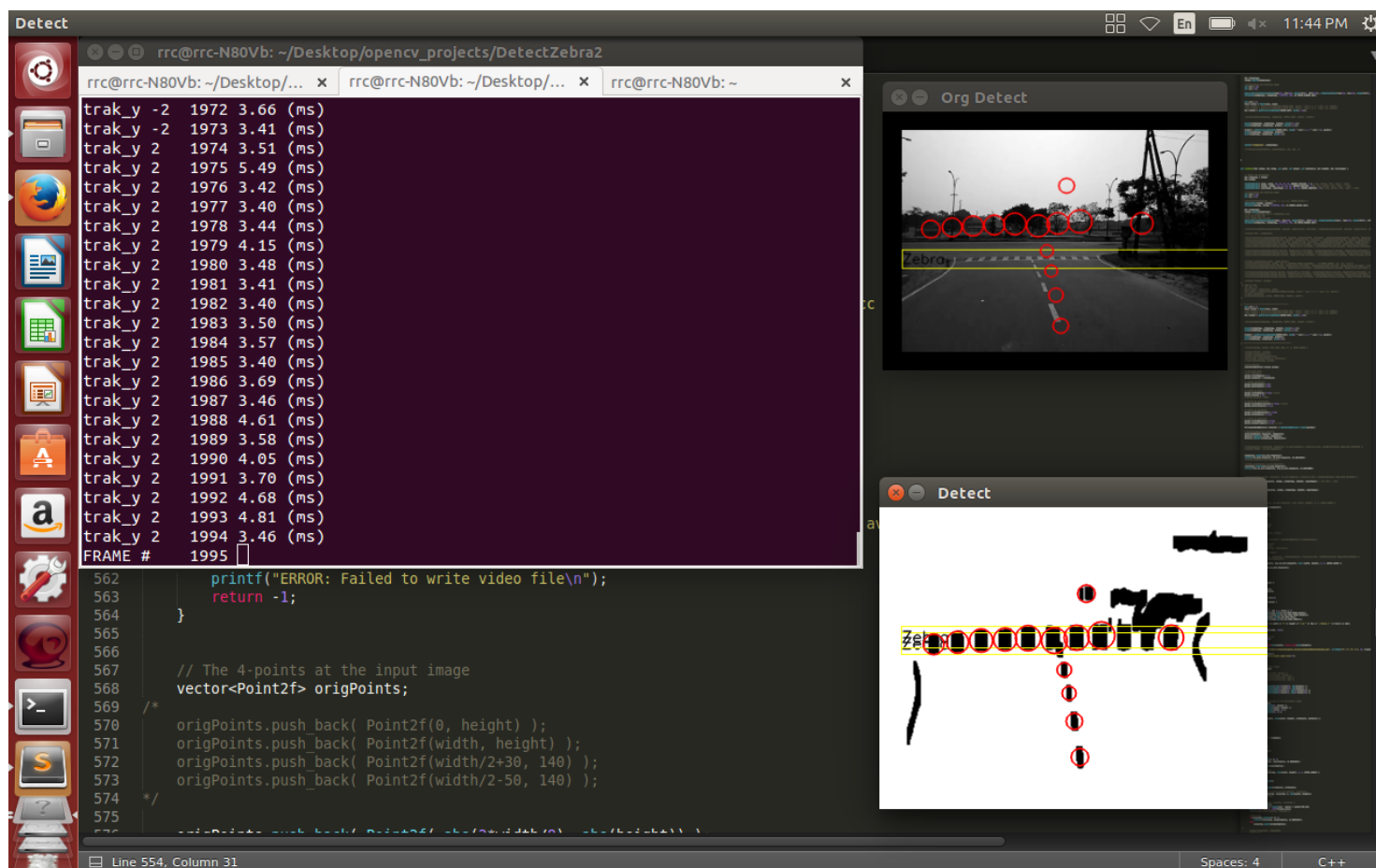
- > read a video frame
- > resize frame to 320x240
- > get homography matrix using 4 fixed points, set heuristically
- > warp perspective to get IPM
- > histogram equalization
- > binary global thresholding
- > erode and dilate with vertical structuring element
- > blob detection
- > applying stripe detection using y-location, blob diameter, inter-blob distance in x and y, inter-blob diameter
- > reverse y-location using inverse homography matrix
- > draw yellow rectangle, write black "Zebra", and draw red circles around blobs at y-location with +-10 precision
- > track a true detection up to 3 previous frames before marking it, as true

Algo 2



NALCO dataset in fixed IPM original(UP) vs processed(DOWN)

Algo 2



NALCO dataset with temporal tracking upto 3 frames)

Results

- INPUT: Lara3D, Lara3D1, Nalco, Urmi1
- OUTPUT: ZebraLara3D_5, ZebraLara3D1_5, ZebraNalco_10, ZebraUrmi_1